

$\{X_n\}$  MC, initial dist is  $\alpha^T$  (dist of  $X_0$ ),  
transition matrix  $P$



dist of  $X_n$ :  $\alpha^T \cdot P^n$



limiting dist is

$$\lim_{n \rightarrow \infty} \alpha^T \cdot P^n$$

$$\alpha^T \cdot \boxed{\lim_{n \rightarrow \infty} P^n}$$

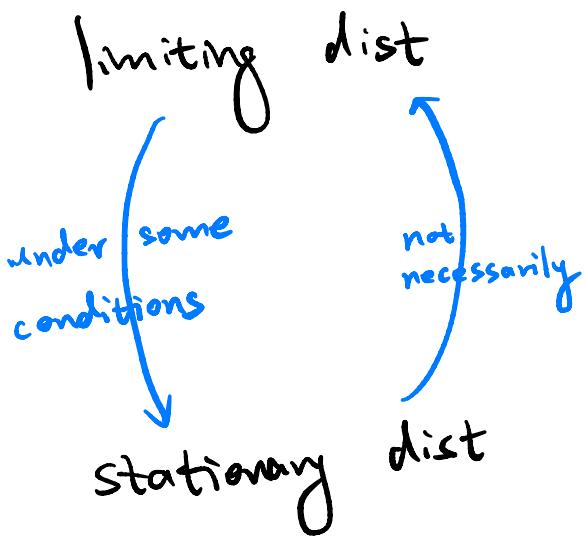
depends on the  
asymptotic behavior  
of  $P^n$ .

( $\pi$  is always a column  
vector)

stationary dist:  $\pi^T$  is a stationary  
dist if

$$\left\{ \begin{array}{l} \textcircled{1}: \underbrace{\pi_1 + \pi_2 + \dots + \pi_n = 1}_{\pi \text{ gives a distribution}}, \quad \forall i, \pi_i \geq 0 \\ \textcircled{2}: \underbrace{\pi^T P = \pi^T} \end{array} \right.$$

if  $X_n \sim \pi$ , then  $X_{n+1} \sim \pi$



$\pi$

refer to jupyter notebook  
for week 5, I have some  
examples to show the difference  
between those concepts.

e.g:  $\{X_n\}$  MC, state space  $S = \{1, 2, 3\}$ ,

$$P = \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix}, \text{ compute stationary dist } \pi.$$

PF:

$$\pi^T \cdot P = \pi^T$$

①: Plug in  $P$ , solve linear system for  $\pi$ .

②: Interpretation of eigenvector

①:

$$(\pi_1, \pi_2, \pi_3) \cdot \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix} = (\pi_1, \pi_2, \pi_3)$$

$$\left\{ \begin{array}{l} \frac{1}{4}\pi_1 + \frac{2}{3}\pi_3 = \pi_1 \\ \frac{1}{2}\pi_2 + \frac{1}{3}\pi_3 = \pi_2 \\ \frac{3}{4}\pi_1 + \frac{1}{2}\pi_2 = \pi_3 \\ \hline \pi_1 + \pi_2 + \pi_3 = 1 \end{array} \right. \Rightarrow \begin{array}{l} \text{linear system for} \\ \pi_1, \pi_2, \pi_3 \end{array}$$

normalization

solve it to get

$$\pi = \begin{pmatrix} \frac{8}{23} \\ \frac{6}{23} \\ \frac{9}{23} \end{pmatrix}$$

$$\textcircled{2}: \pi^T P = \pi^T$$

↓ take transpose

$$(\pi^T P)^T = \underbrace{P^T}_{\text{red}} \underbrace{\pi}_{\text{red}} = \pi$$

$\pi$  is the eigenvector of  $P^T$

Correspondent to eigenvalue 1

(e.g:  $Ax = \lambda x, x \neq 0$ )

$$(P^T - I) \cdot \pi = 0$$

↓

$$P = \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix}, \quad P^T = \begin{pmatrix} \frac{1}{4} & 0 & \frac{2}{3} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{3}{4} & \frac{1}{3} & 0 \end{pmatrix}$$

$$P^T - I = \begin{pmatrix} -\frac{3}{4} & 0 & \frac{2}{3} \\ 0 & -\frac{1}{2} & \frac{1}{3} \\ \frac{3}{4} & \frac{1}{2} & -1 \end{pmatrix}$$

$\pi$  is in the null space of  $P^T - I$ .

$$\left( \begin{array}{ccc} -\frac{3}{4} & 0 & \frac{2}{3} \\ 0 & -\frac{1}{2} & \frac{1}{3} \\ \frac{3}{4} & \frac{1}{2} & -1 \end{array} \right) \xrightarrow{\begin{array}{l} \text{row 2} \\ \times (-2) \\ \text{row 1} \\ \text{add row 3} \\ 3 \end{array}} \left( \begin{array}{ccc} 0 & \frac{1}{2} & -\frac{1}{3} \\ 0 & 1 & -\frac{2}{3} \\ \frac{3}{4} & \frac{1}{2} & -1 \end{array} \right)$$

↓  
row 3 ×  $\frac{4}{3}$   
row 1 - (row 2 ×  $\frac{1}{2}$ )

$$\left( \begin{array}{ccc} 0 & 0 & 0 \\ 0 & 1 & -\frac{2}{3} \\ -1 & \frac{2}{3} & -\frac{4}{3} \end{array} \right)$$

↓

$$\begin{cases} \pi_2 - \frac{2}{3}\pi_3 = 0 \\ \pi_1 + \frac{2}{3}\pi_2 - \frac{4}{3}\pi_3 = 0 \end{cases}$$

null space is

$$\left( \begin{array}{c} \frac{8}{9}a \\ \frac{2}{3}a \\ a \end{array} \right)$$

Normalization step

$$\frac{8}{9}a + \frac{2}{3}a + a = 1 \quad (\pi \text{ prob dist})$$

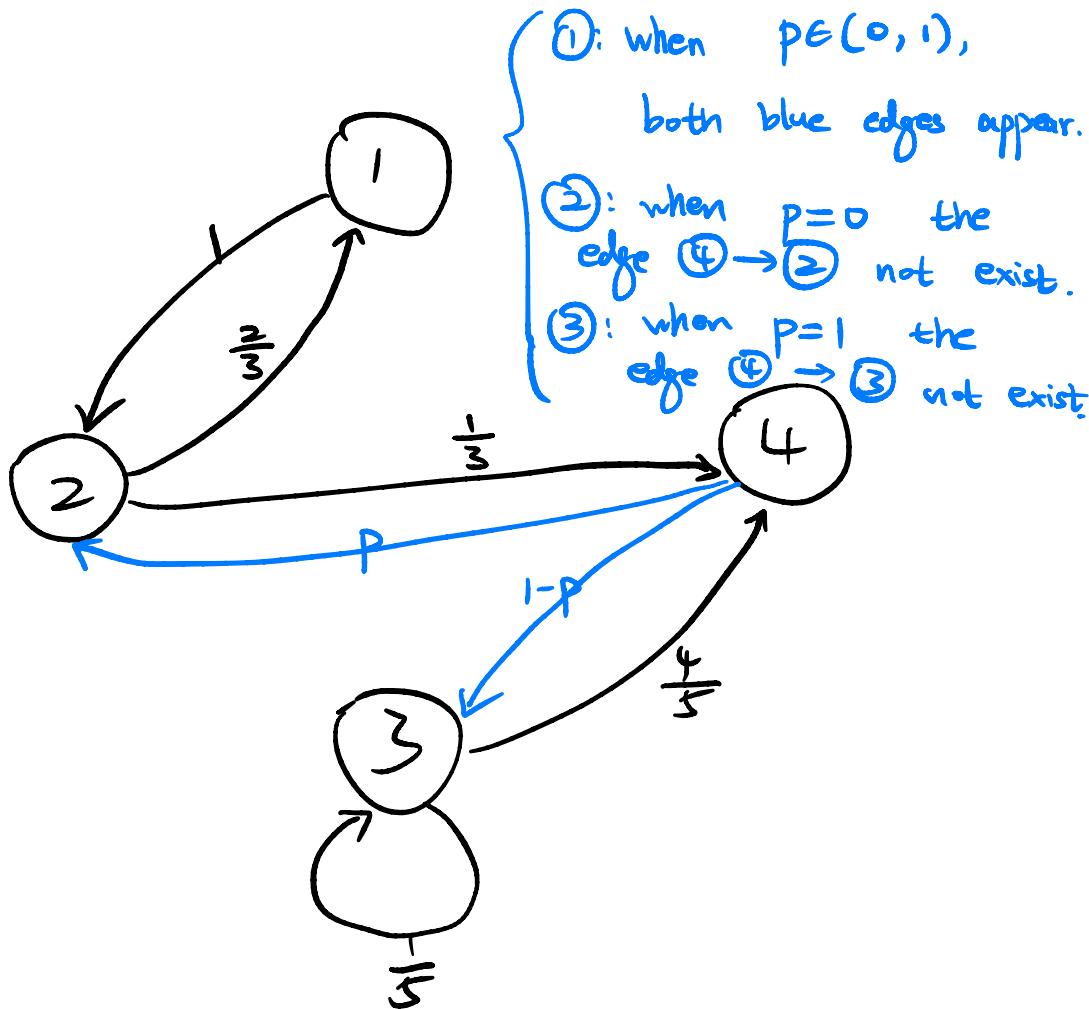
$$\Rightarrow a = \frac{9}{23} \Rightarrow \pi = \left( \begin{array}{c} \frac{8}{23} \\ \frac{6}{23} \\ \frac{9}{23} \end{array} \right)$$

same answer.

e.g:  $\{X_n\}$  MC, state space  $S = \{1, 2, 3, 4\}$ ,

$$P = \begin{pmatrix} 0 & 1 & 0 & 0 \\ \frac{2}{3} & 0 & 0 & \frac{1}{3} \\ 0 & 0 & \frac{1}{5} & \frac{4}{5} \\ 0 & p & 1-p & 0 \end{pmatrix}, \quad p \in [0, 1]$$

(a): Provide transition graph.



for any two states in the same comm class,  
they can reach each other.

(b): Determine all communication classes, which  
classes are closed?

a comm class is closed if A state in the  
comm class, it can never reach states out  
of the comm class.

If: If  $p \in (0, 1)$ , since every two states  
can reach each other, com class is  
 $\{1, 2, 3, 4\}$ , closed.

If  $p=0$ , two comm class  $\{1, 2\}$   
and  $\{3, 4\}$ .  $\leftarrow$  closed

If  $p=1$ , two comm class  $\{1, 2, 4\}$   
and  $\{3\}$ .

$\uparrow$   
not closed  
(since 3 can reach 4)

$\uparrow$   
closed  
(since 2 can reach 4)

(c): Now fix  $p=0$ . Initial dist is  $\alpha^T = (0, 0, \frac{5}{9}, \frac{4}{9})$ , compute dist of  $X_1$ , and dist of  $X_{103}$ .

Pf: Dist of  $X_1$  is  $\alpha^T \cdot P$

$$\underbrace{(0, 0, \frac{5}{9}, \frac{4}{9})}_{\alpha^T} \cdot \begin{pmatrix} 0 & 1 & 0 & 0 \\ \frac{2}{9} & 0 & 0 & \frac{1}{9} \\ 0 & 0 & \frac{1}{5} & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & \frac{5}{9} & \frac{4}{9} \end{pmatrix}$$

$$\underbrace{\alpha^T}_{\alpha^T}$$

$\Rightarrow \alpha^T$  is the stationary distribution.

Dist of  $X_{103}$  is  $\alpha^T \cdot P^{103}$

$$= \underbrace{(\alpha^T P)}_{\alpha^T} \cdot P^{102} = \alpha^T \cdot P^{102} = \dots = \alpha^T \cdot P$$

$$= \alpha^T = (0 \ 0 \ \frac{5}{9} \ \frac{4}{9}).$$