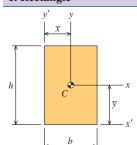
### Table A.1 Properties of Plane Figures

# 1. Rectangle



$$A = bh$$

$$\overline{y} = \frac{h}{2}$$

$$\overline{y} = \frac{h}{2} \qquad I_x = \frac{bh^3}{12}$$

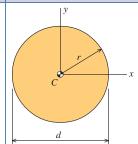
$$\overline{x} = \frac{b}{2}$$

$$\overline{x} = \frac{b}{2} \qquad I_y = \frac{hb^3}{12}$$

$$I_{x'} = \frac{bh^3}{3}$$

$$I_{x'} = \frac{bh^3}{3}$$
  $I_{y'} = \frac{hb^3}{3}$ 

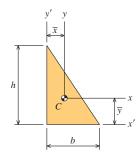
#### 6. Circle



$$A = \pi r^2 = \frac{\pi d^2}{4}$$

$$I_x = I_y = \frac{\pi r^4}{4} = \frac{\pi d^4}{64}$$

#### 2. Right Triangle



$$A = \frac{bh}{2}$$

$$\overline{y} = \frac{h}{3}$$

$$\overline{y} = \frac{h}{3} \qquad I_x = \frac{bh^3}{36}$$

$$\overline{x} = \frac{b}{3}$$

$$\overline{x} = \frac{b}{3} \qquad I_y = \frac{hb^3}{36}$$

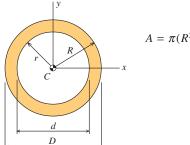
$$I_{x'} = \frac{bh^3}{12}$$
  $I_{y'} = \frac{hb^3}{12}$ 

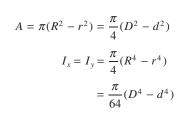
$$= \frac{36}{36}$$

$$= \frac{hb^3}{36}$$

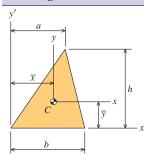
$$= \frac{hb^3}{36}$$

#### 7. Hollow Circle





#### 3. Triangle



$$A = \frac{bh}{2}$$

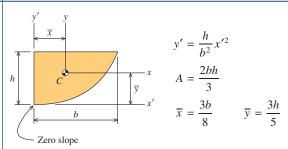
$$\overline{y} = \frac{h}{3}$$

$$\overline{y} = \frac{h}{3} \qquad I_x = \frac{bh^3}{36}$$

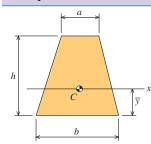
$$\overline{x} = \frac{(a+b)}{2}$$

$$\overline{x} = \frac{(a+b)}{3} \quad I_y = \frac{bh}{36} (a^2 - ab + b^2)$$

# 8. Parabola



#### 4. Trapezoid

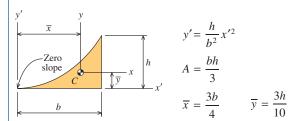


$$A = \frac{(a+b)h}{2}$$

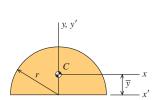
$$\overline{y} = \frac{1}{3} \left( \frac{2a+b}{a+b} \right) h$$

$$\int_{\overline{y}}^{x} I_{x} = \frac{h^{3}}{36(a+b)} (a^{2} + 4ab + b^{2})$$

### 9. Parabolic Spandrel



#### 5. Semicircle

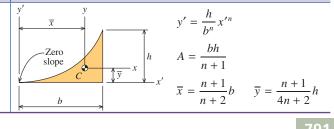


$$A = \frac{\pi r^2}{2}$$

$$\overline{y} = \frac{4r}{3\pi} \qquad I_x = \left(\frac{\pi}{8} - \frac{8}{9\pi}\right)r^4$$

$$\frac{3\pi}{\sqrt[3]{y}} x I_{x'} = I_{y'} = \frac{\pi r^4}{8}$$

#### 10. General Spandrel



# Fundamental Mechanics of Materials Equations

# **Common Greek letters**

$\alpha$	Alpha	μ	Mu
β	Beta	V	Nu
γ	Gamma	$\pi$	Pi
$\Delta$ , $\delta$	Delta	$\rho$	Rho
$\varepsilon$	Epsilon	Σ, σ	Sigma
$\theta$	Theta	τ	Tau
κ	Kappa	$\phi$	Phi
λ	Lambda	ω	Omega

#### **Basic definitions**

Average normal stress in an axial member

$$\sigma_{\text{avg}} = \frac{F}{A}$$

Average direct shear stress

$$\tau_{\text{avg}} = \frac{V}{A_V}$$

Average bearing stress

$$\sigma_b = \frac{F}{A_b}$$

Average normal strain in an axial member

$$\varepsilon_{\text{long}} = \frac{\Delta L}{L} = \frac{\delta}{L}$$

$$\varepsilon_{\text{lat}} = \frac{\Delta d}{d} \quad \text{or} \quad \frac{\Delta t}{t} \quad \text{or} \quad \frac{\Delta h}{h}$$

Average normal strain caused by temperature change

$$\varepsilon_T = \alpha \Delta T$$

Average shear strain

$$\gamma$$
 = change in angle from  $\frac{\pi}{2}$  rad

Hooke's law (one-dimensional)

$$\sigma = E\varepsilon$$
 and  $\tau = G\gamma$ 

Poisson's ratio

$$v = -\frac{\varepsilon_{\text{lat}}}{\varepsilon_{\text{long}}}$$

Relationship between E, G, and v

$$G = \frac{E}{2(1+v)}$$

Definition of allowable stress

$$\sigma_{\mathrm{allow}} = \frac{\sigma_{\mathrm{failure}}}{\mathrm{FS}} \qquad \mathrm{or} \qquad au_{\mathrm{allow}} = \frac{ au_{\mathrm{failure}}}{\mathrm{FS}}$$

Factor of safety

$$FS = \frac{\sigma_{failure}}{\sigma_{actual}} \qquad \text{or} \qquad FS = \frac{\tau_{failure}}{\tau_{actual}}$$

#### **Axial deformation**

Deformation in axial members

$$\delta = \frac{FL}{AE}$$
 or  $\delta = \sum_{i} \frac{F_{i}L_{i}}{A_{i}E_{i}}$ 

Force-temperature-deformation relationship

$$\delta = \frac{FL}{AE} + \alpha \Delta T L$$

#### **Torsion**

Maximum torsion shear stress in a circular shaft

$$\tau_{\text{max}} = \frac{Tc}{J}$$

where the polar moment of inertia J is defined as:

$$J = \frac{\pi}{2} [R^4 - r^4] = \frac{\pi}{32} [D^4 - d^4]$$

Angle of twist in a circular shaft

$$\phi = \frac{TL}{JG}$$
 or  $\phi = \sum_{i} \frac{T_i L_i}{J_i G_i}$ 

Power transmission in a shaft

$$P = T\omega$$

Power units and conversion factors

$$1 \text{ W} = \frac{1 \text{ N} \cdot \text{m}}{\text{s}} \qquad 1 \text{ hp} = \frac{550 \text{ lb} \cdot \text{ft}}{\text{s}} = \frac{6,600 \text{ lb} \cdot \text{in.}}{\text{s}}$$
$$1 \text{ Hz} = \frac{1 \text{ rev}}{\text{s}} \qquad 1 \text{ rev} = 2\pi \text{ rad}$$

$$1 \text{ rpm} = \frac{2\pi \text{ rad}}{60 \text{ s}}$$

Gear relationships between gears A and B

$$\frac{T_A}{R_A} = \frac{T_B}{R_B} \qquad R_A \phi_A = -R_B \phi_B \qquad R_A \omega_A = R_B \omega_B$$

$$Gear ratio = \frac{R_A}{R_B} = \frac{D_A}{D_B} = \frac{N_A}{N_B}$$

# Six rules for constructing shear-force and bending-moment diagrams

Rule 1: 
$$\Delta V = P_0$$

Rule 2: 
$$\Delta V = V_2 - V_1 = \int_{x}^{x_2} w(x) dx$$

Rule 3: 
$$\frac{dV}{dx} = w(x)$$

Rule 4: 
$$\Delta M = M_2 - M_1 = \int_{x_1}^{x_2} V \, dx$$

Rule 5: 
$$\frac{dM}{dx} = V$$

Rule 6: 
$$\Delta M = -M_0$$

#### **Flexure**

Flexural strain and stress

$$\varepsilon_x = -\frac{1}{\rho}y$$
  $\sigma_x = -\frac{E}{\rho}y$ 

extree Formula
$$\sigma_x = -\frac{My}{I_z} \quad \text{or} \quad \sigma_{\text{max}} = \frac{Mc}{I} = \frac{M}{S} \quad \text{where } S = \frac{I}{C}$$

Transformed-section method for beams of two materials [where material (2) is transformed into an equivalent amount of material (1)]

$$n = \frac{E_2}{E_1}$$
  $\sigma_{x1} = -\frac{My}{I_{\text{transformed}}}$   $\sigma_{x2} = -n\frac{My}{I_{\text{transformed}}}$ 

Bending due to eccentric axial load

$$\sigma_x = \frac{F}{A} - \frac{My}{I}$$

Unsymmetric bending of arbitrary cross sections

$$\sigma_{x} = \left[ \frac{I_{z}z - I_{yz}y}{I_{y}I_{z} - I_{yz}^{2}} \right] M_{y} + \left[ \frac{-I_{y}y + I_{yz}z}{I_{y}I_{z} - I_{yz}^{2}} \right] M_{z}$$

$$\sigma_{x} = -\frac{(M_{z}I_{y} + M_{y}I_{yz})y}{I_{y}I_{z} - I_{yz}^{2}} + \frac{(M_{y}I_{z} + M_{z}I_{yz})z}{I_{y}I_{z} - I_{yz}^{2}}$$

$$\tan \beta = \frac{M_{y}I_{z} + M_{z}I_{yz}}{M_{z}I_{y} + M_{y}I_{yz}}$$

Unsymmetric bending of symmetric cross sections

$$\sigma_x = \frac{M_y z}{I_y} - \frac{M_z y}{I_z}$$
  $\tan \beta = \frac{M_y I_z}{M_z I_y}$ 

Bending of curved bars

$$\sigma_x = -\frac{M(r_n - r)}{rA(r_c - r_n)}$$
 where  $r_n = \frac{A}{\int_A \frac{dA}{r}}$ 

Horizontal shear stress associated with bending

$$\tau_H = \frac{VQ}{It}$$
 where  $Q = \Sigma \overline{y_i} A_i$ 

Shear flow formula

$$q = \frac{VQ}{I}$$

Shear flow, fastener spacing, and fastener shear relationship

$$qs \le n_f V_f = n_f \tau_f A_f$$

For circular cross sections

$$Q = \frac{2}{3}r^3 = \frac{1}{12}d^3$$
 (solid sections)  

$$Q = \frac{2}{3}[R^3 - r^3] = \frac{1}{12}[D^3 - d^3]$$
 (hollow sections)

#### Beam deflections

Elastic curve relations between w, V, M,  $\theta$ , and v for constant EI

Deflection = v

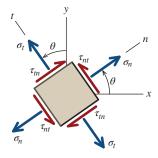
Slope = 
$$\frac{dv}{dx} = \theta$$
 (for small deflections)

$$Moment M = EI \frac{d^2v}{dx^2}$$

Shear 
$$V = \frac{dM}{dx} = EI \frac{d^3v}{dx^3}$$

Load 
$$w = \frac{dV}{dx} = EI \frac{d^4v}{dx^4}$$

## Plane stress transformations



Stresses on an arbitrary plane

$$\sigma_n = \sigma_x \cos^2 \theta + \sigma_y \sin^2 \theta + 2\tau_{xy} \sin \theta \cos \theta$$

$$\sigma_t = \sigma_x \sin^2 \theta + \sigma_y \cos^2 \theta - 2\tau_{xy} \sin \theta \cos \theta$$

$$\tau_{nt} = -(\sigma_x - \sigma_y)\sin\theta\cos\theta + \tau_{xy}(\cos^2\theta - \sin^2\theta)$$

Ω1

$$\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta$$

$$\sigma_t = \frac{\sigma_x + \sigma_y}{2} - \frac{\sigma_x - \sigma_y}{2} \cos 2\theta - \tau_{xy} \sin 2\theta$$

$$\tau_{nt} = -\frac{\sigma_x - \sigma_y}{2} \sin 2\theta + \tau_{xy} \cos 2\theta$$

Principal stress magnitudes

$$\sigma_{p1,p2} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}$$

Orientation of principal planes

$$\tan 2\theta_p = \frac{2\tau_{xy}}{\sigma_x - \sigma_y}$$

Maximum in-plane shear stress magnitude

$$\tau_{\text{max}} = \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \quad \text{or} \quad \tau_{\text{max}} = \frac{\sigma_{p1} - \sigma_{p2}}{2}$$

$$\sigma_{\text{avg}} = \frac{\sigma_x + \sigma_y}{2}$$

$$\tan 2\theta_s = -\frac{\sigma_x - \sigma_y}{2\tau_{xy}} \quad \text{note: } \theta_s = \theta_p \pm 45^\circ$$

Absolute maximum shear stress magnitude

$$\tau_{\text{abs max}} = \frac{\sigma_{\text{max}} - \sigma_{\text{min}}}{2}$$

Normal stress invariance

$$\sigma_x + \sigma_y = \sigma_n + \sigma_t = \sigma_{p1} + \sigma_{p2}$$

#### Plane strain transformations

Strain in arbitrary directions

$$\varepsilon_n = \varepsilon_x \cos^2 \theta + \varepsilon_y \sin^2 \theta + \gamma_{xy} \sin \theta \cos \theta 
\varepsilon_t = \varepsilon_x \sin^2 \theta + \varepsilon_y \cos^2 \theta - \gamma_{xy} \sin \theta \cos \theta 
\gamma_{nt} = -2(\varepsilon_x - \varepsilon_y) \sin \theta \cos \theta + \gamma_{xy} (\cos^2 \theta - \sin^2 \theta)$$

or

$$\varepsilon_{n} = \frac{\varepsilon_{x} + \varepsilon_{y}}{2} + \frac{\varepsilon_{x} - \varepsilon_{y}}{2} \cos 2\theta + \frac{\gamma_{xy}}{2} \sin 2\theta$$

$$\varepsilon_{t} = \frac{\varepsilon_{x} + \varepsilon_{y}}{2} - \frac{\varepsilon_{x} - \varepsilon_{y}}{2} \cos 2\theta - \frac{\gamma_{xy}}{2} \sin 2\theta$$

$$\gamma_{nt} = -(\varepsilon_{x} - \varepsilon_{y}) \sin 2\theta + \gamma_{xy} \cos 2\theta$$

Principal strain magnitudes

$$\varepsilon_{p1,p2} = \frac{\varepsilon_x + \varepsilon_y}{2} \pm \sqrt{\left(\frac{\varepsilon_x - \varepsilon_y}{2}\right)^2 + \left(\frac{\gamma_{xy}}{2}\right)^2}$$

Orientation of principal strains

$$\tan 2\theta_p = \frac{\gamma_{xy}}{\varepsilon_x - \varepsilon_y}$$

Maximum in-plane shear strain

$$\gamma_{\text{max}} = \pm 2\sqrt{\left(\frac{\varepsilon_x - \varepsilon_y}{2}\right)^2 + \left(\frac{\gamma_{xy}}{2}\right)^2} \quad \text{or} \quad \gamma_{\text{max}} = \varepsilon_{p1} - \varepsilon_{p2}$$

$$\varepsilon_{\text{avg}} = \frac{\varepsilon_x + \varepsilon_y}{2}$$

Normal strain invariance

$$\varepsilon_x + \varepsilon_y = \varepsilon_n + \varepsilon_t = \varepsilon_{p1} + \varepsilon_{p2}$$

#### Generalized Hooke's law

Normal stress/normal strain relationships

$$\varepsilon_{x} = \frac{1}{E} [\sigma_{x} - v(\sigma_{y} + \sigma_{z})]$$

$$\varepsilon_{y} = \frac{1}{E} [\sigma_{y} - v(\sigma_{x} + \sigma_{z})]$$

$$\varepsilon_{z} = \frac{1}{E} [\sigma_{z} - v(\sigma_{x} + \sigma_{y})]$$

$$\sigma_{x} = \frac{E}{(1+v)(1-2v)} [(1-v)\varepsilon_{x} + v(\varepsilon_{y} + \varepsilon_{z})]$$

$$\sigma_{y} = \frac{E}{(1+v)(1-2v)} [(1-v)\varepsilon_{y} + v(\varepsilon_{x} + \varepsilon_{z})]$$

$$\sigma_{z} = \frac{E}{(1+v)(1-2v)} [(1-v)\varepsilon_{z} + v(\varepsilon_{x} + \varepsilon_{y})]$$

Shear stress/shear strain relationships

$$\gamma_{xy} = \frac{1}{G} \tau_{xy}; \qquad \gamma_{yz} = \frac{1}{G} \tau_{yz}; \qquad \gamma_{zx} = \frac{1}{G} \tau_{zx}$$

where

$$G = \frac{E}{2(1+v)}$$

Volumetric strain or Dilatation

$$e = \frac{\Delta V}{V} = \varepsilon_x + \varepsilon_y + \varepsilon_z = \frac{1 - 2v}{E} (\sigma_x + \sigma_y + \sigma_z)$$

Bulk modulus

$$K = \frac{E}{3(1 - 2\nu)}$$

Normal stress/normal strain relationships for plane stress

$$\varepsilon_{x} = \frac{1}{E}(\sigma_{x} - v\sigma_{y})$$

$$\varepsilon_{y} = \frac{1}{E}(\sigma_{y} - v\sigma_{x})$$

$$\varepsilon_{z} = -\frac{v}{E}(\sigma_{x} + \sigma_{y})$$
or
$$\sigma_{x} = \frac{E}{1 - v^{2}}(\varepsilon_{x} + v\varepsilon_{y})$$

$$\sigma_{y} = \frac{E}{1 - v^{2}}(\varepsilon_{y} + v\varepsilon_{x})$$

$$\varepsilon_{z} = -\frac{v}{1 - v}(\varepsilon_{x} + \varepsilon_{y})$$

Shear stress/shear strain relationships for plane stress

$$\gamma_{xy} = \frac{1}{G} \tau_{xy}$$
 or  $\tau_{xy} = G \gamma_{xy}$ 

# Thin-walled pressure vessels

Tangential stress and strain in spherical pressure vessel

$$\sigma_t = \frac{pr}{2t} = \frac{pd}{4t}$$
  $\varepsilon_t = \frac{pr}{2tE}(1-v)$ 

Longitudinal and circumferential stresses in cylindrical pressure vessels

$$\sigma_{\text{long}} = \frac{pr}{2t} = \frac{pd}{4t}$$
  $\varepsilon_{\text{long}} = \frac{pr}{2tE}(1 - 2v)$ 

$$\sigma_{\text{hoop}} = \frac{pr}{t} = \frac{pd}{2t}$$
  $\varepsilon_{\text{hoop}} = \frac{pr}{2tE}(2 - v)$ 

# Thick-walled pressure vessels

Radial stress in thick-walled cylinder

$$\sigma_r = \frac{a^2 p_i - b^2 p_o}{b^2 - a^2} - \frac{a^2 b^2 (p_i - p_o)}{(b^2 - a^2)r^2}$$

01

$$\sigma_r = \frac{a^2 p_i}{b^2 - a^2} \left( 1 - \frac{b^2}{r^2} \right) - \frac{b^2 p_o}{b^2 - a^2} \left( 1 - \frac{a^2}{r^2} \right)$$

Circumferential stress in thick-walled cylinder

$$\sigma_{\theta} = \frac{a^2 p_i - b^2 p_o}{b^2 - a^2} + \frac{a^2 b^2 (p_i - p_o)}{(b^2 - a^2)r^2}$$

Ωt

$$\sigma_{\theta} = \frac{a^2 p_i}{b^2 - a^2} \left( 1 + \frac{b^2}{r^2} \right) - \frac{b^2 p_o}{b^2 - a^2} \left( 1 + \frac{a^2}{r^2} \right)$$

Maximum shear stress

$$\tau_{\text{max}} = \frac{1}{2}(\sigma_{\theta} - \sigma_r) = \frac{a^2b^2(p_i - p_o)}{(b^2 - a^2)r^2}$$

Longitudinal normal stress in closed cylinder

$$\sigma_{\text{long}} = \frac{a^2 p_i - b^2 p_o}{b^2 - a^2}$$

Radial displacement for internal pressure only

$$\delta_r = \frac{a^2 p_i}{(b^2 - a^2)rE} [(1 - v)r^2 + (1 + v)b^2]$$

Radial displacement for external pressure only

$$\delta_r = -\frac{b^2 p_o}{(b^2 - a^2)rE} [(1 - v)r^2 + (1 + v)a^2]$$

Radial displacement for external pressure on solid cylinder

$$\delta_r = -\frac{(1-v)p_o r}{E}$$

Contact pressure for interference fit connection of thick cylinder onto a thick cylinder

$$p_c = \frac{E\delta(c^2 - b^2)(b^2 - a^2)}{2b^3(c^2 - a^2)}$$

Contact pressure for interference fit connection of thick cylinder onto a solid cylinder

$$p_c = \frac{E\delta(c^2 - b^2)}{2bc^2}$$

### **Failure theories**

Mises equivalent stress for plane stress

$$\sigma_{M} = \left[\sigma_{p1}^{2} - \sigma_{p1}\sigma_{p2} + \sigma_{p2}^{2}\right]^{1/2} = \left[\sigma_{x}^{2} - \sigma_{x}\sigma_{y} + \sigma_{y}^{2} + 3\tau_{xy}^{2}\right]^{1/2}$$

# Column buckling

Euler buckling load

$$P_{cr} = \frac{\pi^2 EI}{(KL)^2}$$

Euler buckling stress

$$\sigma_{cr} = \frac{\pi^2 E}{(KL/r)^2}$$

Radius of gyration

$$r^2 = \frac{I}{A}$$

Secant formula

$$\sigma_{\text{max}} = \frac{P}{A} \left[ 1 + \frac{ec}{r^2} \sec \left( \frac{KL}{2r} \sqrt{\frac{P}{EA}} \right) \right]$$

Simply Supported Beams

$\frac{1}{a^2}$ $\frac{1}{a^2}$ $\frac{1}{a^2}$ $\frac{1}{a^2}$ $-a^2$	Deflection Elastic Curve	$v_{\text{max}} = -\frac{PL^3}{48EI}$ $for 0 \le x \le \frac{L}{2}$	$v = -\frac{Pa^2b^2}{3LEI}$ $v = -\frac{Pbx}{6LEI}(L^2 - b^2 - x^2)$ $at x = a$ $for 0 \le x \le a$	$v_{\text{max}} = -\frac{ML^2}{9\sqrt{3}EI}$ $v = -\frac{Mx}{6LEI}(2L^2 - 3Lx + x^2)$ at $x = L\left(1 - \frac{\sqrt{3}}{3}\right)$	$v_{\text{max}} = -\frac{5wL^4}{384EI}$ $v = -\frac{wx}{24EI}(L^3 - 2Lx^2 + x^3)$	$v = -\frac{wx}{24LEI}(Lx^3 - 4aLx^2 + 2a^2x^2 + 4aLEI)$ $v = -\frac{wa^3}{24LEI}(4L^2 - 7aL + 3a^2)$ $at x = a$ $v = -\frac{wa^2}{24LEI}(2x^3 - 6Lx^2 + a^2x + 4L^2x - a^2L)$ for $a \le x \le L$	0.000 $0.00$
Beam $ \begin{array}{c} P \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1$					$\frac{wL^3}{24EI}$		$\theta_1 = -\frac{7w_0 L^3}{360EI}$ $v_{\text{max}} = -0.00652 \frac{w_0 L^4}{EI}$
	Beam	P	β		W W W W W W W W W W W W W W W W W W W		

**Cantilever Beams** 

Elastic Curve	$v = -\frac{Px^2}{6EI}(3L - x)$	$v = -\frac{Px^2}{12EI}(3L - 2x)$ for $0 \le x \le \frac{L}{2}$ $v = -\frac{PL^2}{48EI}(6x - L)$ for $\frac{L}{2} \le x \le L$	$v = -\frac{Mx^2}{2EI}$	$v = -\frac{wx^2}{24EI}(6L^2 - 4Lx + x^2)$	$v = -\frac{w_0 x^2}{120 LEI} (10 L^3 - 10 L^2 x + 5 L x^2 - x^3)$
Deflection	$v_{\text{max}} = -\frac{PL^3}{3EI}$	$v_{\text{max}} = -\frac{5PL^3}{48EI}$	$v_{\rm max} = -\frac{ML^2}{2EI}$	$v_{\rm max} = -\frac{wL^4}{8EI}$	$\nu_{\rm max} = -\frac{w_0 L^4}{30EI}$
Slope	$ heta_{ m max} = -rac{PL^2}{2EI}$	$ heta_{ m max} = -rac{PL^2}{8EI}$	$ heta_{ m max} = -rac{ML}{EI}$	$ heta_{ m max} = -rac{wL^3}{6EI}$	$\theta_{\text{max}} = -\frac{w_0 L^3}{24 EI}$
Beam	P P P P P P P P P P P P P P P P P P P	$\begin{array}{c c} V \\ \hline \\$	$ \begin{array}{c c} V & M & M \\ \hline V & M $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	V W <sub>0</sub> V W <sub>0</sub> V V V V V V V V V V V V V V V V V V V
	7	∞	6	10	11