Circular Trajectory Approach (CTA) for Sine Wave Distortion Monitoring and Visualization



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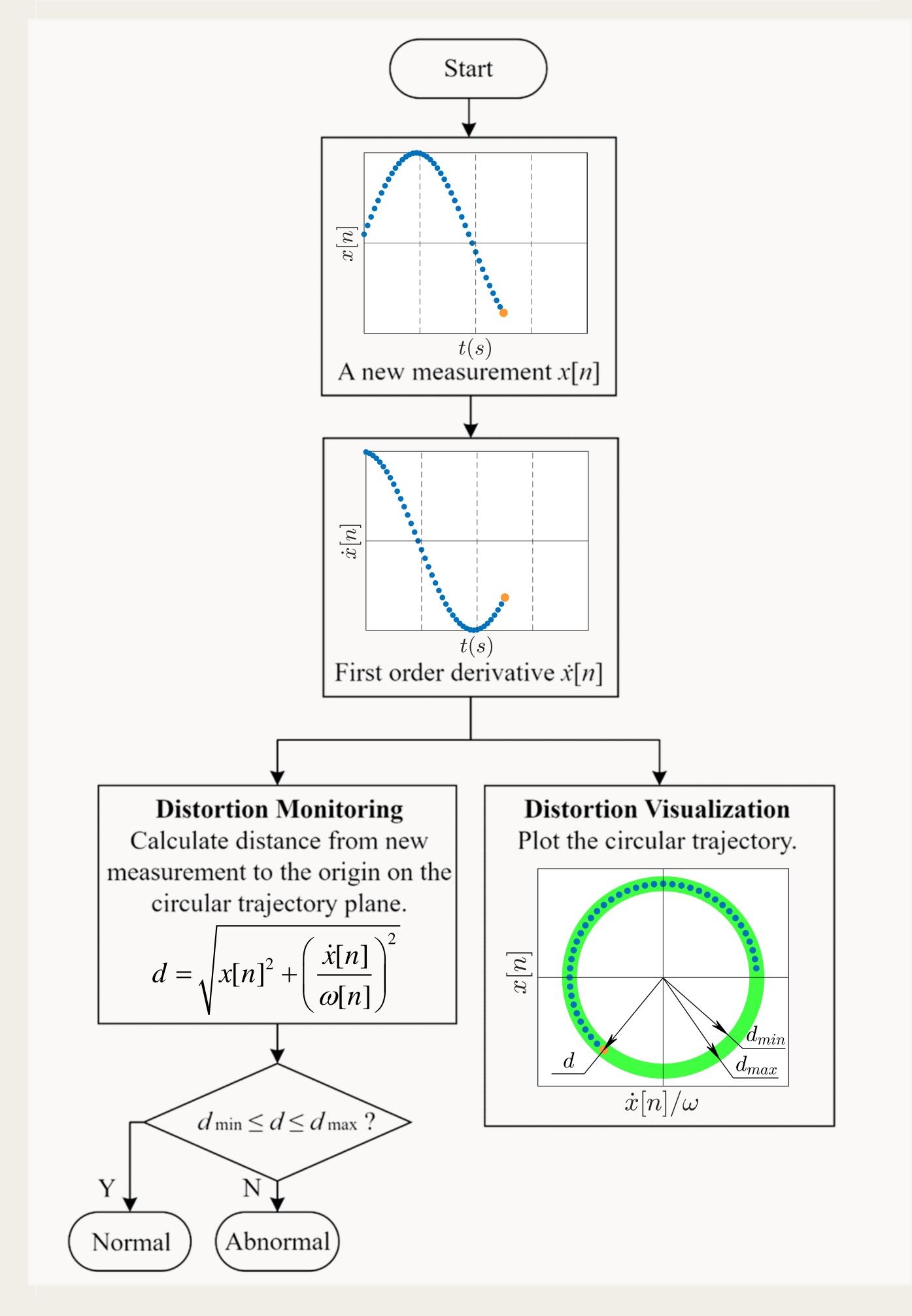


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Main Idea

To transpose a fluctuating <u>Sine Wave</u> into a <u>Static Shape</u> so that its distortions are easier to monitor.

Workflow

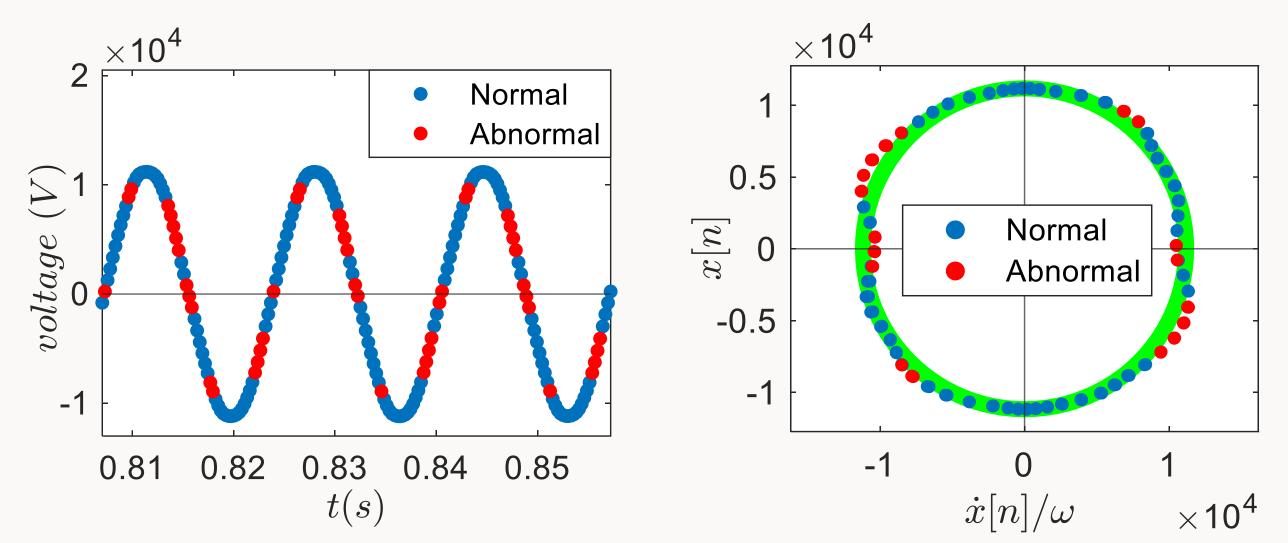


Applications

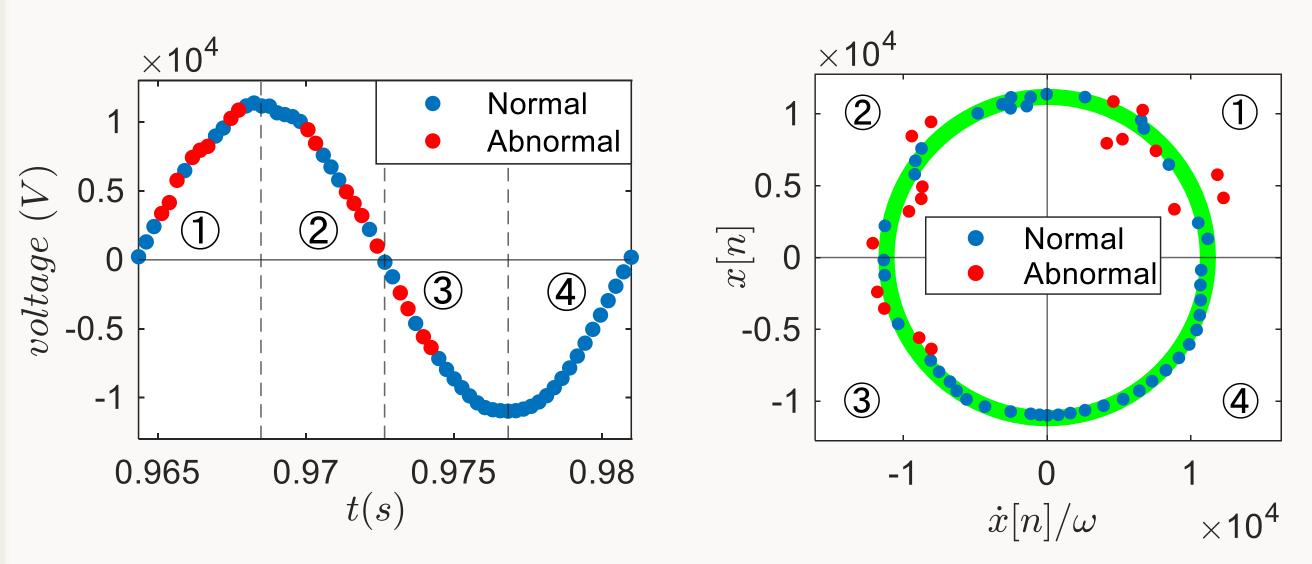
Advantages

- High-resolution
- Adjustable sensitivity
- Easy computation
- Immediate detection
- Apply to all distortions
- Suitable for online use

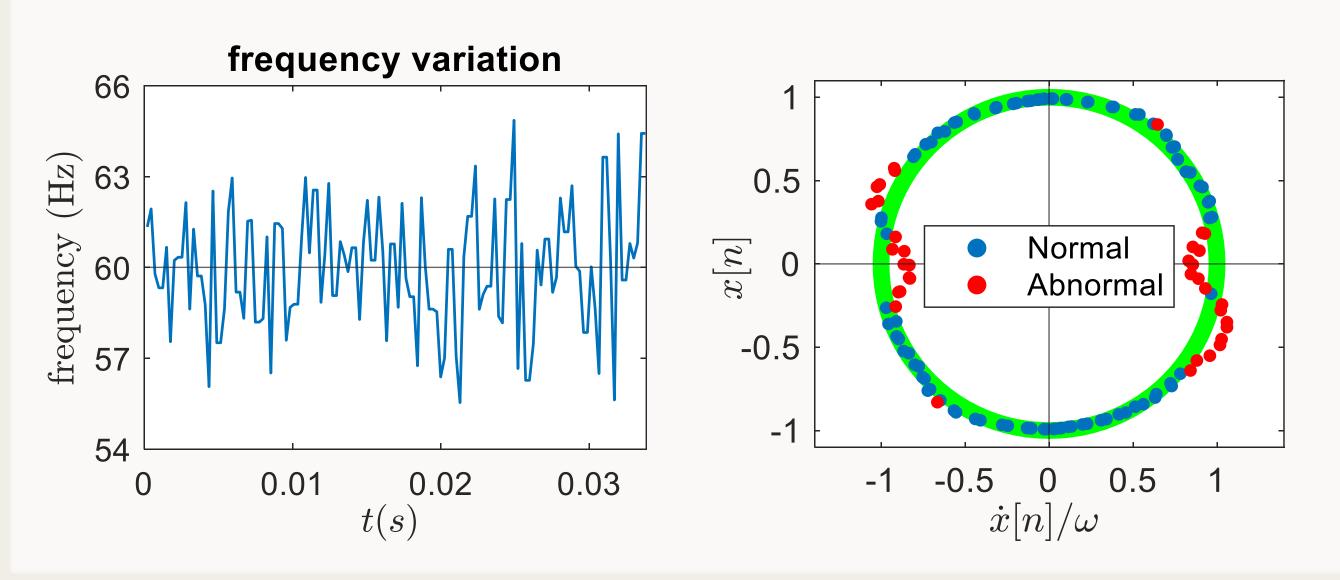
Revelation of Small Distortions



Revelation of Distorted Sections



Resistance to Frequency Variations



Theory

Origin of This Idea

$$\sin^2(\omega t) + \cos^2(\omega t) = 1$$

Ideal Case

Perfect Continuous Sine Wave

$$x(t) = A\sin(\omega t + \varphi)$$

$$\dot{x}(t) = A\omega\cos(\omega t + \varphi)$$

$$x(t)^{2} + \left(\frac{\dot{x}(t)}{\omega}\right)^{2} = A^{2}$$

Real Case

Discrete Signal + Frequency Fluctuation

$$x[n] = A\sin(\sum_{0}^{n} \omega[n]\Delta t + \varphi)$$

$$\dot{x}[n] = A\omega[n] \cdot \cos(\sum_{n=0}^{n} \omega[n] \Delta t + \varphi)$$

$$x[n]^{2} + \left(\frac{\dot{x}[n]}{\omega[n]}\right)^{2} = A^{2} \qquad \dot{x}[n] = \frac{x[n+1] - x[n-1]}{2\Delta t}$$

Theoretical Basis

Proposition: Equation \Rightarrow holds \Leftrightarrow x(t) is a Sine Wave. *Proof*:

$$\frac{dx(t)}{dt} = \pm \omega \sqrt{A^2 - x(t)^2} \qquad \arcsin\left(\frac{x(t)}{A}\right) = \pm \omega t + C_1$$

$$\frac{dx(t)}{\sqrt{A^2 - x(t)^2}} = \pm \omega dt \qquad x(t) = \pm A \sin\left(\omega t + \varphi\right). \quad \blacksquare$$

Conclusion

- This work provides a general solution for sine wave distortion monitoring and visualization the Circular Trajectory Approach (CTA).
- <u>Future works</u> include how CTA may help with anomaly classification.







