



Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

Institut für Integrierte Systeme
Integrated Systems Laboratory

Department of Information Technology and Electrical Engineering

Machine Learning on Microcontrollers

227-0155-00G

Exercise 1

Installation guide for ML on MCU Labs

ETH Center for Project-Based Learning

Wednesday 17th September, 2025

1 Introduction

Welcome to the laboratory of Machine Learning on Microcontrollers.

In this exercise, you will learn to install Docker and to create a Docker environment that we will use in our future exercises.

2 Notation

Student Task: Parts of the exercise that require you to complete a task will be explained in a shaded box like this.

Note: You find notes and remarks in boxes like this one.

3 What is Docker?

Docker is a platform for building and running applications in lightweight, isolated *containers*. A container bundles everything an application needs (OS libraries, Python, packages, and startup commands) so that the same code runs consistently on Linux, macOS, and Windows.

Why we use it here:

- **Reproducibility:** everyone runs the exact same environment.
- **Isolation:** no conflicts with system Python or other projects.
- **Portability:** one setup works across different machines and OSes.

4 What is Jupyter Notebook (Lab)?

Jupyter Notebook (and Jupyter Lab) is an interactive, web-based environment for writing and running code, visualizing results, and documenting experiments in a single place. Each notebook consists of cells that can contain code, text, formulas, and plots.

Why we use it here:

- **Exploration:** iterate quickly on experiments and visualize results inline.
- **Documentation:** combine code, figures, and explanations for reproducible reports.
- **Convenience:** runs in your browser; the server runs inside our Docker container.

5 Preparation

To ensure a smooth and identical setup across all machines, this course uses a Dockerized environment that already includes Python, system libraries (e.g., `ffmpeg`, `libsndfile`), and all Python packages from `requirements.txt`. At a high level, you will:

1. Install Docker.
2. Clone the course repository and place the provided `dockerfiles/` folder inside it.
3. Build the Docker image once with `docker compose build`.
4. Run Jupyter with `docker compose up` and you will be ready for Python exercises.

6 Docker-based Environment

6.1 Installation

Docker can be installed on all major platforms.¹ Please select your corresponding OS and CPU family and download&install Docker desktop.

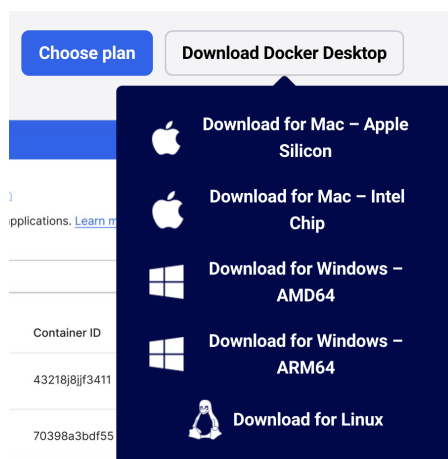


Figure 1: Downloading Docker Desktop

Note:

For **Windows and macOS**, downloading Docker Desktop and installing it via the graphical installer is sufficient. For **Linux**, you will be redirected to the *Supported platforms* page. Select your distribution (e.g., **Ubuntu**), then under *Install Docker Desktop* click *Download the latest DEB package*. After the download completes, install it from the terminal:

```
sudo apt-get update
sudo apt-get install ./docker-desktop-amd64.deb
```

¹ See: <https://www.docker.com/products/docker-desktop/>

After installation, launch Docker Desktop and ensure the engine is running.

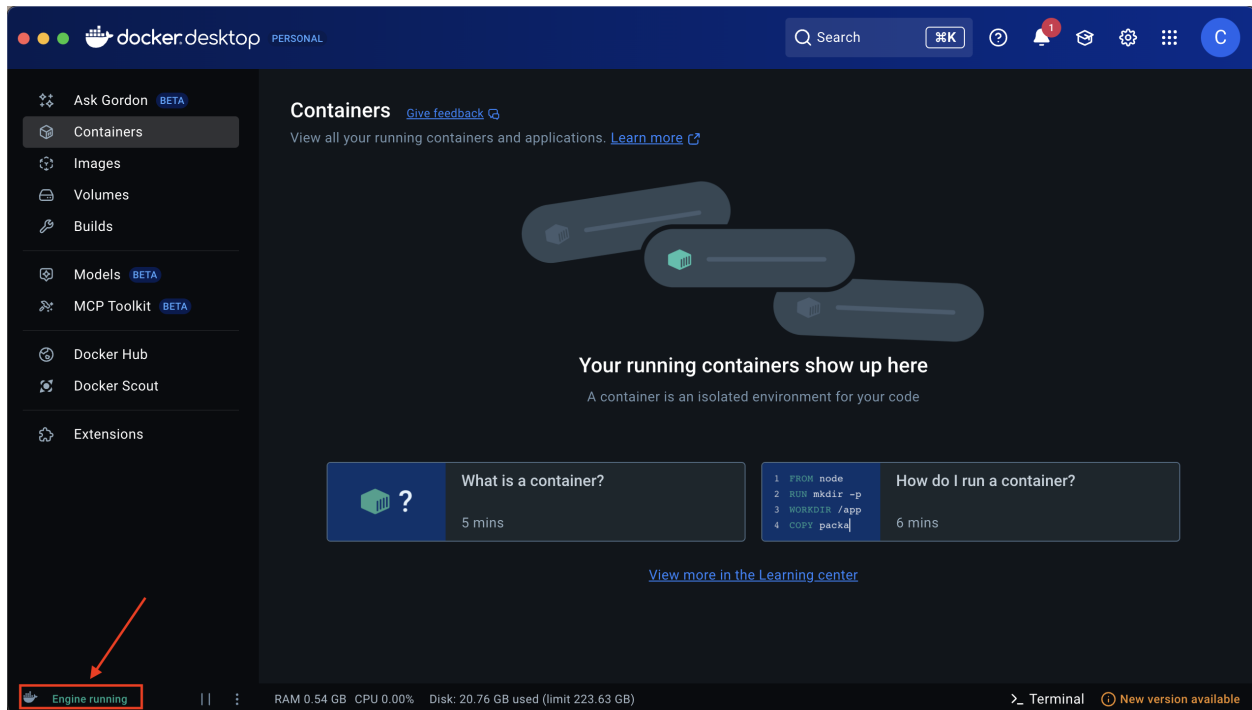


Figure 2: Docker Desktop Engine Running

Verify the installation in a terminal:

- `$ docker --version`
- `$ docker compose version`

6.2 Repository Layout and Files

Start from a fresh clone of the original repository:

- `$ git clone https://github.com/ETH-PBL/MLonMCU.git`

Your folder should look like:

```
MLonMCU/
├── ex1
├── ex2
├── ...
└── dockerfiles/
    ├── Dockerfile
    ├── README.md    ← Please follow the setup instructions in parallel with the README
    ├── docker-compose.yml
    ├── requirements.txt
    └── start.sh
```

6.3 Build the Image

Change to the `dockerfiles` directory and build:

- `$ cd MLonMCU/dockerfiles`
- `$ docker compose build`

The first build may take some time. You can check the build status following **Builds** → **Active Builds**.

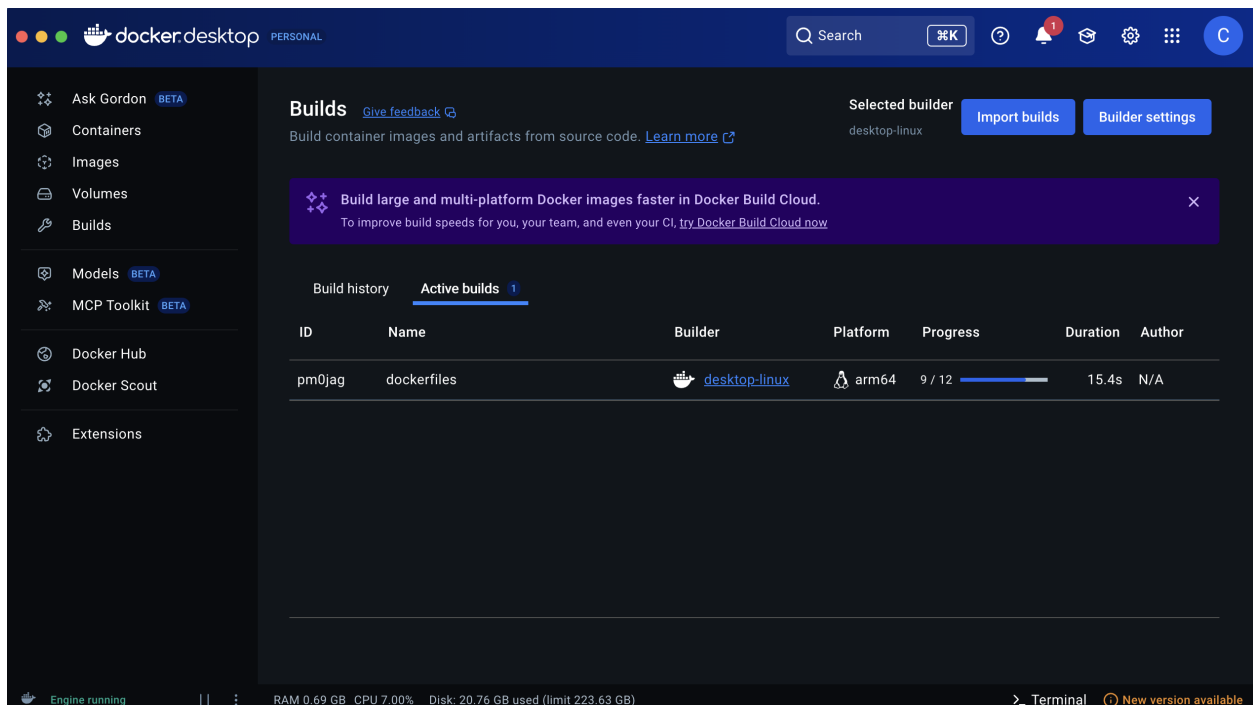


Figure 3: Docker Desktop Active Builds

When it finishes, you can see the built image from **Images** → **Local**.

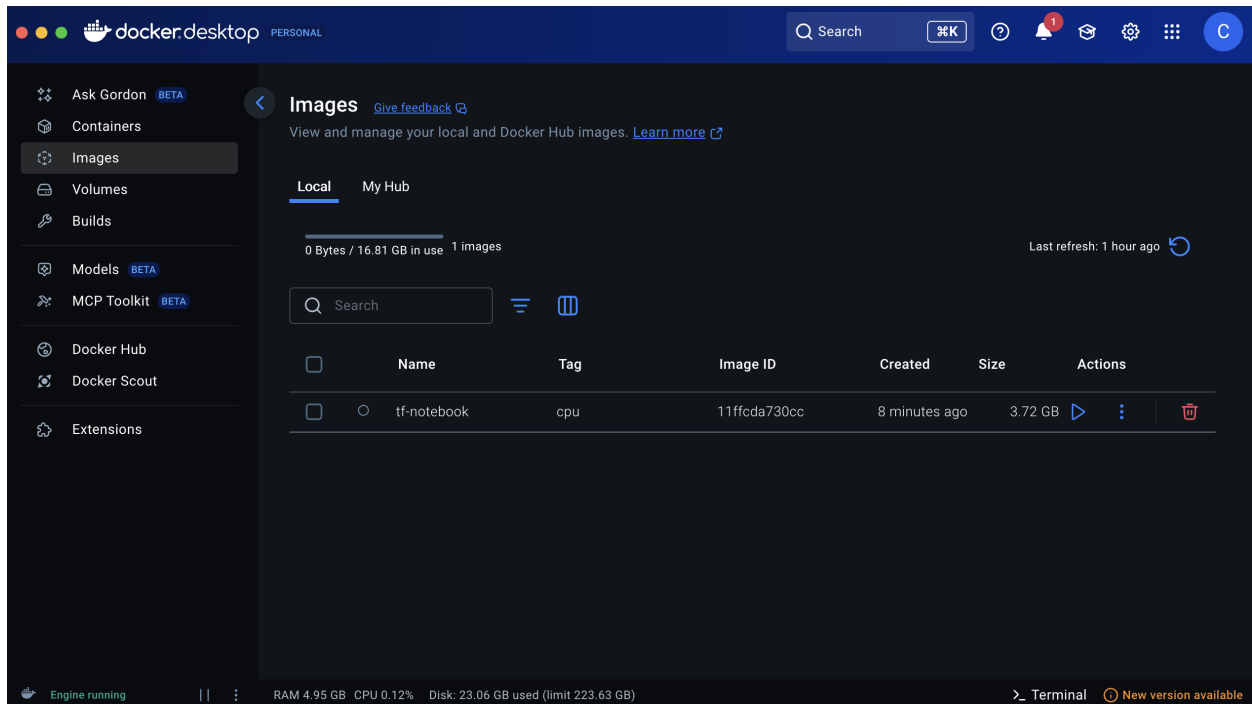


Figure 4: Docker Desktop Built Image

6.4 Run Jupyter

Start the container and launch Jupyter:

- `$ docker compose up`

When it starts, the terminal prints a URL like:

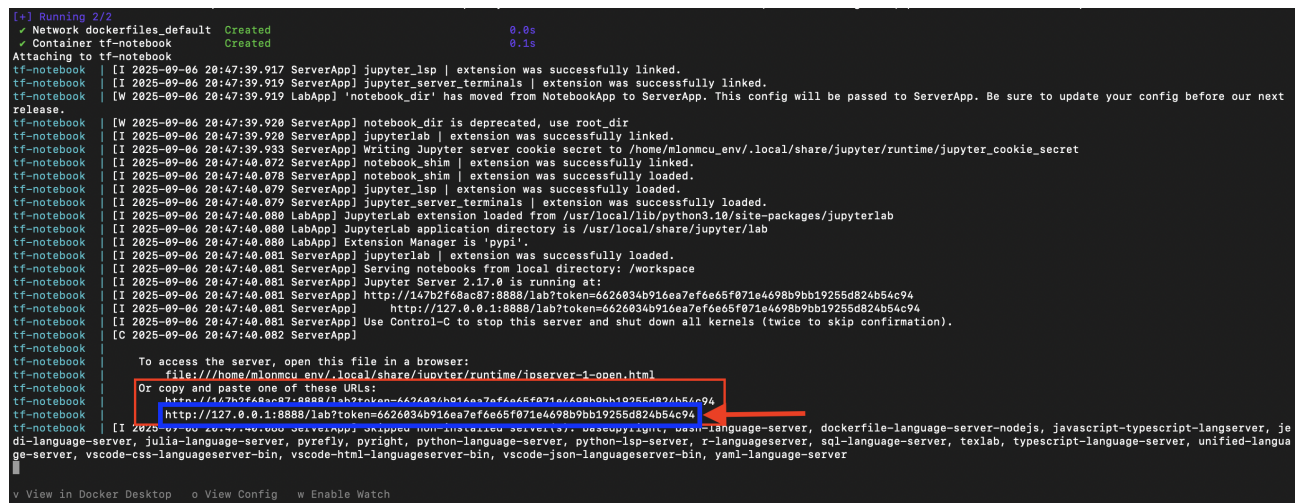


Figure 5: Jupyter Notebook URL

Copy the link that looks like:

```
http://127.0.0.1:8888/lab?token=XXXXXXXXXXXXXXXXXXXXXXXXXXXX
```

and paste it into your web browser (Google Chrome is recommended). Keep this terminal open for the entire Jupyter session.

Inside Jupyter, you start in the container's `/workspace` directory (it may appear simply as `/` in the file browser). This path is mapped to your host folder `MLonMCU/dockerfiles/workspace`.

Open a terminal in `MLonMCU/dockerfiles/workspace`, and run:

```
# Move all exercise folders from the repo root into the current workspace
mv ../../ex* .

# Verify the repo root contents two levels up
ls ../../

# Verify that the exercises are now in the current workspace
ls
```

Example output:

```
(base) your@username workspace % mv ../../ex* .
(base) your@username workspace % ls ../../
LICENSE  README.md  dockerfiles
(base) your@username workspace % ls
ex1  ex2  ex3  ex4  ex5  ex6  ex7  ex8
```

With this, all exercise folders have been moved into `workspace`, so they are easily accessible and visible within Docker and JupyterLab. Please reload your JupyterLab page if you do not see them after moving.

Student Task 1 (Docker Setup): Using the instructions above, prepare your Docker environment and verify you can run the exercises:

1. Install Docker Desktop for your OS.
2. Clone the repository: `git clone https://github.com/ETH-PBL/MLonMCU.git`
3. Build and run the docker.
4. Open the JupyterLab and move the folders to your workspace.

Now you can close the docker by typing `docker compose down` to your terminal. You should see the following output verifying that the running environment is closed:

```
(base) your@username dockerfiles % docker compose down
[+] Running 2/2
Container tf-notebook          Removed
Network dockerfiles_default    Removed
```

7 Running the Docker-Based Environment Test

This section explains how to run `test_env.ipynb` inside the Docker container.

7.1 Start the Container

1. Open a terminal and navigate to the course Docker folder:

```
MlonMCU/dockerfiles
```

2. Launch the container with Docker Compose:

```
docker compose up
```

3. Wait until a tokenized JupyterLab URL appears in the logs (e.g., `http://127.0.0.1:8888..`). Open this link in your browser.
4. In JupyterLab's file browser, open the freshly prepared workspace folder and navigate to **ex1/task/test_env.ipynb**
5. Run the notebook (run the cell with Shift + Enter or use Run All button) and verify the output.

7.2 What You Should See

- Tables for **Package Versions** and **Import-Only Checks** with OK statuses and matching versions.
- Some **Functional Smoke-Tests** table with all tests showing PASS.
- A **Final Status**: ALL TESTS PASSED.
- Two figures created in the same folder: `test_plot.png` and `model_visualization.png`.

Student Task 2 (Environment Test):

1. Do the printed versions match those in `MlonMCU/dockerfiles/requirements.txt`?
2. What kind of model visualization do you see, and why? _____
3. What do you see in the test plot? _____

7.3 Shut Down the Container

When you are done, stop and remove the services:

```
docker compose down
```

That is all for the Python-related setup.

8 STM32 CUBE IDE

In the following weeks you will learn how to configure and program the STM Microcontroller (MCU) that you will use throughout the first half of this course. The development board for this course is the B-U585I-IOT02A featuring an STM32U585AI low-power MCU with a maximum clock frequency of 160 MHz, 786 KB of RAM and 2 MB of flash memory. The processor core is based on the ARM Cortex M33, featuring advanced Digital Signal Processor (DSP) operation capabilities and a floating-point unit.

Today, we will simply test the integrity of our MCU and verify the correctness of the STM32 CUBE IDE installation.

Student Task 3 (Blinking LED):

1. Import the blinky project in the STM32 CUBE IDE as shown on the screenshot figure 6. Do not unzip the project before importing it as archive.
2. Compile the code using the BUILD button and flash it to the MCU using the RUN button.
3. What is the behavior of the MCU?

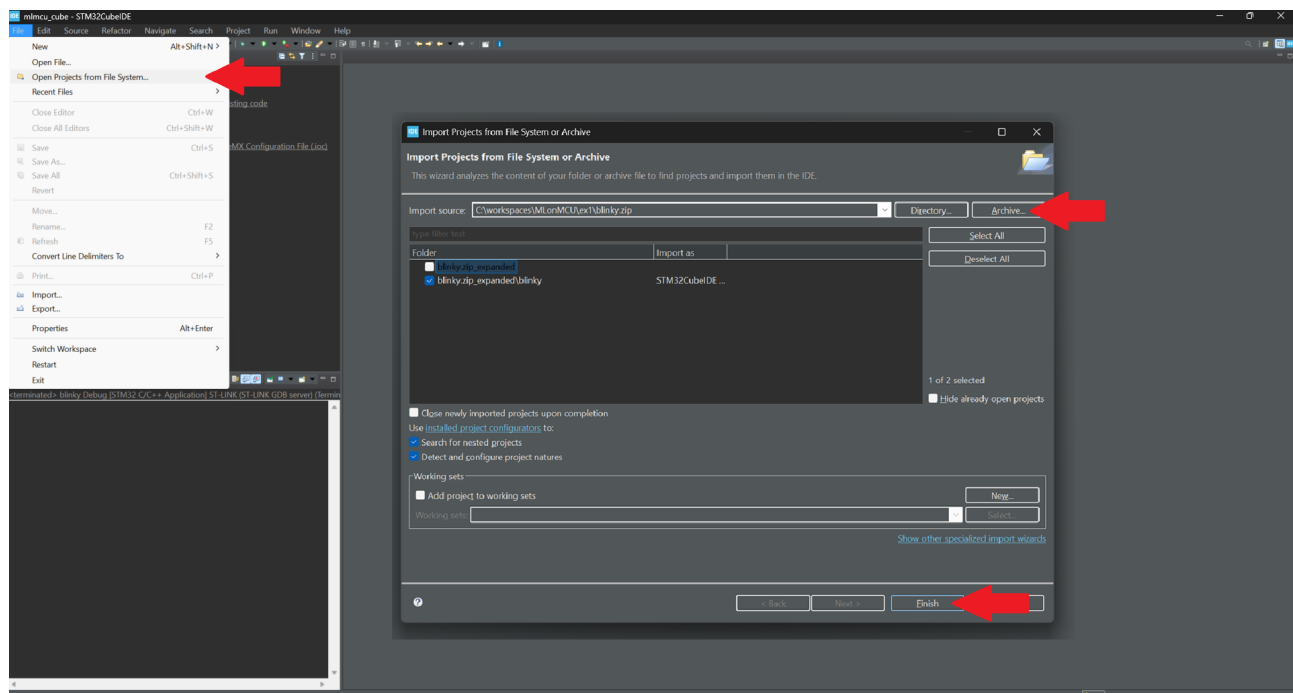


Figure 6: Importing Projects

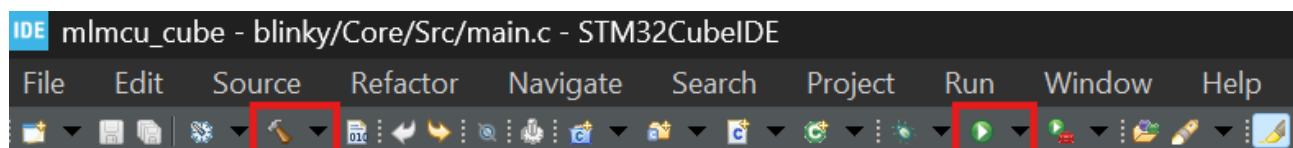


Figure 7: Flashing a Project

\mathcal{E}

**Congratulations! You have reached the end of the exercise.
If you are unsure of your results, discuss with an assistant.**

 \mathcal{E}