

ECS 170 Programming Assignment 1

Code Infrastructure & Requirements

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Outline

- 1 Heuristic Search Review
- 2 Code Infrastructure
- 3 Assignment Requirements & Grading Policy

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3 Assignment Requirements & Grading Policy

Heuristic Search

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A heuristic $h(n)$ is admissible if and only if $h(n)$ *never overestimate* the cost to reach the goal.

- i.e. $h(n)$ is by nature optimistic and provide a lower bound for the cost to reach the goal.
- A^* is optimal if $h(n)$ is an admissible heuristic (using TREE-SEARCH? Why?)
- Read P97-99 on AIMA 2e

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Overview

All relevant modules:

- Main : primary program entry *
- AIModule : Base class of all AI implementations
- StupidAI : Sample class of AI implementation ***
- DijkstraAI : Sample class of AI implementation, Demo use only, no source code.
- TerrainMap : A class representing the world, start and end points, and visited squares. ***
- PerlinTerrainGenerator : A class that generates random terrains using Perlin noise functions. *

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Skim through the code

First play with the sample and read the code a little bit:

- test DijkstraAI
- read Main.java, see the possible command line arguments
- find `getCost(final Point p1, final Point p2)` function in TerrainMap.java
- read the two `getCost()` functions
- other code mentioned above

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Part 1

Creating Heuristics for 4 cost-action combination each.

Part 2

- Implement the heuristic and A* algorithm, only for 8-option action and two cost functions.
- copy the StupidAI.java and rename it.
- create getHeuristic() as a member function of your implemented AI module.
- implement A* algorithm in createPath() function using your getHeuristic() function
- you might need to read TerrainMap.java for reference

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Part 3

- Try out your code for 10 scenarios (2 cost functions * 5 random seeds)
- read Main.java to see how to input arguments (random seeds) (default map size is 500x500)
- record each command you use and the result (the cost of the shortest path and the number of nodes expanded)

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- Try out your code for 10 scenarios (2 cost functions * 5 random seeds)
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- Implemented a variant of standard A* and modify heuristic to cope with the much larger grid in MTAFT.XYZ
- consider using memory-bounded heuristic search
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- CREATE heuristic, DOCUMENT the exact form of the heuristic and PROVE it is admissible
- 6 points for each cost-action combination

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- Implement A* algorithm. 20 points
- Implement your AI Module for two cost functions. 5 points each
- You shall lose points with wrong filenames.

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- For two cost function and corresponding heuristic, experiment with seeds 1,2,3,4,5
- hand in the record for each case (command, cost of shortest path, number of nodes expanded)
- For each case:
 - $5 \text{ points} \times (\text{shortest path cost}) / (\text{your path cost})$
 - if you get 5 points above, you shall have bonus marks depends on rank.

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Part 4

- Describe your modified A* algorithm and admissible heuristic clearly and concisely ? points
- hand in the right files. 10 points
- record and hand in the cost, number of nodes expanded, time for each cost function. 10 points
- if you have any doubts about the validity of your approach then first contact Prof.Davidson.

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- Good luck with coding!