CHONGKAI GAO

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EDUCATION

National University of Singapore, Singapore

01/2024 – present

PhD in School of Computing, Advisior: Prof. Lin Shao

Tsinghua University, Beijing, China

08/2020 - 06/2023

Master in Department of Automation, Advisior: Prof. Feng Chen, GPA 3.74/4.0, Rank 39/161

Tsinghua University, Beijing, China

08/2016 - 07/2020

B.Eng. in Department of Automation, GPA 3.62/4.0, Rank 38/158

PUBLICATIONS

- 1. Zhixuan Xu*, **Chongkai Gao***, Zixuan Liu*, Gang Yang*, Chenrui Tie, Haozhuo Zheng, Haoyu Zhou, Weikun Peng, Debang Wang, Tianyi Chen, Zhouliang Yu, Lin Shao, "**ManiFoundation Model for General-Purpose Robotic Manipulation of Contact Synthesis with Arbitrary Objects and Robots**", *in ArXiv*, [paper][website]
- 2. Chongkai Gao, Zhengrong Xue, Shuying Deng, Tianhai Liang, Siqi Yang, Lin Shao, Huazhe Xu, "RiEMann: Near Real-Time SE(3)-Equivariant Robot Manipulation without Point Cloud Segmentation", in CVPR Workshop on Equivariant Vision: From Theory to Practice 2024, [paper][website]
- 3. Bo Liu*, Yifeng Zhu*, Chongkai Gao*, Yihao Feng, Qiang Liu, Peter Stone, Yuke Zhu, "LIBERO: Benchmarking Knowledge Transfer in Lifelong Robot Learning", NeurIPS Track Datasets and Benchmarks 2023, [paper][website]
- 4. Chongkai Gao, Zekun Li, Haichuan Gao, Feng Chen, "Iterative Interactive Modeling for Knotting Plastic Bags", in CoRL 2022, Best Systems Paper Nomination, [paper][website]
- 5. Chongkai Gao, Yizhou Jiang, Feng Chen, "Transfering Hierarchical Structure with Dual Meta Imitation Learning", in CoRL 2022, [paper]
- 6. Chongkai Gao, Haichuan Gao, Shangqi Guo, Tianren Zhang, Feng Chen, "CRIL: Continual Robot Imitation Learning via Generative and Prediction Model", *in IROS*, 2021, [paper]
- 7. Tianren zhang, Yizhou Jiang, Xin Su, Shangqi Guo, **Chongkai Gao**, Feng Chen, "**Subjective Learning for Conflicting Data**", *in ICLR Workshop on Agent Learning in Open-Endedness*, 2022, [paper]

EXPERIENCE

Tsinghua Embodied AI Lab (TEA Lab)

Tsinghua University

Research Assistant (Supervisor: Prof. Huazhe Xu)

06/2023 - 01/2024

Equivariant Robot Learning for Manipulation Tasks

Mech-Mind Robotics

Beijing, China

Robot Algorithm Intern

03/2023 - 06/2023

Kinematic Parameter Identification for Serial Robot, Online 3D Bin Packing

SELECTED HONORS

 President's Graduate Fellowship, National University of Singapore 	2024
Comprehensive Excellence Award, Tsinghua University	2022& 2021& 2019
Excellent Graduates, Tsinghua University	2020
Philobiblion Scholarship, Tsinghua University	2019
Scientific and Technological Innovation Award, Tsinghua University	2019
• Third Place Award, Southern California Software Pioneer Hackathon	2019
• Best Team Culture Award, International Aerial Robotics Competition (Asia-Pacific Venue)	2019

SKILLS

TOEFL 100 (Reading 29, Listening 25, Speaking 22, Writing 24), GRE 154(V) + 168(Q) + 4.0 Python, C++, ROS, LATEX, PyTorch, Mujoco, Git