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# 6. GRAPH ALGORITHMS HANDBOOK

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Data Structures and Algorithms [19ECSC201]



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Note: Bellman-Ford is referenced from CLRS and others from Levitin text book.

### 1. Dijkstra's Algorithm

ALGORITHM Dijkstra( $G, s$ )

// Dijkstra's algorithm for single source shortest path

// Input: A weighted connected graph  $G(V, E)$  with non-negative weights and its vertex  $s$

// Output: the length  $d_v$  of a shortest path from  $s$  to  $v$  and its penultimate vertex  $p_v$  for every vertex  $v$  in  $V$

Initialize( $Q$ ) // Initialize vertex priority queue to empty

for every vertex  $v$  in  $V$  do

$d_v \leftarrow \infty$

$p_v \leftarrow \text{null}$

Insert ( $Q, v, d_v$ ) // Initialize vertex priority in priority queue

$d_s \leftarrow 0$

Decrease ( $Q, s, d_s$ ) // Update priority of  $s$  with  $d_s$

$V_T \leftarrow \emptyset$

for  $i \leftarrow 0$  to  $|V| - 1$  do

$u^* \leftarrow \text{DeleteMin}(Q)$

$V_T = V_T \cup \{u^*\}$

for every vertex  $u$  in  $V - V_T$  that is adjacent to  $u^*$  do

if  $d_{u^*} + w(u^*, u) < d_u$

$d_u \leftarrow d_{u^*} + w(u^*, u)$

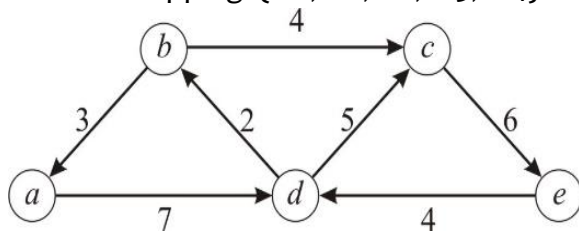
$p_u \leftarrow u^*$

Decrease ( $Q, u, d_u$ )

**Intuition:**

Example: Find the shortest path form vertex c to all other vertices.

Vertices Mapping: {a:0, b:1, c:2, d:3, e:4}



cost [5][5] =

	0	1	2	3	4
0					
1					
2					
3					
4					

### Initialization:

$S = \{ 2 \}$

$V - S = \{ 0, 1, 3, 4 \}$

dist

0	
1	
2	
3	
4	

path

0	
1	
2	
3	
4	

### Iteration 01:

u =

dist[u] =

dist

0	
1	
2	
3	
4	

path

0	
1	
2	
3	
4	

S =

$V - S =$

### Iteration 02:

u =

dist[u] =

dist

0	
1	
2	
3	
4	

path

0	
1	
2	
3	
4	

S =

$V - S =$

Working Space:

**Iteration 03:**

u =

dist[u] =

dist

0	
1	
2	
3	
4	

path

0	
1	
2	
3	
4	

S =

V – S =

**Iteration 04:**

u =

dist[u] =

dist

0	
1	
2	
3	
4	

path

0	
1	
2	
3	
4	

S =

V – S =

**Trace the path from vertex 2 to vertex 4:**

**Design Technique:**

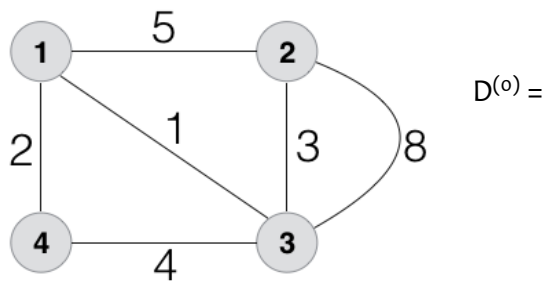
**Efficiency Analysis:**

## 2. Floyd's Algorithm

**Intuition:**

```
ALGORITHM Floyd ( $W[1..n, 1..n]$ )  
// Implements Floyd's algorithm for all pair shortest path problem  
// Input: The weight matrix  $W$  of the graph with no negative length cycle  
// Output: The distance matrix of the shortest path's lengths  
 $D \leftarrow W$   
for  $k \leftarrow 1$  to  $n$  do  
    for  $i \leftarrow 1$  to  $n$  do  
        for  $j \leftarrow 1$  to  $n$  do  
             $D[i, j] \leftarrow \min \{D[i, j], D[i, k] + D[k, j]\}$   
return  $D$ 
```

Example: Apply Floyd's algorithm on the given graph:



$D^{(1)} =$

$D^{(2)} =$

$D^{(3)} =$

$D^{(4)} =$

**Design Technique:**

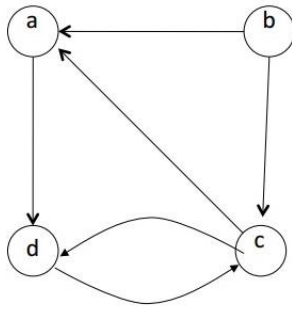
**Efficiency Analysis:**

### 3. Warshall's Algorithm

Intuition:

```
ALGORITHM Warshall ( $A[1..n,1..n]$ )  
// Implements Warshall's algorithm for computing transitive closure  
// Input: The adjacency matrix A of a diagraph with n vertices  
// Output: The transitive closure of the diagraph  
 $R^{(0)} \leftarrow A$   
for  $k \leftarrow 1$  to  $n$  do  
    for  $i \leftarrow 1$  to  $n$  do  
        for  $j \leftarrow 1$  to  $n$  do  
             $R^{(k)}[i, j] \leftarrow R^{(k-1)}[i, j] \text{ or } (R^{(k-1)}[i, k] \text{ and } R^{(k-1)}[k, j])$   
return  $R^{(n)}$ 
```

**Example:**



$$R^{(0)} =$$

$$R^{(1)} =$$

$$R^{(2)} =$$

$$R^{(3)} =$$

$$R^{(4)} =$$

**Design Technique:**

**Efficiency Analysis:**



#### 4. Kruskal's Algorithm

ALGORITHM Kruskal( $G$ )

// Kruskal's algorithm to construct a minimum spanning tree

// Input: A weighted connected graph  $G(V, E)$

// Output:  $E_T$ , the set of edges composing of MST of  $G$

sort  $E$  in nondecreasing order of the edge weights  $w(e_{i1}) \leq \dots \leq w(e_{i|E|})$

$E_T \leftarrow \emptyset$

ecounter  $\leftarrow 0$

$k \leftarrow 0$

while ecounter  $< |V| - 1$  do

$k \leftarrow k + 1$

    if  $E_T \cup \{e_{ik}\}$  is acyclic

$E_T \leftarrow E_T \cup \{e_{ik}\}$

        ecounter  $\leftarrow$  ecounter + 1

return  $E_T$

#### Disjoint-Set:

For the given array, perform the said union operations:

0	1	2	3	4	5	6	7	8
0	1	2	3	4	5	6	7	8

Union (3, 4)

0	1	2	3	4	5	6	7	8

Union (1, 4)

0	1	2	3	4	5	6	7	8

Union (3, 7)

0	1	2	3	4	5	6	7	8

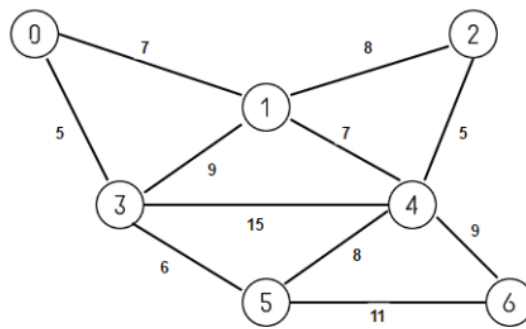
Union (6, 8)

0	1	2	3	4	5	6	7	8

Union (6, 5)

0	1	2	3	4	5	6	7	8

Example:



Sorted Edges:

- 1.
- 2.
- 3.
- 4.
- 5.
- 6.
- 7.
- 8.
- 9.
- 10.
- 11.

steps	( u, v )	i=find(u) j=find(v)	output	Union( i, j )						
				0	1	2	3	4	5	6
init										
1										
2										
3										
4										
5										
6										
7										
8										
9										

**Design Technique:**

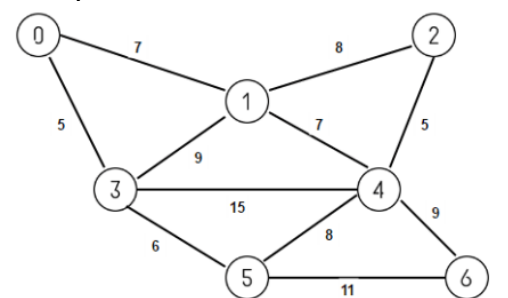
**Efficiency Analysis:**

5. Prim’s Algorithm

```
ALGORITHM Prim(G)
// Prim’s algorithm to construct a minimum spanning tree
// Input: A weighted connected graph G(V, E)
// Output: ET, the set of edges composing of MST of G
VT ← {vo}
ET ← ∅
for i ← 1 to |V| - 1 do
    find a minimum weight edge e* = (v*,u*) along all the edges (v, u) such that
    v is in VT and u is in V – VT
    VT ← VT ∪ {u*}
    ET ← ET ∪ {e*}
return ET
```

Intuition:

Example:



cost[ ][ ] =

	0	1	2	3	4	5	6
0							
1							
2							
3							
4							
5							
6							

Initialization: Step 0

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =  
V – S =  
u =  
dist[u] =  
output =

Initialization: Step 1

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =  
V – S =  
u =  
dist[u] =  
output =

Initialization: Step 2

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =  
V – S =  
u =  
dist[u] =  
output =

Initialization: Step 3

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =  
V – S =  
u =  
dist[u] =  
output =

Initialization: Step 4

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =  
V – S =  
u =  
dist[u] =  
output =

Initialization: Step 5

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =

V – S =

u =

dist[u] =

output =

Initialization: Step 6

	dist	path
0		
1		
2		
3		
4		
5		
6		

S =

V – S =

Cost of MST is \_\_\_\_\_

**Design Technique:**

**Efficiency Analysis:**

## 6. Bellman Ford Algorithm

```

 $d[s] \leftarrow 0$ 
for each  $v \in V - \{s\}$  } initialization
do  $d[v] \leftarrow \infty$ 

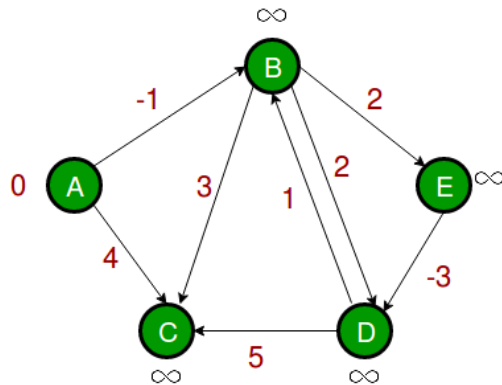
for  $i \leftarrow 1$  to  $|V| - 1$ 
do for each edge  $(u, v) \in E$ 
do if  $d[v] > d[u] + w(u, v)$ 
then  $d[v] \leftarrow d[u] + w(u, v)$  } relaxation step

for each edge  $(u, v) \in E$ 
do if  $d[v] > d[u] + w(u, v)$ 
then report that a negative-weight cycle exists

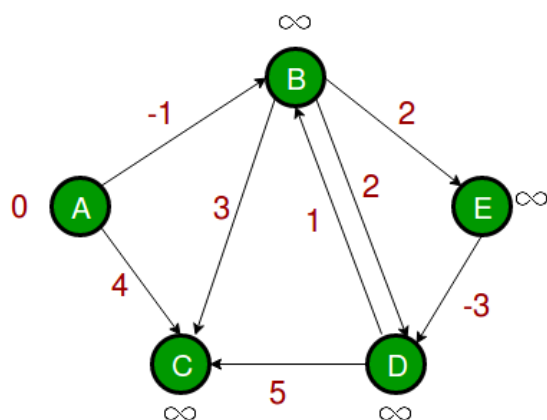
At the end,  $d[v] = \delta(s, v)$ , if no negative-weight cycles.
    
```

Example:

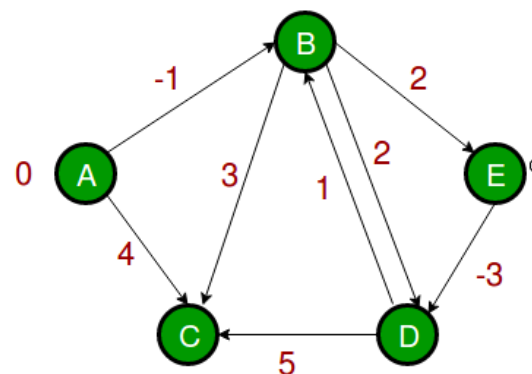
Edge List: (B, E), (D, B), (B, D), (A, B), (A, C), (D, C), (B, C), (E, D).



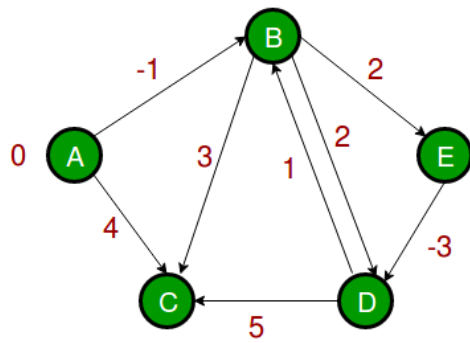
Iteration 01:



Iteration 02:



Iteration 03:



**Design Technique:**

**Efficiency Analysis:**

~\*~\*~\*~\*