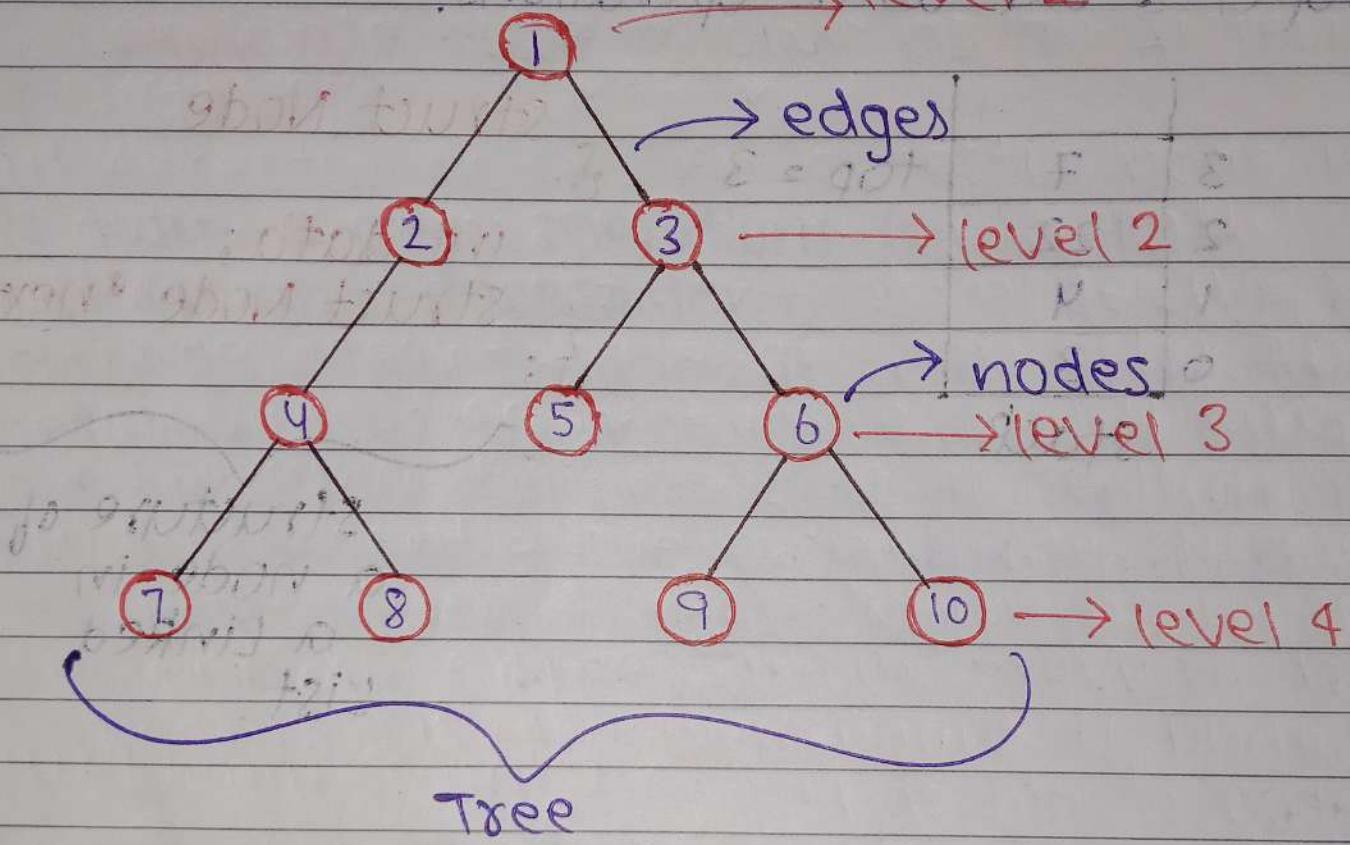


Tree represents the nodes connected by edges.



Other Data Structures, like :- arrays, linked list; stack and queue are linear data structures that store data sequentially. In order to perform any operation in a linear data structure, the time complexity increases with the increase in the data size, which is not acceptable in today's computational world.

Different tree data structures allow quicker & easier access to the data as it is a non-linear data structure.

* Some key points of the tree data structure

- i) A tree data structure is defined as a collection of objects or entities known as nodes that are linked together to represent or simulate hierarchy.
- ii) A tree data structure is a non-linear data structure because it does not store in a sequential manner. It is a hierarchical structure as elements in a tree are arranged in multiple levels.
- iii) In the Tree Data Structure, the topmost node is known as a root node. Each node contains some data, and data can be of any type.
- iv) Each node contains some data & the link or reference of other nodes that can be called children.

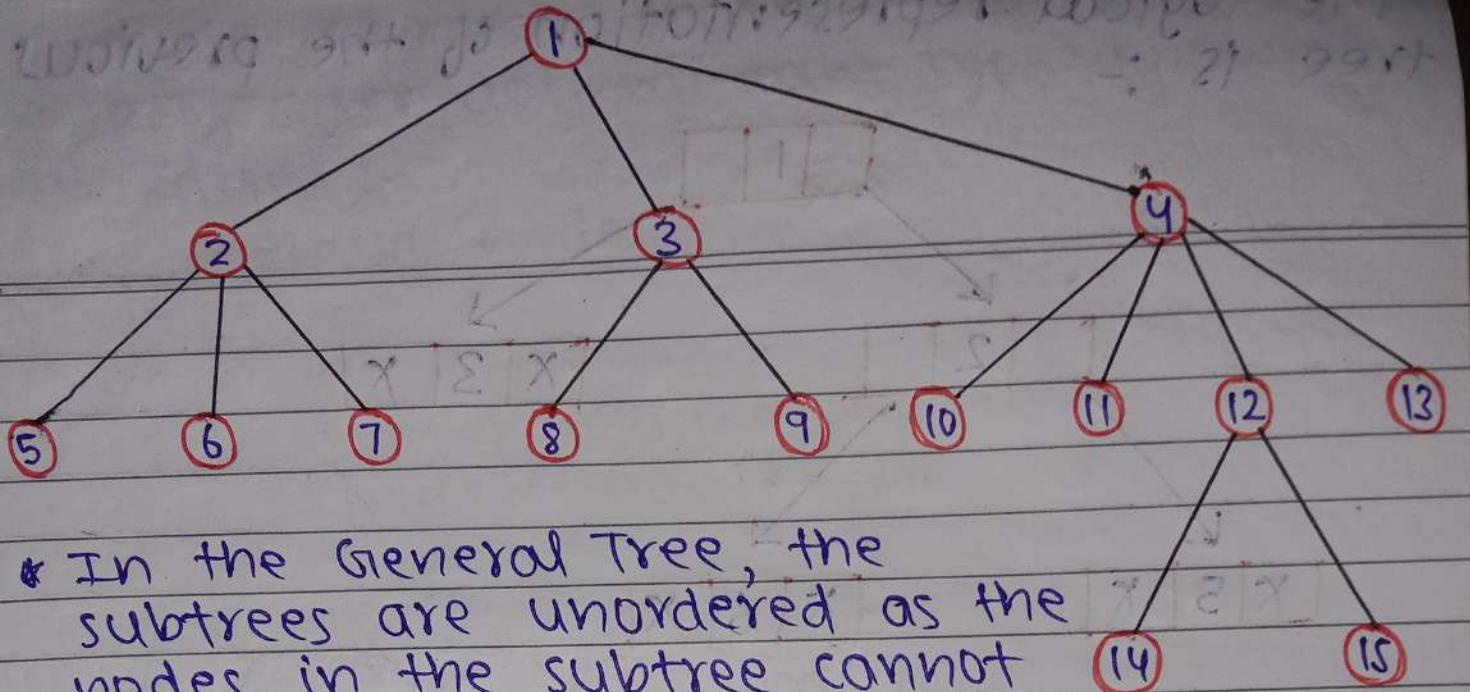
& Terminologies in Tree Data Structure :-

- i) Root = The root node is the topmost node in the tree hierarchy. In other words, the root node is the one that doesn't have any parent. If a node is directly linked to some other node, it would be called as Parent-Child Relationship.
- ii) Child Node = If the node is a descendant of any node, then the node is known as child node.
- iii) Parent = If the node contains any sub-node, then that node is said to be the parent of that sub-node.
- iv) Sibling = The nodes that have the same parent are known as sibling.

- v) Leaf Node = The node of the tree which doesn't have any child node, is called a Leaf Node. A leaf node is the bottom node of the tree. There can be any number of Leaf Nodes present in a general tree. Leaf Nodes can also be called External Nodes.
- vi) Internal Node = A Node has atleast one child node known as an Internal Node.
- vii) Ancestor Node = An ancestor node is any predecessor node on a path from the root to that node. The root node doesn't have any ancestor. In our previous tree, node 1, 2 and 4 are the ancestor nodes of node 10.
- viii) Descendant = The immediate successor of the given node is known as descendant of a node. In our previous tree, node 8 is the descendant of node 4.

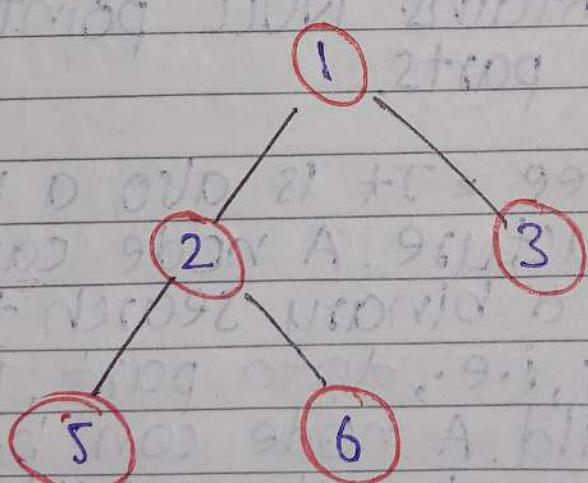
* Types of Tree Data Structures:-

- i) General Tree = The General Tree is one of the types of tree data structure. In this, a node can have either 0 or maximum n number of nodes. There is no restrictions imposed on the degree of the node.



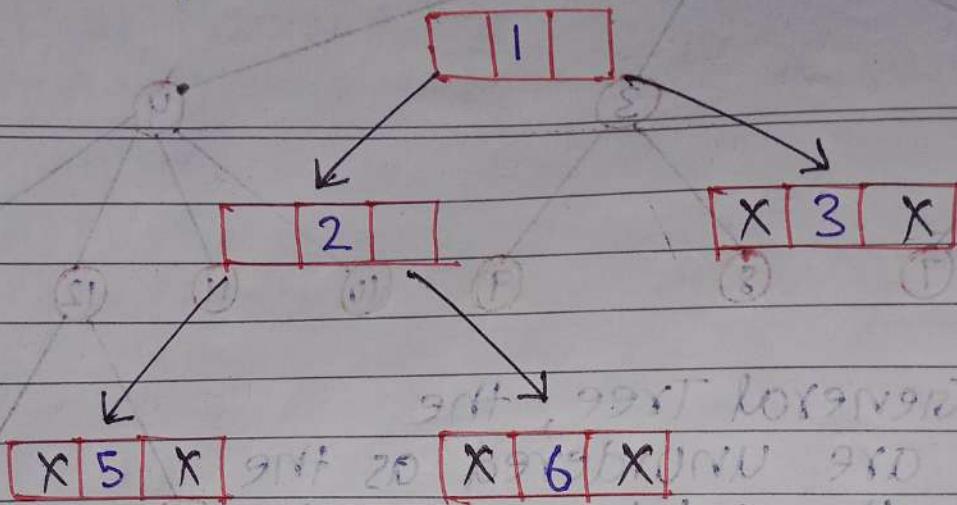
* In the General Tree, the subtrees are unordered as the nodes in the subtree cannot be ordered.

ii) Binary Tree = The Binary Tree means that the node can have maximum 2 children. Each node can have either 0, 1 or 2 children.



This is a binary tree because each node contains the utmost 2 children.

The logical representation of the previous tree is :-



In the above tree, node 1 contains two pointers, i.e., left and a right pointer pointing to the left and right node respectively. The node 2 contains both the nodes (left and right), therefore, it has two pointers. The nodes 3, 5 and 6 are the leaf nodes, so all these nodes contains NULL pointer on both left and right parts.

(iii) Binary Search Tree = It is also a node based data structure. A node can be represented in a binary search tree with three fields, i.e., data part, left child & right child. A node can be connected to the utmost 2 child, so the node contains two pointers. Every node in the left sub-tree must contain a value less than the value of the root node & the value of each node in the right - sub-tree must be bigger than the value of the root node.

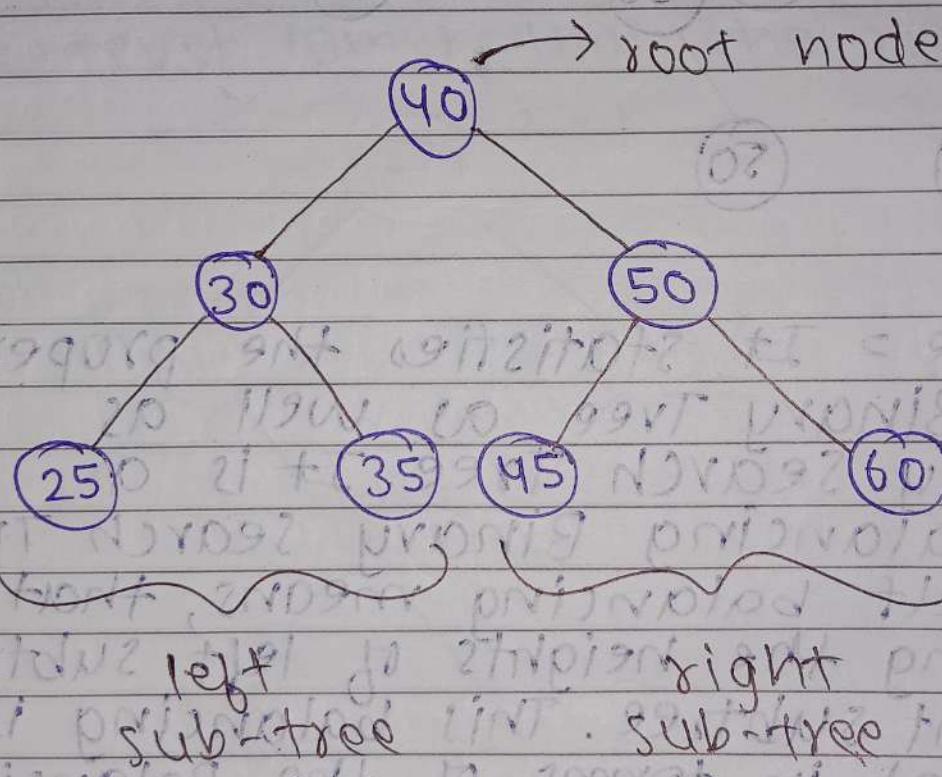
A node can be created with the help of user defined data type known as struct :-

struct node

{

int data;
struct node *left;
struct node *right;

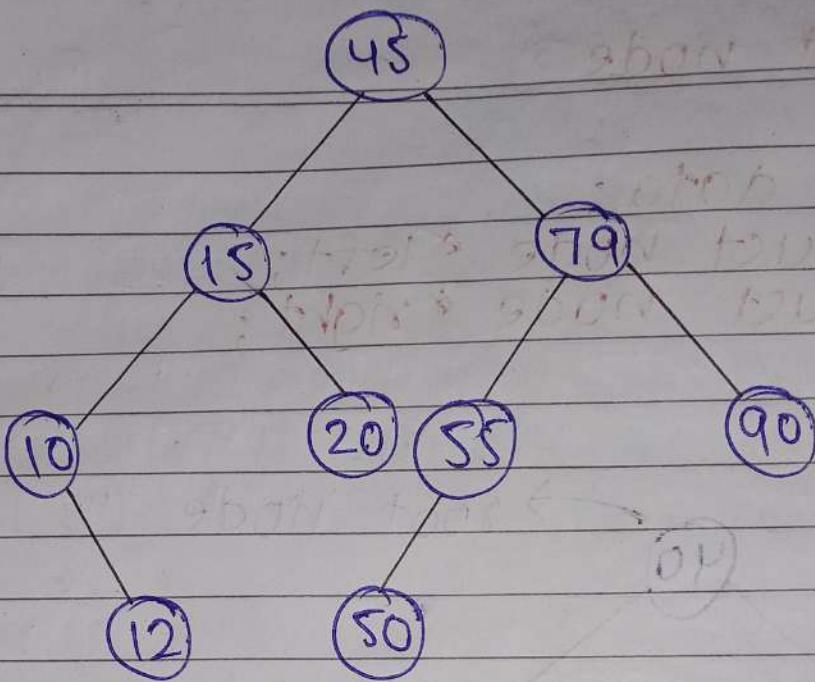
};



& Advantages of Binary Search Tree (BST) :-

- i) Searching an element in BST is easy as we always have a hint that which sub-tree has the desired element.
- ii) As compare to Array and Linked List, Insertion & deletion operations are faster in BST.

Eg:- create a Binary Search Tree:
45, 15, 79, 90, 10, 55, 12, 20, 50

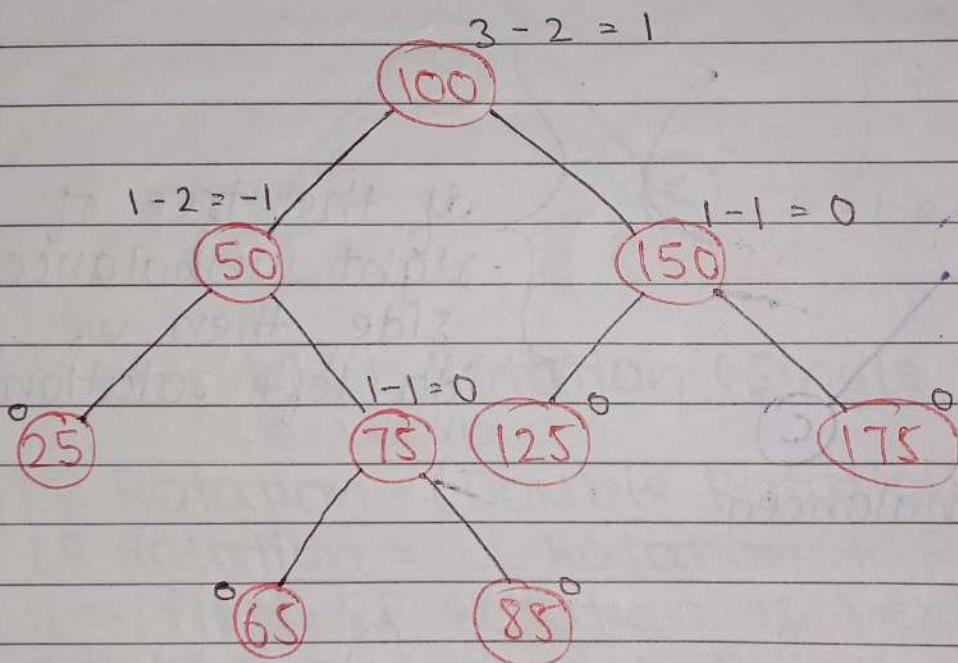


iv) AVL Tree = It satisfies the property of the Binary Tree as well as Binary Search Tree. It is a Self Balancing Binary search Tree. Here, self balancing means, that balancing the heights of left subtree and right subtree. This balancing is measured in terms of the Balancing Factor. The balancing factor can be defined as the difference between the height of the left sub-tree & the height of the right sub-tree. The value of balancing factor must be 0, -1 or +1, therefore, each node in the AVL tree should have the value of the balancing factor either as 0, -1 or +1.

If the balance factor of any node is 1, it means that the left sub-tree is one level higher than the right sub-tree.

If the balance factor of any node is 0, it means that the left sub-tree & right sub-tree contains equal height.

If the balance factor of any node is -1, it means that the left sub-tree is one level lower than the right sub-tree



* Rotations in AVL Tree :-

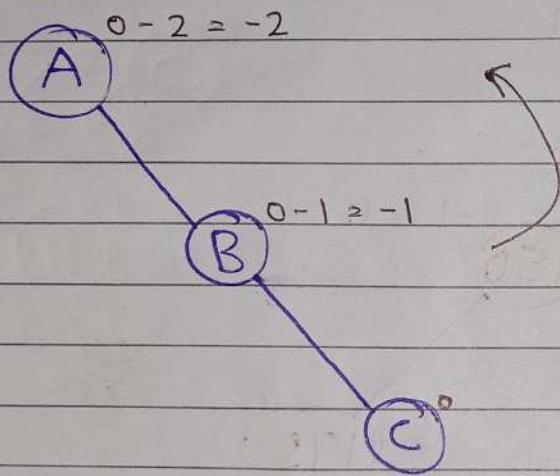
We perform rotation in AVL tree only in case if Balance Factor is other than -1, 0, 1.

There are 'basically 4 types' of rotations in AVL trees:-

i) LL Rotation (Left Left) = Inserted node is in the left subtree of left subtree of A.

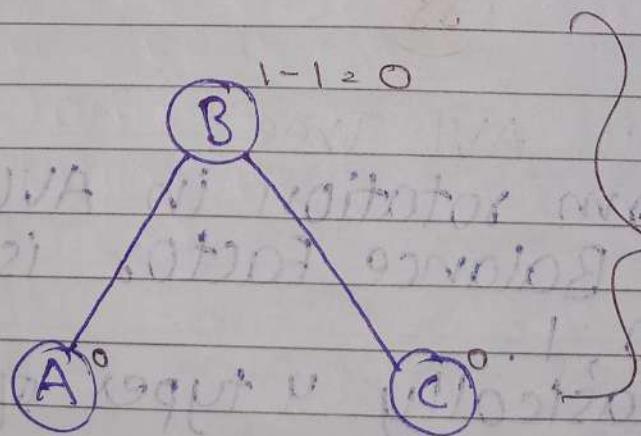
- ii) RR Rotation : Inserted node is in the right sub-tree of right sub-tree of A.
- iii) LR Rotation : Inserted node is in the right sub-tree of left subtree of A.
- iv) RL Rotation : Inserted node is in the left sub-tree of right subtree of A.

Note : Node A is the node whose balancing factor is other than -1, 0, +1.



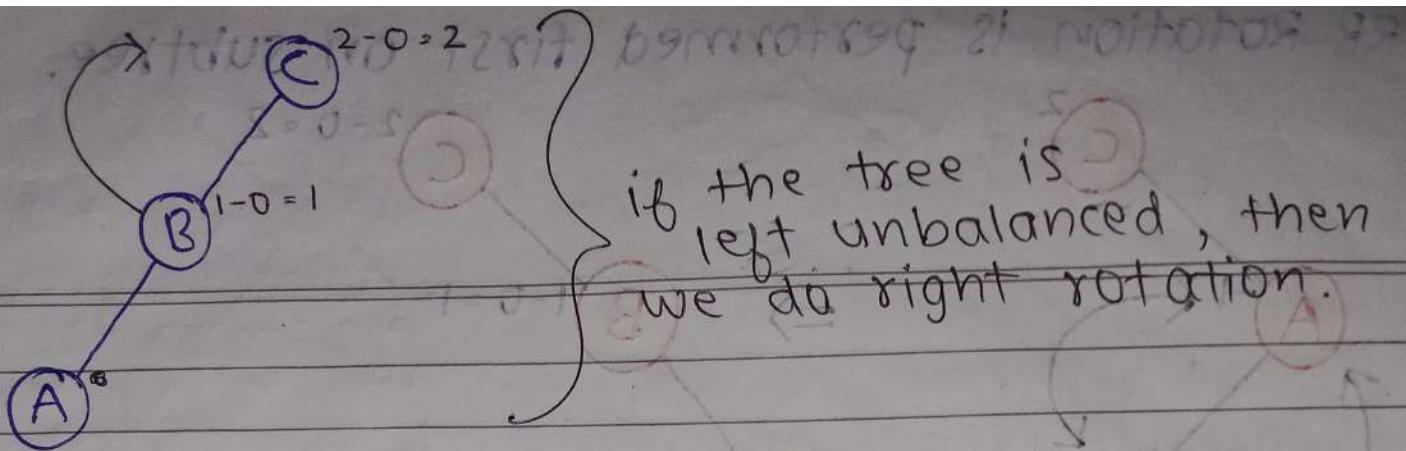
} if the tree of right unbalanced side, then we do left rotation.

* Right Unbalanced Tree



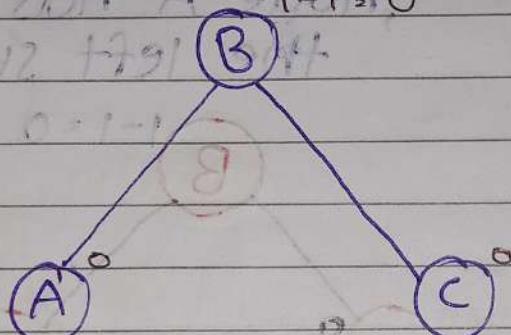
} Now, the tree is balanced.

a) RR Rotation, (Single Rotation)



* Left Unbalanced

Tree

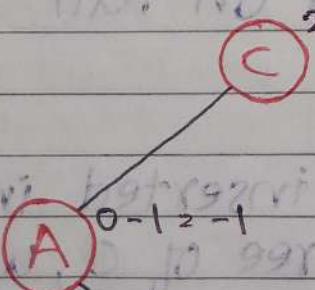


Now, the tree is Balanced Tree

b) LL Rotation (Single Rotation).

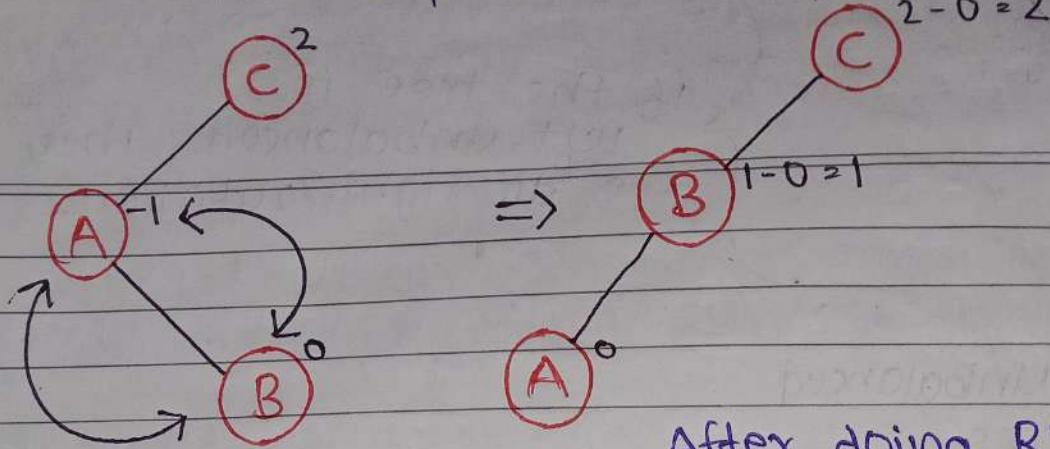
c) LR Rotation = (Double Rotation)

LR Rotation = LL Rotation + RR Rotation,
i.e., first RR Rotation is performed on subtree and then LL Rotation is performed on full tree.

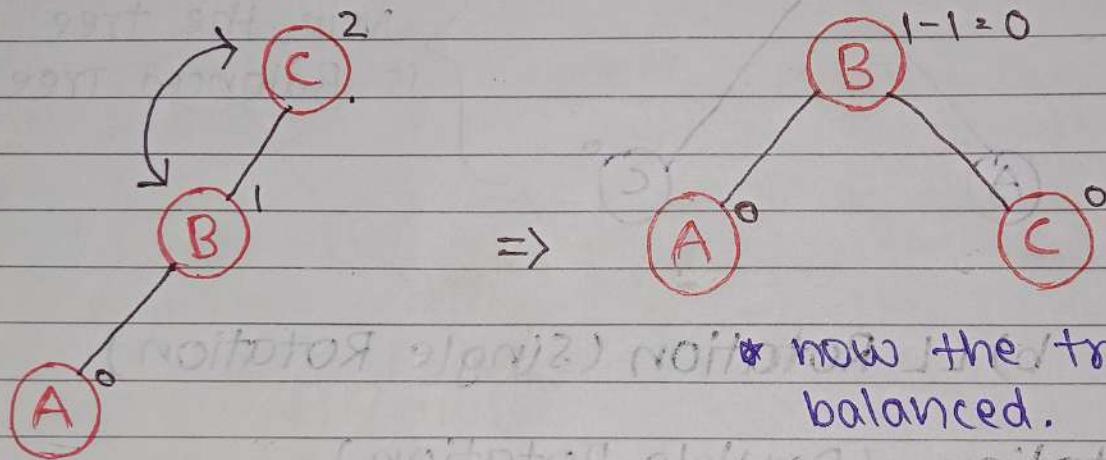


Node B has inserted into the right subtree of A which is a right subtree of C, because of which C has become the unbalanced node. Now, we do LR Rotation.

RR Rotation is performed first on subtree.



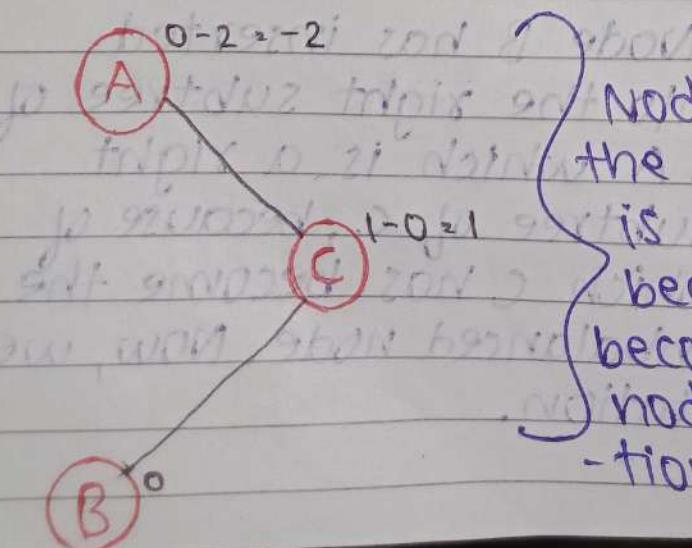
After doing RR Rotation,
node A has become
the left subtree of B.



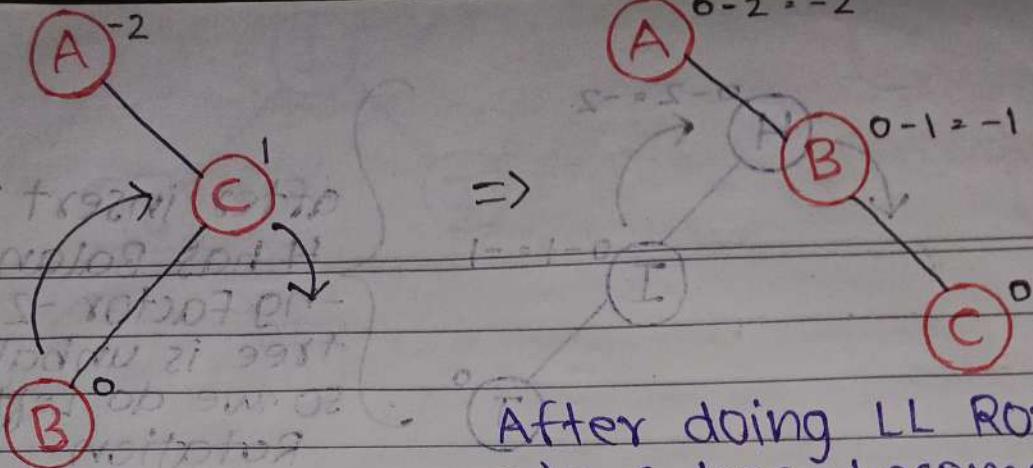
* now the tree is balanced.

d) RL Rotation = (Double Rotation)

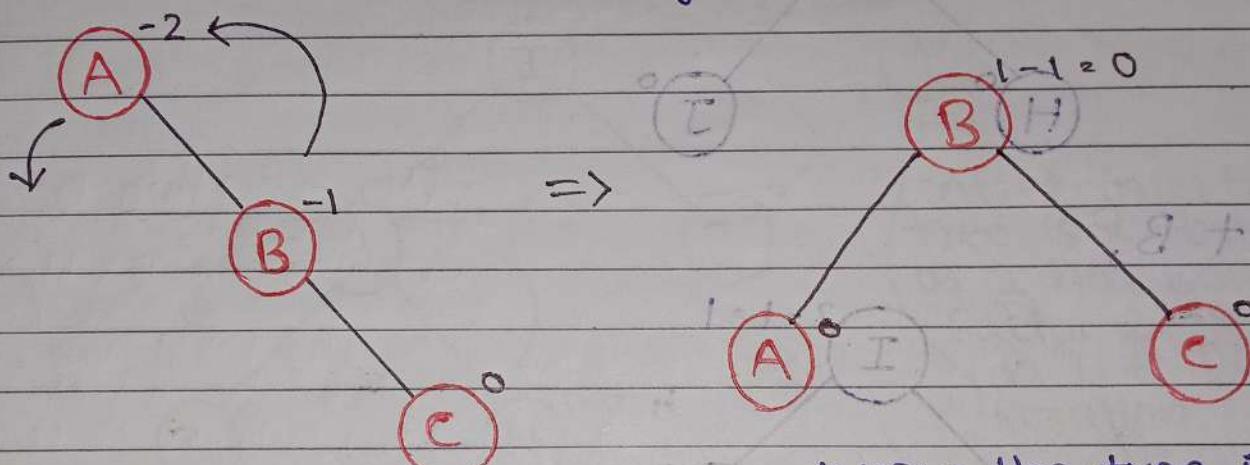
RL Rotation = RR Rotation + LL Rotation,
first LL Rotation is performed on subtree
then RR Rotation is performed on full
tree.



Node B has inserted into
the left subtree of C, which
is a right subtree of A,
because of which A has
become the unbalanced
node. Now, we do RL Rota-
tion.



After doing LL Rotation,
node C has become the
right subtree of B.

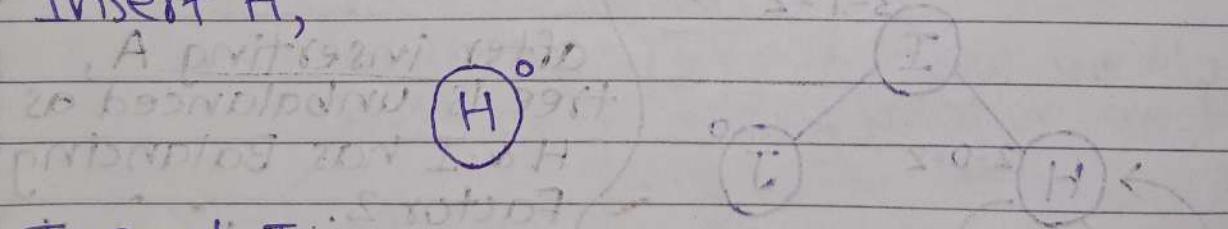


* now the tree is
balanced.

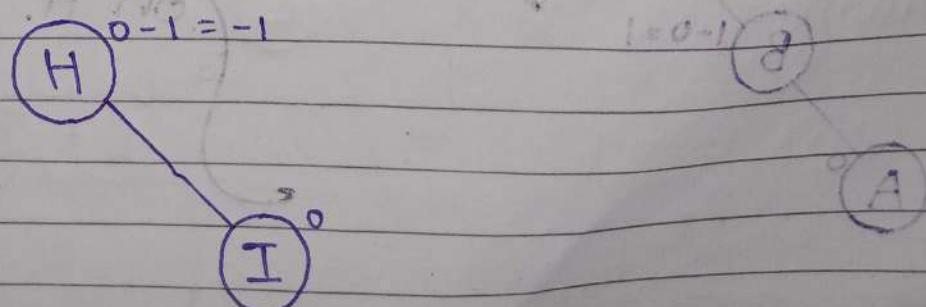
X — X — X — X — X —

Eg:- construct AVL Tree :-
H, I, J, B, A, E, C, F, D, G, K, L

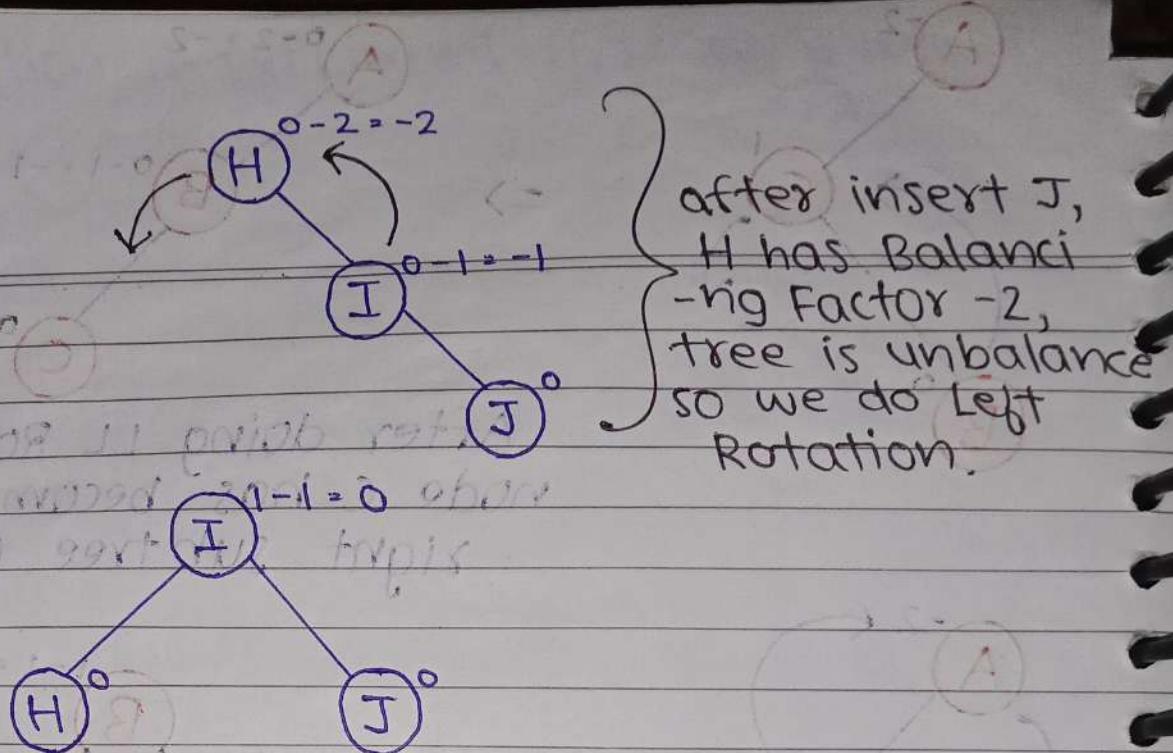
Insert H,



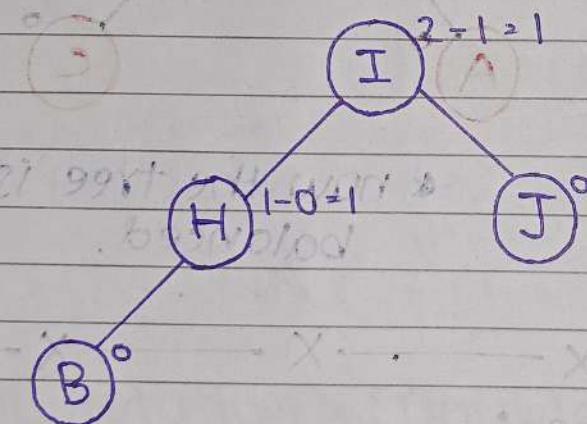
Insert I,



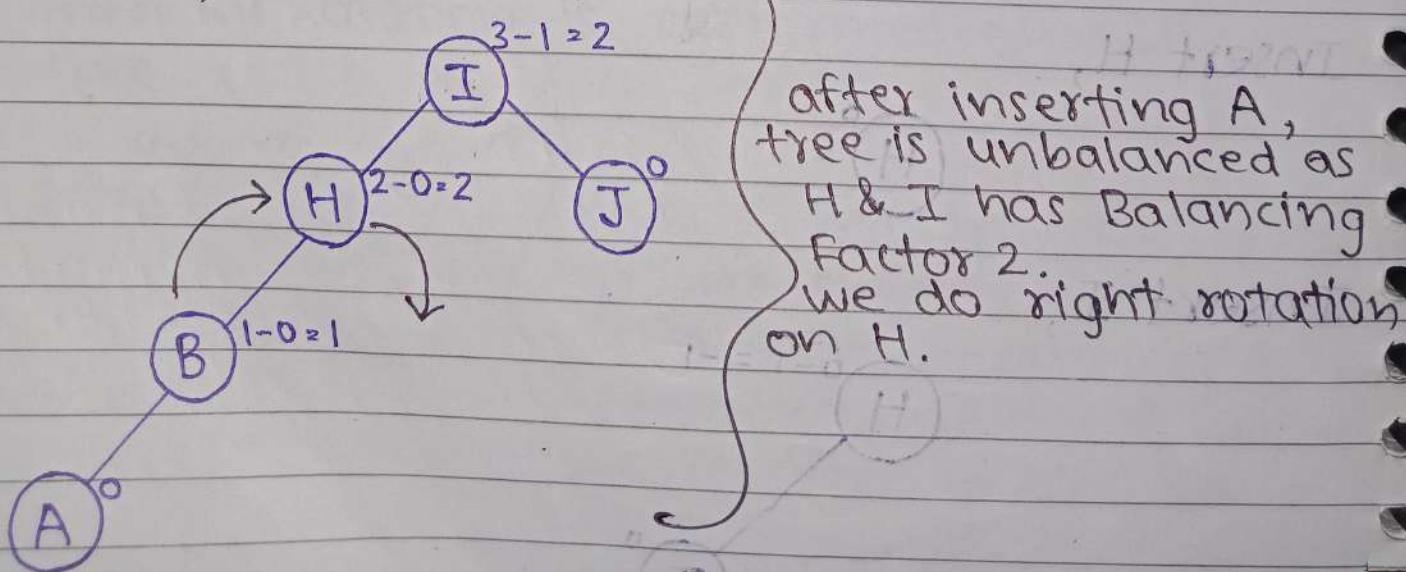
Insert J,

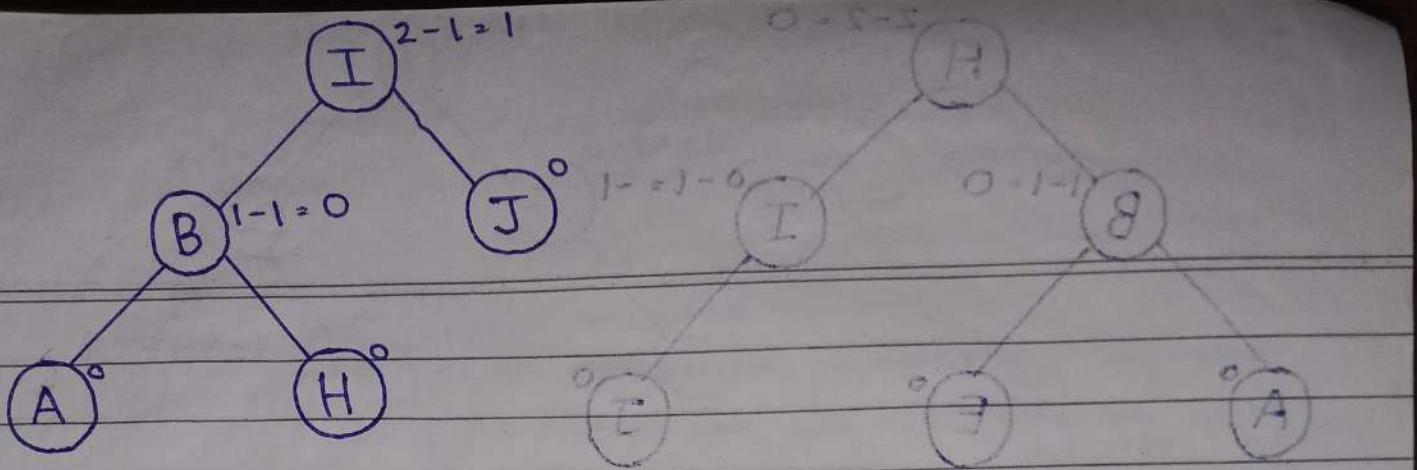


Insert B,



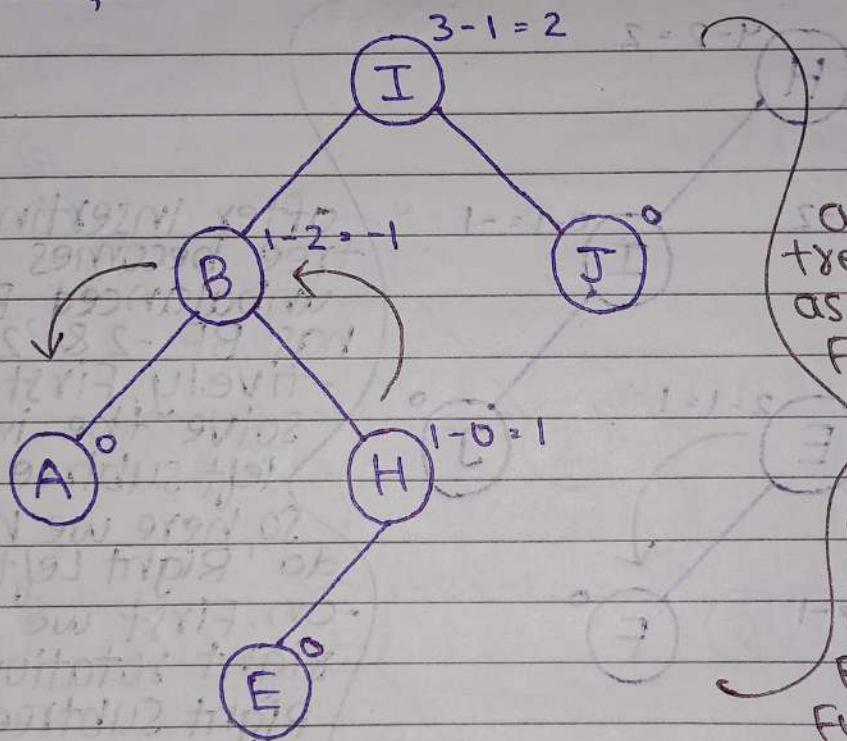
Insert A,





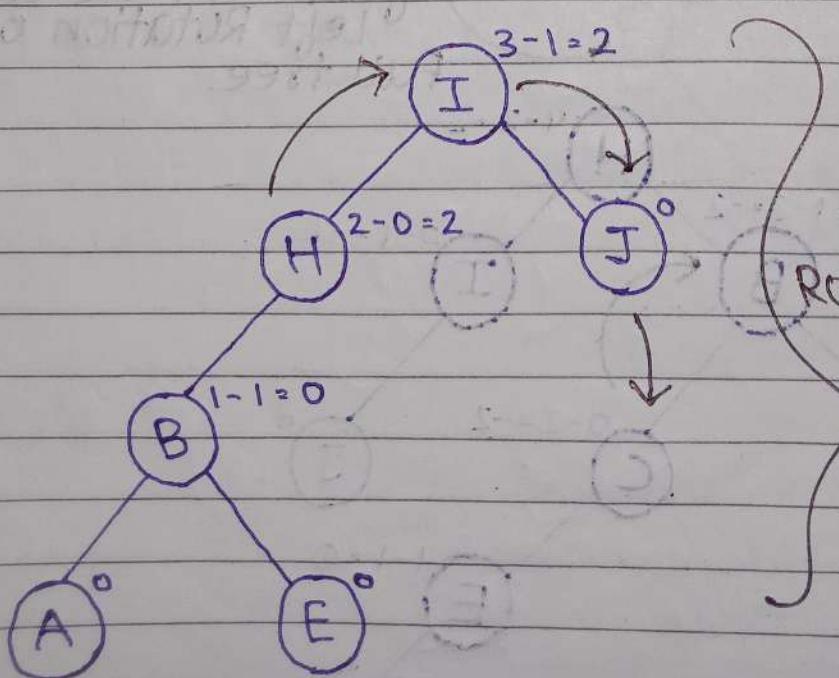
Insert E,

Q, F, D from I

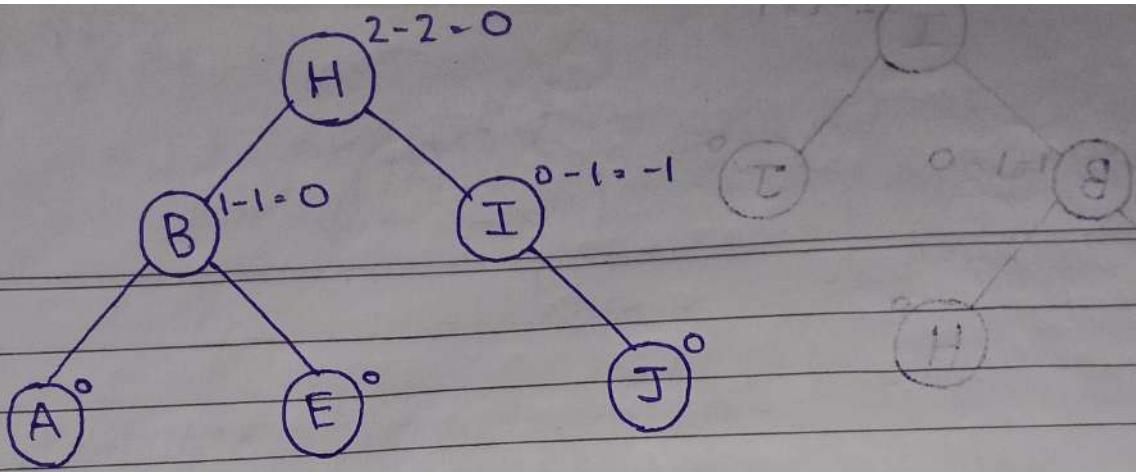


after inserting E,
tree is unbalanced,
as I has Balancing
Factor 2. Here, we
do Left Right
Rotation.

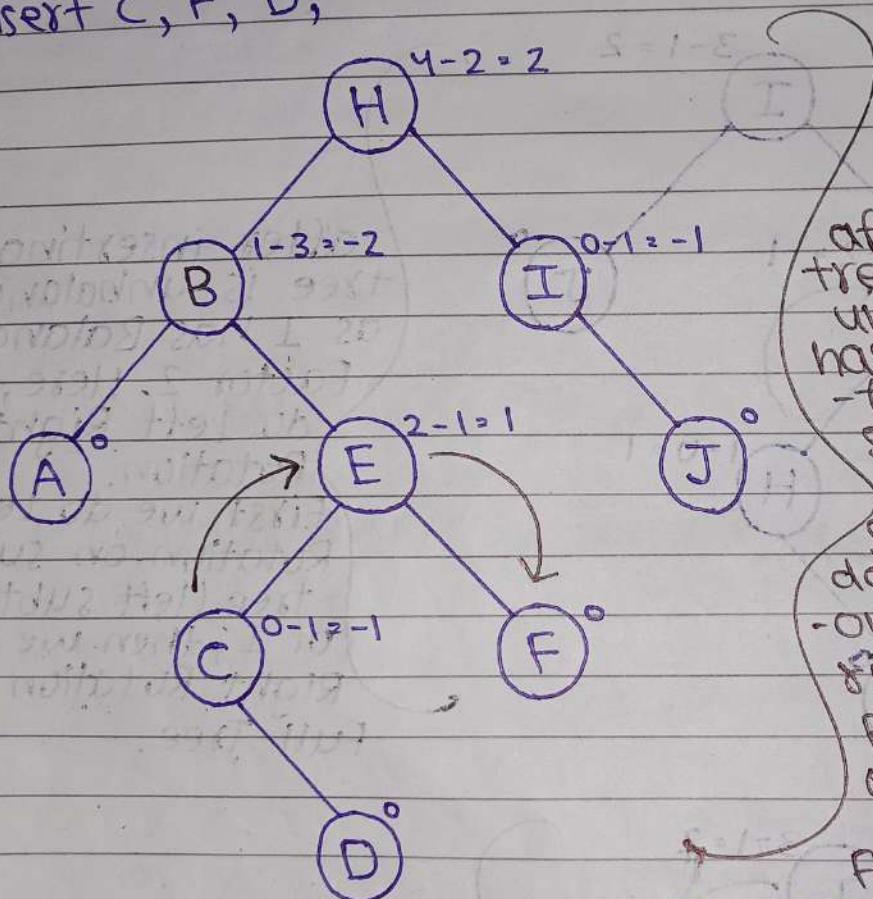
First we do Left
Rotation on sub
tree ('left subtree')
of I, then we do
Right Rotation on
Full Tree.



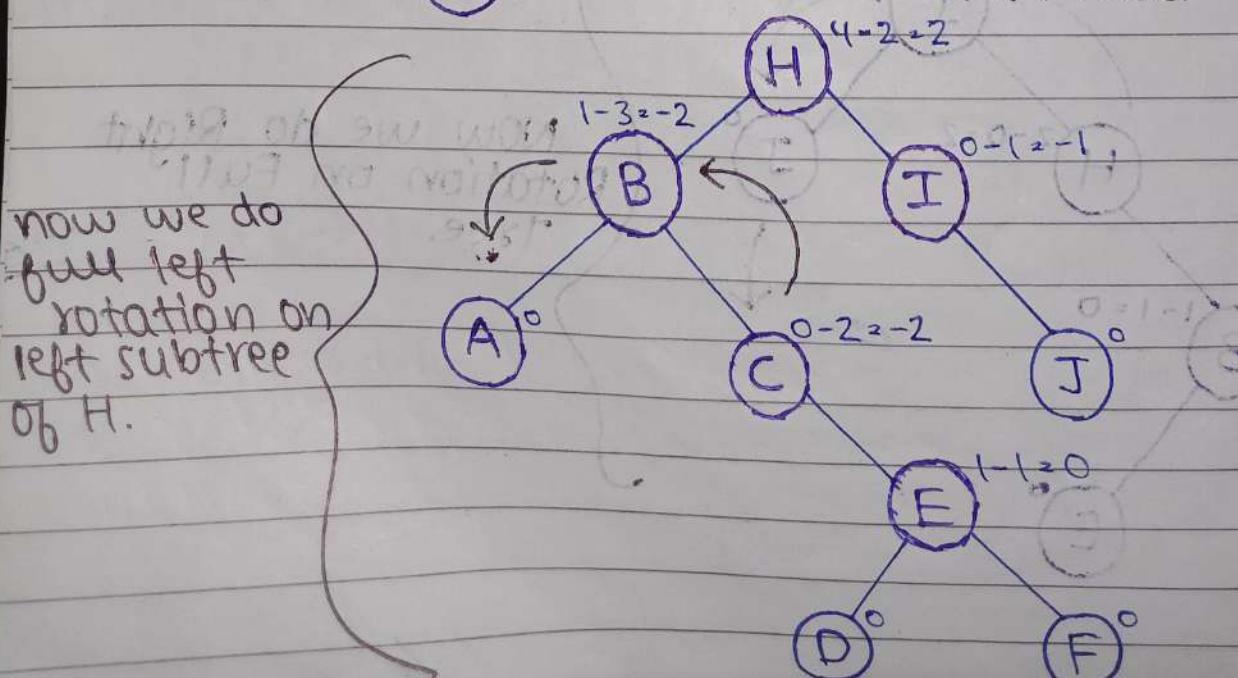
NOW we do Right
Rotation on Full
Tree.



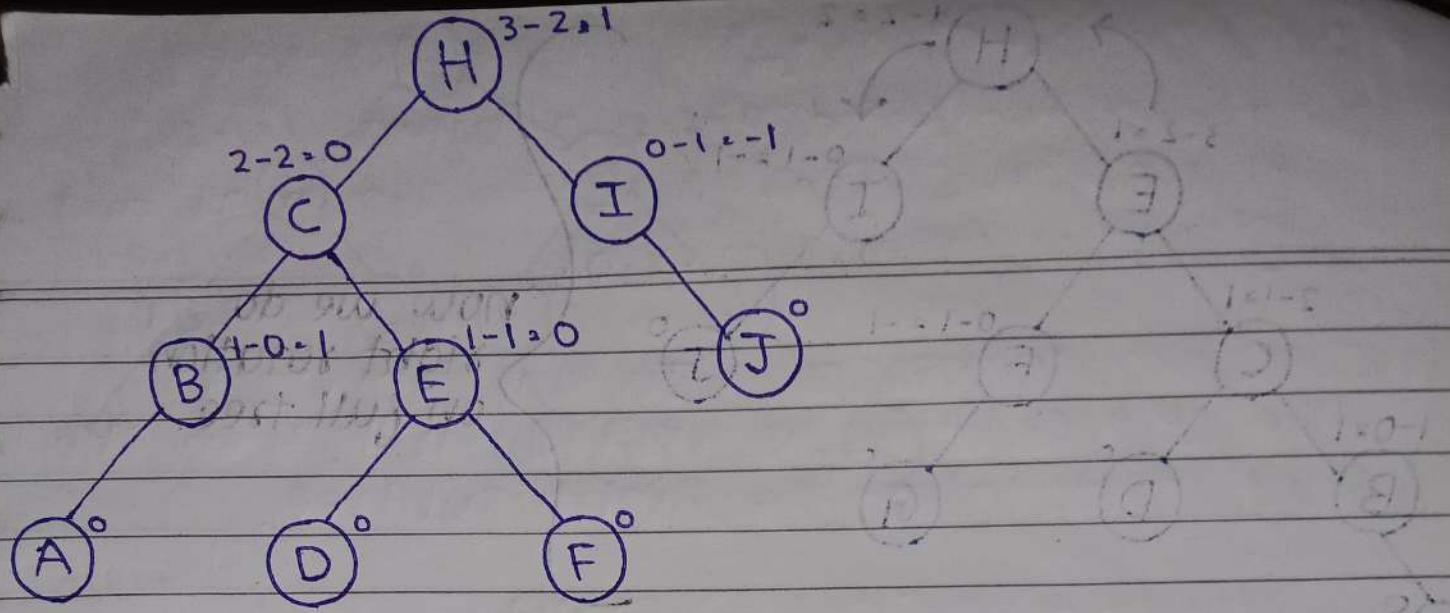
Insert C, F, D,



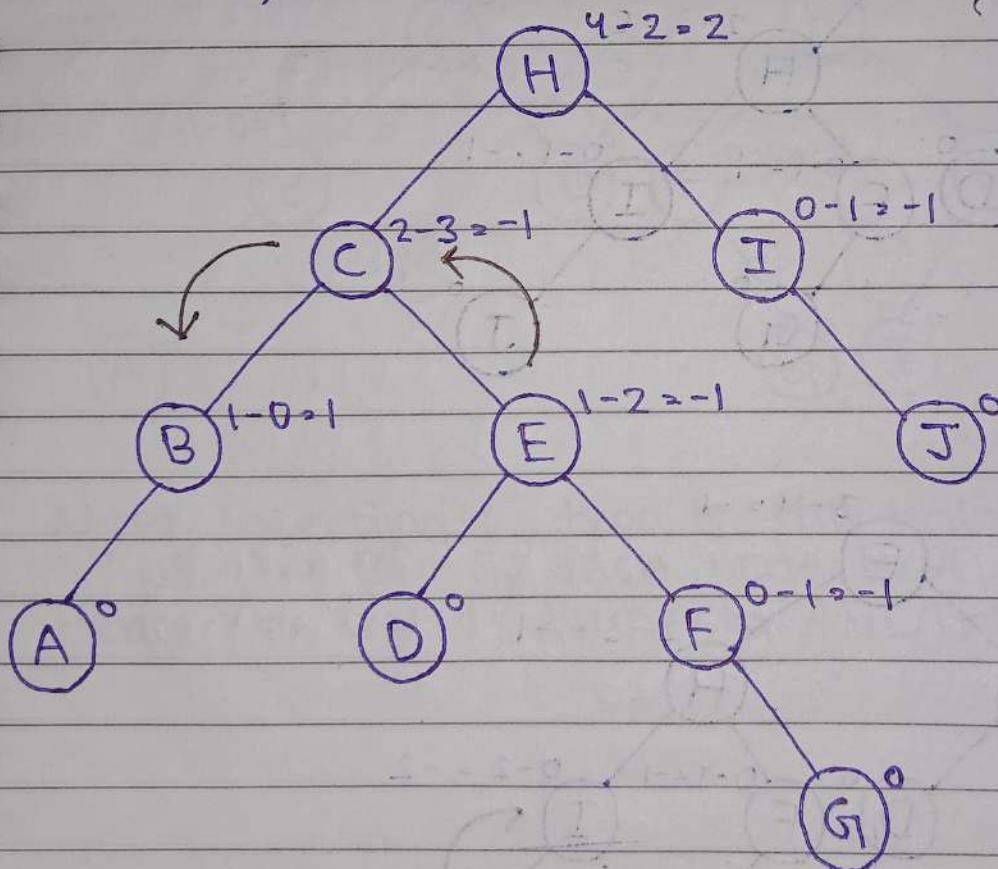
after inserting D,
tree becomes
unbalanced, B & H
has BF -2 & 2 respec-
tively. First, we
solve the inner
left subtree of H.
So, here we have to
do 'Right Left Rotati-
on'. First we do
right rotation of
Right subtree
of B. Then we do
Left Rotation on
full tree.



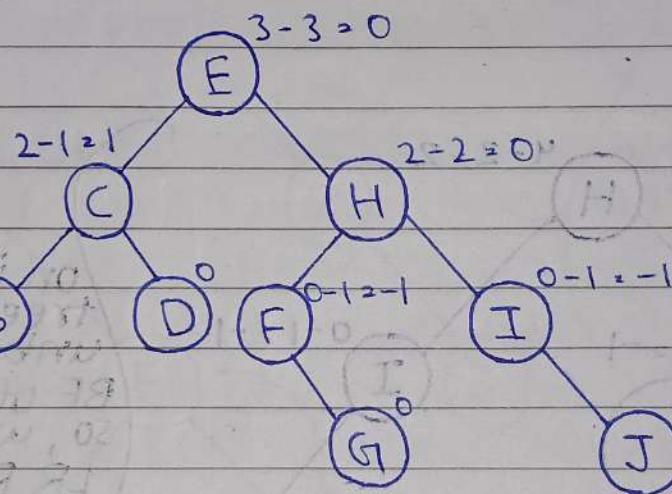
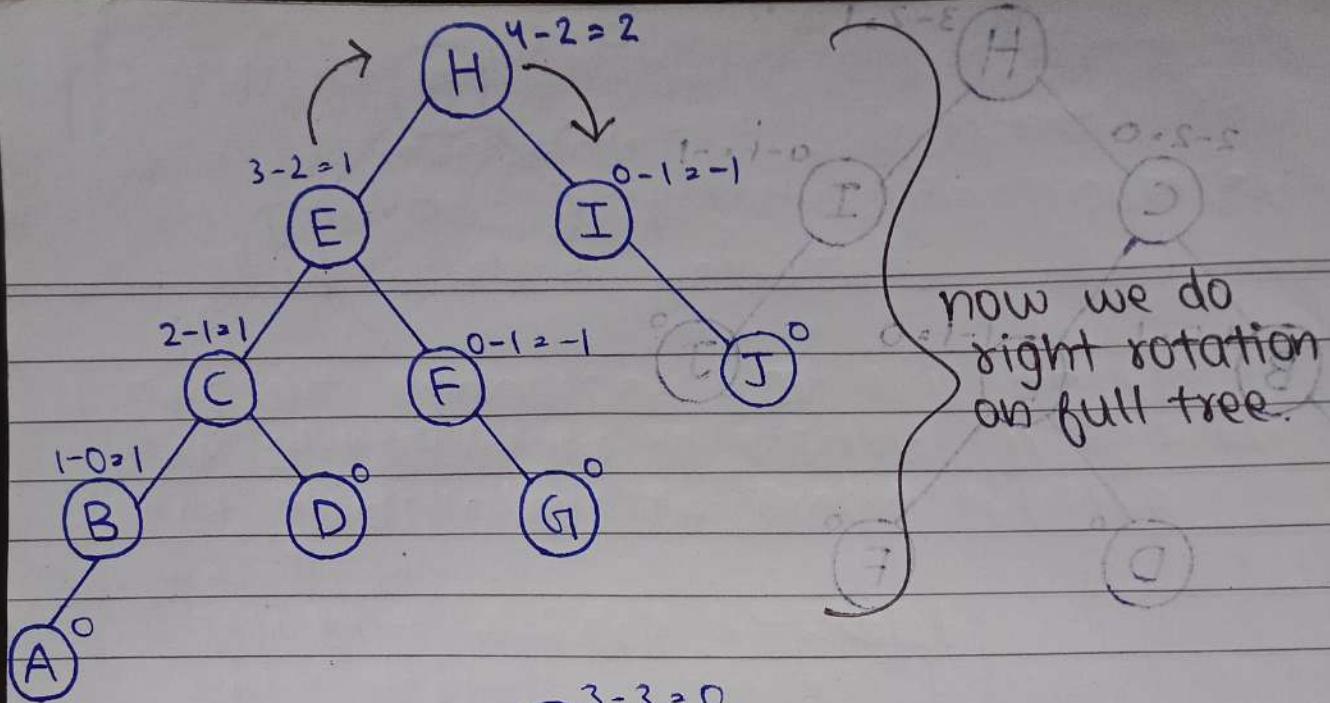
now we do
full left
rotation on
left subtree
of H.



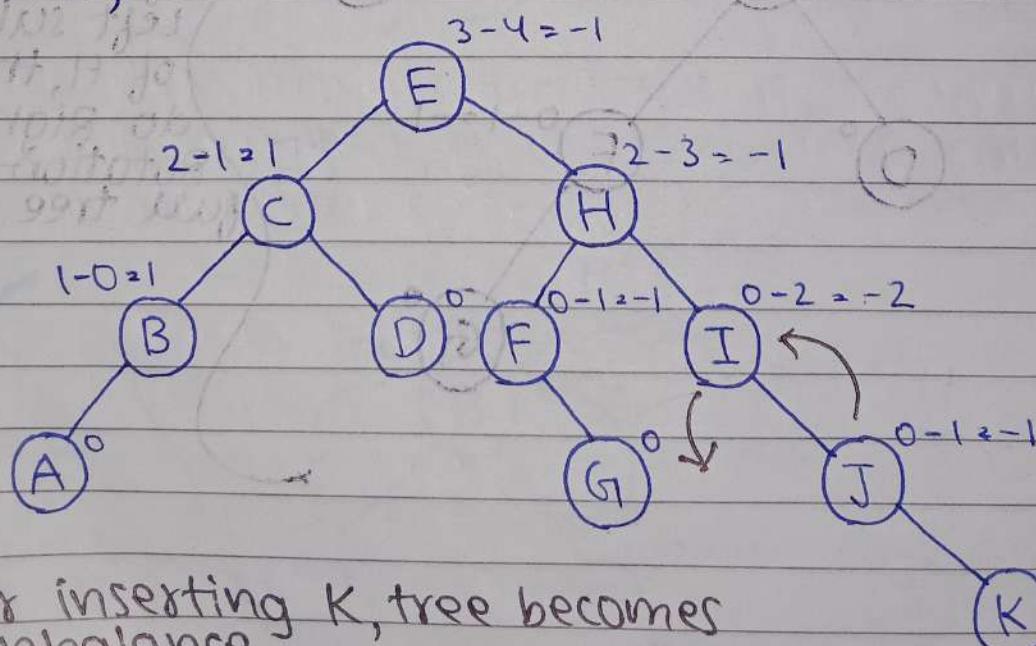
Insert G,



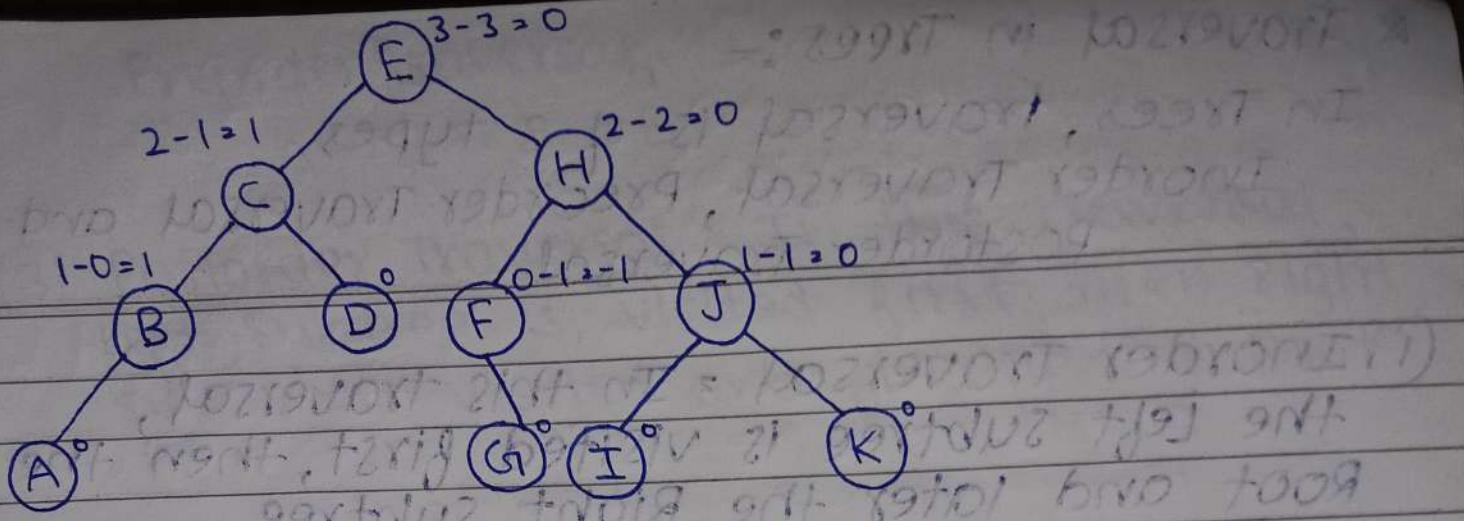
on inserting G,
tree becomes
unbalanced,
BF of H is 2,
so, we perform
LR Rotation.
First we perform
Left Rotation on
Left subtree
of H, then we
do Right
Rotation on
full tree.



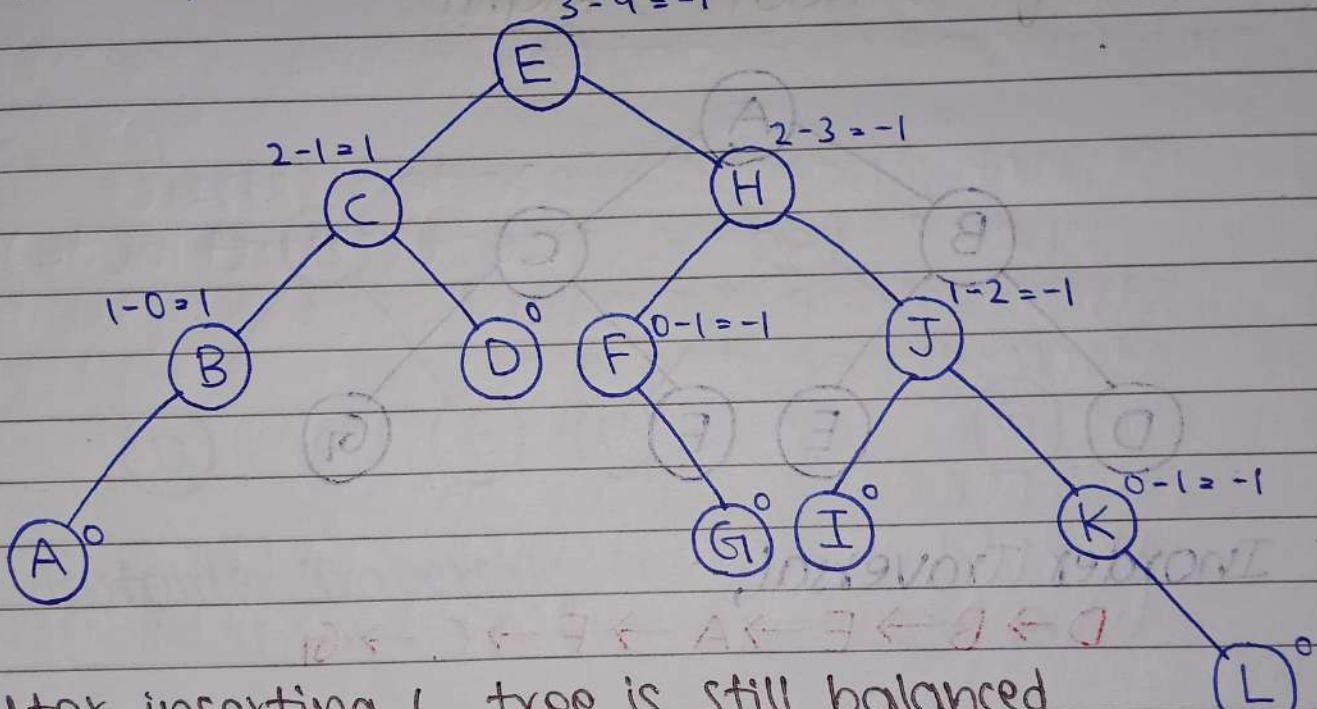
Insert K,



after inserting K, tree becomes unbalance
so, we do left rotation on right subtree of I.



Insert L,



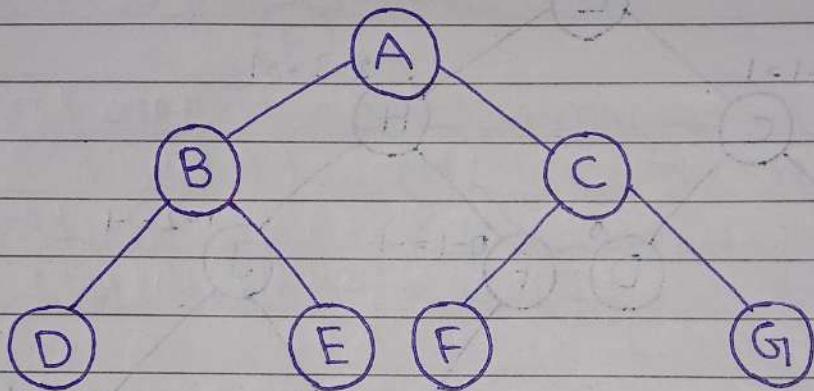
After inserting L, tree is still balanced
as the BF of each node is -1, 0, +1.
Hence, the tree is Balanced AVL Tree.

* Traversal in Trees :-

In Trees, traversal is of 3 types
Inorder Traversal, Preorder Traversal and
Postorder Traversal.

- ① Inorder Traversal = In this traversal,
the Left subtree is visited first, then the
Root and later the Right subtree.

Left → Root → Right

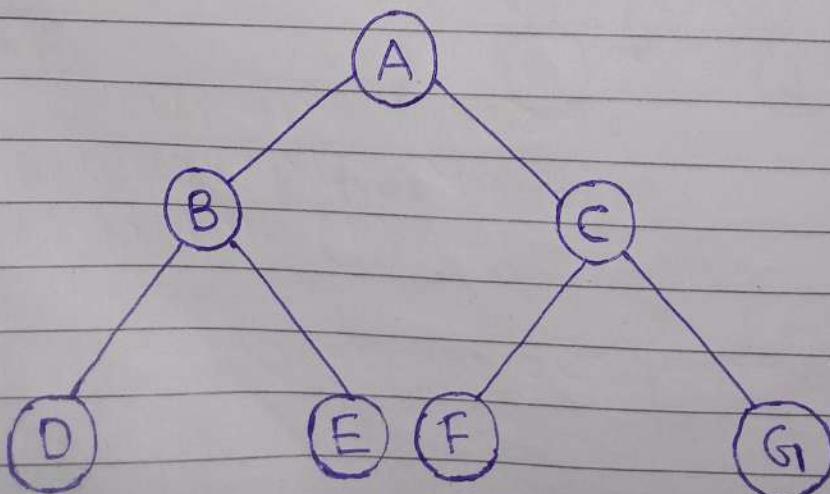


Inorder Traversal,

D → B → E → A → F → C → G

- ② Preorder Traversal = In this traversal,
Root is visited first, then left subtree
& finally right subtree.

Root → Left → Right

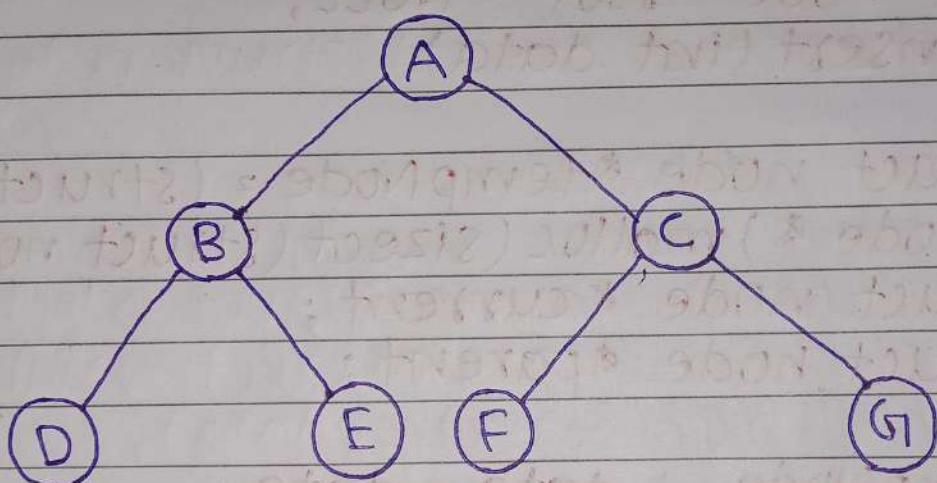


Preorder Traversal,

A → B → D → E → C → F → G

- ③ Postorder Traversal = In this traversal, left subtree is visited first, then right subtree is visited and finally the root node

Left → Right → Root



Postorder Traversal,

D → E → B → F → G → C → A

* Inorder - Preorder - Postorder Program.

```
#include <stdio.h>
#include <stdlib.h>
struct node
{
    int data;
    struct node *leftchild;
    struct node *rightchild;
};
struct node *root = NULL;
void insert(int data)
{
    struct node *tempNode = (struct
        node *)malloc(sizeof(struct node));
    struct node *current;
    struct node *parent;
    tempNode->data = data;
    tempNode->leftchild = NULL;
    tempNode->rightchild = NULL;
    // If tree is empty.
    if (root == NULL)
    {
        root = tempNode;
    }
    else
    {
        current = root;
        parent = NULL;
        while (1)
        {
            parent = current;
            if (data < current->data)
```

```
    void f() {
        // go to the left of the tree
        if (data < parent->data) {
            current = current->leftchild;
            // insert to the left
            if (current == NULL) {
                parent->leftchild = tempNode;
                return;
            }
        } else {
            current = current->rightchild;
            // insert to the right
            if (current == NULL) {
                parent->rightchild = tempNode;
                return;
            }
        }
    }
}
```

```
void pre_order_traversal(struct node *root)
{
    if (root != NULL) {
        printf("%d ", root->data);
        pre_order_traversal(root->leftchild);
        pre_order_traversal(root->rightchild);
    }
}
```

```
void in_order_traversal(struct node  
*root)
```

{

```
if (root != NULL)
```

```
{ in_order_traversal (root -> leftchild);  
printf ("%d ", root -> data);  
inorder_traversal (root -> rightchild);
```

}

}

```
void post_order_traversal (struct node *root)
```

{

```
if (root != NULL)
```

```
{ post_order_traversal (root -> leftchild);  
post_order_traversal (root -> rightchild);  
printf ("%d ", root -> data);
```

}

}

```
int main()
```

{

```
int i;
```

```
int array[7] = {27, 14, 35, 10, 19, 31, 42};
```

```
for (i = 0; i < 7; i++)
```

{

```
insert (array[i]);
```

}

```
printf ("Preorder: ");
```

```
pre_order_traversal (root);
```

```
printf ("Inorder: ");
```

```
in_order_traversal (root);
```

```
printf("Postorder:");  
post_order_traversal(root);  
printf("\n");  
return 0;  
}
```

* Convert expression from Infix to Postfix
using stack.

```
#include <stdio.h>  
#include <ctype.h>  
char stack[100];  
int top = -1;  
void push(char x)  
{  
    stack[++top] = x;  
}  
char pop()  
{  
    if (top == -1)  
    {  
        return -1;  
    }  
    else  
    {  
        return stack[top--];  
    }  
}  
int priority(char x)  
{  
    if (x == '(')  
    {  
        return 0;  
    }
```

```
if (x == '+' || x == '-')
{
    return 1;
}

if (x == '*' || x == '/')
{
    return 2;
}

return 0;
}

int main()
{
    char exp[100];
    char *e, x;
    printf("enter the expression:");
    scanf("%s", exp);
    e = exp;
    while (*e != '\0')
    {
        if (isalnum(*e))
        {
            printf("%c", *e);
        }
        else if (*e == '(')
        {
            push(*e);
        }
        else if (*e == ')')
        {
            while ((x = pop()) != '(')
            {
                printf("%c", x);
            }
        }
        else
        {
            while (priority(stack[top]) >=
                    priority(*e))
            {
                printf("%c", pop());
            }
        }
    }
}
```

```

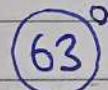
        push(*e);
    } // for every character
    } // for every word
    } // for every sentence
    while (top != -1)
    {
        printf("%c", pop());
    }
    return 0;
}

```

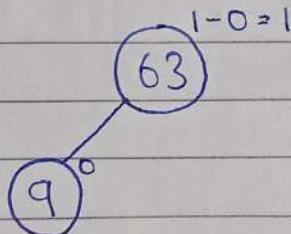
Eg :- Construct AVL Tree :-

63, 9, 19, 27, 18, 108, 99, 81

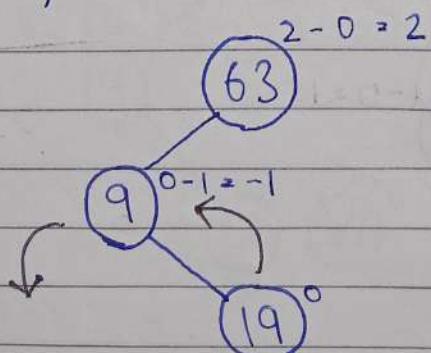
Insert 63,



Insert 9,

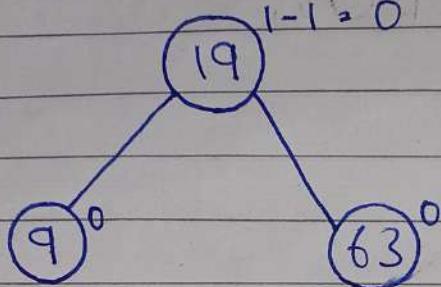
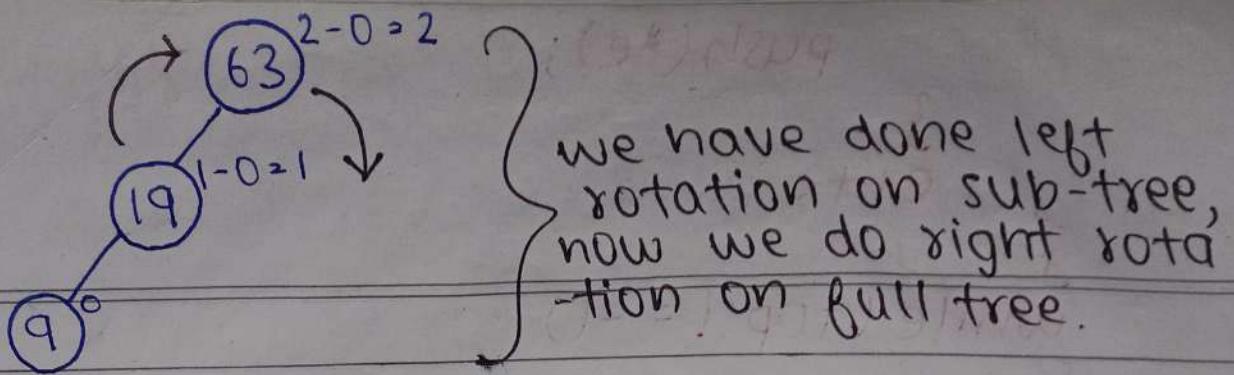


Insert 19,

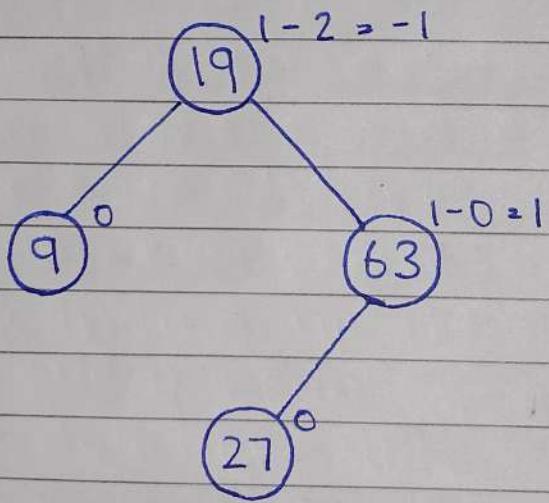


} after inserting 19, the BF of 63 is 2, 19 is placed at Left Right side of 63, so we do LR Rotation.

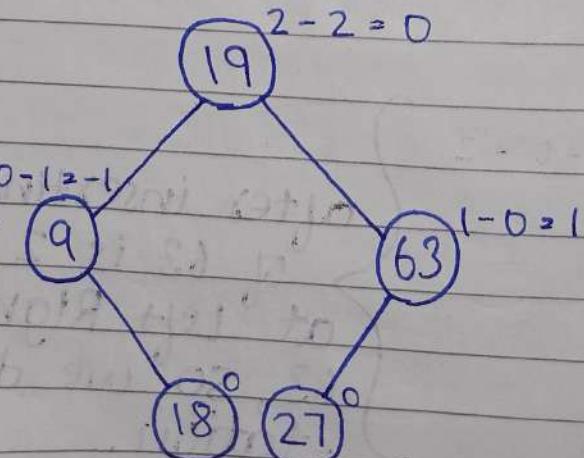
First we do Left Rotation on subtree the Right Rotation on full tree.



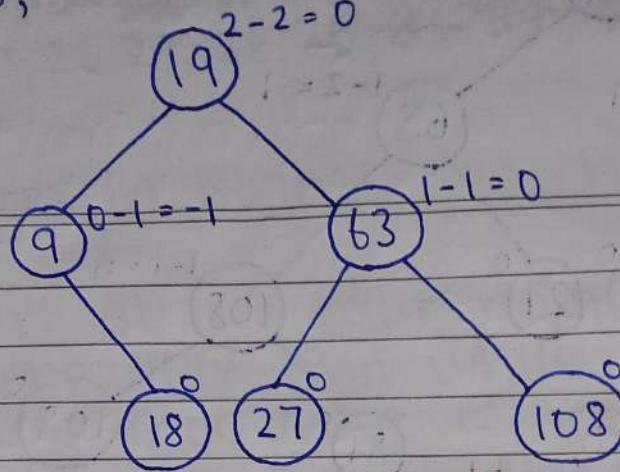
Insert 27,



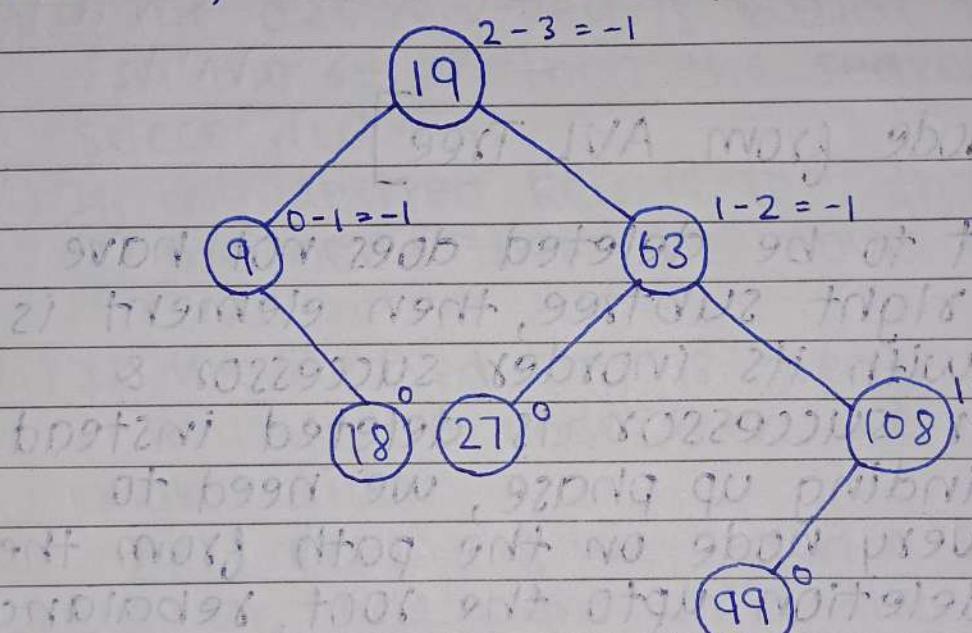
Insert 18,



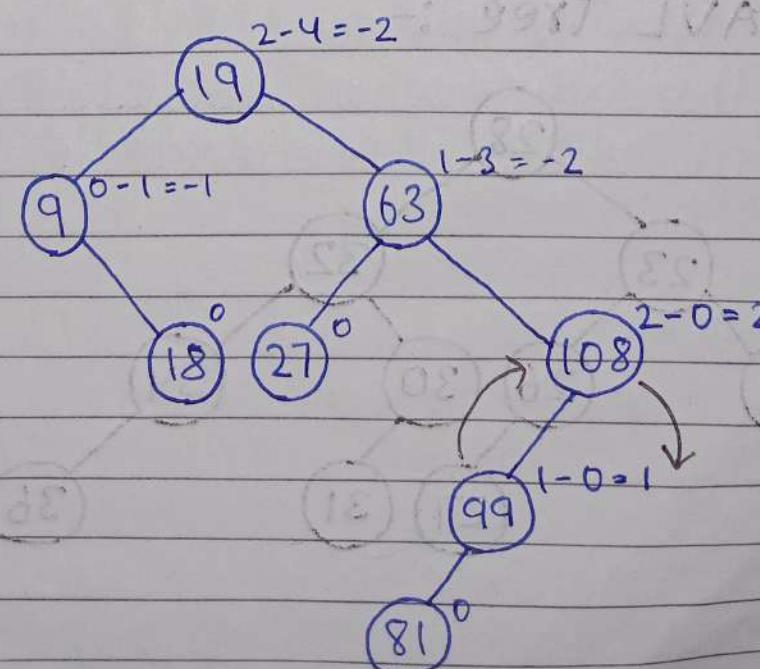
Insert 108,



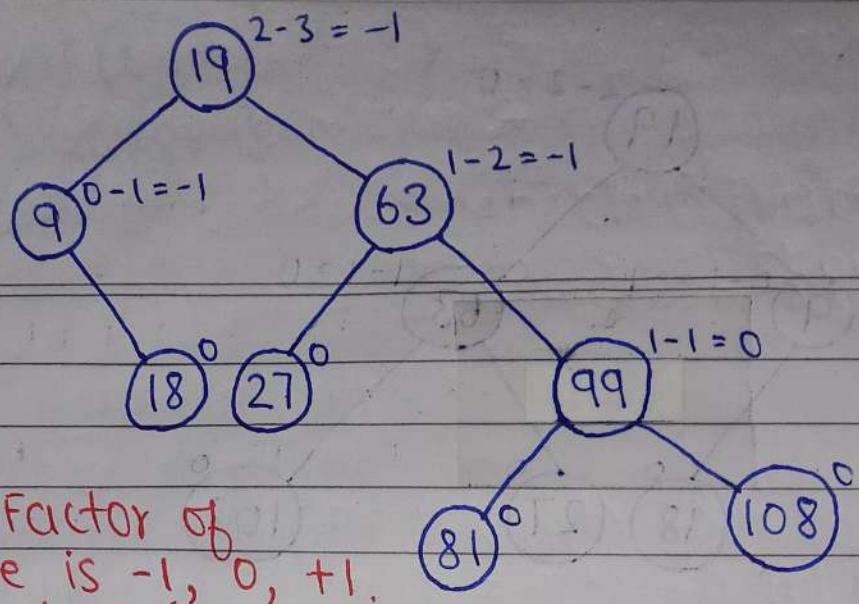
Insert 99,



Insert 81,



after insert
81, the BF
of 108 is
2 so we
do right
rotation.

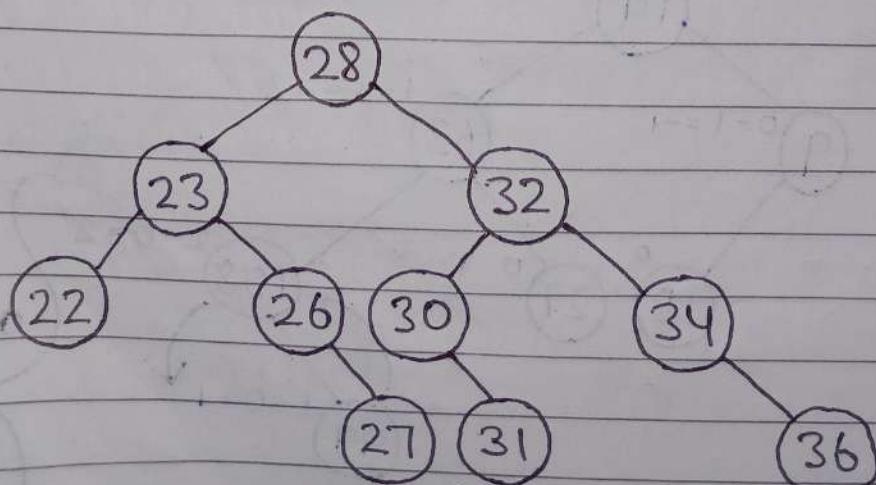


* Balancing Factor of each node is $-1, 0, +1$.
Hence, the tree is Balanced AVL Tree.

[Deleting Node from AVL Tree]

- * If element to be deleted does not have empty right subtree, then element is replaced with its inorder successor & its inorder successor is deleted instead.
- * During winding up phase, we need to revisit every node on the path from the point of deletion upto the root, rebalance the tree if require.

Eg:- Given AVL Tree :-



Inorder Traversal, 22, 23, 26, 27, 28, 30, 31, 32, 34, 36

* Searching in Binary Search Tree and AVL Tree :-

We start at the root node and move down the tree and while descending when we encounter a node, we compare the desired key with the key of that node and take appropriate action.

- i) If the desired key is equal to the key in the node then the search is successful.
- ii) If the desired key is less than the key of the node then we move to left child.
- iii) If the desired key is greater than the key of the node then we move to right child.

In the process, if we reach a NULL left child or NULL right child then the search is unsuccessful, i.e., desired element is not present in the tree.

The non-recursive function for searching a node is given below :-

```
struct node *search(struct node *ptr, int skey)
{
    while(ptr != NULL)
    {
        if(skey < ptr->info)
            move to left child ←
        else if(skey > ptr->info)
            move to right child ←
        else
            if skey found
                return its address.
            else
                return NULL;
    }
    if skey not found
        return null.
```

The above function is passed the address of the root of the tree & the key to be search. It returns the address of the node having the desired key or NULL, if the node is not found.

The recursive function for searching a node is given below:-

```
struct node *search (struct node  
*ptr, int skey)  
{  
    if (ptr == NULL) {  
        printf("not found");  
        return NULL;  
    }  
    else if (skey < ptr -> info) {  
        return search (ptr -> lchild,  
                       skey);  
    }  
    else if (skey > ptr -> info) {  
        return search (ptr -> rchild,  
                       skey);  
    }  
    else {  
        return ptr;  
    }  
}
```

* Finding minimum node :- The last node in the leftmost path starting from the root is the minimum element. To find this node we start with the root & move along the leftmost path until we get a node with no left child.

```

struct node *min (struct node *ptr)
{
    if (ptr == NULL)
    {
        while (ptr->lchild != NULL)
        {
            ptr = ptr->lchild;
        }
    }
    return ptr;
}

```

* Finding Maximum Node :- The last node in the rightmost path starting from root is the maximum element. To find this node we start at the root & move along the rightmost path until we get a node with no right child.

```

struct node *max (struct node *ptr)
{
    if (ptr != NULL)
    {
        while (ptr->rchild != NULL)
        {
            ptr = ptr->rchild;
        }
    }
    return ptr;
}

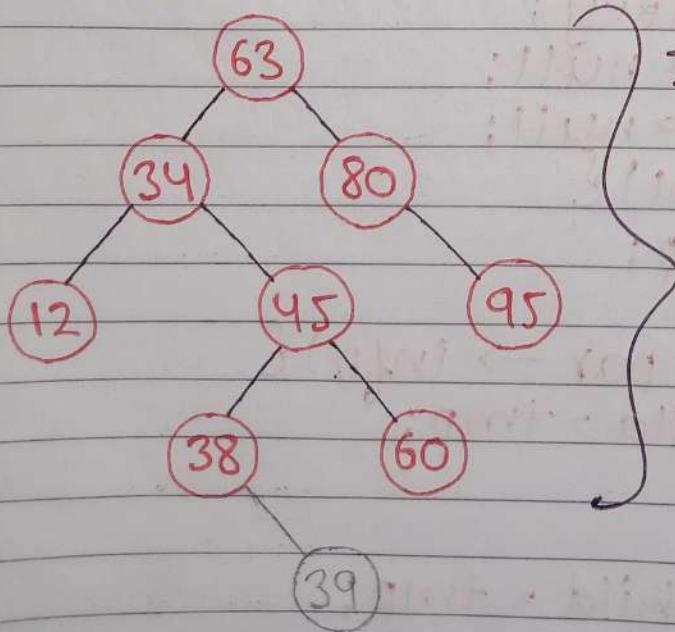
```

* Insertion in Binary Search Tree:-

For inserting a new node, first the key is searched & if it is not found in the tree then it is inserted at the place where search terminates. we start at the root node and move down the tree & while descending when we encounter a node we compare the key to be inserted with the key of that node & take appropriate action.

- i) if the key to be inserted is equal to the key in the node then there is nothing to be done as duplicate keys are not allowed.
- ii) If the key to be inserted is less than the key of the node then we move to left child.
- iii) If the key to be inserted is greater than the key of the node then we move to right child.

* we insert the new key when we reach a NULL left or right child.



Insert 39,

39 < 63, move to left child

39 > 34, move to right child

39 < 45, move to left child.

39 > 38, move to right child

NULL Right child.

Insert 39 as Right child
of 38.

The non-recursive function for inserting a node is given below :-

struct node *insert (struct node *root,
int iKey)

{ struct node *tmp, *par, *ptr;

ptr = root;

par = null;

while (ptr != null) {

par = ptr;

if (iKey < ptr -> info) {

ptr = ptr -> lchild;

}

else if (iKey > ptr -> info) {

ptr = ptr -> rchild;

}

else {

printf ("Duplicate Key");

return root;

}

tmp = (struct node *) malloc (sizeof
(struct node));

tmp -> info = iKey;

tmp -> lchild = null;

tmp -> rchild = null;

if (par == null) {

root = tmp;

}

else if (iKey < par -> info) {

par -> lchild = tmp;

else {

par -> rchild = tmp;

return root;

The recursive function for inserting a node is given below:

```
struct node *insert(struct node
```

```
*ptr, int ikey)
```

```
{ if(ptr == null) {
```

```
    ptr = (struct node*) malloc(sizeof(struct node));
```

```
    ptr->info = ikey;
```

```
    ptr->lchild = null;
```

```
    ptr->rchild = null;
```

```
    return ptr; }
```

```
    else if(ikey < ptr->info) {
```

```
        ptr->lchild = insert(ptr->lchild, ikey);
```

```
}
```

```
else if(ikey > ptr->info) {
```

```
    ptr->rchild = insert(ptr->rchild, ikey);
```

```
}
```

```
else {
```

```
    printf("Duplicate Key ");
```

```
}
```

```
return ptr;
```

```
}
```

To insert in empty tree, root is made to point to the new node. As we move down the tree, we keep track of the parent of the node because this is required for the insertion of new node.

The pointer "ptr" walks down the path and the parent of the "ptr" is maintained through pointer "par". When search terminates unsuccessfully, "ptr" is NULL and "par" points to the node whose link should be changed to insert the new node. The new node "tmp" is made the left or right child of the parent "par".

* Insertion and Deletion operations in AVL Trees :-

```
#include<stdio.h>
#include<stdlib.h>
#define FALSE 0
#define TRUE 1
struct node {
    struct node *lchild;
    int info;
    struct node *rchild;
    int balance;
};

struct node *RotateLeft (struct node *pptr);
struct node *RotateRight (struct node *pptr);
struct node *insert (struct node *pptr,
                     int ikey);
struct node *insert_left_check (struct node
                                 *pptr, int *ptaller);
struct node *insert_right_check (struct
                                 . . . . . node *pptr, int *ptaller);
struct node *insert_LeftBalance (struct
                                 node *pptr);
struct node *insert_RightBalance (struct
                                 . . . . . node *pptr);
struct node *del (struct node *pptr, int
                  dkey);
struct node *del_left_check (struct node
                             *pptr, int *pshorter);
struct node *del_right_check (struct node
                             *pptr, int *pshorter);
struct node *del_LeftBalance (struct node
                             *pptr, int *pshorter);
struct node *del_RightBalance (struct node
                             *pptr, int *pshorter);
```

```
main() {  
    int choice, key;  
    struct node *root = NULL;  
    while (1) {  
        printf("\n");  
        printf("1. insertion\n");  
        printf("2. Deletion\n");  
        printf("3. Inorder Traversal");  
        printf("4. QUIT");  
        printf("Enter choice = ");  
        scanf("%d", &choice);  
        switch (choice) {  
            case 1: {  
                printf("Enter key to be  
inserted = ");  
                scanf("%d", &key);  
                root = insert(root, key);  
                break;  
            }  
            case 2: {  
                printf("Enter key to be  
deleted = ");  
                scanf("%d", &key);  
                root = del(root, key);  
                break;  
            }  
            case 3: {  
                inorder(root);  
                break;  
            }  
            case 4: {  
                exit(1);  
            }  
            default: {  
                printf("wrong choice");  
            }  
        }  
    }  
}
```

```
struct node *rotateLeft(struct node *pptr)
{
    struct node *aptr;
    aptr = pptr -> rchild;
    pptr -> rchild = aptr -> lchild;
    aptr -> lchild = pptr;
    return aptr;
}
```

```
struct node *rotateRight(struct node *pptr)
{
    struct node *aptr;
    aptr = pptr -> lchild;
    pptr -> lchild = aptr -> rchild;
    aptr -> rchild = pptr;
    return aptr;
}
```

```
struct node *insert(struct node *pptr,
                    int ikey)
{
    static int taller;
    if (pptr == NULL) {
        pptr = (struct node *) malloc
            (sizeof (struct node));
        pptr -> info = ikey;
        pptr -> lchild = NULL;
        pptr -> rchild = NULL;
        pptr -> balance = 0;
        taller = TRUE;
    }
}
```

```
else if (ikey < pptr -> info) {
    pptr -> lchild = insert(pptr -> lchild,
                            ikey);
```

```
if (taller == TRUE) {  
    pptr = insert_left_check (pptr,  
                             &taller);  
}  
}  
else if (ikey > pptr->info) {  
    pptr->rchild = insert (pptr->  
                           rchild, ikey);  
    if (taller == TRUE) {  
        pptr = insert_right_check  
              (pptr, &taller);  
    }  
}  
else {  
    printf ("Duplicate Key");  
    taller = FALSE;  
}  
}  
return pptr;
```

```
struct node *insert_left_check (struct node  
                               *pptr, int *ptaller)  
{
```

```
    switch (pptr->balance) {  
        case 0:  
            pptr->balance = 1;  
            break;  
        case -1:  
            pptr->balance = 0;  
            *ptaller = FALSE;  
            break;  
        case 1:  
            pptr = insert_left_balance (pptr);  
            *ptaller = FALSE;  
    }  
    return pptr;
```

```
struct node *insert_right_check (struct node *pptr, int *ptaller)
{
    switch (pptr->balance) {
        case 0:
            pptr->balance = -1;
            break;
        case 1:
            pptr->balance = 0;
            *ptaller = FALSE;
            break;
        case -1:
            pptr = insert_RightBalance(pptr);
            *ptaller = FALSE;
    }
    return pptr;
}
```

```
struct node *insert_leftBalance (struct node *pptr)
{
    struct node *aptr, *bptr;
    aptr = pptr->lchild;
    if (aptr->balance >= 1) {
        pptr->balance = 0;
        aptr->balance = 0;
        pptr = RotateRight(pptr);
    }
    else {
        bptr = aptr->rchild;
        switch (bptr->balance) {
            case -1:
                pptr->balance = 0;
                aptr->balance = 1;
                break;
            case 0:
                pptr->balance = 0;
                aptr->balance = 0;
                break;
            case 1:
                pptr->balance = 1;
                aptr->balance = 0;
                break;
        }
    }
}
```

case 1:

 pptr → balance = -1;
 aptr → balance = 0;
 break;

case 0:

 pptr → balance = 0;
 aptr → balance = 0;

}

 bptr → balance = 0;

 pptr → lchild = RotateLeft(aptr);
 pptr = RotateRight(pptr);

return pptr;

}

struct node * insert_RightBalance (struct
node * pptr)

 struct node *aptr, *bptr;

 aptr = pptr → rchild;

 if (aptr → balance == -1) {

 pptr → balance = 0;

 aptr → balance = 0;

 pptr = RotateLeft(pptr);

}

else {

 bptr = aptr → lchild;

 switch (bptr → balance) {

 case -1:

 pptr → balance = 1;

 aptr → balance = 0;

 break;

 case 1:

 pptr → balance = 0;

 aptr → balance = -1;

```
        break;
    case 0:
        pptra->balance = 0;
        apra->balance = 0;
    }
}
bptr->balance = 0;
pptr->rchild = RotateRight(aptr);
pptr = RotateLeft(pptr);
}
return pptr;
```

```
struct node *del (struct node *pptr, int dkey)
{
    struct node *tmp, *succ;
    static int shorter;
    if (pptr == NULL) {
        printf("not present");
        shorter = FALSE;
        return pptr;
    }
    if (dkey < pptr->info) {
        pptr->lchild = del(pptr->lchild, dkey);
        if (shorter == TRUE) {
            pptr = del_left_check(pptr,
                &shorter);
        }
    }
    else if (dkey > pptr->info) {
        pptr->rchild = del(pptr->rchild, dkey);
        if (shorter == TRUE) {
            pptr = del_right_check(pptr,
                &shorter);
        }
    }
}
```

```
else {
    if (pptr->lchild != NULL && pptr->
        rchild != NULL)
    {
        succ = pptr->rchild;
        while (succ->lchild) {
            succ = succ->lchild;
        }
        pptr->info = succ->info;
        pptr->rchild = del(pptr->
                             rchild, succ->info);
        if (shorter == TRUE)
            pptr = del_right_check
                (pptr, &shorter);
    }
    else {
        tmp = pptr;
        if (pptr->lchild != NULL) {
            pptr = pptr->lchild;
        }
        else if (pptr->rchild != NULL) {
            pptr = pptr->rchild;
        }
        else {
            pptr = NULL;
        }
        free(tmp);
        shorter = TRUE;
    }
}
return pptr;
```

```
struct node * del_left_check ( struct  
node * pptr, int * pshorter  
-ter )
```

```
{ switch ( pptr -> balance )
```

```
{ case 0 :
```

```
    pptr -> balance = -1;  
    * pshorter = FALSE;  
    break;
```

```
case 1 :
```

```
    pptr -> balance = 0;  
    break;
```

```
case -1 :
```

```
    pptr = del_RightBalance ( pptr,  
                               pshorter );
```

```
}
```

```
return pptr;
```

```
}
```

```
struct node * del_right_check ( struct  
node * pptr, int * pshorter )
```

```
{
```

```
switch ( pptr -> balance )
```

```
{
```

```
case 0 :
```

```
    pptr -> balance = 1;  
    * pshorter = FALSE;  
    break;
```

```
case -1 :
```

```
    pptr -> balance = 0;  
    break;
```

```
case 1 :
```

```
    pptr = del_LeftBalance ( pptr,  
                             pshorter );
```

```
}
```

```
    fun(3) return pptr; // above function  
    case 3: st(3); sh(0);  
(3) struct node *del_leftBalance (struct  
    {  
        node *aptr, *bptr;  
        int *pshorter)
```

```
        aptr = pptr ->lchild;  
        if (aptr -> balance == 0) {  
            pptr -> balance = 1;  
            aptr -> balance = -1;  
            *pshorter = FALSE;  
            pptr = RotateRight(pptr);
```

```
        else if (aptr -> balance == 1) {  
            pptr -> balance = 0;  
            aptr -> balance = 0;  
            pptr = RotateRight(pptr);
```

}

```
else {
```

```
    bptr = aptr ->rchild;  
    switch (bptr -> balance) {  
        case 0:
```

```
            pptr -> balance = 0;  
            aptr -> balance = 0;  
            break;
```

```
        case 1:
```

```
            pptr -> balance = -1;  
            aptr -> balance = 0;  
            break;
```

```
        case -1:
```

```
            pptr -> balance = 0;  
            aptr -> balance = 1;
```

3

bptr → balance == 0;
pptr → lchild; RotateLeft(aptr);
pptr = RotateRight(pptr);

}

return pptr;

}

struct node *del_RightBalance (struct node
*pptr, int *pshorter)

{

struct node *aptr, *bptr;

aptr = pptr → rchild;

if (aptr → balance == 0) {

pptr → balance = -1;

aptr → balance = 1;

bno GUI *pshorter = FALSE; bno nod short o

pptr = RotateLeft(pptr);

bno 301 short o, 33rd bno 921 pow m o nt

else if (aptr → balance == -1) {

pptr → balance = 0;

aptr → balance = 0;

pptr = RotateLeft(pptr);

bno 301 short o, 33rd bno 921 pow m o nt

else {

bptr = aptr → lchild;

switch (bptr → balance) {

case 0:

pptr → balance = 0;

aptr → balance = 0;

break;

case 1:

pptr → balance = 0;

aptr → balance = -1;

break;

case - t: ~~node <= 8/3~~

$\text{pptr} \rightarrow \text{balance} = 1;$

$\text{aptr} \rightarrow \text{balance} = 0;$

}

$\text{bptr} \rightarrow \text{balance} = 0;$

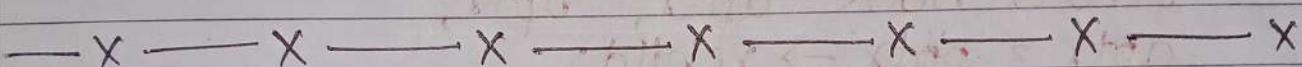
$\text{pptr} \rightarrow \text{rchild} = \text{Rotate Right}(\text{aptr});$

$\text{pptr} = \text{Rotate Left}(\text{pptr});$

shown above

return pptr;

}



Multiway Search Tree (M-way Tree)

Till now, in all the trees that we have seen, a node can hold only one key value and can have atmost two children.

In a m-way search tree, a node can hold more than one value and can have more than two children.

Till now, we have studied about internal searching only, i.e., we have assumed that data to be searched is present in primary storage area. In this, we see external searching in which data is to be retrieved from secondary storage like disk files.

We know that the access time in the case of secondary storage is much more than that of primary storage. So, while doing external searching we should try to reduce the number of accesses. When data is accessed from a disk, a whole block is read instead of a single word. For this purpose, m-way tree is used.

* B-Tree :- In external searching, our aim is to minimize the file access, and this can be done by reducing the height of the tree.

The height of m-way tree is less because of its large branching factor but its height can still be reduced if it is balanced.

So, a new tree structure was developed, i.e., height balancing m-way search tree, also called b-tree.

A B-Tree of order m can be defined as an m-way search tree which is either empty or satisfies the following properties :-

- i) All leaf nodes are at the same level.
- ii) All non-leaf nodes (except root node) should have atleast $(m/2)$ children.
- iii) All nodes (except root node) should have atleast $(m-2)-1$ keys.
- iv) If the root node is a leaf node (only node in the tree), then it will have no children and will have atleast one key.
If the root node is a non-leaf node, then it will have atleast 2 children and atleast one key.
- v) A non leaf node with $n-1$ key values should have n non NULL children.

* Insertion in B-Tree :- (order 5)

10, 40, 30, 35, 20, 15, 50, 28, 25, 5, 60, 19, 12, 38, 27, 0, 90, 45, 48

Insert 10,

10

Insert 40,

10 40

Insert 30,

10 30 40

? 30 will be inserted between 10 & 40 since all the keys in a node should be in ascending order.

Insert 35,

10 30 35 40

the max no. of keys for a node of B-tree of order 5 is 4

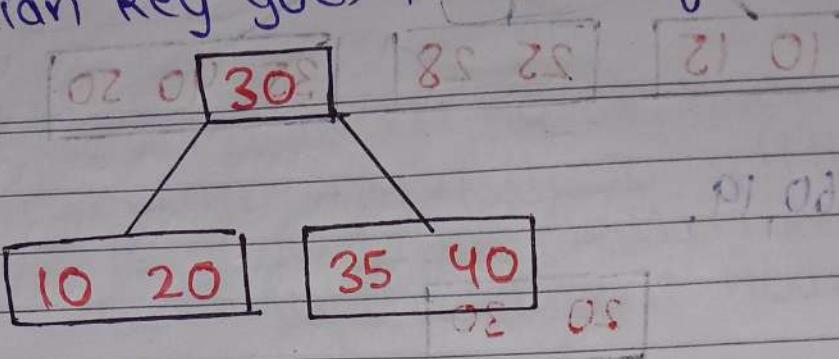
After insertion of 35, node become full.

Insert 20,

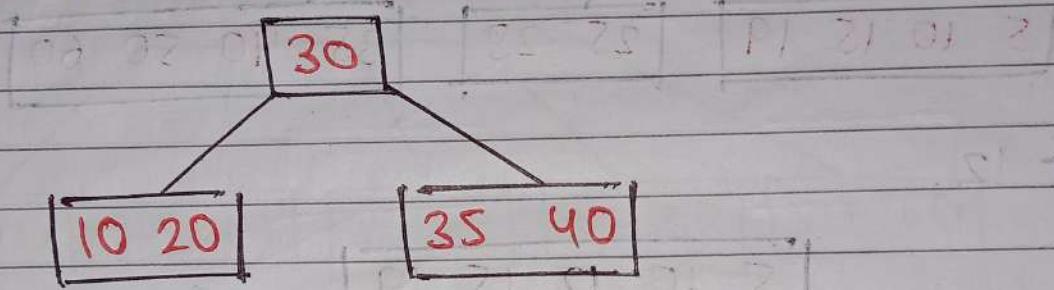
10 20 30 35 40

if we insert 20 here, the node become overfull so, splitting is done at the median key 30. After splitting, the median key goes to the parent node.

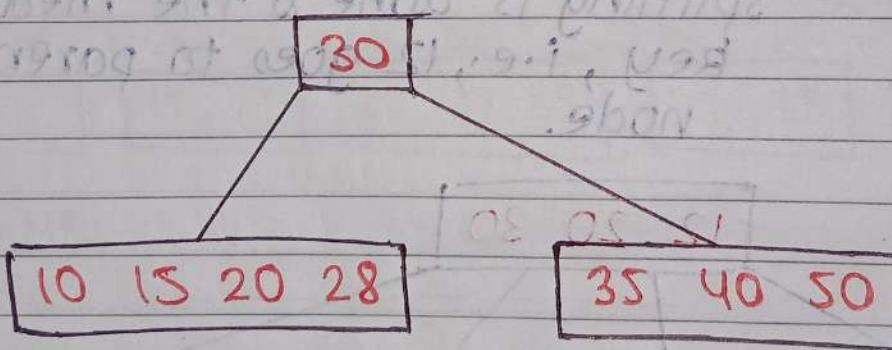
The key greater than the median key, goes in the right side & keys smaller than the median key goes in the left side.



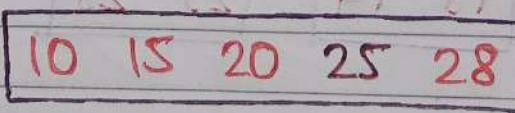
Insert 15, 50, 28,



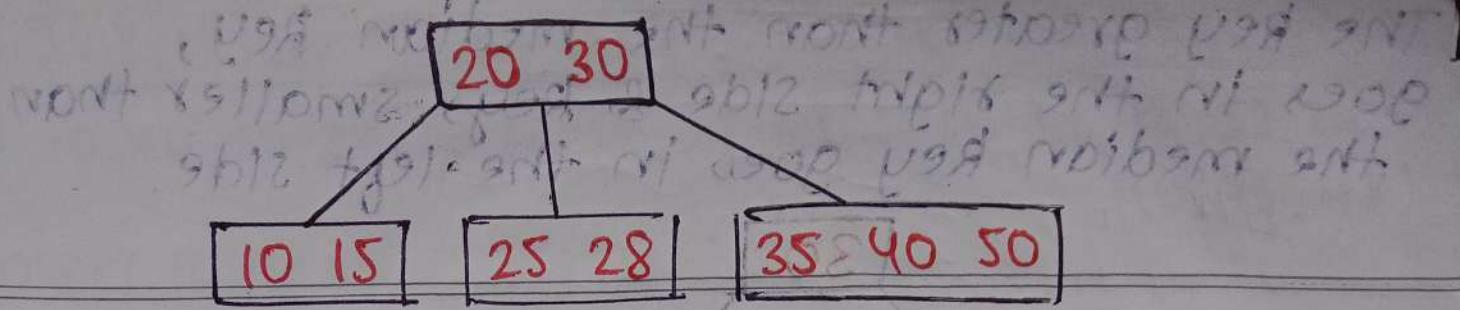
15 & 28 are less than 30, so they are inserted in the left node at appropriate place & 50 is greater than 30, so it is inserted in the right node.



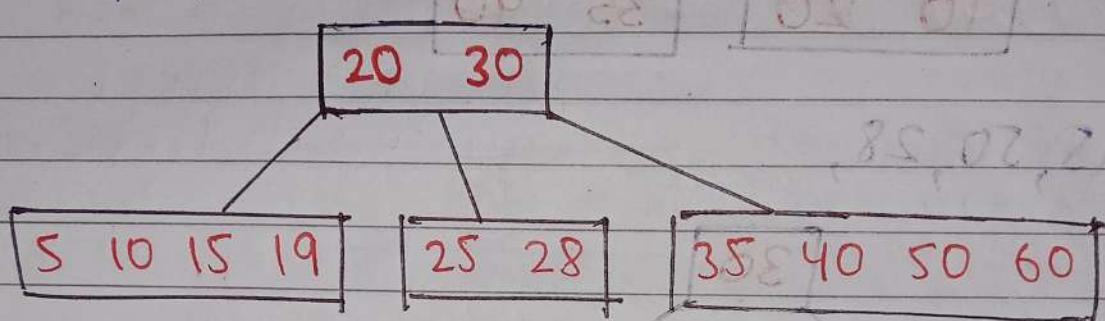
Insert 25,



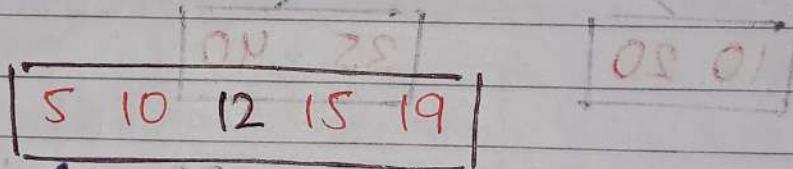
after inserting 25, the node became overfull. So, splitting is done at the median key, i.e., 20, and 20 goes to the parent node.



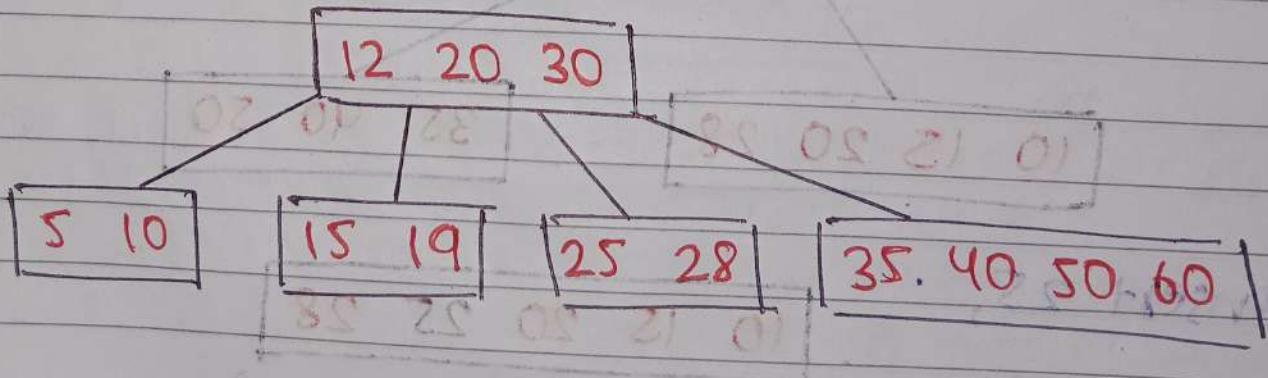
Insert 5, 60, 19,



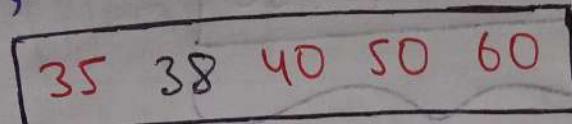
Insert 12,



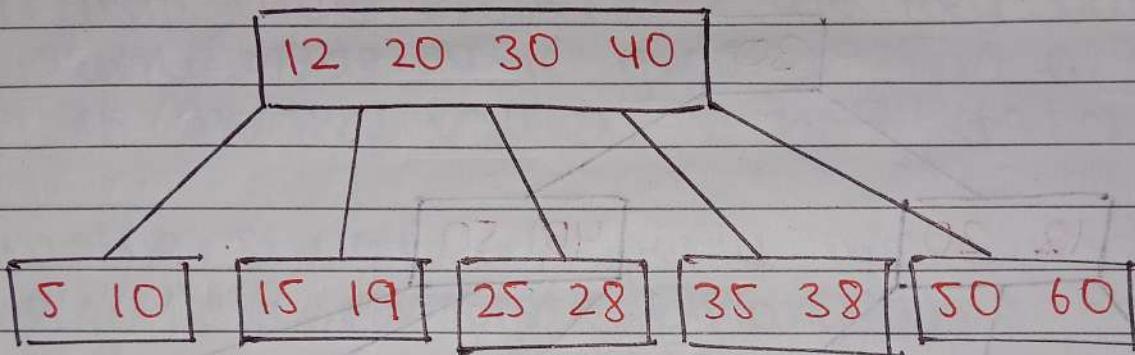
after inserting 12, the node became overfull. So, splitting is done & the median key, i.e., 12 goes to parent node.



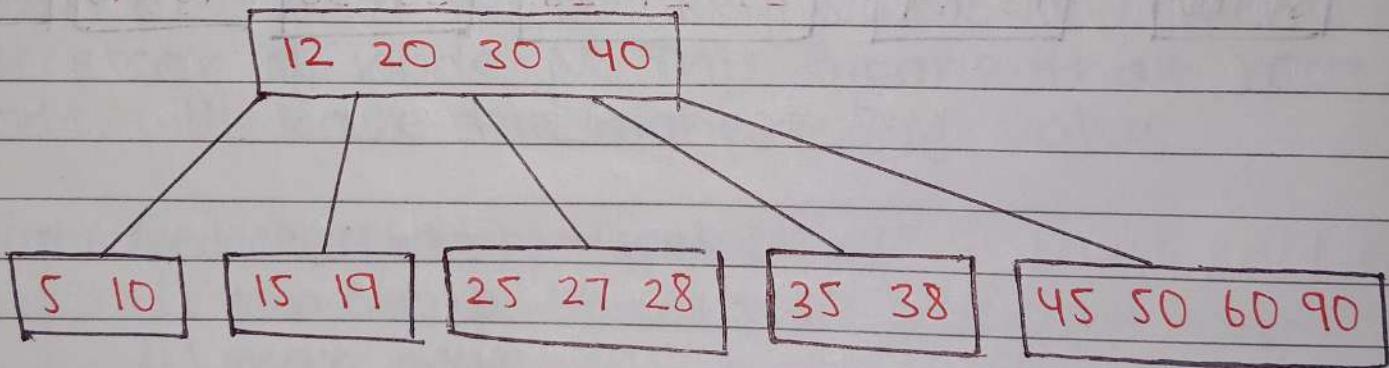
Insert 38,



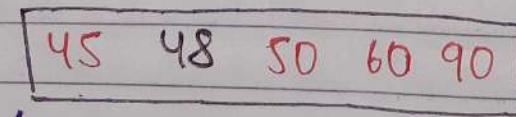
after inserting 38, node became overfull. so, splitting is done & the median key, 40 goes to the parent node.



Insert 27, 90, 45,



Insert 48,



after inserting 48, node became overfull. so, splitting is done & the median key, i.e., 50 goes to the parent.

12 20 30 40 50

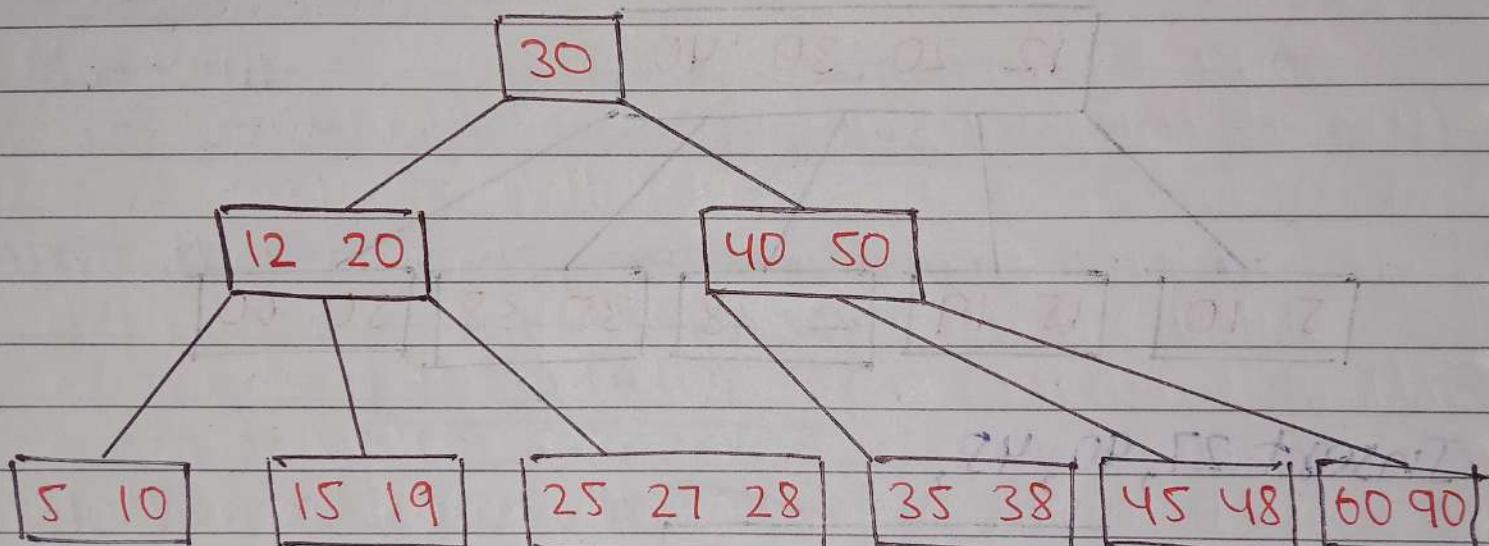
8E front

0 12 20 30 40 50

after inserting 50 in the

parent node, parent node
also become overfull. So,

again splitting is done, and
the median key 30 become the
parent node.



3H front

DP 01 02 8H 2H

similar above 3H partition go to
left & right in splitting 02, 11, 16, 20
etc at 000, 02, etc used unbalance