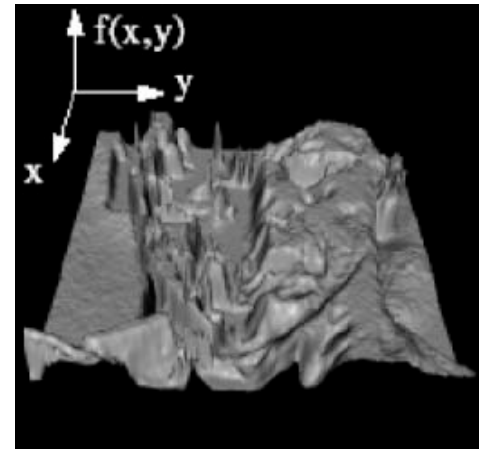


Digital Images

- What is an image?
- Digital images and pixels
- Image size and resolution
- Color components
- Number of gray levels
- Brightness discrimination experiment
- Weber's Law

What is an Image?

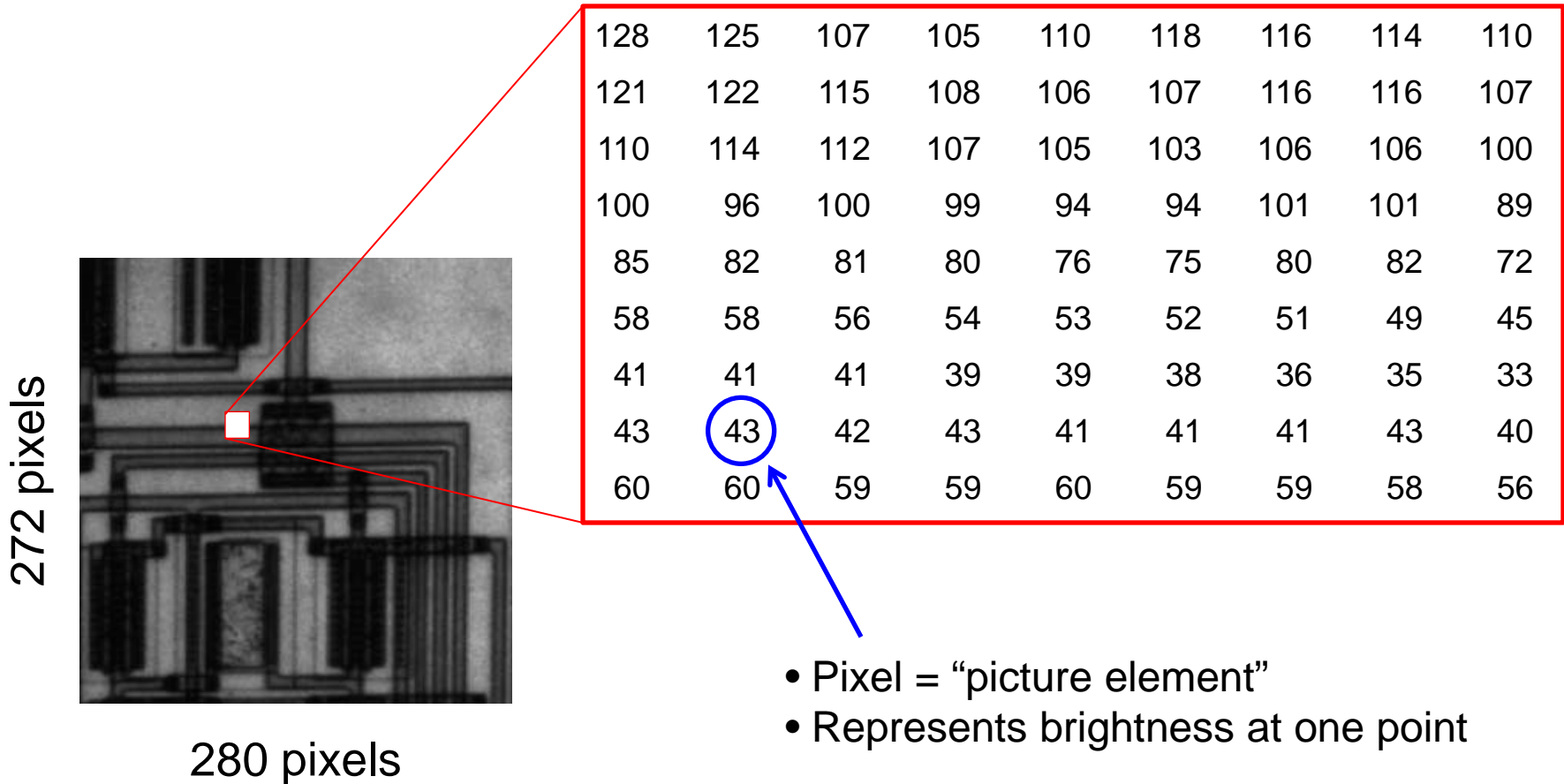
- Ideally, a 2-dimensional **light intensity function** $f(x,y)$, where x and y are spatial coordinates, and f at (x,y) is related to the brightness or color of the image at that point.
- In practice, most images are defined over a **rectangle**.
- **Continuous in amplitude** (“continuous-tone”)
- **Continuous in space**: no pixels!



Digital Images and Pixels

- A **digital image** is the representation of a continuous image $f(x,y)$ by a **2-d array of discrete samples**. The **amplitude of each sample is quantized** to be represented by a finite number of bits.
- Each element of the 2-d array of samples is called a **pixel** or **pel** (from “picture element”)
- Pixels are point samples, without extent.
- A **pixel is not**:
 - Round, square, or rectangular
 - An element of an image sensor
 - An element of a display

A Digital Image is Represented by Numbers

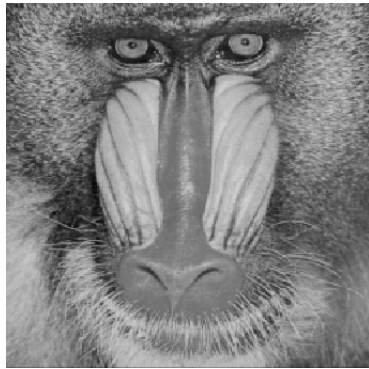


A Digital Image Represented by a Matrix

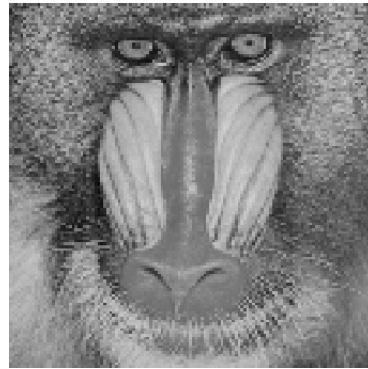
$$f = \begin{matrix} & \xrightarrow{\quad} & x \\ \begin{bmatrix} f(0,0) & f(1,0) & \cdots & f(W-1,0) \\ f(0,1) & f(1,1) & \cdots & f(W-1,1) \\ \vdots & \vdots & \ddots & \vdots \\ f(0,H-1) & f(1,H-1) & \cdots & f(W-1,H-1) \end{bmatrix} & \downarrow & y \end{matrix}$$

- The pixel values $f(x,y)$ are sorted into the matrix in “natural” order, with x corresponding to the column and y to the row index. Matlab uses this convention. This results in $f(x,y)=f_{yx}$, where f_{yx} denotes an individual element in common matrix notation.
- For a color image, f might be one of the components.

Image Size and Resolution



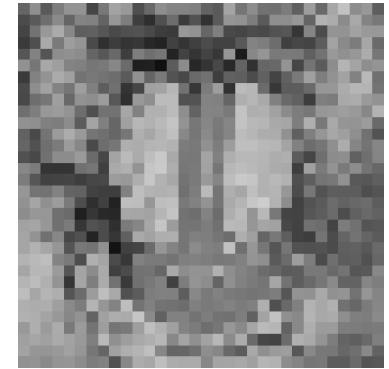
256x256



$n=2$



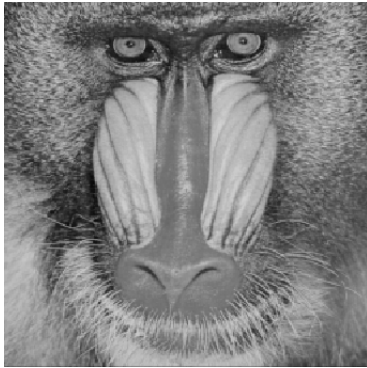
$n=4$



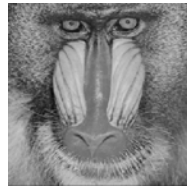
$n=8$

- These images were produced by simply picking every n -th sample horizontally and vertically and replicating that value $n \times n$ times.
- We can do better
 - Prefiltering before subsampling to avoid aliasing
 - Smooth interpolation

Images of Different Size



256x256



128x128

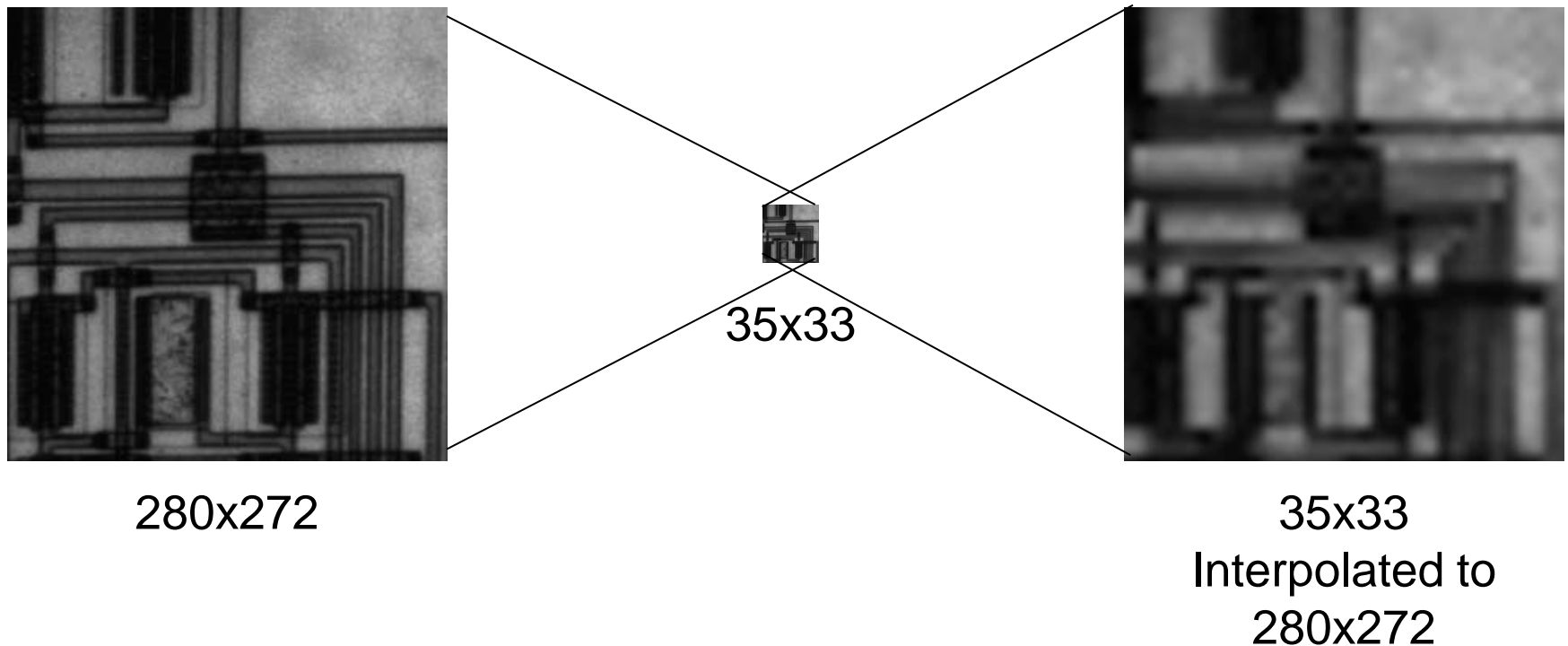


64x64



32x32

Fewer Pixels Mean Lower Spatial Resolution



Color Components

- Color images typically represented by three values per sample location, for **red**, **green** and **blue** primary components

$$x_R(x, y), \quad x_G(x, y), \quad x_B(x, y)$$

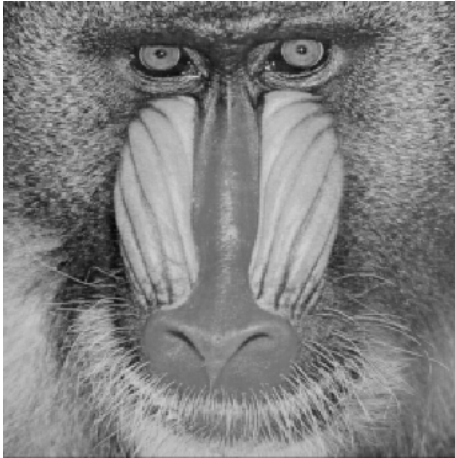
- General multi-component image

$$x_c(x, y), \quad c = 1, 2, \dots, C$$

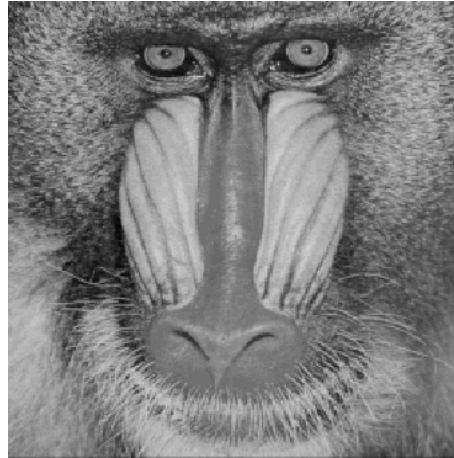
- Examples:
 - Color printing: cyan, magenta, yellow, black dyes, sometimes more
 - Hyperspectral satellite imaging: 100s of channels

Different Number of Gray Levels

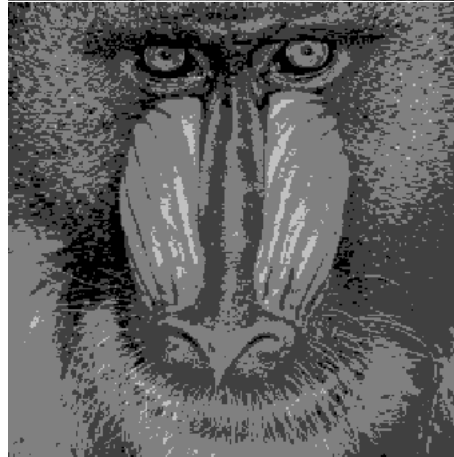
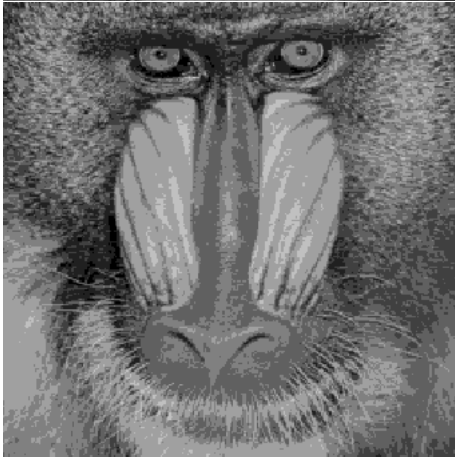
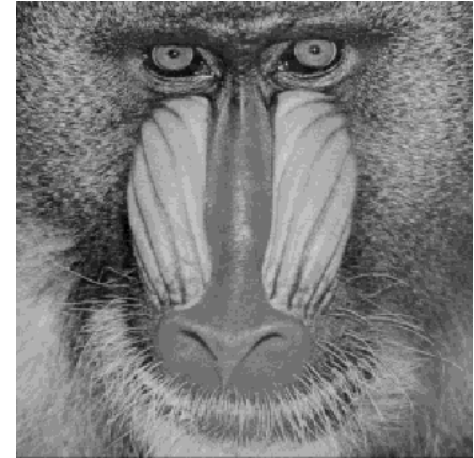
256



32



16



8

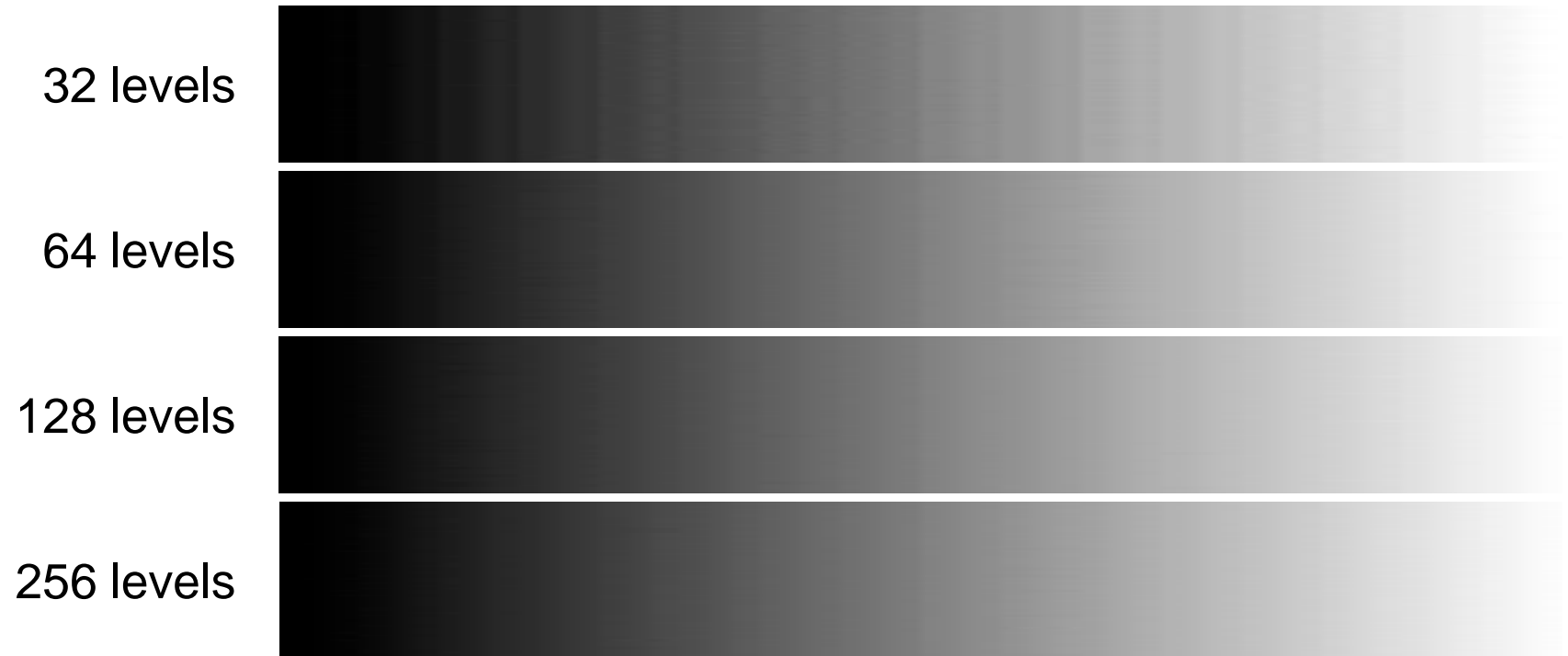
“Contouring”

4

2

How Many Gray Levels are Required?

- Contouring is most visible for a ramp



- Digital images typically are quantized to 256 gray levels.

Storage Requirements for Digital Images

- Image $W \times H$ pixels, 2^B gray levels, c color components

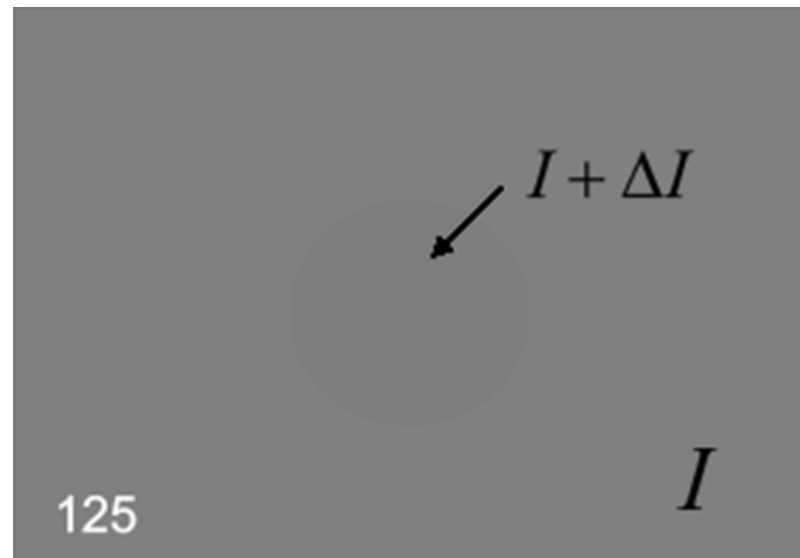
$$\text{Size} = W \times H \times B \times c$$

- Example: $W = H = 512$, $B=8$, $c=1$ (i.e., monochrome)
Size = 2,097,152 bits (or 256 kByte)
- Example: $W \times H = 1280 \times 1024$, $B=8$, $c=3$ (24 bit RGB image)
Size = 31,457,280 bits (or 3.75 MByte)

- Much less with (lossy) compression!

Brightness Discrimination Experiment

- Can you see the circle?



Note: I is luminance, measured in cd/m^2

- Visibility threshold

$$\frac{\Delta I}{I} \approx \text{const.} \approx 1 \dots 2\%$$

“Weber fraction”
“Weber’s Law”



Contrast with 8 Bits According to Weber's Law

- Assume that the luminance difference between two successive representative levels is just at visibility threshold

$$\frac{I_{max}}{I_{min}} = (1 + const.)^{255}$$

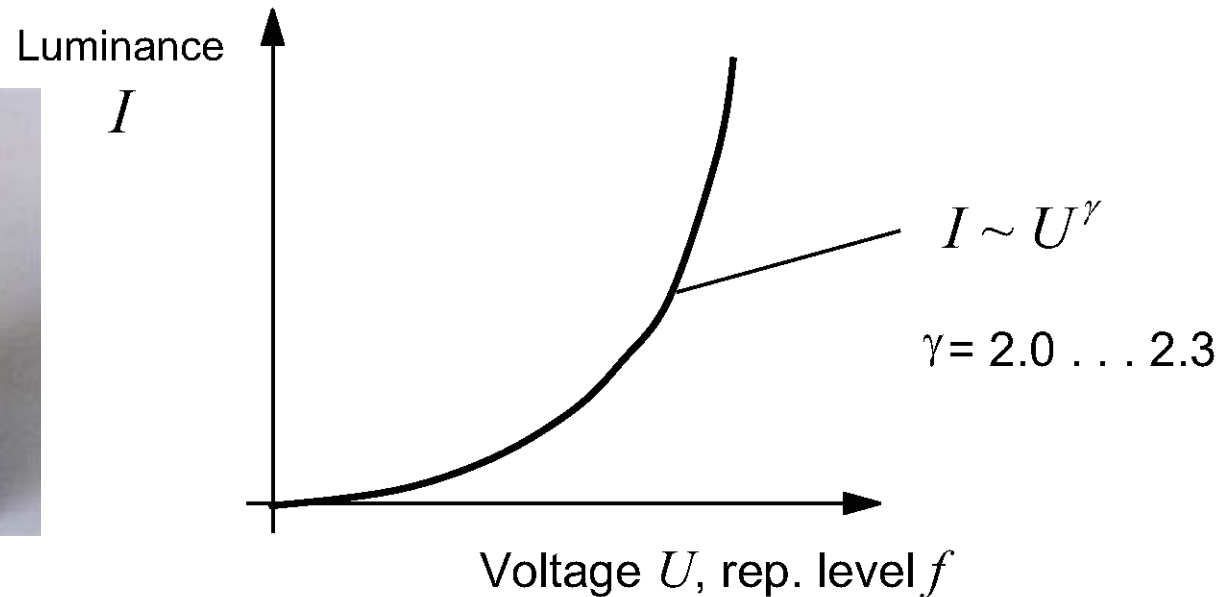
- For

$$const. = 0.01 \dots 0.02 \qquad \frac{I_{max}}{I_{min}} = 13 \dots 156$$

- Typical display contrast
 - Cathode ray tube 100:1
 - Print on paper 10:1
- Suggests uniform quantization in the $\log(I)$ domain

Gamma Characteristic

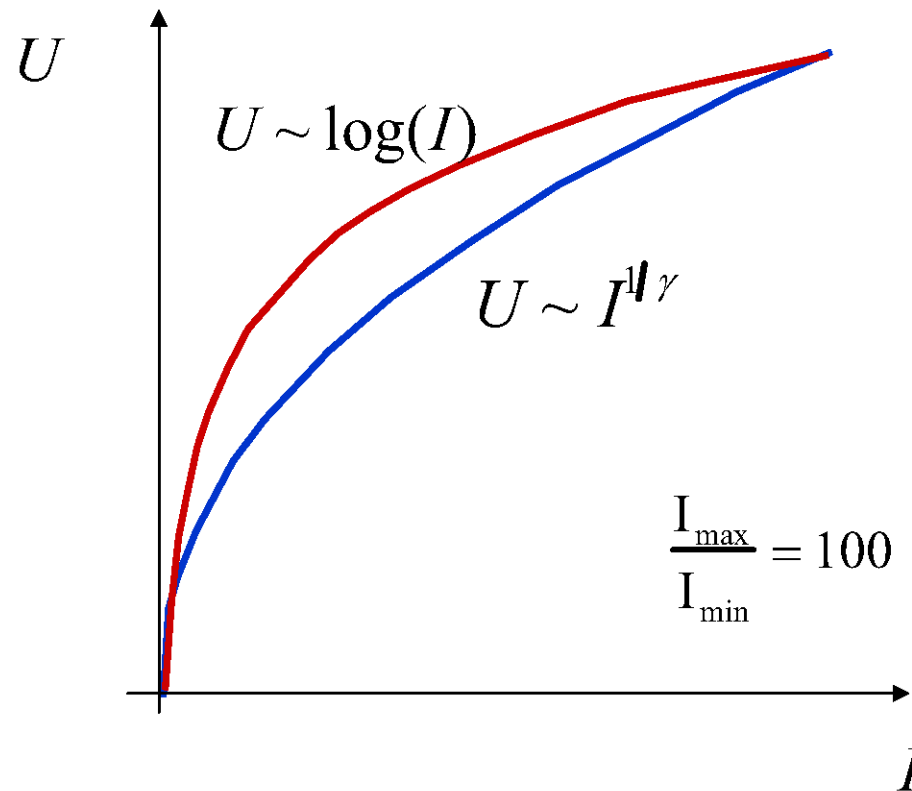
- Cathode ray tubes (CRT) are nonlinear



- Cameras contain γ -predistortion circuit

$$U \sim I^{\frac{1}{\gamma}}$$

Log vs. γ -predistortion



- Similar enough for most practical applications