CHAPTER 3 DATA STRUCTURES: HASHING

3.2 Hashing

• Basic Principle:

- Derive a number from a given element, and use that number to store & access the given element.
- Here, the given element is referred to as Key, and the derived number is referred to as Index.

• Definition:

 "Hashing is a search technique which directly finds out the location of a given data element in a constant search time."

3.2.1 Hash Function

Definition:

 "Hashing uses some function to find out the location of a given data element using that element. Such functions are referred to as Hash Functions."

Various Hash Functions:

Some of the known Hash Functions are given below:

1. Division Method:

- Divide key by size, and use the remainder as an Index.
- Index = Key % Size where, Key = given data element,
 Size = total capacity of storage,
 Index = location of given data element.
- Example: Suppose we have to store integer value '15' in an array of size '10'. Then, we can use –

Index =
$$15 \% 10 = 5$$

2. Mid-square Method:

- Take the square of key, and use the middle digits of square value as an Index.
- Example: Suppose, key = $15 \rightarrow \text{key}^2 = 15^2 = 225 \rightarrow 2$

3. Folding Method:

- Consider that the key is in binary form.
- Take EX-OR operation among lower & upper bits.
- Example: Suppose, key = $39 \rightarrow 100111 \rightarrow 100 \land 111 \rightarrow 011 \rightarrow 3$

4. Multiplicative Method:

- Multiply key with some constant value which is between 0 and 1
- Extract fractional part
- Multiply it by size
- Use integer value of this multiplication as an index
- index = floor (Size * (C * Key % 1))

Where c is a constant value between 0 and 1

- Example: Consider Key = 15, Size = 10, C = 0.75

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Index = floor (Size * ( C * Key % 1 ) )
= floor (10 * (0.75 * 15 % 1 ) )
= floor (10 * (11.25 % 1 ) )
= floor (10 * (0.25) )
= floor ( 2.5 )
= 2
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3.2.2 Hash Collision

- Definition:
 - "A situation in which -
 - Two different 'key' values produce the same index, and
 - Tries to occupy the same location."
- Collision Resolution Techniques:
 - A. Open Addressing
 - 1. Linear Probing:
 - Store colliding element into the next available space.
 - index = (key + n) % size

Where n is no. of times collision occurs.

Example: Collision between 15 and 25

Index = (25 + 3) % 10 = 8 and so on until empty location is found

- Disadvantage: Tends to clustering.

2. Quadratic Probing

- Avoids the problem of Linear Probing of Clustering.
- index = $(key + n^2)$ % size

Where n is no. of times collision occurs.

Example: Collision between 15 and 25

Index = 15 % 10 = 5
Index = 25 % 10 = 5 # Collision at index 5
Index =
$$(25 + 1^2)$$
 % 10 = 6
Index = $(25 + 2^2)$ % 10 = 9
Index = $(25 + 3^2)$ % 10 = 4 and so on until empty location is found

3. Re-hashing / Double Hashing

- Use colliding index as key, and Generate a new index.
- Example: Collision between 15 and 25

Index1 = 15 % 10 = 5

Index1 = 25 % 10 = 5

Offset = Prime – (Key2 % Prime) # Key2 = Colliding Index =
$$7 - (5\%7) = 2$$
 # 7 is prime number < Size

Index2 = (Index1 + (n * Offset)) % Size # Collision number
$$\rightarrow (5 + (1 * 2)) \% 10 = 7$$

$$\rightarrow (5 + (2 * 2)) \% 10 = 9 \text{ and so on until empty location is found}$$

4. Random Probing

- Select any other index randomly until the free location is found.
- Example: Collision between 15 and 25

B. Chaining

- Use an array of Singly Linked List.
- Use an index to point to a particular SLL from an array.
- Then, **search** in that particular SLL.

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