

Basic Concepts & Finite Automata

Basic Definitions

Alphabet	Non empty set Σ of objects called symbols
String	A finite set of sequence from the alphabet
Σ^*	If Σ is an alphabet then we use Σ^* to denote the set of strings obtained by concatenating zero or more symbols from Σ
Language	Language is collection of appropriate strings. It is generally subset of Σ^*
Sentence	A string in a language L will be called as a sentence of L

Operations on Languages

Union	$L_1 \cup L_2$	
Intersection	$L_1 \cap L_2$	
Difference	$L_1 - L_2$	
Concatenation	$L_1 . L_2$	$L_1 . L_2 = \{x . y \mid x \in L_1 \text{ and } y \in L_2\}$ Special case: L^n , L concatenated with itself n times
Complement	$L(\text{bar}) = \Sigma^* - L$	
Reverse	L^R : It is the set of all string in reverse format	
Star Closure	L^* : $L^0 \cup L^1 \cup L^2 \cup L^3 \cup \dots$	
Positive Closure	L^+ : $L^1 \cup L^2 \cup L^3 \cup \dots$	
Examples	$\Sigma = \{a, b\}$	
	L_1	$\{a . b^n \mid n \geq 0\}$
		$\{a, ab, ab^2, ab^3, \dots\}$
	L_2	$\{a^n b^n \mid n \geq 0\}$
		$\{ab, a^2b^2, a^3b^3, \dots\}$
	L_3	$\{a^m b^n \mid n \geq 0\}$
		$\{b, ab, a^2b, a^3b, a^2b^2, \dots\}$
	Operations	$L_1 \cup L_2$ $\{a, ab, a b^2, a^2b^2, \dots\}$
		$L_1 \cap L_2$ $\{ab\}$
		$L_1 - L_2$ $\{a, ab^2, ab^3, \dots\}$
	$L_1 . L_2$	$\{aab, aaab, abab, abaabb, \dots\}$
	L_1^R	$\{a, ba, b^2a, b^3a, \dots\}$
	L_2^R	$\{ba, b^2a^2, b^3a^3, \dots\}$

Finite Automata

They are used to represent Finite State Machines	Representation of FSM	Input Tape	Linear tape having number of symbols. Each cell has one symbol
		Tape Reader	It reads symbols from left to right one at a time
		Finite Control	It decides the next state on receiving a particular input
What is Finite Automata?	They are models used for computers that have extremely limited memory	Q is a finite set of states	
		Σ is the input alphabet	
		$\delta: Q \times \Sigma \rightarrow Q$ is a Transition Function or Mapping Function	
		q_0 is the initial state, $q_0 \in Q$	
		F is a set of finite states	
		A finite automata is a collection of five tuples $(Q, \Sigma, \delta, q_0, F)$	
Why do we use Finite Automata?	We use it to model the behavior as present in various electromechanical devices that use a limited amount of memory		
How to use Finite Automata?	State Diagram	Refer to FA1.png	A machine can accept multiple strings but understands only one language
	Transition Table		
	If A is a set of all strings that a machine accepts, we say A is the language of machine M and write $L(M) = A$		

Deterministic Finite Automata (DFA)

Each transition in this automata is uniquely determined on current state and current input
The Finite Automata is called Deterministic Finite Automata (DFA) if there is only one path for specific input from the current state to the next state.
Examples

Applications and Limitations of FA

Text editor for RE	Applications
Lexical Analysis	
Well formed parenthesis	Limitations
Palindrome check	

Finite State Machine (FSM) with Output

DFA and NFA are machines that specify YES or NO by indicating Final and Non-Final state respectively			
Next state is defined by Current State and Current Input Symbol		Moore Machine	
If the length of the input string is n, then length of the output string is n + 1			
Formal Definition			
Examples			
$M = (Q, \Sigma, \Delta, \delta, \lambda, q_0)$ Where Q is a finite set of internal states Σ is a finite set of symbols called the input alphabet Δ is Output Alphabet $\delta: Q \times \Sigma \rightarrow Q$ is a Transition Function (State Function) q_0 is an initial state $q_0 \in Q$ $\lambda: Q \rightarrow \Delta$ is a output Function			
The output symbol is dependent on the Present State and Present Input Symbol		Mealy Machine	
If the length of the input string is n, then length of the output string is n			
Formal Definition			
Examples			
$M = (Q, \Sigma, \Delta, \delta, \lambda, q_0)$ Where Q is a finite set of internal states Σ is a finite set of symbols called the input alphabet Δ is Output Alphabet $\delta: Q \times \Sigma \rightarrow Q$ is a Transition Function (State Function) q_0 is an initial state $q_0 \in Q$ $\lambda: Q \times \Sigma \rightarrow \Delta$ is a output Function			
Associated with States		Moore	Output
Associated with Transitions		Mealy	
n + 1		Moore	Length of Output
n		Mealy	
$\lambda: Q \rightarrow \Delta$		Moore	Output Function
$\lambda: Q \times \Sigma \rightarrow \Delta$		Mealy	
How to differentiate			

Minimization of DFA

Distinguishable States	If for some input string w, $\delta(p, w)$ gives an accepting state and $\delta(q, w)$ gives a non accepting state or vice versa
	Then p and q are distinguishable or non - equivalent state
Indistinguishable States	If for some input string w, $\delta(p, w)$ and $\delta(q, w)$ both produces either accepting state or non accepting state
	Then p and q are indistinguishable or equivalent state
Process	Step 1: Draw a table for all pair of states (P, Q)
	Step 2: Mark all pairs where P belongs to set of Final States and Q does not belong to set of Final states
	Step 3: If there are any unmarked pairs (P, Q) such that $[\delta(P, x), \delta(Q, x)]$ is marked then mark $[P, Q]$ where x is an input symbol
	Step 4: Repeat step 3 until No more marking can be made
	Step 5: Combine all the unmarked pairs and make them single state in minimized DFA

Conversion from NFA to DFA

Step 1	If Epsilon closure is present first eliminate that
	Hence q_0 will be part of Q'
	Find all the transitions from the start state
Step 2	I. $\delta'(\{q_0, q_1, q_2, \dots, q_i\}, a) = \delta(q_0, a) \cup \delta(q_1, a) \cup \delta(q_2, a) \dots \delta(q_i, a) = \{q_1, q_2, \dots, q_k\}$ (May be some state)
	II. Add the state $\{q_1, q_2, \dots, q_k\}$ to DFA if it is not already in Q'
	III. Find the transitions for every input symbol from Σ for new state $\{q_1, q_2, \dots, q_k\}$.
Step 3	IV. If no new state is generating then stop the process after finding all the transitions.
	If we get some new state $\{q_1, q_2, \dots, q_n\}$ which is not in Q' , then add it to Q'
	For the state $\{q_1, q_2, \dots, q_n\} \in Q'$ of DFA if any one state q_i is a final state of NFA then $\{q_1, q_2, \dots, q_n\}$ becomes final state
	States that cannot be reached from the initial state may be discarded

Nondeterministic (NFA)

Difference in Transition Function	Next state can not be determined uniquely for a given transition with current state and current input
	The Finite Automata is called Non - Deterministic Finite Automata (NFA) when there exists many paths for a specific input from current state to next state.
	Transition Function accepts two parameters one is current state and other is input symbol
Examples	It is described as $\delta: Q \times \Sigma \rightarrow 2^*Q$
	Here the power set of Q (2^*Q) has been taken because in case of NFA, from a state, transition can occur to any combination of Q states
	Please refer to first 3 examples to clear your concept in case you haven't already
Epsilon Transition	The ϵ - transition in NFA are given in order to move from one state to another without having any symbol from input set Σ
	Examples
Epsilon Closure	The epsilon closure (ϵ - closure) is set of all states which are reachable from p on transitions such that
	ϵ - closure (p) = p where $p \in Q$
Eliminating Epsilon Closure	If there exist ϵ - closure (p) = {q} and $\delta(q, \epsilon) = r$ then ϵ - closure (p) = {q, r}
	Step 1: Find ϵ - closure of all states for given NFA
	Step 2: Find δ' Transition function for NFA without ϵ
	Step 3: Construction of Transition Table (δ')
Example	$\delta'(q_0, 0) = \epsilon$ - closure ($\delta(\epsilon$ - closure (q_0), 0))
Hint: Will have more final states	
Step 4: Construction of Transition Diagram	