

Assignment-5

1) Introduction

In this lab we have used PWM for Brightness control from previous lab and implemented a type of Finite State Machine(FSM) for digit rotation from right to left in a circular way.

2) Implementation Design

Implementation for Brightness control is modified a little bit compare to previous lab implementation because in this case brightness of any 7 segment LED display is not fixed instead brightness corresponding to each digit has 4 level of brightness where 4 levels are decided by 2 bit value or basically 2 switches.

As there are 4 digit whose brightness are to be setup using 8 switches similarly to change input 4 digit we have to use all 16 switches for that. Now as 8 switches are common for brightness control of digits or for changing the 4 digits , to decide which operation users want can be decided by two Pushbuttons.

Pushbuttons switch :

It is an electrical switch actuated by a person's hand motion.

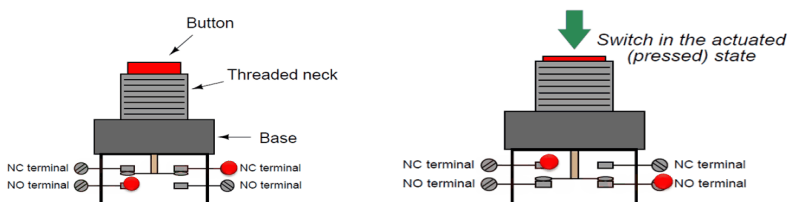


Fig 1 : Working of Push Button

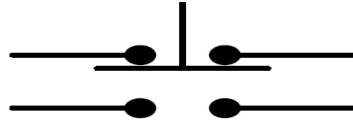


Fig 2: Symbol of Push button

Some important concept related to push button

Debounce :

Push button always got the mechanical property of bouncing state within microseconds.



Fig 3 : Figure describes the debouncing output result when pushbutton is pressed.

When we pull down the push button from high to low state. It bounce back to high and low a few times before it settles at proper output. In order to avoid in such a bouncing state, we need to create a debounce logic circuit.

Condition for debouncing used in our case : To ensure well working of Push button , we checked for 10 consecutive times during rising – edge of clock that push button signal value to be "1" for it to consider it a stable signal. If the given condition is not fulfilled then we will reset the counter value to be 0.

Let me now define the Finite State Machine (FSM) for digit rotation w.r. t boolean condition to be satisfied to be in a particular state.

We have define a integer variable "counter" initialise to "0" which is increment by 1 in every rising – edge of clock.

Let S_1, S_2, S_3 and S_4 be state of digit on 7 segment LED display from left to right respectively.

Boolean Condition	L_1	L_2	L_3	L_4
$0 \leq (\text{Counter mod } 400000000) < 100000000$	S_1	S_2	S_3	S_4
$100000000 \leq (\text{Counter mod } 400000000) < 200000000$	S_2	S_3	S_4	S_1
$200000000 \leq (\text{Counter mod } 400000000) < 300000000$	S_3	S_4	S_1	S_2
$300000000 \leq (\text{Counter mod } 400000000) < 400000000$	S_4	S_3	S_2	S_1

Table 1 : Rotation related table for FSM as per boolean condition

Note : a) L_1 denotes the leftmost 7 segment LED display , L_2 is on right of L_1 L_3 is on right of L_2 and L_4 denote the rightmost 7 segment LED display

b) Similar logic is followed for rotation of digit brightness.

3) *Simulation Waveform*

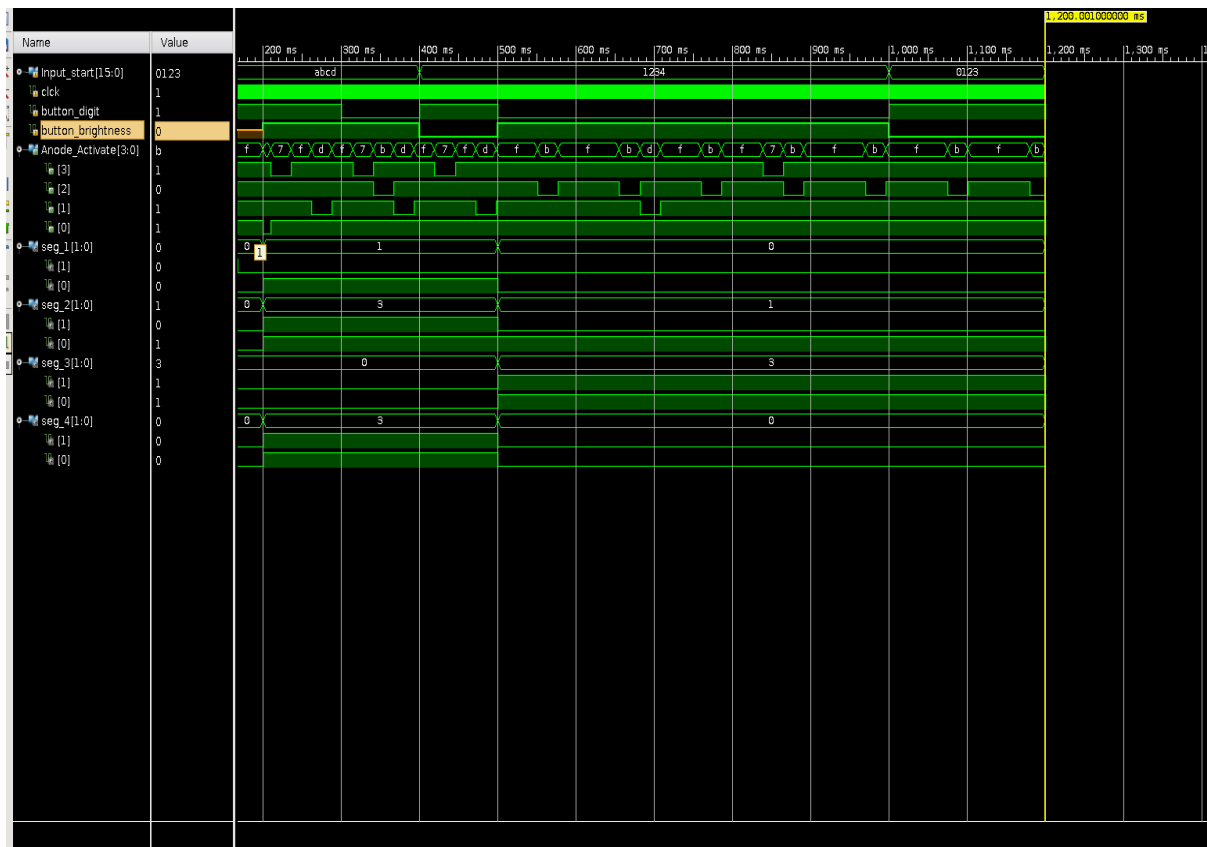


Fig 4: Waveform of 4 segment LED display with rotation and brightness

4) Digital Circuit for 4 – digit 7 Segment Display with rotation and brightness

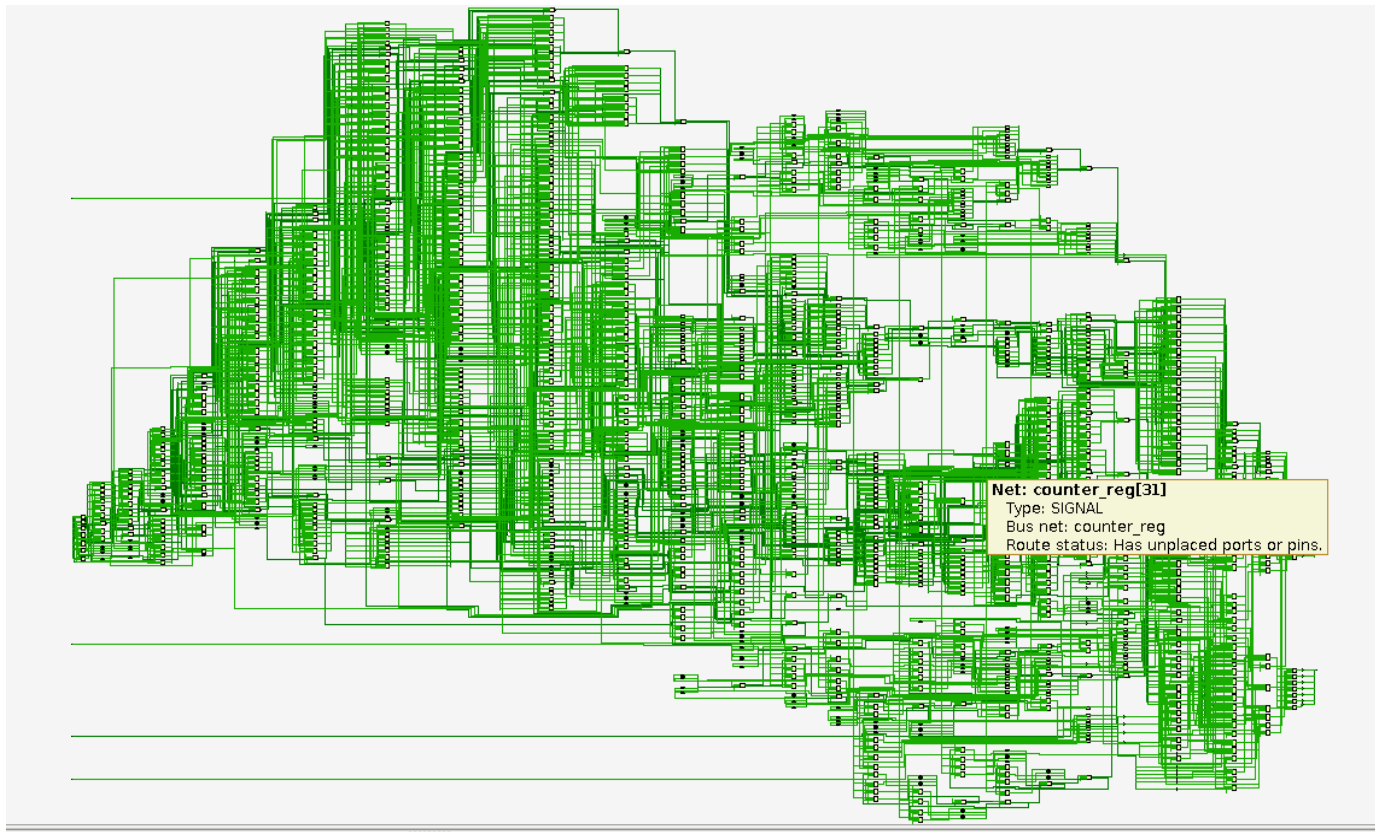


Fig 5 : Complex Digital circuit for LED brightness control and rotation of digit

5) Resource Utilisation

- a) LUT Memory =0
- b) LUT logic = 709
- c) DSP =0
- d) Flip Flops =150
- e) BRAM = 0

6) Some other relevant diagram for resource utilisation

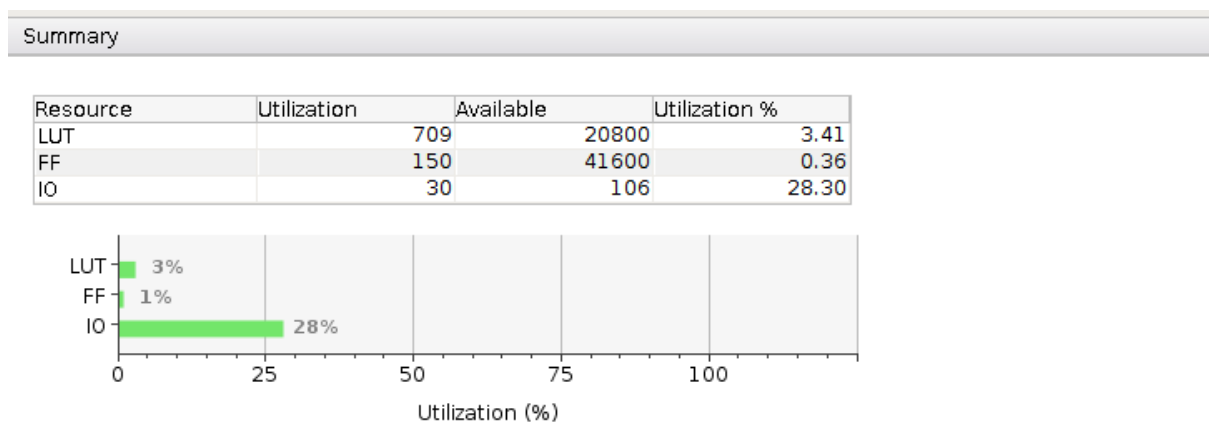


Fig 6 : Summary

Primitives		
Ref Name	Used	Functional Category
LUT6	234	LUT
LUT3	220	LUT
LUT1	198	LUT
FDRE	150	Flop & Latch
CARRY4	133	CarryLogic
LUT2	119	LUT
LUT5	83	LUT
LUT4	42	LUT
IBUF	19	IO
OBUF	11	IO
BUFG	1	Clock

Fig 7 : Primitives

Hierarchy					
	Name	Slice LUTs (20800)	Slice Registers (41600)	Bonded IOB (106)	BUFGCTRL (32)
	LED_scrolling_brightness	709	150	30	1

Fig 8 : Hierarchy

7) Some photographs of FPGA Board

