

Assignment -4

ESP32 Programming with IBM Cloud

Assignment Date	3 November 2022
Student Name	Ramgenesh P
Student Roll Number	717819F143
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud.

Solution:

```
#include <WiFi.h> //library for wifi #include
<PubSubClient.h> //library for MQTT

#define ECHO_GPIO 12
#define TRIGGER_GPIO 13
#define MAX_DISTANCE_CM 100 // Maximum of 5 meters
#include "Ultrasonic.h"

Ultrasonic ultrasonic(13, 12); int
distance;

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "2melo1" //IBM ORGANITION ID
#define DEVICE_TYPE "Kruthika" //Device type mentioned in ibm Watson IOT
Platform
#define DEVICE_ID "0405" //Device ID mentioned in ibm watson IOT
Platform #define TOKEN "12345678" //Token
String data3; float
h, t;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of event perform and
format in which data to be send char subscribetopic[] = "iot-2/cmd/command/fmt/String"; //
cmd REPRESENT command type AND
COMMAND IS TEST OF FORMAT STRING char authMethod[] =
"use-token-auth"; // authentication
method char token[] = TOKEN; char clientId[] = "d:" ORG ":"
DEVICE_TYPE ":" DEVICE_ID; //client id

//-----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by
passing parameter like server id,portand wificredential
```

```

void setup()// configuring the ESP32 {

    Serial.begin(115200);
    delay(10); Serial.println();
    wificonnect(); mqttconnect();
}

void    loop()// Recursive Function
{

    distance = ultrasonic.read(CM); if(distance
    < 100){
    Serial.print("Distance in CM: ");
    Serial.println(distance);
    PublishData(distance);
    delay(1000); if
    (!client.loop()) {
        mqttconnect();
    }

    }

    delay(1000);

}

/*.....retrieving to Cloud.....*/

void    PublishData(float temp) {
mqttconnect();//function call for connecting to ibm
/* creating the String in in form JSon to update the data to ibm cloud
*/
String payload = "{\"Alert Distance\":\""; payload
+= temp;
    payload += "}";

    Serial.print("Sending payload: ");
    Serial.println(payload);

    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will
        print publish ok in Serial monitor or else it will print publish    failed
    } else { Serial.println("Publish
        failed");
    }

}

void    mqttconnect() { if
(!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server); while
    (!!!client.connect(clientId, authMethod, token))

```

```

        { Serial.print(".");
          delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}
void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6); //passing the wifi credentials to establish the
    connection while (WiFi.status() != WL_CONNECTED) { delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
}
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic); for (int i = 0;
i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }
    Serial.println("data: "+ data3);
    if(data3=="lighton") {
    Serial .println(data3);
    } else
    {
    Serial .println(data3);
    }
    data3= "";
}

```

The screenshot displays the Wokwi IoT simulator interface. At the top, there are tabs for 'diagram.json', 'libraries.txt', 'Ultrasonic.h', 'Ultrasonic.cpp', and 'Library Manager'. The main workspace is divided into three sections:

- Code Editor (Left):** Contains the C++ code for the ultrasonic sensor project, including comments in Chinese and C++ code for pin definitions and logic.
- Hardware Diagram (Right):** Shows a visual representation of the circuit. It includes an ESP32 microcontroller board connected to an HC-SR04 ultrasonic sensor module. The sensor's VCC pin is connected to the ESP32's 5V pin, GND to GND, and the Trig pin to digital pin 5. The Echo pin is connected to digital pin 4.
- Terminal (Bottom):** Displays the serial output of the program. The output shows the sensor's range being measured as 28 cm, with the payload formatted as {"Alert Distance":28.00}.

The terminal output is as follows:

```

Publish ok
Distance in CM: 28
Sending payload: {"Alert Distance":28.00}
Publish ok
Distance in CM: 28
Sending payload: {"Alert Distance":28.00}
Publish ok
  
```