```
app.py
from flask import Flask, request, render template, redirect, url for
import cv2
import numpy as np
import os
app = Flask( name )
# Load the YOLO model
net = cv2.dnn.readNet("yolov3.weights", "yolov3.cfg")
# Define helmet-specific classes
classes = ["helmet","nohelmet"]
# Function to perform object detection for helmets
def detect_helmet(image_path):
  image = cv2.imread(image path)
  height, width, _ = image.shape
    blob = cv2.dnn.blobFromImage(image, 1/255.0, (416, 416), swapRB=True,
crop=False)
  net.setInput(blob)
  output layers names = net.getUnconnectedOutLayersNames()
  outputs = net.forward(output layers names)
  boxes = []
  confidences = []
  class_ids = []
```

for output in outputs:

for detection in output:

scores = detection[5:]

class id = np.argmax(scores)

```
confidence = scores[class id]
       if confidence > 0.5 and class id < len(classes):
         center_x = int(detection[0] * width)
         center y = int(detection[1] * height)
         w = int(detection[2] * width)
         h = int(detection[3] * height)
         x = int(center x - w / 2)
         y = int(center y - h / 2)
         boxes.append([x, y, w, h])
         confidences.append(float(confidence))
         class ids.append(class id)
      indexes = cv2.dnn.NMSBoxes(boxes, confidences, score threshold=0.5,
nms threshold=0.4)
  # Draw bounding boxes and add labels
  for i in indexes.flatten():
    x, y, w, h = boxes[i]
    label = str(classes[class ids[i]])
    confidence = confidences[i]
    color = (0, 255, 0) if label == "helmet" else (0, 0, 255)
    text = f"{label}: {confidence:.2f}"
    cv2.rectangle(image, (x, y), (x + w, y + h), color, 2)
     cv2.putText(image, text, (x, y - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.5,
color, 2)
  output_image_path = "static/detected_image.jpg"
  cv2.imwrite(output image path, image)
  return output image path
```

```
@app.route('/', methods=['GET', 'POST'])
def index():
  if request.method == 'POST':
    if 'file' not in request.files:
      return redirect(request.url)
    file = request.files['file']
    if file.filename == '':
      return redirect(request.url)
     file path = os.path.join("static", file.filename)
    file.save(file path)
    # Perform helmet detection
    output image = detect helmet(file path)
    return render template('index.html', output image=output image)
  return render template('index.html', output image=None)
if name == " main ":
  app.run(debug=True)
```

Desctiption For Code

1. Importing Necessary Libraries

The application imports libraries:

- Flask for web application functionality.
- cv2 (OpenCV) for image processing and object detection.
- numpy for numerical computations.
- os for file handling.

2. YOLO Model Initialization

```
net = cv2.dnn.readNet("yolov3.weights", "yolov3.cfg")
classes = ["helmet","nohelmet"]
```

- The YOLO model is loaded using pre-trained weights (yolov3.weights) and its configuration file (yolov3.cfg).
- The classes "helmet" and "nohelmet" are defined, indicating the model is trained to classify objects as either wearing a helmet or not.

3. Function for Helmet Detection

```
def detect helmet(image path):
```

This function performs the main task of helmet detection:

Load the Input Image:

```
image = cv2.imread(image_path)
height, width, = image.shape
```

The image is read and its dimensions are extracted.

Preprocessing for YOLO:

```
blob = cv2.dnn.blobFromImage(image, 1/255.0, (416, 416), swapRB=True, crop=False)
```

The image is converted into a blob to feed into YOLO:

- Normalized pixel values.
- o Resized to 416x416, as required by YOLO.

Forward Pass Through the Network:

```
net.setInput(blob)
output_layers_names = net.getUnconnectedOutLayersNames()
outputs = net.forward(output_layers_names)
```

The blob is passed to the network, and predictions are extracted from the output layers.

Extract Bounding Boxes, Class IDs, and Confidence Scores:

```
for detection in output:

scores = detection[5:]

class_id = np.argmax(scores)

confidence = scores[class_id]

if confidence > 0.5:
```

- o Scores for each class are evaluated.
- o Only detections with confidence > 50% are considered.

o The bounding box dimensions (x, y, w, h) are calculated and stored.

Non-Maximum Suppression (NMS):

```
indexes = cv2.dnn.NMSBoxes(boxes, confidences, score_threshold=0.5, nms_threshold=0.4)
```

Overlapping boxes are filtered to retain only the most relevant detections.

Annotating the Image:

```
for i in indexes.flatten():

x, y, w, h = boxes[i]

label = str(classes[class_ids[i]])

color = (0, 255, 0) if label == "helmet" else (0, 0, 255)

cv2.rectangle(image, (x, y), (x + w, y + h), color, 2)

cv2.putText(image, text, (x, y - 10), ...)
```

Detected objects are annotated with:

- o Green rectangles for helmets.
- o Red rectangles for "nohelmet".
- o Confidence scores as text.

Save Annotated Image:

```
output_image_path = "static/detected_image.jpg" cv2.imwrite(output_image_path, image)
```

The processed image is saved in the static folder.

4. Flask Application Routes

Home Route (/)

```
@app.route('/', methods=['GET', 'POST'])
```

- **GET Request:** Renders an HTML page (index.html) with an option to upload an image.
- POST Request:
 - 1. Validates if a file is uploaded.
 - 2. Saves the uploaded file in the static folder.
 - 3. Calls detect helmet to process the image.
 - 4. Returns the processed image to the frontend.

Serving the App

```
if __name__ == "__main__":
app.run(debug=True)
```

Runs the Flask app in debug mode for development.

5. Expected Workflow

- 1. User uploads an image via the web interface.
- 2. The server processes the image using YOLO to detect helmets.
- 3. The processed image with detections is displayed on the webpage.

Key Files Required

• YOLO Files:

- o yolov3.weights (model weights).
- o yolov3.cfg (model configuration).

• Frontend:

o index.html template to handle the upload form and display the results.