# Crate commonware\_runtime\_\_

### Settings

### Help

### Summary

### Source

Execute asynchronous tasks with a configurable scheduler.

This crate provides a collection of runtimes that can be used to execute asynchronous tasks in a variety of ways. For production use, the tokio module provides a runtime backed by Tokio. For testing and simulation, the deterministic module provides a runtime that allows for deterministic execution of tasks (given a fixed seed).

### **Status**

commonware-runtime is ALPHA software and is not yet recommended for production use. Developers should expect breaking changes and occasional instability.

### Modules

- deterministic
- A deterministic runtime that randomly selects tasks to run based on a seed
- mocks
- A mock implementation of a channel that implements the Sink and Stream traits.
- tokic
- A production-focused runtime based on Tokio with secure randomness and storage backed by the local filesystem.

### **Structs**

- Handle
- Handle to a spawned task.
- Signaler
- Coordinates a one-time signal across many tasks.

### **Enums**

Error

### **Traits**

- Blob
- Interface to read and write to a blob.
- Clock
- Interface that any task scheduler must implement to provide time-based operations.
- Listener
- Interface that any runtime must implement to handle incoming network connections.
- Network
- Interface that any runtime must implement to create network connections.
- Runner
- Interface that any task scheduler must implement to start running tasks.
- Sink
- Interface that any runtime must implement to send messages over a network connection.
- Spawner
- Interface that any task scheduler must implement to spawn sub-tasks in a given root task.
- Storage
- Interface to interact with storage.
- Stream
- Interface that any runtime must implement to receive messages over a network connection.

### **Functions**

- reschedule
- Yield control back to the runtime.

# Type Aliases

- Signal
- A one-time broadcast that can be awaited by many tasks. It is often used for coordinating shutdown across many tasks.

commonware runtime

## Module deterministic\_\_\_

### Settings

#### Help

### Summary

#### Source

A deterministic runtime that randomly selects tasks to run based on a seed

### **Panics**

If any task panics, the runtime will panic (and shutdown).

## Example

```
use commonware_runtime::{Spawner, Runner,
deterministic::Executor};

let (executor, runtime, auditor) = Executor::default();
executor.start(async move {
    println!("Parent started");
    let result = runtime.spawn("child", async move {
        println!("Child started");
        "hello"
    });
    println!("Child result: {:?}", result.await);
    println!("Parent exited");
});
println!("Auditor state: {}", auditor.state());
```

### **Structs**

- Auditor
- Track the state of the runtime for determinism auditing.
- Blob
- Implementation of crate::Blob for the deterministic runtime.
- Config
- Configuration for the deterministic runtime.
- Context

- Implementation of crate::Spawner, crate::Clock, crate::Network, and crate::Storage for the deterministic runtime.
- Executor
- Deterministic runtime that randomly selects tasks to run based on a seed.
- Listener
- Implementation of crate::Listener for the deterministic runtime.
- Runner
- Implementation of crate::Runner for the deterministic runtime.
- Sink
- Implementation of crate::Sink for the deterministic runtime.
- Stream
- Implementation of crate::Stream for the deterministic runtime.

## Type Aliases

- Partition
- Map of names to blob contents.

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## Module mocks...

### Settings

Help

Summary

Source

A mock implementation of a channel that implements the Sink and Stream traits.

### **Structs**

- Channel
- A mock channel struct that is used internally by Sink and Stream.
- Sink
- A mock sink that implements the Sink trait.
- Stream
- A mock stream that implements the Stream trait.

commonware runtime

## Module tokio

### Settings

### Help

### Summary

### Source

A production-focused runtime based on Tokio with secure randomness and storage backed by the local filesystem.

### **Panics**

By default, the runtime will catch any panic and log the error. It is possible to override this behavior in the configuration.

### Example

```
use commonware_runtime::{Spawner, Runner, tokio::Executor};

let (executor, runtime) = Executor::default();
executor.start(async move {
    println!("Parent started");
    let result = runtime.spawn("child", async move {
        println!("Child started");
        "hello"
    });
    println!("Child result: {:?}", result.await);
    println!("Parent exited");
});
```

### **Structs**

- Blob
- Implementation of crate::Blob for the tokio runtime.
- Config
- Configuration for the tokio runtime.
- Context

- Implementation of crate::Spawner, crate::Clock, crate::Network, and crate::Storage for the tokio runtime.
- Executor
- Runtime based on Tokio.
- Listener
- Implementation of crate::Listener for the tokio runtime.
- Runner
- Implementation of crate::Runner for the tokio runtime.
- Sink
- Implementation of crate::Sink for the tokio runtime.
- Stream
- Implementation of crate::Stream for the tokio runtime.

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## Struct Handle

#### Settings

### Help

### Summary

#### Source

```
pub struct Handle<T>
where
    T: Send + 'static,
{ /* private fields */ }
```

Handle to a spawned task.

## **Implementations**

```
impl<T> Handle<T>
where
    T: Send + 'static,

Source
pub fn abort(&self)
```

## **Trait Implementations**

```
Source
```

```
impl<T> Future for Handle<T>
where
    T: Send + 'static,

Source

type Output = Result<T, Error>
    The type of value produced on completion.

Source
fn poll(self: Pin<&mut Self>, cx: &mut Context<'_>) ->
Poll<Self::Output>
    Attempts to resolve the future to a final value, registering the current task for wakeup if the value is not yet available. Read more
```

### **Auto Trait Implementations**

```
impl<T> Freeze for Handle<T>
impl<T> !RefUnwindSafe for Handle<T>
impl<T> Send for Handle<T>
impl<T> Sync for Handle<T>
impl<T> Unpin for Handle<T>
impl<T> !UnwindSafe for Handle<T>
```

## **Blanket Implementations**

```
impl<T> Any for T
where
```

```
T: 'static + ?Sized,
Source
impl<T> Borrow<T> for T
where
    T: ?Sized,
Source
impl<T> BorrowMut<T> for T
where
    T: ?Sized,
Source
impl<T> From<T> for T
Source
impl<T> FutureExt for T
where
    T: Future + ?Sized,
Source
impl<T> Instrument for T
Source
impl<T, U> Into<U> for T
where
    U: From<T>,
Source
impl<F> IntoFuture for F
where
```

```
F: Future,
Source
impl<T> Same for T
Source
§
impl<T, U> TryFrom<U> for T
where
    U: Into<T>,
Source
impl<F, T, E> TryFuture for F
where
    F: Future<Output = Result<T, E>> + ?Sized,
Source
impl<Fut> TryFutureExt for Fut
where
    Fut: TryFuture + ?Sized,
Source
impl<T, U> TryInto<U> for T
where
    U: TryFrom<T>,
Source
impl<V, T> VZip<V> for T
where
    V: MultiLane<T>,
```

```
impl<T> WithSubscriber for T
```

commonware\_runtime

# Struct Signaler...

Settings

Help

Summary

#### Source

```
pub struct Signaler { /* private fields */ }
```

Coordinates a one-time signal across many tasks.

### Example

### Basic Usage

```
use commonware_runtime::{Spawner, Runner, Signaler,
deterministic::Executor};

let (executor, _, _) = Executor::default();
executor.start(async move {
    // Setup signaler and get future
    let (mut signaler, signal) = Signaler::new();

    // Signal shutdown
    signaler.signal(2);

    // Wait for shutdown in task
    let sig = signal.await.unwrap();
    println!("Received signal: {}", sig);
    });
```

### Advanced Usage

While Futures:: Shared is efficient, there is still meaningful overhead to cloning it (i.e. in each iteration of a loop). To avoid a performance regression from introducing Signaler, it is recommended to wait on a reference to Signal (i.e. &mut signal).

```
use commonware macros::select;
```

```
use commonware runtime::{Clock, Spawner, Runner, Signaler,
deterministic::Executor};
use futures::channel::oneshot;
use std::time::Duration;
let (executor, context, ) = Executor::default();
executor.start(async move {
    // Setup signaler and get future
    let (mut signaler, mut signal) = Signaler::new();
    // Loop on the signal until resolved
    let (tx, rx) = oneshot::channel();
    context.spawn("task", {
        let context = context.clone();
        async move {
            loop {
                // Wait for signal or sleep
                select! {
                     sig = &mut signal => {
                         println!("Received signal: {}",
sig.unwrap());
                         break;
                     },
                     = context.sleep(Duration::from secs(1)) =>
{ },
                };
            let = tx.send(());
    });
    // Send signal
   signaler.signal(9);
   // Wait for task
   rx.await.expect("shutdown signaled");
  });
```

### **Implementations**

Source

impl Signaler

```
pub fn new() -> (Self, Signal)

Create a new Signaler.

Returns a Signaler and a Signal that will resolve when signal is called.
Source
```

```
pub fn signal(&mut self, value: i32)
Resolve the Signal for all waiters (if not already resolved).
```

## **Auto Trait Implementations**

```
impl Freeze for Signaler
impl !RefUnwindSafe for Signaler
impl Send for Signaler
impl Sync for Signaler
impl Unpin for Signaler
impl !UnwindSafe for Signaler
```

### **Blanket Implementations**

#### Source

```
impl<T> Any for T
where
    T: 'static + ?Sized,

Source
impl<T> Borrow<T> for T
where
    T: ?Sized,
```

```
impl<T> BorrowMut<T> for T
where
    T: ?Sized,
Source
impl<T> From<T> for T
Source
impl<T> Instrument for T
Source
impl<T, U> Into<U> for T
where
    U: From<T>,
Source
impl<T> Same for T
Source
impl<T, U> TryFrom<U> for T
where
    U: Into<T>,
Source
impl<T, U> TryInto<U> for T
where
    U: TryFrom<T>,
Source
impl<V, T> VZip<V> for T
where
```

```
V: MultiLane<T>,
Source
impl<T> WithSubscriber for T
commonware_runtime
Enum Error
Settings
Help
Summary
Source
pub enum Error {
Show 19 variants}
Variants
Exited
Closed
Timeout
BindFailed
ConnectionFailed
WriteFailed
ReadFailed
SendFailed
RecvFailed
PartitionCreationFailed(String)
PartitionMissing(String)
PartitionCorrupt(String)
BlobOpenFailed(String, String)
```

```
BlobMissing(String, String)
BlobTruncateFailed(String, String)
BlobSyncFailed(String, String)
BlobCloseFailed(String, String)
BlobInsufficientLength
OffsetOverflow
Trait Implementations
Source
impl Debug for Error
Source
fn fmt(&self, f: &mut Formatter<' >) -> Result
  Formats the value using the given formatter. Read more
Source
impl Display for Error
Source
fn fmt(&self, __formatter: &mut Formatter<'_>) -> Result
  Formats the value using the given formatter. Read more
```

```
impl Error for Error
1.30.0 · Source
fn source(&self) -> Option<&(dyn Error + 'static)>
  Returns the lower-level source of this error, if any. Read more
1.0.0 · Source
fn description(&self) -> &str
  Deprecated since 1.42.0: use the Display impl or to_string()
  Read more
1.0.0 · Source
fn cause(&self) -> Option<&dyn Error>
  Poprecated since 1.33.0: replaced by Error::source, which can support downcasting
Source
fn provide<'a>(&'a self, request: &mut Request<'a>)
```

#### Source

impl Sync for Error

impl Unpin for Error

impl UnwindSafe for Error

```
impl PartialEq for Error
Source
fn eq(&self, other: &Error) -> bool
   Tests for self and other values to be equal, and is used by ==.
1.0.0 · Source
fn ne(&self, other: &Rhs) -> bool
   Tests for ! =. The default implementation is almost always sufficient, and should not be
  overridden without very good reason.
Source
impl StructuralPartialEq for Error
Auto Trait Implementations
impl Freeze for Error
impl RefUnwindSafe for Error
impl Send for Error
```

## **Blanket Implementations**

```
Source
impl<T> Any for T
where
    T: 'static + ?Sized,
Source
impl<T> Borrow<T> for T
where
    T: ?Sized,
Source
impl<T> BorrowMut<T> for T
where
    T: ?Sized,
Source
impl<T> From<T> for T
Source
impl<T> Instrument for T
Source
impl<T, U> Into<U> for T
where
    U: From<T>,
Source
impl<T> Same for T
```

```
Source
impl<T> ToString for T
where
    T: Display + ?Sized,
Source
impl<T, U> TryFrom<U> for T
where
    U: Into<T>,
Source
impl<T, U> TryInto<U> for T
where
    U: TryFrom<T>,
Source
impl<V, T> VZip<V> for T
where
    V: MultiLane<T>,
Source
impl<T> WithSubscriber for T
commonware_runtime
Trait Blob
Settings
```

Summary

Help

```
pub trait Blob:
    Clone
    + Send
    + Sync
    + 'static {
    // Required methods
    fn len(&self) -> impl Future<Output = Result<u64, Error>>
+ Send;
   fn read at (
        &self,
        buf: &mut [u8],
        offset: u64,
    ) -> impl Future<Output = Result<(), Error>> + Send;
   fn write at(
        &self,
        buf: &[u8],
        offset: u64,
    ) -> impl Future<Output = Result<(), Error>> + Send;
   fn truncate(
        &self,
        len: u64,
    ) -> impl Future<Output = Result<(), Error>> + Send;
   fn sync(&self) -> impl Future<Output = Result<(), Error>> +
Send;
   fn close(self) -> impl Future<Output = Result<(), Error>> +
Send;
}
```

Interface to read and write to a blob.

To support blob implementations that enable concurrent reads and writes, blobs are responsible for maintaining synchronization.

Cloning a blob is similar to wrapping a single file descriptor in a lock whereas opening a new blob (of the same name) is similar to opening a new file descriptor. If multiple blobs are opened with the same name, they are not expected to coordinate access to underlying storage and writing to both is undefined behavior.

## **Required Methods**

#### Source

```
fn len(&self) -> impl Future<Output = Result<u64, Error>> +
Send
```

Get the length of the blob.

#### Source

```
fn read_at(
    &self,
    buf: &mut [u8],
    offset: u64,
) -> impl Future<Output = Result<(), Error>> + Send
```

Read from the blob at the given offset.

read\_at does not return the number of bytes read because it only returns once the entire buffer has been filled.

### Source

```
fn write_at(
    &self,
    buf: &[u8],
    offset: u64,
) -> impl Future<Output = Result<(), Error>> + Send
```

Write to the blob at the given offset.

```
fn truncate(&self, len: u64) -> impl Future<Output =
Result<(), Error>> + Send
```

Truncate the blob to the given length.

#### Source

```
fn sync(&self) -> impl Future<Output = Result<(), Error>> +
Send
```

Ensure all pending data is durably persisted.

#### Source

```
fn close(self) -> impl Future<Output = Result<(), Error>> +
Send
```

Close the blob.

## **Dyn Compatibility**

### Ş

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

### **Implementors**

```
impl Blob for commonware_runtime::deterministic::Blob
Source
impl Blob for commonware_runtime::tokio::Blob
commonware_runtime
```

## Trait Clock....

### Settings

### Help

### Summary

### Source

```
pub trait Clock:
   Clone
   + Send
   + Sync
    + 'static {
    // Required methods
    fn current(&self) -> SystemTime;
   fn sleep(
        &self,
        duration: Duration,
    ) -> impl Future<Output = ()> + Send + 'static;
   fn sleep_until(
        &self,
        deadline: SystemTime,
    ) -> impl Future<Output = ()> + Send + 'static;
}
```

Interface that any task scheduler must implement to provide time-based operations.

It is necessary to mock time to provide deterministic execution of arbitrary tasks.

## Required Methods

#### Source

```
fn current(&self) -> SystemTime
```

Returns the current time.

```
fn sleep(&self, duration: Duration) -> impl Future<Output =
  ()> + Send + 'static

Sleep for the given duration.

Source
fn sleep_until(
    &self,
    deadline: SystemTime,
) -> impl Future<Output = ()> + Send + 'static
```

## **Dyn Compatibility**

This trait is not dyn compatible.

Sleep until the given deadline.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

## **Implementors**

```
Source
```

```
impl Clock for
commonware_runtime::deterministic::Context
Source
impl Clock for commonware_runtime::tokio::Context
commonware runtime
```

## Trait Listener

#### Settings

Help

### Summary

#### Source

Interface that any runtime must implement to handle incoming network connections.

## Required Methods

### Source

```
fn accept(
    &mut self,
) -> impl Future<Output = Result<(SocketAddr, Si, St), Error>>
+ Send
```

Accept an incoming connection.

## **Dyn Compatibility**

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

## **Implementors**

```
impl Listener<Sink, Stream> for
commonware runtime::deterministic::Listener
Source
impl Listener<Sink, Stream> for
commonware runtime::tokio::Listener
commonware_runtime
Trait Network
Settings
Help
Summary
Source
pub trait Network<L, Si, St>:
   Clone
   + Send
   + Sync
   + 'static
where
   L: Listener<Si, St>,
   Si: Sink,
   St: Stream,
   // Required methods
   fn bind(
       &self,
       socket: SocketAddr,
   ) -> impl Future<Output = Result<L, Error>> + Send;
  fn dial(
       &self,
       socket: SocketAddr,
```

Interface that any runtime must implement to create network connections.

}

) -> impl Future<Output = Result<(Si, St), Error>> + Send;

## Required Methods

#### Source

```
fn bind(
    &self,
    socket: SocketAddr,
) -> impl Future<Output = Result<L, Error>> + Send

Bind to the given socket address.

Source
fn dial(
    &self,
    socket: SocketAddr,
) -> impl Future<Output = Result<(Si, St), Error>> + Send

Dial the given socket address.
```

### **Dyn Compatibility**

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

### **Implementors**



```
impl Network<Listener, Sink, Stream> for
commonware_runtime::deterministic::Context
Source
impl Network<Listener, Sink, Stream> for
commonware runtime::tokio::Context
```

## Trait Runner

### Settings

### Help

### Summary

### Source

Interface that any task scheduler must implement to start running tasks.

## Required Methods

#### Source

```
fn start<F>(self, f: F) -> F::Output
where
    F: Future + Send + 'static,
    F::Output: Send + 'static,
```

Start running a root task.

### Dyn Compatibility

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

## **Implementors**

```
impl Runner for
commonware_runtime::deterministic::Runner
Source
impl Runner for commonware_runtime::tokio::Runner
commonware_runtime
```

## Trait Sink

### Settings

Help

Summary

### Source

Interface that any runtime must implement to send messages over a network connection.

## **Required Methods**

#### Source

```
fn send(&mut self, msg: &[u8]) -> impl Future<Output =
Result<(), Error>> + Send
```

Send a message to the sink.

### **Dyn Compatibility**

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

### **Implementors**

```
Source
```

```
impl Sink for commonware_runtime::deterministic::Sink
Source
impl Sink for commonware_runtime::mocks::Sink
Source
impl Sink for commonware_runtime::tokio::Sink
commonware_runtime
```

# Trait Spawner

### Settings

Help

Summary

### Source

Interface that any task scheduler must implement to spawn sub-tasks in a given root task.

## Required Methods

#### Source

```
fn spawn<F, T>(&self, label: &str, f: F) -> Handle<T> i)
where
    F: Future<Output = T> + Send + 'static,
    T: Send + 'static,
```

Enqueues a task to be executed.

Label can be used to track how many instances of a specific type of task have been spawned or are running concurrently (and is appened to all metrics). Label is automatially appended to the parent task labels (i.e. spawning "fun" from "have" will be labeled "have fun").

Unlike a future, a spawned task will start executing immediately (even if the caller does not await the handle).

#### Source

```
fn stop(&self, value: i32)
```

Signals the runtime to stop execution and that all outstanding tasks should perform any required cleanup and exit. This method is idempotent and can be called multiple times.

This method does not actually kill any tasks but rather signals to them, using the Signal returned by stopped, that they should exit.

```
fn stopped(&self) -> Signal
```

Returns an instance of a Signal that resolves when stop is called by any task.

If stop has already been called, the returned Signal will resolve immediately.

## Dyn Compatibility

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

## **Implementors**

```
Source
```

```
impl Spawner for
commonware_runtime::deterministic::Context
Source
impl Spawner for commonware_runtime::tokio::Context
commonware_runtime
```

# Trait Storage....

### Settings

Help

Summary

```
pub trait Storage<B>:
    Clone
    + Send
    + Sync
    + 'static
where
    B: Blob,
{
    // Required methods
    fn open(
```

```
&self,
    partition: &str,
    name: &[u8],
) -> impl Future<Output = Result<B, Error>> + Send;

fn remove(
    &self,
    partition: &str,
    name: Option<&[u8]>,
) -> impl Future<Output = Result<(), Error>> + Send;

fn scan(
    &self,
    partition: &str,
) -> impl Future<Output = Result<Vec<Vec<u8>>, Error>> + Send;
}
```

Interface to interact with storage.

To support storage implementations that enable concurrent reads and writes, blobs are responsible for maintaining synchronization.

Storage can be backed by a local filesystem, cloud storage, etc.

### **Required Methods**

#### Source

```
fn open(
    &self,
    partition: &str,
    name: &[u8],
) -> impl Future<Output = Result<B, Error>> + Send
```

Open an existing blob in a given partition or create a new one.

Multiple instances of the same blob can be opened concurrently, however, writing to the same blob concurrently may lead to undefined behavior.

#### Source

```
fn remove(
    &self,
    partition: &str,
    name: Option<&[u8]>,
) -> impl Future<Output = Result<(), Error>> + Send
```

Remove a blob from a given partition.

If no name is provided, the entire partition is removed.

#### Source

```
fn scan(
    &self,
    partition: &str,
) -> impl Future<Output = Result<Vec<Vec<u8>>>, Error>> + Send
    Return all blobs in a given partition.
```

## Dyn Compatibility

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

### **Implementors**

```
impl Storage<Blob> for
commonware_runtime::deterministic::Context
Source
impl Storage<Blob> for
commonware runtime::tokio::Context
```

# Trait Stream....

### Settings

### Help

### Summary

#### Source

```
pub trait Stream:
    Sync
+ Send
+ 'static {
    // Required method
    fn recv(
        &mut self,
        buf: &mut [u8],
    ) -> impl Future<Output = Result<(), Error>> + Send;
}
```

Interface that any runtime must implement to receive messages over a network connection.

## Required Methods

#### Source

```
fn recv(
    &mut self,
    buf: &mut [u8],
) -> impl Future<Output = Result<(), Error>> + Send
```

Receive a message from the stream, storing it in the given buffer. Reads exactly the number of bytes that fit in the buffer.

### Dyn Compatibility

This trait is not dyn compatible.

In older versions of Rust, dyn compatibility was called "object safety", so this trait is not object safe.

# **Implementors**

```
impl Stream for
commonware_runtime::deterministic::Stream
Source
impl Stream for commonware_runtime::mocks::Stream
Source
impl Stream for commonware runtime::tokio::Stream
```