# **Python For Data Science** Cheat Sheet SciPv - Linear Algebra

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# SciPv

The SciPy library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.



# Interacting With NumPy

#### Also see NumPy

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5\frac{1}{2},2\frac{1}{2},3\frac{1}{2}), (4\frac{1}{2},5\frac{1}{2},6\frac{1}{2})])
>>> c = np.array([[(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)]])
```

#### Index Tricks

>>>	np.mgrid[0:5,0:5]	Create a dense meshgrid
>>>		Create an open meshgrid
>>>	np.r_[3,[0]*5,-1:1:10j]	stack arrays vertically (row-wise)
>>>	np.c [b,c]	Create stacked column-wise arrays

## Shape Manipulation

>>>	np.transpose(b)	Permute array dimensions
>>>	b.flatten()	Flatten the array
>>>	np.hstack((b,c))	Stack arrays horizontally (column-wise)
>>>	np.vstack((a,b))	Stack arrays vertically (row-wise)
>>>	np.hsplit(c,2)	Split the array horizontally at the 2nd index
>>>	np.vpslit(d,2)	Split the array vertically at the 2nd index

## Polynomials

>>>	from numpy import polyla	
>>>	p = poly1d([3,4,5])	Create a polynomial object

# **Vectorizing Functions**

```
>>> def myfunc(a):
         if a < 0:
           return a*2
           return a/2
                                     Vectorize functions
>>> np.vectorize(myfunc)
```

## Type Handling

		Return the real part of the array elements Return the imaginary part of the array element
>>>	np.real_if_close(c,tol=1000)	Return a real array if complex parts close to o
>>>	np.cast['f'](np.pi)	Cast object to a data type

Return the angle of the complex argument

## Other Useful Functions

>>> nn anglo(h dog=Truo)

proving angle (b) deg-11 de	
>>> g = np.linspace(0,np.pi,n	um=5) Create an array of evenly spaced values
>>> g [3:] += np.pi	(number of samples)
>>> np.unwrap(g)	Unwrap
>>> np.logspace(0,10,3)	
>>> np.select([c<4],[c*	2]) Return values from a list of arrays depending or
	conditions
>>> misc.factorial(a)	Factorial
>>> misc.comb(10,3,exact=T	rue) Combine N things taken at k time
>>> misc.central_diff_weight:	
>>> misc.derivative(myfunc,1	) Find the n-th derivative of a function at a point

#### Linear Algebra Also see NumPv

```
You'll use the linalg and sparse modules. Note that scipy, linalg contains and expands on numpy, linalg.
```

#### >>> from scipy import linalg, sparse

# Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))
>>> B = np.asmatrix(b)
>>> C = np.mat(np.random.random((10,5)))
>>> D = np.mat([[3,4], [5,6]])
```

## **Basic Matrix Routines**

#### Inverse

>>> A.I >>> linalg.inv(A)

## Transposition

>>>	A.T
>>>	A.H

#### Trace

>>> np.trace(A)

#### Norm

>>>	linalg.norm(A)
>>>	linalg.norm(A,1)
>>>	<pre>linalg.norm(A,np.inf)</pre>

#### Rank

>>> np.linalg.matrix rank(C)

#### Determinant

>>> linalq.det(A)

# Solving linear problems

>>>	linalg.solve(A,b)
>>>	E = np.mat(a).T
>>>	linalg.lstsq(F,E)

## Generalized inverse

>>>	linalg.pinv(C)
>>>	linalg.pinv2(C)

#### Inverse Inverse

Tranpose matrix Conjugate transposition

#### Trace

```
Frobenius norm
L1 norm (max column sum)
L inf norm (max row sum)
```

#### Matrix rank

Determinant

#### Solver for dense matrices Solver for dense matrices Least-squares solution to linear matrix equation

# Compute the pseudo-inverse of a matrix

#### (least-squares solver) Compute the pseudo-inverse of a matrix (SVD)

# Creating Sparse Matrices

	<pre>F = np.eye(3, k=1) G = np.mat(np.identity(2))</pre>	Create a 2X2 identity matrix Create a 2x2 identity matrix
>>>	C[C > 0.5] = 0	
>>>	<pre>H = sparse.csr_matrix(C)</pre>	Compressed Sparse Row matrix
>>>	I = sparse.csc matrix(D)	Compressed Sparse Column matrix
>>>	<pre>J = sparse.dok matrix(A)</pre>	Dictionary Of Keys matrix
>>>	E.todense()	Sparse matrix to full matrix
>>>	sparse.isspmatrix csc(A)	Identify sparse matrix

## Sparse Matrix Routines

## Inverse

>>>	sparse	. :	linal	Lg.	inv	(I)
No	rm					

#### >>> sparse.linalg.norm(I) Solving linear problems >>> sparse.linalg.spsolve(H,I)

## Inverse

Norm

## Solver for sparse matrices

## Sparse Matrix Functions

>>>	sparse.linalg.expm(I)	Sparse matrix exponential

## Matrix Functions

## Addition

>>> np.add(A,D)

#### Subtraction

>>> np.subtract(A.D)

#### Division

>>> np.divide(A,D)

#### Multiplication >>> A @ D

```
>>> np.multiplv(D,A)
>>> np.dot(A,D)
>>> np.vdot(A,D)
>>> np.inner(A,D)
>>> np.outer(A,D)
>>> np.tensordot(A,D)
>>> np.kron(A,D)
```

## **Exponential Functions**

-/	ponential ranceions
>>>	linalg.expm(A)
>>>	linalg.expm2(A)
>>>	linalg.expm3(D)

## **Logarithm Function**

>>> linalg.logm(A)

## **Trigonometric Functions**

///	TIMATG.SIMM(D)
>>>	linalg.cosm(D)
>>>	linalg.tanm(A)

## **Hyperbolic Trigonometric Functions**

>>>	linalg.sinhm(D)
>>>	linalg.coshm(D)
>>>	linalg.tanhm(A)

# Matrix Sign Function

#### >>> np.signm(A) **Matrix Square Root**

#### >>> linalg.sgrtm(A) **Arbitrary Functions**

>>> linalg.funm(A, lambda x: x\*x)

# Addition

Subtraction

#### Division

# Multiplication operator

(Python 3) Multiplication Dot product Vector dot product Inner product Outer product Tensor dot product Kronecker product

#### Matrix exponential Matrix exponential (Taylor Series) Matrix exponential (eigenvalue

## Matrix logarithm

decomposition)

Matrix sine Matrix cosine Matrix tangent

#### Hypberbolic matrix sine Hyperbolic matrix cosine Hyperbolic matrix tangent

# Matrix sign function

## Matrix square root

#### Evaluate matrix function

# Decompositions

# Figenvalues and Figenvectors

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>>>	la, v = linalg.eig(A)
>>>	11, 12 = la
>>>	v[:,0]
>>>	v[:,1]

# Singular Value Decomposition

Jingalai	varac Decemposition
>>> U,s,V	h = linalg.svd(B)
>>> M,N =	B.shape
>>> Sig =	linalg.diagsvd(s,M,N)

# III Decomposition

LU	Decoi	пþ	OSILIOII
>>>	P, L, U	=	linalg.lu(

>>> linalg.eigvals(A)

>>>	P,L,U	=	linalg.lu(C)	

Solve ordinary or generalized eigenvalue problem for square matrix Unpack eigenvalues First eigenvector Second eigenvector Unpack eigenvalues

# Singular Value Decomposition (SVD)

Construct sigma matrix in SVD

#### LU Decomposition

## Sparse Matrix Decompositions

>>>	la, v = sparse.linalg.eigs(F,	1)
>>>	sparse.linalg.svds(H, 2)	

Eigenvalues and eigenvectors

# Asking For Help

>>> help(scipy.linalg.diagsvd) >>> np.info(np.matrix)



