Conformal Algebra

 ${\bf Hariprashad~Ravikumar}^1$

¹New Mexico State University, USA

May 10, 2024

hari1729@nmsu.edu 1/23

Conformal Transformations

A conformal transformation is a smooth, invertible map $x \to x'$ which locally preserves the angle between any two lines:

$$g'_{\rho\sigma}(x')\frac{\partial x'^{\rho}}{\partial x^{\mu}}\frac{\partial x'^{\sigma}}{\partial x^{\nu}} = \Lambda(x)g_{\mu\nu}(x), \tag{1.1}$$

Let us next consider the infinitesimal coordinate transformations ($\epsilon(x) << 1$):

$$x'^{\rho} = x^{\rho} + \epsilon^{\rho}(x) + \mathcal{O}(\epsilon^2). \tag{1.2}$$

hari1729@nmsu.edu 2 / 23

Conformal Transformations

For $d \geq 3$, there are ONLY 4 calsses of solutions for $\epsilon_{\mu}(x)$ of $x'_{\mu} = x_{\mu} + \epsilon_{\mu}(x) + \mathcal{O}(\epsilon^{2})$.

(Infinitesimal Translation)
$$\epsilon^{\mu}(x) = a^{\mu}$$
 (constant) (1.3)

(Infinitesimal Rotation)
$$\epsilon^{\mu}(x) = M^{\mu}_{\nu} x^{\nu}$$
 (1.4)

(Infinitesimal Scaling)
$$\epsilon^{\mu}(x) = \lambda x^{\mu}$$
 (1.5)

(Infinitesimal SCT)
$$\epsilon^{\mu}(x) = 2(b.x)x^{\mu} - x^2b^{\mu}$$
 (1.6)

The Finite conformal transformations are:

(translation)
$$x'^{\mu} = x^{\mu} + a^{\mu}$$
(rotation)
$$x'^{\mu} = M^{\mu}_{\ \nu} x^{\nu}$$
(dilatation)
$$x'^{\mu} = \alpha x^{\mu}$$
(SCT)
$$x'^{\mu} = \frac{x^{\mu} - b^{\mu} x^{2}}{1 - 2b \cdot x + b^{2} x^{2}}$$

hari1729@nmsu.edu 3 / 23

SCT

Inversions are given by

$$\boxed{x^{\mu}} \longrightarrow \left| x'^{\mu} = \frac{x^{\mu}}{x^2} \right| \tag{1.7}$$

The SCTs can be understood as an inversion of x^{μ} , followed by a translation b^{μ} , and followed again by an inversion.

$$\boxed{x^{\mu}} \longrightarrow \boxed{x'^{\mu} = \frac{x^{\mu}}{x^{2}}} \longrightarrow \boxed{x''^{\mu} = \frac{x^{\mu}}{x^{2}} - b^{\mu}} \longrightarrow \boxed{x'''^{\mu} = \frac{\frac{x^{\mu}}{x^{2}} - b^{\mu}}{(\frac{x^{\mu}}{x^{2}} - b^{\mu})^{2}} = \frac{x^{\mu} - b^{\mu}x^{2}}{1 - 2b \cdot x + b^{2}x^{2}}}$$

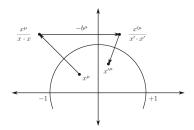


Figure 1: Illustration of a finite SCT

hari1729@nmsu.edu 4 / 23

Conformal algebra

The generators of conformal transformations are: $P^{\mu} = i\partial^{\mu}$ (translation), $M^{\mu\nu} = i \left(x^{\mu}\partial^{\nu} - x^{\nu}\partial^{\mu}\right)$ (rotation), $D = ix_{\mu}\partial^{\mu}$ (dilation or scaling), and $\mathfrak{R}^{\mu} = i \left(2x^{\mu}x_{\nu}\partial^{\nu} - x^{2}\partial^{\mu}\right)$ (SCT).

Therefore, the full Conformal algebra is given by

$$\begin{split} [P_{\mu}, P_{\nu}] &= 0; \ [\mathfrak{K}_{\mu}, \mathfrak{K}_{\nu}] = 0; \\ [D, P_{\mu}] &= -iP_{\mu}; \ [D, \mathfrak{K}_{\mu}] = i\mathfrak{K}_{\mu}; \\ [P_{\rho}, M_{\mu\nu}] &= i \left(g_{\rho\mu} P_{\nu} - g_{\rho\nu} P_{\mu} \right); \\ [\mathfrak{K}_{\rho}, M_{\mu\nu}] &= i \left(g_{\rho\mu} \mathfrak{K}_{\nu} - g_{\rho\nu} \mathfrak{K}_{\mu} \right); \\ [M_{\alpha\beta}, M_{\rho\sigma}] &= -i \left(g_{\beta\sigma} M_{\alpha\rho} - g_{\beta\rho} M_{\alpha\sigma} + g_{\alpha\rho} M_{\beta\sigma} - g_{\alpha\sigma} M_{\beta\rho} \right); \\ [\mathfrak{K}_{\mu}, P_{\nu}] &= -2i \left(g_{\mu\nu} D + M_{\mu\nu} \right); \ [D, M_{\mu\nu}] &= 0. \end{split}$$

hari1729@nmsu.edu 5 / 23

Boost as Rotations in 4D

The 4D Angular momentum tensor is given by:

$$M_{\mu\nu} = i(x_{\mu}\partial_{\nu} - x_{\nu}\partial_{\mu}) = \begin{pmatrix} 0 & -K^{1} & -K^{2} & -K^{3} \\ K^{1} & 0 & J^{3} & -J^{2} \\ K^{2} & -J^{3} & 0 & J^{1} \\ K^{3} & J^{2} & -J^{1} & 0 \end{pmatrix}.$$
(3.1)

$$[M^{\alpha\beta}, M^{\rho\sigma}] = -i \left(g^{\beta\sigma} M^{\alpha\rho} - g^{\beta\rho} M^{\alpha\sigma} + g^{\alpha\rho} M^{\beta\sigma} - g^{\alpha\sigma} M^{\beta\rho} \right)$$
(3.2)

There are $\frac{n(n-1)}{2}$ number of planes in n dimension:

Dimension	# of planes				
1D	0				
2D	1				
3D	3				
4D	6				
5D	10				
6D	15				

hari1729@nmsu.edu 6 / 23

(3.3)

We define the following 6×6 tensor in the projective-space-time:

$$J_{a,b} = \begin{pmatrix} 0 & -D & -\frac{\Re_0}{\sqrt{2}} & -\frac{\Re_1}{\sqrt{2}} & -\frac{\Re_2}{\sqrt{2}} & -\frac{\Re_3}{\sqrt{2}} \\ D & 0 & \frac{P_0}{\sqrt{2}} & \frac{P_1}{\sqrt{2}} & \frac{P_2}{\sqrt{2}} & \frac{P_3^2}{\sqrt{2}} \\ \frac{\Re_0}{\sqrt{2}} & -\frac{P_0}{\sqrt{2}} & 0 & \mathcal{D}^{\hat{1}} & \mathcal{D}^{\hat{2}} & K^3 \\ \frac{\Re_1}{\sqrt{2}} & -\frac{P_1}{\sqrt{2}} & -\mathcal{D}^{\hat{1}} & 0 & J^3 & -\mathcal{K}^{\hat{1}} \\ \frac{\Re_2}{\sqrt{2}} & -\frac{P_2}{\sqrt{2}} & -\mathcal{D}^{\hat{2}} & -J^3 & 0 & -\mathcal{K}^{\hat{2}} \\ \frac{\Re_3}{\sqrt{2}} & -\frac{P_3}{\sqrt{2}} & -K^3 & \mathcal{K}^{\hat{1}} & \mathcal{K}^{\hat{2}} & 0 \end{pmatrix}_{(6\times6)}$$

Then, the simplified conformal algebra SO(4+1,1) is:

$$[J_{ab}, J_{cd}] = -i \left(g_{bd} J_{ac} - g_{bc} J_{ad} + g_{ac} J_{bd} - g_{ad} J_{bc} \right)$$
(3.5)

where,

$$g_{\hat{a},\hat{b}} = \begin{pmatrix} 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 \end{pmatrix}_{6 \times 6}$$

$$(3.6)$$

(3.4)

where $a, b \in \{-2, -1, 0, 3\}$.

hari1729@nmsu.edu 7 / 23

Isomorphism with Dirac matrices

Dirac¹ has shown the existence of isomorphism between SO(4,2) conformal group and Dirac matrices. Later, Hepner² has explicitly shown the isomorphism between the group of Dirac's four-row γ -matrices and the continuous conformal group in Euclidean space.

We show

$$J'_{a,b} = \begin{pmatrix} 0 & \gamma_5 & \frac{(1-\gamma_5)\gamma_0}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_1}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_2}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_3}{\sqrt{2}} \\ -\gamma_5 & 0 & \frac{(1+\gamma_5)\gamma_0}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_1}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_2}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_3}{\sqrt{2}} \\ \frac{-(1-\gamma_5)\gamma_0}{\sqrt{2}} & -\frac{-(1+\gamma_5)\gamma_0}{\sqrt{2}} & 0 & \gamma_0\gamma_1 & \gamma_0\gamma_2 & \gamma_0\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_1}{\sqrt{2}} & -\frac{-(1+\gamma_5)\gamma_1}{\sqrt{2}} & \gamma_1\gamma_0 & 0 & \gamma_1\gamma_2 & \gamma_1\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_2}{\sqrt{2}} & -\frac{-(1+\gamma_5)\gamma_2}{\sqrt{2}} & \gamma_2\gamma_0 & \gamma_2\gamma_1 & 0 & \gamma_2\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_3}{\sqrt{2}} & -\frac{-(1+\gamma_5)\gamma_3}{\sqrt{2}} & \gamma_3\gamma_0 & \gamma_3\gamma_1 & \gamma_3\gamma_2 & 0 \end{pmatrix}.$$
 (3.7)

This $J'_{a,b}$ obeys the SO(4+1,1) algebra $[J_{ab},J_{cd}]=-i\left(g_{bd}J_{ac}-g_{bc}J_{ad}+g_{ac}J_{bd}-g_{ad}J_{bc}\right)$

¹Dirac, P. A. M. Annals Math. 37, 429-442 (1936)

²Hepner, W. A. Nuovo Cim. 26, 351–368 (1962).

Isomorphism with Dirac matrices

The representation of the conformal group in terms of 4×4 gamma matrices are the following;

$$P_{\mu} = \frac{i}{2} (1 + \gamma_5) \gamma_{\mu}; \tag{3.8}$$

$$\mathfrak{K}_{\mu} = \frac{-i}{2} (1 - \gamma_5) \gamma_{\mu}; \tag{3.9}$$

$$K^{1} = \frac{i}{2}\gamma_{1}\gamma_{0}; \quad K^{2} = \frac{i}{2}\gamma_{2}\gamma_{0}; \quad K^{3} = \frac{i}{2}\gamma_{3}\gamma_{0};$$
 (3.10)

$$J^{1} = \frac{i}{2}\gamma_{2}\gamma_{3}; \quad J^{2} = \frac{i}{2}\gamma_{3}\gamma_{1}; \quad J^{3} = \frac{i}{2}\gamma_{1}\gamma_{2};$$
 (3.11)

$$D = \frac{-i}{2}\gamma_5. \tag{3.12}$$

hari1729@nmsu.edu 9 / 23

We have:

$$J_{ab} = \begin{pmatrix} 0 & -D & -\frac{\hat{\aleph}_0}{\sqrt{2}} & -\frac{\hat{\aleph}_3}{\sqrt{2}} \\ D & 0 & \frac{P_0}{\sqrt{2}} & \frac{P_3}{\sqrt{2}} \\ \frac{\hat{\aleph}_0}{\sqrt{2}} & -\frac{P_0}{\sqrt{2}} & 0 & -K^3 \\ \frac{\hat{\aleph}_3}{\sqrt{2}} & -\frac{P_3}{\sqrt{2}} & K^3 & 0 \end{pmatrix}_{(4\times4)}$$

Then, the 1+1 conformal algebra in LFD is given by

$$[J_{ab}, J_{cd}] = -i \left(g_{bd} J_{ac} - g_{bc} J_{ad} + g_{ac} J_{bd} - g_{ad} J_{bc} \right) \tag{4.2}$$

where,

$$g_{ab} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}_{4 \times 4}$$
 (4.3)

From (4.2), one can write

$$J_{ab} = i(x_a \partial_b - x_b \partial_a) \tag{4.4}$$

(4.1)

where $a, b \in \{-2, -1, 0, 3\}$.

hari1729@nmsu.edu 10 / 23

Let's say that A^a is hyper-4-vector; suppose A^a and B^a transform under 6d rotation:

$$A'^{a} = R^{a}_{b}A^{b}, \quad B'^{a} = R^{a}_{b}B^{b}.$$
 (4.5)

Then the inner products $A' \cdot B'$ and $A \cdot B$ can be written as

$$A_b'B'^b = (g_{ab}R^a_{\ c}R^b_{\ d})A^cB^d, \tag{4.6}$$

$$A_b B^b = g_{cd} A^c B^d. (4.7)$$

In order for A'.B' = A.B to hold for any A and B, the coefficients of A^cB^d should be the same term by term:

$$g_{ab}R^{a}_{\ c}R^{b}_{\ d} = g_{cd}. (4.8)$$

Let's start by looking at a hyper-4d rotation transformation, which is (has to be) infinitesimally close to the identity:

$$R^{a}_{\ b} = g^{a}_{\ b} + \omega^{a}_{\ b} \ , \tag{4.9}$$

where ω^a_b is a set of small (real) numbers.

hari1729@nmsu.edu 11 / 23

Inserting this into the defining condition, we get

$$g^{cd} = R^{c}{}_{b}R^{bd} , \qquad (4.10)$$

$$= (g^{c}{}_{b} + \omega^{c}{}_{b})(g^{bd} + \omega^{bd}) ,$$

$$= g^{cd} + \omega^{cd} + \omega^{dc} + \mathcal{O}(\omega^{2}). \qquad (4.11)$$

Keeping terms to the first order in ω , we then obtain

$$\omega^{ab} = -\omega^{ba} \ . \tag{4.12}$$

Thus, it has 6 independent parameters:

$$\omega^{ab} = \begin{pmatrix} 0 & \omega^{-2,-1} & \omega^{-2,0} & \omega^{-2,3} \\ -\omega^{-2,-1} & 0 & \omega^{-1,0} & \omega^{-1,3} \\ -\omega^{-2,0} & -\omega^{-1,0} & 0 & \omega^{0,3} \\ -\omega^{-2,3} & -\omega^{1,3} & -\omega^{0,3} & 0 \end{pmatrix}_{(4\times4)} . \tag{4.13}$$

This can be conveniently parameterized using 6 anti-symmetric matrices as

$$\omega^{ab} = -i \sum_{c < \hat{d}} \omega^{cd} (J_{cd})^{ab} , \qquad (4.14)$$

hari1729@nmsu.edu 12 / 23

where

$$(J_{cd})^{ab} = i(g^a_{\ c}g^b_{\ d} - g^b_{\ c}g^a_{\ d}). \tag{4.15}$$

then

$$\omega^{ab} = -i\sum_{c < d} \omega^{cd} (J_{cd})^{ab} = -i\sum_{c > d} \omega^{cd} (J_{cd})^{ab} = -\frac{i}{2} \omega^{cd} (J_{cd})^{ab} , \qquad (4.16)$$

where in the last expression, the sum over all values of \hat{c} and \hat{d} is implied. The infinitesimal transformation (hyper-4d rotation) ((4.9)) can then be written a

$$R^{a}_{b} = g^{a}_{b} - \frac{i}{2}\omega^{cd}(J_{cd})^{a}_{b} , \qquad (4.17)$$

The generator representation $(J_{cd})^a_b$ can be obtained by

$$(J_{cd})_b^a = (J_{cd})^{af} g_{fb} (4.18)$$

hari1729@nmsu.edu 13 / 23

The representation matrices of conformal generators are defined by taking the first index to be superscript and the second subscript:

$$\frac{-\mathfrak{K}_{\mu}}{\sqrt{2}} \equiv (J_{-2\mu})^a_{\ b} \ ; \quad \frac{P_{\mu}}{\sqrt{2}} \equiv (J_{-1\mu})^a_{\ b} \ ; \quad -D \equiv (J_{-2-1})^a_{\ b} \ ; \quad K^3 \equiv (J_{3,0})^a_{\ b}. \tag{4.19}$$

where $a, b \in \{-2, -1, 0, 3\}$ and $\mu \in \{0, 3\}$. Explicitly³,

hari1729@nmsu.edu 14 / 23

³H. Ravikumar, Chueng Ji. to be published

We define the conformal transformations as those transformations preserving the light cone. This is equivalent to preserving angles, and also equivalent to preserving ratios of lengths. Let's consider a hyper-4d vector;

$$\tilde{x}_{-1} = \frac{-\lambda}{\sqrt{2}};\tag{4.21}$$

$$\tilde{x}_{-2} = \frac{-\lambda}{\sqrt{2}} (x^{\mu}.x_{\mu});$$
(4.22)

$$\tilde{x}_{\mu} = \lambda x_{\mu}; \tag{4.23}$$

Now, let's consider the hyper-4d dot product,

$$g_{ab}\tilde{x}^a\tilde{x}^b = \tilde{x}^{-2}\tilde{x}_{-2} + \tilde{x}^{-1}\tilde{x}_{-1} + \tilde{x}^\mu\tilde{x}_\mu \tag{4.24}$$

$$\tilde{x}_a.\tilde{x}^a = -2\tilde{x}_{-2}\tilde{x}_{-1} + \tilde{x}^{\mu}\tilde{x}_{\mu}$$
 (since, $\tilde{x}_{-1} = -\tilde{x}^{-2}$ & $\tilde{x}_{-2} = -\tilde{x}^{-1}$) (4.25)

$$\tilde{x}_a.\tilde{x}^a = -2\frac{-\lambda}{\sqrt{2}}(x^{\mu}.x_{\mu})\frac{-\lambda}{\sqrt{2}} + \lambda^2 x^{\mu}x_{\mu} = -\lambda^2 x^{\mu}x_{\mu} + \lambda^2 x^{\mu}x_{\mu} \tag{4.26}$$

$$\tilde{x}_a.\tilde{x}^a = 0 \tag{4.27}$$

hari1729@nmsu.edu 15 / 23

then,

$$x_{\mu} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\mu}}{\tilde{x}_{-1}} \tag{4.28}$$

$$\frac{\bar{x}_{\mu}}{x^{2}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\mu}}{\tilde{x}_{-1}} \frac{2\tilde{x}_{-1}\tilde{x}_{-1}}{\tilde{x}_{\mu}\tilde{x}^{\mu}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\mu}}{\tilde{x}_{-1}} \frac{2\tilde{x}_{-1}\tilde{x}_{-1}}{2\tilde{x}_{-2}\tilde{x}_{-1}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\mu}}{\tilde{x}_{-2}} \tag{4.29}$$

Also,
$$x^2 = \frac{\tilde{x}_{-2}}{\tilde{x}_{-1}}$$
.

Let's find the space-time transformation under each conformal generators in 1 + 1.

16 / 23

For \mathfrak{K}_0 :

$$\begin{pmatrix} \tilde{x}'_{-2} \\ \tilde{x}'_{-1} \\ \tilde{x}'_{0} \\ \tilde{x}'_{3} \end{pmatrix} = \exp\left(-ib^{0}\mathfrak{K}_{0}\right) \begin{pmatrix} \tilde{x}_{-2} \\ \tilde{x}_{-1} \\ \tilde{x}_{0} \\ \tilde{x}_{3} \end{pmatrix}$$
(4.30)

$$\begin{pmatrix}
\tilde{x}'_{-2} \\
\tilde{x}'_{-1} \\
\tilde{x}'_{0} \\
\tilde{x}'_{3}
\end{pmatrix} = \begin{pmatrix}
1 & 0 & 0 & 0 \\
(b^{0})^{2} & 1 & \sqrt{2}b^{0} & 0 \\
\sqrt{2}b^{0} & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{pmatrix} \begin{pmatrix}
\tilde{x}_{-2} \\
\tilde{x}_{-1} \\
\tilde{x}_{0} \\
\tilde{x}_{3}
\end{pmatrix}$$
(4.31)

$$\begin{pmatrix}
\tilde{x}'_{-2} \\
\tilde{x}'_{-1} \\
\tilde{x}'_{0} \\
\tilde{x}'_{3}
\end{pmatrix} = \begin{pmatrix}
\tilde{x}_{-2} \\
(b^{0})^{2}\tilde{x}_{-2} + \tilde{x}_{-1} + \sqrt{2}b^{0}\tilde{x}_{0} \\
\sqrt{2}b^{0}\tilde{x}_{-2} + \tilde{x}_{0} \\
\tilde{x}_{3}
\end{pmatrix} (4.32)$$

hari1729@nmsu.edu 17 / 23

On space-time, this transformation gives

$$x_0' = \frac{-1}{\sqrt{2}} \frac{\tilde{x}_0'}{\tilde{x}_1'} \tag{4.33}$$

$$= \frac{-1}{\sqrt{2}} \frac{\sqrt{2}b^0 \tilde{x}_{-2} + \tilde{x}_0}{(b^0)^2 \tilde{x}_{-2} + \tilde{x}_{-1} + \sqrt{2}b^0 \tilde{x}_0}$$
(4.34)

$$= \frac{-1}{\sqrt{2}} \frac{\sqrt{2}b^0 \frac{\tilde{x}_{-2}}{\tilde{x}_{-1}} + \frac{\tilde{x}_0}{\tilde{x}_{-1}}}{(b^0)^2 \frac{\tilde{x}_{-2}}{\tilde{x}_{-1}} + 1 + \sqrt{2}b^0 \frac{\tilde{x}_0}{\tilde{x}_{-1}}}$$
(4.35)

$$= -\frac{1}{\sqrt{2}} \frac{\sqrt{2}b^0 x^2 + (-\sqrt{2}x_0)}{(b^0)^2 x^2 + 1 + \sqrt{2}b^0 (-\sqrt{2}x_0)}$$
(4.36)

$$= \frac{-b^0 x^2 + x_0}{(b^0)^2 x^2 + 1 - 2b^0 x_0} \tag{4.37}$$

$$x_0' = \frac{x_0 - b_0 x^2}{1 - 2b^0 x_0 + (b^0)^2 x^2} \checkmark \tag{4.38}$$

hari1729@nmsu.edu 18 / 23

Transformation of x_0 and x_3 under conformal transformation

In the instant form:

Generators	x'_0	x_3'		
\mathfrak{K}_0	$x_0' = \frac{x_0 - b_0 x^2}{1 - 2b_0 x_0 + (b_0)^2 x^2}$	$x_3' = \frac{x_3}{1 - 2b_0x_0 + (b_0)^2x^2}$		
$-\mathfrak{K}_3$	$x_0' = \frac{x_0}{1 - 2b_3x_{\hat{-}} - (b_3)^2 x^2}$	$x_3' = \frac{x_3 + b_3 x^2}{1 - 2b_3 x_3 - (b_3)^2 x^2}$		
P_0	$x_0' = x_0 + a_0$	$x_3' = x_3$		
$-P_3$	$x_0' = x_0$	$x_3' = x_3 - a_3$		
D	$x_0' = e^{-\alpha} x_0$	$x_3' = e^{-\alpha} x_3$		
K^3	$x_0' = (\cosh \eta_3)x_0 - (\sinh \eta_3)x_3$	$x_3' = -(\sinh \eta_3)x_0 + (\cosh \eta_3)x_3$		

hari1729@nmsu.edu 19 / 23

Under boosts along the z-axis,

$$\begin{bmatrix} x'^0 \\ x'^3 \end{bmatrix} = \begin{bmatrix} \cosh \eta & -\sinh \eta \\ -\sinh \eta & \cosh \eta \end{bmatrix} \begin{bmatrix} x^0 \\ x^3 \end{bmatrix}$$
 (4.39)

this gives,

$$x^{\prime 0} = x^0 \cosh \eta - x^3 \sinh \eta \tag{4.40}$$

$$x^{\prime 3} = -x^0 \sinh \eta + x^3 \cosh \eta \tag{4.41}$$

then the light-front coordinates under the boost,

$$x'^{\pm} = \frac{(x'^0 \pm x'^3)}{\sqrt{2}} = \frac{((x^0 \cosh \eta - x^3 \sinh \eta)) \pm (-x^0 \sinh \eta + x^3 \cosh \eta)))}{\sqrt{2}}$$
(4.42)

$$= (\cosh \eta \mp \sinh \eta)x^{\pm} \tag{4.43}$$

$$x'^{\pm} = e^{\mp \eta} x^{\pm} \tag{4.44}$$

Thus boost along the x^3 -axis becomes a **scale transformation** for the variables x'^+ & x'^- and $x^+=0$ plane is invariant under the boost along x^3 -axis.

In IFD (1+1), we have:

Table 1: 1 + 1 conformal algebra in IFD

	P_0	\mathfrak{K}_0	D	$-P_3$	\mathfrak{K}_3	K^3
P_0	0	2iD	iP_0	0	$2iK^3$	$-iP_3$
\mathfrak{K}_0	-2iD	0	$-i\mathfrak{K}_0$	$-2iK^3$	0	$-i\mathfrak{K}_3$
D	$-iP_0$	$i\mathfrak{K}_0$	0	iP_3	$i\mathfrak{K}_3$	0
$-P_3$	0	$2iK^3$	$-iP_3$	0	2iD	iP_0
\mathfrak{K}_3	$-2iK^3$	0	$-i\mathfrak{K}_3$	-2iD	0	$-i\mathfrak{K}_0$
K^3	iP_3	$i\mathfrak{K}_3$	0	$-iP_0$	$i\mathfrak{K}_0$	0

hari1729@nmsu.edu 21 / 23

In LFD,

Table 2: 1 + 1 conformal algebra in LFD⁴

	P_{+}	\mathfrak{K}_+	D_{+}	P_	R_	D_{-}
P_+	0	$2\sqrt{2}iD_{+}$	$\sqrt{2}iP_{+}$	0	0	0
\mathfrak{K}_+	$-2\sqrt{2}iD_{+}$	0	$-\sqrt{2}i\mathfrak{K}_{+}$	0	0	0
D_+	$-\sqrt{2}iP_{+}$	$\sqrt{2}i\mathfrak{K}_{+}$	0	0	0	0
P_	0	0	0	0	$2\sqrt{2}iD_{-}$	$\sqrt{2}iP_{-}$
£_	0	0	0	$-2\sqrt{2}iD_{-}$	0	$-\sqrt{2}i\mathfrak{K}_{-}$
D_{-}	0	0	0	$-\sqrt{2}iP_{-}$	$\sqrt{2}i\mathfrak{K}_{-}$	0

where,
$$P_{\pm} = \frac{P_0 \pm P_3}{\sqrt{2}}$$
, $\mathfrak{K}_{\pm} = \frac{\mathfrak{K}_0 \mp \mathfrak{K}_3}{\sqrt{2}}$, and $D_{\pm} = \frac{D \mp K^3}{\sqrt{2}}$.

hari1729@nmsu.edu 22 / 23

⁴H. Ravikumar, Chueng Ji. to be published

We find⁵ that SO(2,2) splits into a direct sum of two identical algebras:

$$SO(2,2) \simeq SO(1,2) \oplus SO(1,2)$$
 (4.45)

Lets make two new 3×3 anti symmetric tensors, namely J_{ab}^+ and J_{ab}^- . Where, $a, b \in \{0, 1, 2\}$.

$$J_{ab}^{+} = \frac{1}{2} \begin{pmatrix} 0 & P_{+} & D - K^{3} \\ -P_{+} & 0 & \Re \\ -D + K^{3} & -\Re & 0 \end{pmatrix}_{3\times3}; \quad J_{ab}^{-} = \frac{1}{2} \begin{pmatrix} 0 & P_{-} & D + K^{3} \\ -P_{-} & 0 & \Re_{+} \\ -D - K^{3} & -\Re_{+} & 0 \end{pmatrix}_{3\times3}$$
(4.46)

and with the new metric g_{ab} ,

$$g_{ab} = \frac{1}{2} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}_{3\times3}$$
 (4.47)

they fulfill the SO(1,2) commutation relations;

$$[J_{ab}^{\pm}, J_{cd}^{\pm}] = -i \left(g_{bd} J_{ac}^{\pm} - g_{bc} J_{ad}^{\pm} + g_{ac} J_{bd}^{\pm} - g_{ad} J_{bc}^{\pm} \right); \qquad [J_{ab}^{+}, J_{cd}^{-}] = 0$$

These are perfectly consistent with the above table in the LFD limit.

hari1729@nmsu.edu 23 / 23

⁵Daniel Meise's Relations between 2D and 4D Conformal Quantum Field Theory