

The Poincaré Algebra Interpolation between Instant Form Dynamics (IFD) and Light Front Dynamics (LFD)

Dissertations External presentation

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ABSTRACT

The instant form and the front form of relativistic dynamics introduced by Dirac in 1949 can be interpolated by introducing an interpolation angle parameter δ spanning between the instant form dynamics (IFD) at $\delta = 0$ and the front form dynamics, which is now known as the light-front dynamics (LFD) at $\delta = \frac{\pi}{4}$. We present the Poincaré algebra interpolating between instant and light-front time quantizations. We show the Boost K^3 is dynamical in the region where $0 \leq \delta < \frac{\pi}{4}$ but becomes kinematic in the light-front limit ($\delta = \frac{\pi}{4}$). We show this will then be extended to Conformal algebra.

Commutations

The generators of the Poincaré group are

$$(\text{translation}) \quad P^{\hat{\mu}} = -i\partial^{\hat{\mu}} , \quad (1)$$

$$(\text{rotation}) \quad L^{\hat{\mu}\hat{\nu}} = i (x^{\hat{\mu}}\partial^{\hat{\nu}} - x^{\hat{\nu}}\partial^{\hat{\mu}}) , \quad (2)$$

Then the Poincaré algebra (commutation rules) can be derived as,

1) Commutation among P^{μ} ,

$$\begin{aligned} [P^{\mu}, P^{\nu}] &= P^{\mu}P^{\nu} - P^{\nu}P^{\mu} = i^2(\partial^{\mu}\partial^{\nu} - \partial^{\nu}\partial^{\mu}) = 0 , \\ [P^{\mu}, P^{\nu}] &= 0 \checkmark . \end{aligned} \quad (3)$$

2) Commutation among P^{ρ} and $L^{\mu\nu}$,

$$\begin{aligned} [P^{\rho}, L^{\mu\nu}] &= P^{\rho}L^{\mu\nu} - L^{\mu\nu}P^{\rho} = -i^2(\partial^{\rho}(x^{\mu}\partial^{\nu} - x^{\nu}\partial^{\mu}) - (x^{\mu}\partial^{\nu} - x^{\nu}\partial^{\mu})\partial^{\rho}) , \\ &= -i^2(\partial^{\rho}x^{\mu}\partial^{\nu} + x^{\mu}\partial^{\rho}\partial^{\nu} - \partial^{\rho}x^{\nu}\partial^{\mu} - x^{\nu}\partial^{\rho}\partial^{\mu} - x^{\mu}\partial^{\nu}\partial^{\rho} + x^{\nu}\partial^{\mu}\partial^{\rho}) , \\ &= -i^2(\partial^{\rho}x^{\mu}\partial^{\nu} - \partial^{\rho}x^{\nu}\partial^{\mu}) = i(g^{\rho\mu}(-i\partial^{\nu}) - g^{\rho\nu}(-i\partial^{\mu})) , \\ [P^{\rho}, L^{\mu\nu}] &= i(g^{\rho\mu}P^{\nu} - g^{\rho\nu}P^{\mu}) \checkmark . \end{aligned} \quad (4)$$

Commutations

3) Commutation among $L^{\mu\nu}$,

$$\begin{aligned}
 [L^{\alpha\beta}, L^{\rho\sigma}] &= L^{\alpha\beta} L^{\rho\sigma} - L^{\rho\sigma} L^{\alpha\beta} , \\
 &= i^2 \left((x^\alpha \partial^\beta - x^\beta \partial^\alpha) (x^\rho \partial^\sigma - x^\sigma \partial^\rho) - (x^\rho \partial^\sigma - x^\sigma \partial^\rho) (x^\alpha \partial^\beta - x^\beta \partial^\alpha) \right) \\
 [L^{\alpha\beta}, L^{\rho\sigma}] &= -i (g^{\beta\sigma} L^{\alpha\rho} - g^{\beta\rho} L^{\alpha\sigma} + g^{\alpha\rho} L^{\beta\sigma} - g^{\alpha\sigma} L^{\beta\rho}) \checkmark .
 \end{aligned}$$

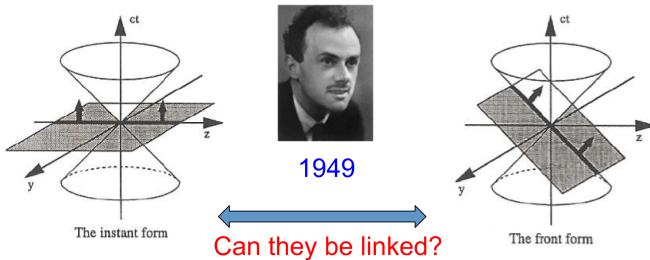
So, the Poincaré algebra are:

$$[P^\mu, P^\nu] = 0 , \tag{5}$$

$$[P^\rho, L^{\mu\hat{\nu}}] = i (g^{\rho\mu} P^\nu - g^{\rho\nu} P^\mu) , \tag{6}$$

$$[L^{\alpha\beta}, L^{\rho\sigma}] = -i (g^{\beta\sigma} L^{\alpha\rho} - g^{\beta\rho} L^{\alpha\sigma} + g^{\alpha\rho} L^{\beta\sigma} - g^{\alpha\sigma} L^{\beta\rho}) . \tag{7}$$

Dirac's Proposition



According to Dirac “ ... the three-dimensional surface in space-time formed by a plane wave front advancing with the velocity of light. Such a surface will be called *front* for brevity”. An example of a light-front is given by the equation $x^+ = x^0 + x^3 = 0$.

The variables $x^+ = \frac{x^0+x^3}{\sqrt{2}}$ and $x^- = \frac{x^0-x^3}{\sqrt{2}}$ are called light-front time and longitudinal space variables respectively. Transverse variable $x^\perp = (x^1, x^2)$. We denote the four-vector x^μ by

$$x^\mu = (x^0, x^1, x^2, x^3) = (x^0, x^\perp, x^3) . \quad (8)$$

Scalar product

$$x.y = x^+y^- + x^-y^+ - x^\perp.y^\perp. \quad (9)$$

The metric tensor is

$$g^{\mu\nu} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} , \quad (10)$$

$$g_{\mu\nu} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} . \quad (11)$$

Let us denote the three generators of boosts by K^i and the three generators of rotations by J^i in equal-time dynamics. Define $E^1 = -K^1 + J^2$, $E^2 = -K^2 - J^1$, $F^1 = -K^1 - J^2$, and $F^2 = -K^2 + J^1$. The explicit expressions for the 6 generators K^3 , E^1 , E^2 , J^3 , F^1 , and F^2 in the finite dimensional representation are

$$K^3 = -i \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, \quad E^1 = -i \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}, \quad (12)$$

$$E^2 = -i \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}, \quad J^3 = -i \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad (13)$$

$$F^1 = -i \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}, \quad F^2 = -i \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}. \quad (14)$$

Note that K^3 , E^1 , E^2 , and J^3 leave $x^+ = 0$ invariant and are kinematical generators while F^1 and F^2 do not and are dynamical generators.

From the Lagrangian density one may construct the stress tensor $T^{\mu\nu}$ and from the stress tensor one may construct a four-momentum P^μ and a generalized angular momentum $L^{\mu\nu}$.

$$P^\mu = \int dx^- d^2x^\perp T^{+\mu}, \quad (15)$$

$$L^{\mu\nu} = \int dx^- d^2x^\perp [x^\nu T^{+\mu} - x^\mu T^{+\nu}]. \quad (16)$$

Note that $L^{\mu\nu}$ is antisymmetric and hence has six independent components. Poincare algebra in terms of P^μ and $L^{\mu\nu}$ is

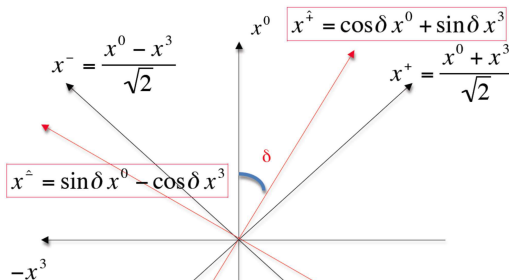
$$[P^\mu, P^\nu] = 0, \quad (17)$$

$$[P^\mu, L^{\rho\sigma}] = i[g^{\mu\rho} P^\sigma - g^{\mu\sigma} P^\rho], \quad (18)$$

$$[L^{\mu\nu}, L^{\rho\sigma}] = i[-g^{\mu\rho} L^{\nu\sigma} + g^{\mu\sigma} L^{\nu\rho} - g^{\nu\sigma} L^{\mu\rho} + g^{\nu\rho} L^{\mu\sigma}]. \quad (19)$$

In light-front dynamics P^- is the Hamiltonian and P^+ and P^i ($i = 1, 2$) are the momenta. $L^{-+} = K^3$ and $L^{+i} = E^i$ are the boosts. $L^{12} = J^3$ and $L^{-i} = F^i$ are the rotations.

Interpolation between Instant and Front Forms



K. Hornbostel, PRD45, 3781 (1992) – **RQFT**

C.Ji and S.Rey, PRD53,5815(1996) – **Chiral Anomaly**

C.Ji and C. Mitchell, PRD64,085013 (2001) – **Poincare Algebra**

C.Ji and A. Suzuki, PRD87,065015 (2013) – **Scattering Amps**

C.Ji, Z. Li and A. Suzuki, PRD91, 065020 (2015) – **EM Gauges**

Z.Li, M. An and C.Ji, PRD92, 105014 (2015) – **Spinors**

C.Ji, Z.Li, B.Ma and A.Suzuki, in prepartion – **Fermion Prop.**

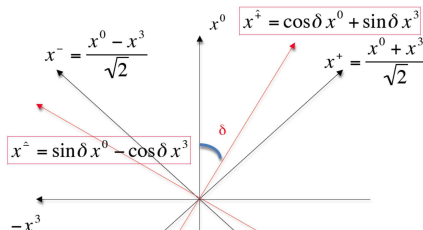
Method of Interpolation Angle

The interpolating space-time coordinates may be defined as a transformation from the ordinary space-time coordinates, $x^{\hat{\mu}} = \mathcal{R}^{\hat{\mu}}_{\nu} x^{\nu}$, i.e.

$$\begin{pmatrix} x^{\hat{+}} \\ x^{\hat{1}} \\ x^{\hat{2}} \\ x^{\hat{-}} \end{pmatrix} = \begin{pmatrix} \cos \delta & 0 & 0 & \sin \delta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sin \delta & 0 & 0 & -\cos \delta \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}, \quad (20)$$

in which the interpolation angle is allowed to run from 0 through 45° , $0 \leq \delta \leq \frac{\pi}{4}$.

Interpolation between Instant and Front Forms



Method of Interpolation Angle

In this interpolating basis, the metric becomes

$$g^{\hat{\mu}\hat{\nu}} = g_{\hat{\mu}\hat{\nu}} = \begin{pmatrix} \mathbb{C} & 0 & 0 & \mathbb{S} \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ \mathbb{S} & 0 & 0 & -\mathbb{C} \end{pmatrix}, \quad (21)$$

where $\mathbb{S} = \sin 2\delta$ and $\mathbb{C} = \cos 2\delta$.

The Poincaré matrix

$$M^{\mu\nu} = \begin{pmatrix} 0 & K^1 & K^2 & K^3 \\ -K^1 & 0 & J^3 & -J^2 \\ -K^2 & -J^3 & 0 & J^1 \\ -K^3 & J^2 & -J^1 & 0 \end{pmatrix} \quad (22)$$

transforms as well, so that

$$M^{\hat{\mu}\hat{\nu}} = \begin{pmatrix} 0 & E^{\hat{1}} & E^{\hat{2}} & -K^3 \\ -E^{\hat{1}} & 0 & J^3 & -F^{\hat{1}} \\ -E^{\hat{2}} & -J^3 & 0 & -F^{\hat{2}} \\ K^3 & F^{\hat{1}} & F^{\hat{2}} & 0 \end{pmatrix} \quad (23)$$

where

$$\begin{aligned} E^{\hat{1}} &= J^2 \sin \delta + K^1 \cos \delta, \\ E^{\hat{2}} &= K^2 \cos \delta - J^1 \sin \delta, \\ F^{\hat{1}} &= K^1 \sin \delta - J^2 \cos \delta, \\ F^{\hat{2}} &= K^2 \sin \delta + J^1 \cos \delta. \end{aligned} \quad (24)$$

The Poincaré matrix

$$M_{\hat{\mu}\hat{\nu}} = g_{\hat{\mu}\hat{\alpha}} M^{\hat{\alpha}\hat{\beta}} g_{\hat{\beta}\hat{\nu}} = \begin{pmatrix} 0 & \mathcal{D}^{\hat{1}} & \mathcal{D}^{\hat{2}} & K^3 \\ -\mathcal{D}^{\hat{1}} & 0 & J^3 & -\mathcal{K}^{\hat{1}} \\ -\mathcal{D}^{\hat{2}} & -J^3 & 0 & -\mathcal{K}^{\hat{2}} \\ -K^3 & \mathcal{K}^{\hat{1}} & \mathcal{K}^{\hat{2}} & 0 \end{pmatrix}, \quad (25)$$

where

$$\begin{aligned} \mathcal{K}^{\hat{1}} &= -K^1 \sin \delta - J^2 \cos \delta, \\ \mathcal{K}^{\hat{2}} &= J^1 \cos \delta - K^2 \sin \delta, \\ \mathcal{D}^{\hat{1}} &= -K^1 \cos \delta + J^2 \sin \delta, \\ \mathcal{D}^{\hat{2}} &= -J^1 \sin \delta - K^2 \cos \delta. \end{aligned} \quad (26)$$

Generators of Poincaré group

$$(\text{translation}) \quad P^{\hat{\mu}} = -i\partial^{\hat{\mu}}, \quad (27)$$

$$(\text{rotation}) \quad L^{\hat{\mu}\hat{\nu}} = i(x^{\hat{\mu}}\partial^{\hat{\nu}} - x^{\hat{\nu}}\partial^{\hat{\mu}}). \quad (28)$$

In the interpolating basis, the metric becomes

$$g^{\hat{\mu}\hat{\nu}} = g_{\hat{\mu}\hat{\nu}} = \begin{pmatrix} \mathbb{C} & 0 & 0 & \mathbb{S} \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ \mathbb{S} & 0 & 0 & -\mathbb{C} \end{pmatrix}, \quad (29)$$

The Poincaré algebra (Contra-variant form) in this interpolating basis is given by

$$[P^{\hat{\mu}}, P^{\hat{\nu}}] = 0, \quad (30a)$$

$$[P^{\hat{\rho}}, L^{\hat{\mu}\hat{\nu}}] = i(g^{\hat{\rho}\hat{\mu}}P^{\hat{\nu}} - g^{\hat{\rho}\hat{\nu}}P^{\hat{\mu}}), \quad (30b)$$

$$[L^{\hat{\alpha}\hat{\beta}}, L^{\hat{\rho}\hat{\sigma}}] = -i(g^{\hat{\beta}\hat{\sigma}}L^{\hat{\alpha}\hat{\rho}} - g^{\hat{\beta}\hat{\rho}}L^{\hat{\alpha}\hat{\sigma}} + g^{\hat{\alpha}\hat{\rho}}L^{\hat{\beta}\hat{\sigma}} - g^{\hat{\alpha}\hat{\sigma}}L^{\hat{\beta}\hat{\rho}}). \quad (30c)$$

A comprehensive table of the 45 commutation relations among the co-variant components of the Poincaré' generators is presented below:

	P_+	P_+	P_+	K^3	\mathcal{D}^1	\mathcal{D}^2	J^3	\mathcal{K}^1	\mathcal{K}^2	P_-
P_+	0	0	0	$i(CP_- - SP_+)$	iCP_+	iCP_+	0	iSP_+	iSP_+	0
P_+	0	0	0	0	iP_+	0	$-iP_+$	iP_-	0	0
P_+	0	0	0	0	0	iP_+	iP_+	0	iP_-	0
K^3	$-i(CP_- - SP_+)$	0	0	0	$iSD^1 - iCK^1$	$iSD^2 - iCK^2$	0	$-iSK^1 - iCD^1$	$-iSK^2 - iCD^2$	$-i(SP_- + CP_+)$
\mathcal{D}^1	$-iCP_+$	$-iP_+$	0	$-iSD^1 + iCK^1$	0	$-iCJ^3$	$-iD^2$	$-iK^3$	$-iSJ^3$	$-iSP_+$
\mathcal{D}^2	$-iCP_+$	0	$-iP_+$	$-iSD^2 + iCK^2$	iCJ^3	0	iD^1	iSJ^3	$-iK^3$	$-iSP_+$
J^3	0	iP_+	$-iP_+$	0	iD^2	$-iD^1$	0	iK^2	$-iK^1$	0
\mathcal{K}^1	$-iSP_+$	$-iP_-$	0	$iSK^1 + iCD^1$	iK^3	$-iSJ^3$	$-iK^2$	0	iCJ^3	iCP_+
\mathcal{K}^2	$-iSP_+$	0	$-iP_-$	$iSK^2 + iCD^2$	iSJ^3	iK^3	iK^1	$-iCJ^3$	0	iCP_+
P_-	0	0	0	$i(SP_- + CP_+)$	iSP_+	iSP_+	0	$-iCP_+$	$-iCP_+$	0

Interpolation angle	Kinematic	Dynamic
$\delta = 0$	$\mathcal{K}^1 = -J^2, \mathcal{K}^2 = J^1, J^3, P^1, P^2, P^3$	$\mathcal{D}^1 = -K^1, \mathcal{D}^2 = -K^2, K^3, P^0$
$0 \leq \delta < \pi/4$	$\mathcal{K}^1, \mathcal{K}^2, J^3, P^1, P^2, P_-$	$\mathcal{D}^1, \mathcal{D}^2, K^3, P_+$
$\delta = \pi/4$	$\mathcal{K}^1 = -E^1, \mathcal{K}^2 = -E^2, J^3, K^3, P^1, P^2, P_-$	$\mathcal{D}^1 = -F^1, \mathcal{D}^2 = -F^2, P_+$

Chueng-Ryong Ji and Chad Mitchell, Phys. Rev. **D 64**, 085013 (2001).

Chueng-Ryong Ji, Ziyue Li, and Alfredo Takashi Suzuki, Phys. Rev. **D 91**, 065020 (2015).

IFD

The following table summarizes the commutation relations (contra-variant form) between the Poincare generators explicitly in Instant Form Dynamics (IFD) (when interpolation angle, $\delta = 0$),

	P^0	P^1	P^2	$-K^3$	K^1	K^2	J^3	J^2	$-J^1$	P^3
P^0	0	0	0	iP_3	iP^1	iP^2	0	0	0	0
P^1	0	0	0	0	iP_0	0	$-iP^2$	$-iP_3$	0	0
P^2	0	0	0	0	0	iP_0	iP^1	0	$-iP_3$	0
$-K^3$	$-iP_3$	0	0	0	iJ^2	$-iJ^1$	0	iK^1	iK^2	iP_0
K^1	$-iP^1$	$-iP_0$	0	$-iJ^2$	0	$-iJ^3$	$-iK^2$	iK^3	0	0
K^2	$-iP^2$	0	$-iP_0$	iJ^1	iJ^3	0	iK^1	0	iK^3	0
J^3	0	iP^2	$-iP^1$	0	iK^2	$-iK^1$	0	$-iJ^1$	$-iJ^2$	0
J^2	0	iP_3	0	$-iK^1$	$-iK^3$	0	iJ^1	0	iJ^3	iP^1
$-J^1$	0	0	$+iP_3$	$-iK^2$	0	$-iK^3$	iJ^2	$-iJ^3$	0	iP^2
P^3	0	0	0	$-iP_0$	0	0	0	$-iP^1$	$-iP^2$	0

LFD

The following table summarizes the commutation relations (contra-variant form) between the Poincare generators explicitly in Light-Front Dynamics (LFD) (when interpolation angle, $\delta = \frac{\pi}{4}$),

	P^+	P^1	P^2	K^3	E^1	E^2	J^3	F^1	F^2	P^-
P^+	0	0	0	iP_-	0	0	0	iP^1	iP^2	0
P^1	0	0	0	0	iP_-	0	$-iP^2$	iP_+	0	
P^2	0	0	0	0	0	iP_-	iP^1	0	iP_+	0
K^3	$-iP_-$	0	0	0	$-iE^1$	$-iE^2$	0	iF^1	iF^2	iP_+
E^1	0	$-iP_-$	0	iE^1	0	0	$-iE^2$	$-iK^3$	$-iJ^3$	$-iP^1$
E^2	0	0	$-iP_-$	iE^2	0	0	iE^1	iJ^3	$-iK^3$	$-iP^2$
J^3	0	iP^2	$-iP^1$	0	iE^2	$-iE^1$	0	iF^2	$-iF^1$	0
F^1	$-iP^1$	$-iP_+$	0	$-iF^1$	iK^3	$-iJ^3$	$-iF^2$	0	0	0
F^2	$-iP^2$	0	$-iP_+$	$-iF^2$	iJ^3	iK^3	iF^1	0	0	0
P^-	0	0	0	$-iP_+$	iP^1	iP^2	0	0	0	0

Kinematic and dynamic generators for different interpolation angles (Phys. Rev. **D 64**, 085013 (2001); Phys. Rev. **D 91**, 065020 (2015))

Interpolation angle	Kinematic	Dynamic
$\delta = 0$	$\mathcal{K}^{\hat{1}} = -J^2, \mathcal{K}^{\hat{2}} = J^1, J^3, P^1, P^2, P^3$	$\mathcal{D}^{\hat{1}} = -K^1, \mathcal{D}^{\hat{2}} = -K^2, K^3, P^0$
$0 \leq \delta < \pi/4$	$\mathcal{K}^{\hat{1}}, \mathcal{K}^{\hat{2}}, J^3, P^1, P^2, P_{\hat{\perp}}$	$\mathcal{D}^{\hat{1}}, \mathcal{D}^{\hat{2}}, K^3, P_{\hat{\perp}}$
$\delta = \pi/4$	$\mathcal{K}^{\hat{1}} = -E^1, \mathcal{K}^{\hat{2}} = -E^2, J^3, K^3, P^1, P^2, P_{\hat{\perp}}$	$\mathcal{D}^{\hat{1}} = -F^1, \mathcal{D}^{\hat{2}} = -F^2, P_{\hat{\perp}}$

- Among the ten Poincaré generators, the six generators $(\mathcal{K}^{\hat{1}}, \mathcal{K}^{\hat{2}}, J^3, P_1, P_2, P_{\hat{\perp}})$ are always kinematic in the sense that the $x^{\hat{\perp}} = 0$ plane is intact under the transformations generated by them. The operator $K^3 = M_{\hat{\perp}\hat{\perp}}$ is dynamical in the region where $0 \leq \delta < \pi/4$ but becomes kinematic in the light-front limit ($\delta = \pi/4$).
- To understand this, note that $[P^{\hat{\perp}}, K^{\hat{3}}] = i(\mathbb{S}P^{\hat{\perp}} - \mathbb{C}P^{\hat{\perp}}) \rightarrow iP^{\hat{\perp}}$ as $\delta \rightarrow \pi/4$. Similarly we have $[x^{\hat{\perp}}, L^{\hat{\perp}\hat{\perp}}] = i(\mathbb{S}x^{\hat{\perp}} - \mathbb{C}x^{\hat{\perp}}) \rightarrow ix^{\hat{\perp}}$ as $\delta \rightarrow \pi/4$. Therefore the instant defined by $x^+ = 0$ becomes invariant under longitudinal boosts as we move to the light front.

Conformal Transformations

The Conformal transformation $x \mapsto x'$ can be defined by,

$$\frac{\partial x'^{\alpha}}{\partial x^{\mu}} \frac{\partial x'^{\beta}}{\partial x^{\nu}} g'_{\alpha\beta} = F(x) g_{\mu\nu} \quad (31)$$

Consider an infinitesimal translation,

$$x'^{\mu} = x^{\mu} + \epsilon^{\mu}(x) . \quad (32)$$

The metric changes by,

$$\delta g_{\mu\nu} = \frac{\partial \epsilon_{\mu}}{\partial x^{\nu}} + \frac{\partial \epsilon_{\nu}}{\partial x^{\mu}} = \partial_{\mu} \epsilon_{\nu}(x) + \partial_{\nu} \epsilon_{\mu}(x) \quad (33)$$

Conformality then requires,

$$\boxed{\partial_{\mu} \epsilon_{\nu}(x) + \partial_{\nu} \epsilon_{\mu}(x) = F(x) \delta_{\mu\nu}} \quad \text{Conformal Killing Equation} \quad (34)$$

contraction with $\delta^{\mu\nu}$ yields

$$2 \partial^{\mu} \epsilon_{\mu} = F(x) d \quad (35)$$

$$\implies F(x) = \frac{2}{d} \partial_{\mu} \epsilon^{\mu} \quad (36)$$

Conformal Transformations

For $d \geq 3$, there are ONLY 4 classes of solutions for $\epsilon_\mu(x)$

$$(\text{Infinitesimal Translation}) \quad \epsilon^\mu(x) = a^\mu \quad (\text{constant}) \quad (37)$$

$$(\text{Infinitesimal Rotation}) \quad \epsilon^\mu(x) = L^\mu{}_\nu x^\nu \quad (38)$$

$$(\text{Infinitesimal Scaling}) \quad \epsilon^\mu(x) = \lambda x^\mu \quad (39)$$

$$(\text{Infinitesimal SCT}) \quad \epsilon^\mu(x) = 2(b \cdot x)x^\mu - x^2 b^\mu \quad (40)$$

The generators of conformal transformations are:

$$(\text{translation}) \quad P^\mu = -i\partial^\mu ,$$

$$(\text{dilation}) \quad D = -ix_\mu \partial^\mu ,$$

$$(\text{rotation}) \quad L^{\mu\nu} = i(x^\mu \partial^\nu - x^\nu \partial^\mu) ,$$

$$(\text{SCT}) \quad \mathcal{K}^\mu = -i(2x^\mu x_\nu \partial^\nu - x^2 \partial^\mu) .$$

Conformal algebra

the full Conformal algebra is given by

$$[P^\mu, P^\nu] = 0,$$

$$[\mathfrak{K}^\mu, \mathfrak{K}^\nu] = 0,$$

$$[D, P^\mu] = iP^\mu,$$

$$[D, \mathfrak{K}^\mu] = -i\mathfrak{K}^\mu,$$

$$[P^\rho, L^{\mu\hat{\nu}}] = i(g^{\rho\mu}P^\nu - g^{\rho\nu}P^\mu),$$

$$[\mathfrak{K}^\rho, L^{\mu\nu}] = i(g^{\rho\mu}\mathfrak{K}^\nu - g^{\rho\nu}\mathfrak{K}^\mu),$$

$$[L^{\alpha\beta}, L^{\rho\sigma}] = -i(g^{\beta\sigma}L^{\alpha\rho} - g^{\beta\rho}L^{\alpha\sigma} + g^{\alpha\rho}L^{\beta\sigma} - g^{\alpha\sigma}L^{\beta\rho}),$$

$$[\mathfrak{K}^\mu, P^\nu] = 2i(g^{\mu\nu}D - L^{\mu\nu}),$$

$$[D, L^{\mu\nu}] = 0.$$

Conclusion & Future Scope

We presented the Poincaré algebra in Interpolation form. We showed the Boost K^3 is dynamical in the region where $0 \leq \delta < \frac{\pi}{4}$ but becomes kinematic in the light-front limit ($\delta = \frac{\pi}{4}$).

Then, we formally developed the Conformal algebra and showed that the set of conformal transformations manifestly forms a group, and it has the Poincaré group as a subgroup. Our future work is to extend the Interpolation method to Conformal algebra.

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