Engineering Electromagnetics

Lecture 8

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by

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Example 1.13. Find the volume of a sphere of radius *R*. **Solution**

$$V = \int d\tau = \int_{r=0}^{R} \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} r^2 \sin\theta \, dr \, d\theta \, d\phi$$
$$= \left(\int_{0}^{R} r^2 \, dr\right) \left(\int_{0}^{\pi} \sin\theta \, d\theta\right) \left(\int_{0}^{2\pi} d\phi\right)$$
$$= \left(\frac{R^3}{3}\right) (2)(2\pi) = \frac{4}{3}\pi R^3$$

Problem-2

Show that over the closed surface of a sphere of radius $b \cdot \oint d\vec{s} = 0$.

EXAMPLE 2.14

Show that over the closed surface of a sphere of radius b, $\oint ds = 0$.

Solution

The outward unit normal to the surface of a sphere of radius b is in the direction of the unit vector \vec{a}_r , as shown in Figure 2.25. Therefore,

$$\oint_{s} d\vec{s} = \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \vec{a}_{r} b^{2} \sin \theta \, d\theta \, d\phi$$

Because the unit vector \vec{a}_r is a function of both θ and ϕ , we must express it in terms of unit vectors in the rectangular coordinate system before integrating. From equation (2.43a,b) we have $\vec{a}_r = \sin \theta \cos \phi \vec{a}_x + \sin \theta \sin \phi \vec{a}_y + \cos \theta \vec{a}_z$. Thus,

$$\oint_{s} d\vec{s} = \vec{a}_{x}b^{2} \int_{0}^{\pi} \sin^{2}\theta \, d\theta \int_{0}^{2\pi} \cos\phi \, d\phi + \vec{a}_{y}b^{2} \int_{0}^{\pi} \sin^{2}\theta \, d\theta$$

$$\times \int_{0}^{2\pi} \sin\phi \, d\phi + \vec{a}_{z}b^{2} \int_{0}^{\pi} \sin\theta \cos\theta \, d\theta \int_{0}^{2\pi} d\phi$$

$$= 0$$

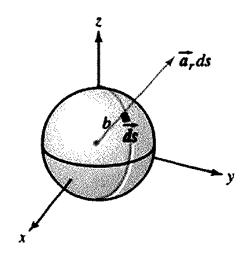


Figure 2.25

Problem-3

The electron density distribution within a spherical volume with radius of 2 meters is given as $n_e = (1000/r)\cos(\phi/4)$ electrons/meter³. Find the charge enclosed if the charge on an electron is -1.6×10^{-19} coulomb.

EXAMPLE 2.16

The electron density distribution within a spherical volume with radius of 2 meters is given as $n_e = (1000/r)\cos(\phi/4)$ electrons/meter³. Find the charge enclosed if the charge on an electron is -1.6×10^{-19} coulomb.

Solution

Let N be the number of electrons in the region bounded by a sphere of 2-meter radius; then

$$N = \int_{v} n_{e} dv = \int_{v} \frac{1000}{r} \cos(\phi/4) dv$$

$$= \int_{0}^{2} \frac{1000}{r} r^{2} dr \int_{0}^{\pi} \sin\theta d\theta \int_{0}^{2\pi} \cos(\phi/4) d\phi$$
= 16,000 electrons

Thus, the total charge enclosed is $Q = 16,000(-1.6 \times 10^{-19}) = -2.56 \times 10^{-15}$ coulomb.

"Ordinary" Derivatives

- Suppose we have a function of one variable: f (x).
- Question: What does the derivative, df/dx, do for us? Answer: It tells us how rapidly the function f (x) varies when we change the argument x by a tiny amount, dx:
- If we increment x by an infinitesimal amount dx, then f changes by an amount df; the derivative is the proportionality factor.

$$df = \left(\frac{df}{dx}\right)dx$$

► The derivative $df/dx \rightarrow slope$ of the graph of f versus x.

Gradient

- Suppose, now, that we have a function of three variables \rightarrow T (x, y, z)
- "How fast does T vary?"

$$dT = \left(\frac{\partial T}{\partial x}\right) dx + \left(\frac{\partial T}{\partial y}\right) dy + \left(\frac{\partial T}{\partial z}\right) dz$$

$$dT = \left(\frac{\partial T}{\partial x}\hat{\mathbf{x}} + \frac{\partial T}{\partial y}\hat{\mathbf{y}} + \frac{\partial T}{\partial z}\hat{\mathbf{z}}\right) \cdot (dx\,\hat{\mathbf{x}} + dy\,\hat{\mathbf{y}} + dz\,\hat{\mathbf{z}})$$
$$= (\nabla T) \cdot (d\mathbf{l}), \quad d\mathbf{l} = dx\,\hat{\mathbf{x}} + dy\,\hat{\mathbf{y}} + dz\,\hat{\mathbf{z}}$$

$$\nabla T \equiv \frac{\partial T}{\partial x} \hat{\mathbf{x}} + \frac{\partial T}{\partial y} \hat{\mathbf{y}} + \frac{\partial T}{\partial z} \hat{\mathbf{z}}$$

This tells us how *T* changes when we alter all three variables by the infinitesimal amounts *dx*, *dy*, *dz*. Notice that we do *not* require an infinite number of derivatives—*three* will suffice: the *partial* derivatives along each of the three coordinate directions.

Geometrical interpretation

- Like any vector, the gradient has magnitude and direction.
- where θ is the angle between ∇T and $d\mathbf{l}$
- ► To determine its geometrical meaning $\Rightarrow dT = \nabla T \cdot d\mathbf{l} = |\nabla T||d\mathbf{l}|\cos\theta$
- Now, if we fix the magnitude |dl| and search around in various directions (that is, vary θ), the maximum change in T is when?
- for a fixed distance |dI|, dT is greatest when I move in the same direction as ∇T .
- ► The gradient **VT** points in the direction of maximum increase of the function T
- ► The magnitude | **VT** | gives the slope (rate of increase) along this maximal direction
- Gradient tells you how much something changes as you move from one point to another (such as the pressure in a stream). The gradient is the multidimensional rate of change of a particular function.*
- Q: What would it mean for the gradient to vanish?

•
$$f(x, y, z) = x^2 + y^3 + z^4$$
 at a point (2,1,0)

$$\nabla T \equiv \frac{\partial T}{\partial x} \hat{\mathbf{x}} + \frac{\partial T}{\partial y} \hat{\mathbf{y}} + \frac{\partial T}{\partial z} \hat{\mathbf{z}}$$

Geometrical interpretation

Gradient tells you how much something changes as you move from one point to another (such as the pressure in a stream). The gradient is the multidimensional rate of change of a particular function.*

 $\Rightarrow dT = \nabla T \cdot d\mathbf{l} = |\nabla T||d\mathbf{l}|\cos\theta$ where θ is the angle between ∇T and $d\mathbf{l}$

$$\nabla T \equiv \frac{\partial T}{\partial x} \hat{\mathbf{x}} + \frac{\partial T}{\partial y} \hat{\mathbf{y}} + \frac{\partial T}{\partial z} \hat{\mathbf{z}}$$

Q: $f(x, y, z) = x^2 + y^3 + z^4$ find ∇f at a point (2,1,0)

Q: $f(x, y, z) = x^2 + y^2 + z^2$ find ∇f at (1,1,1)

Solutions

- $f(x, y, z) = x^2 + y^3 + z^4$ at a point (2,1,0)
- $\nabla f = \frac{\partial f}{\partial x}\hat{x} + \frac{\partial f}{\partial y}\hat{y} + \frac{\partial f}{\partial z}\hat{z} = 2x \hat{x} + 3y^2\hat{y} + 4z^3\hat{z} = 4\hat{x} + 3\hat{y}$
- $f(x, y, z) = x^2 + y^2 + z^2$ at (1,1,1)

Dot product

$$\nabla = \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}.$$

From the definition of ∇ we construct the divergence:

$$\nabla \cdot \mathbf{v} = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}\right) \cdot (v_x \hat{\mathbf{x}} + v_y \hat{\mathbf{y}} + v_z \hat{\mathbf{z}})$$

$$= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}.$$
Vector or scalar?

Examples

$$If \mathbf{v} = x\hat{x} + y\hat{y} - \hat{z} , \nabla \cdot \mathbf{v} = ?$$

If
$$\mathbf{v} = 2\hat{y}$$
, $\nabla \cdot \mathbf{v} = ?$

$$If \mathbf{v} = x^2 \hat{x}, \nabla \cdot \mathbf{v} = ?$$

$$\nabla = \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}.$$

Thank You