Tutorial -2 Signals and Systems

1. Compute and plot y[n] = x[n] * h[n], where

a.
$$x[n] = \begin{cases} 1,3 \le n \le 8 \\ 0, otherwise \end{cases}$$
 and $h[n] = \begin{cases} 1,4 \le n \le 15 \\ 0, otherwise \end{cases}$

b.
$$x[n] = \left(\frac{1}{3}\right)^{-n} u[-n-1]$$
 and $h[n] = u[n-1]$

c.
$$x[n] = \left(\frac{1}{2}\right)^{n-2}u[n-2]$$
 and $h[n] = u[n+2]$

2. Let $x[n] = \begin{cases} 1,0 \le n \le 9 \\ 0, otherwise \end{cases}$ and $h[n] = \begin{cases} 1,0 \le n \le N \\ 0, otherwise \end{cases}$ where $N \le 9$ is an integer.

Determine the value of N given that y[n] = x[n] * h[n] and y[4] = 5 and y[14] = 0.

3. Compute y(t) = x(t) * h(t)

a.
$$x(t) = u(t-3) - u(t-5)$$
 and $h(t) = e^{-3t}u(t)$

b.
$$x(t) = \begin{cases} 1, 0 \le t \le 1 \\ 0, otherwise \end{cases}$$
 and $h(t) = x(t/\alpha)$, where $0 < \alpha \le 1$

4. The following are the impulse responses of discrete-time LTI systems. Determine whether each system is causal and/or stable. Justify your answers.

a.
$$h[n] = (\frac{1}{3})^n u[n]$$

b.
$$h[n] = (5)^n u[3 - n]$$

c.
$$h[n] = \left(-\frac{1}{2}\right)^n u[n] + \left(1.01\right)^n u[1-n]$$

d.
$$h[n] = n(\frac{1}{3})^n u[n-1]$$

5. Which of the following impulse responses correspond(s) to stable LTI systems?

a.
$$h(t) = e^{-(1-2j)t}u(t)$$

b.
$$h(t) = e^{-t} \cos(2t)u(t)$$

c.
$$h[n] = ncos(\frac{\pi}{4}n)u[n]$$

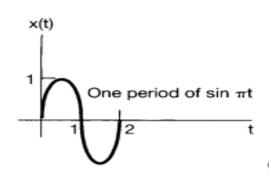
d.
$$h[n] = 3^n u[-n + 10]$$

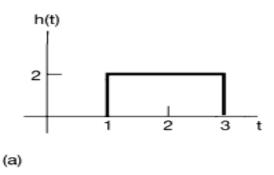
6. Consider an LTI system whose input x(t) and output y(t) are related by the differential equation

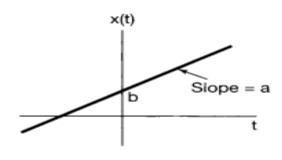
$$\frac{d}{dt}y(t) + 4y(t) = x(t)$$

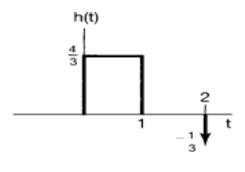
The system also satisfies the condition of initial rest. If $x(t) = e^{(-1+3j)t}u(t)$, what is y(t)?

7. For each of the following pairs of waveforms, use the convolution integral to find the response y(t) of the LTI system with impulse response h(t) to the input x(t). Sketch your results.

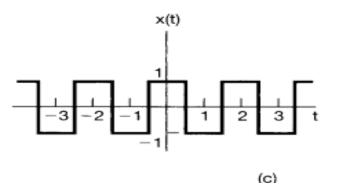


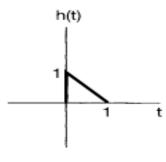






(b)





8. Consider a causal LTI system whose input x[n] and output y[n] are related by the difference equation $y[n] = \frac{1}{4}y[n-1] + x[n]$. Determine y[n] if $x[n] = \delta[n-1]$.

9. Suppose that the signal x(t)=u(t+0.5)-u(t-0.5) is convolved with the signal $h(t)=e^{j\omega_0t}$. Determine a value of ω_0 which ensures that y(0)=0.

10. If $x_1[n] = (0.5)^n u[n]$, $x_2[n] = u[n+3]$ and $x_3[n] = \delta[n] - \delta[n-1]$

a. Evaluate $(x_1[n] * x_2[n]) * x_3[n]$

b. Evaluate $x_1[n] \ ^* \ (x_2[n] \ ^* \ x_3[n])$