

$$\left[\begin{array}{ccccc} 2 & \frac{3}{4} & -1 & -1 & 0 \\ 0 & \frac{7}{24} & \frac{1}{2} & \frac{1}{2} & -1 \\ 0 & \frac{21}{8} & \frac{3}{2} & \frac{3}{2} & -3 \end{array} \right]$$

$$R_3 \rightarrow R_3 - 9R_2$$

$$\left[\begin{array}{ccccc} 2 & \frac{3}{4} & -1 & -1 & 0 \\ 0 & \frac{7}{24} & \frac{1}{2} & \frac{1}{2} & -1 \\ 0 & 0 & -3 & -3 & 6 \end{array} \right]$$

$$R_1 \rightarrow R_1 / 2$$

$$R_2 \rightarrow R_2 / (\frac{7}{24})$$

$$R_3 \rightarrow R_3 / (-3)$$

$$\left[\begin{array}{ccccc} 1 & \frac{3}{8} & -\frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & 1 & \frac{12}{7} & \frac{12}{7} & -\frac{24}{7} \\ 0 & 0 & 1 & +1 & -2 \end{array} \right]$$

$$R_2 \rightarrow R_2 - \frac{12}{7} \cdot R_3$$

$$R_1 \rightarrow R_1 + \frac{1}{2} \cdot R_3$$

$$\left[\begin{array}{ccccc} 1 & \frac{3}{8} & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & -2 \end{array} \right]$$

$$R_1 \rightarrow R_1 - \frac{3}{8} \cdot R_2$$

$$\left[\begin{array}{ccccc} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & -2 \end{array} \right]$$

\Leftarrow Row-Reduced Echelon Form
of A.

ASSIGNMENT - 1
 (MA1002)

① Given:

$$W = \left\{ (x_1, x_2, x_3, x_4, x_5) \in \mathbb{R}^5 \mid \begin{array}{l} (2x_1 + \frac{3}{4}x_2 - x_3 - x_4 = 0), \\ ((x_1 + \frac{2}{3}x_2 - x_5) = 0) \quad \& \\ (9x_1 + 6x_2 - 3x_3 - 3x_4 - 3x_5 = 0) \end{array} \right.$$

To find:

Finite set, 'S', S.T. $\text{span}(S) = W$

Solution:

Given equations are :

$$2x_1 + \frac{3}{4}x_2 - x_3 - x_4 + 0 \cdot x_5 = 0$$

$$x_1 + \frac{2}{3}x_2 + 0 \cdot x_3 + 0 \cdot x_4 - x_5 = 0$$

$$9x_1 + 6x_2 - 3x_3 - 3x_4 - 3x_5 = 0$$

Writing this in the form $AX = 0$

$$\begin{bmatrix} 2 & \frac{3}{4} & -1 & -1 & 0 \\ 1 & \frac{2}{3} & 0 & 0 & -1 \\ 9 & 6 & -3 & -3 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Converting $AX = 0$ into its Row reduced Echelon form

$$\begin{bmatrix} 2 & \frac{3}{4} & -1 & -1 & 0 \\ 1 & \frac{2}{3} & 0 & 0 & -1 \\ 9 & 6 & -3 & -3 & -3 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - \frac{1}{2} \cdot R_1$$

$$\begin{bmatrix} 2 & \frac{3}{4} & -1 & -1 & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & -1 \\ 9 & 6 & -3 & -3 & -3 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - \frac{9}{2} \cdot R_1$$

② Given:

$$A, B \in F^{m \times n}$$

R is the row-reduced echelon form of Matrix A

To prove / disprove:

Non-zero vectors of R form a basis for the row space of A.

Proof:

$$\text{Let } S = \{r_i \in R \mid r_i \neq 0, i \in \{1, 2, \dots, m\}, r_i \rightarrow \text{row of } R\}$$

Let $|S| = n$, i.e. no. of non-zero rows of R = n

As we know,

Row space of A (R.S(A)) is the subspace spanned by the rows of A.

For S to be a basis of R.S(A), it must satisfy:

(a) Linear Independent set

(b) Span(S) = R.S(A)

(a) To prove: S → linearly Independent set

$$S = \{r_1, r_2, \dots, r_n\}; n \rightarrow \text{no. of non-zero rows in } R$$

As we know, for a row-reduced echelon form:

(i) First non-zero entry of each non-zero row of R is 1.

(ii) Each column of R containing leading non-zero entry of some row has all entries as 0.

Consider $c_1 r_1 + c_2 r_2 + \dots + c_n r_n = 0, c_i \in \mathbb{R}$

as each c_i has a unique column in which it has a leading 1, the corresponding column in the RHS vector would result in a non-zero ~~extra~~ value.

$$\therefore c_1 = c_2 = c_3 = \dots = c_n = 0 \quad [\because \forall r_i \in S]$$

$\therefore r_1, r_2, r_3, \dots, r_n$ are linearly independent.

Now,

$$\left[\begin{array}{ccccc} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & -2 \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{array} \right] = \left[\begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right]$$

By observation, (Leading 1)

x_1, x_2 and x_3 are pivot variables &
 x_4 and x_5 are free variables

$$\therefore x_1 - x_5 = 0 \quad \text{---(1)}$$

$$x_2 = 0 \quad \text{---(2)}$$

$$x_3 + x_4 - 2x_5 = 0 \quad \text{---(3)}$$

By Solving (1), (2) and (3) :

$$\boxed{x_1 = x_5}$$

$$\boxed{x_2 = 0}$$

$$\boxed{x_3 + x_4 = 2x_5}$$

Let $x_4 = a$ and $x_5 = b$

$$\therefore x_1 = x_5 = b$$

$$x_2 = 0$$

$$x_3 = 2x_5 - x_4$$

$$= 2b - a$$

$$x_4 = a$$

$$x_5 = b$$

$$\left\{ \begin{array}{l} x_1 = b \\ x_2 = 0 \\ x_3 = 2b - a \\ x_4 = a \\ x_5 = b \end{array} \right. \Rightarrow \left[\begin{array}{c} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{array} \right] = \left[\begin{array}{c} b \\ 0 \\ 2b - a \\ a \\ b \end{array} \right]$$

$$\therefore W = \{ (a, 0, 2a-b, b, a) \mid a, b \in \mathbb{R} \}$$

$$= \{ a(1, 0, 2, 0, 1) + b(0, 0, -1, 1, 0) \}$$

$$W = \text{span of } \{ (1, 0, 2, 0, 1), (0, 0, -1, 1, 0) \}$$

$$\boxed{\therefore S = \{ (1, 0, 2, 0, 1), (0, 0, -1, 1, 0) \}}$$

(b) $\text{span}(S) = R.S(A)$

(i) $\text{Span}(S) \subseteq R.S(A)$

Let $x \in \text{span}(S)$

$\Rightarrow x \in L(S)$, As $\text{span}(S) = L(S)$

$\Rightarrow x = c_1 r_1 + c_2 r_2 + \dots + c_n r_n$, $c_i \in F$ & $r_i \in S$

$\Rightarrow x \rightarrow \text{Linear combination of rows of } A$

$\Rightarrow x \in R.S(A)$

$\Rightarrow \text{span}(S) \subseteq R.S(A)$

Hence Proved.

(ii) $R.S(A) \subseteq \text{span}(S)$

Let $x \in R.S(A)$

$\Rightarrow x = d_1 A_1 + d_2 A_2 + \dots + d_m A_m$, $A_i \in \text{row of } A$, $d_i \in F$

$\Rightarrow x$ is a linear combination of rows of R

$\Rightarrow x \in \text{span}(S)$

$\Rightarrow R.S(A) \subseteq \text{span}(S)$

from (i) and (ii) $\Rightarrow R.S(A) = \text{span}(S)$

From (a) and (b) \rightarrow Proved

R forms a basis for $R.S(A)$.

③ Given:

$$\{(1, 2, 3, 4), (4, 3, 2, 1)\} \subseteq B_{\mathbb{R}^4}$$

To find:

Basis of \mathbb{R}^4

Solution:

$$\text{Let } v_1 = (1, 2, 3, 4)$$

$$v_2 = (4, 3, 2, 1)$$

Checking if v_1 and v_2 are Linearly Independent:

$$c_1 v_1 + c_2 v_2 = 0, c_1, c_2 \in \mathbb{R}$$

$$\Rightarrow c_1(1, 2, 3, 4) + c_2(4, 3, 2, 1) = 0$$

$$\Rightarrow \begin{cases} c_1 + 4c_2 = 0 & \text{---(1)} \\ 2c_1 + 3c_2 = 0 & \text{---(2)} \end{cases} \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad \begin{array}{l} c_1 = 0 \\ c_2 = 0 \end{array}$$

$$3c_1 + 2c_2 = 0 \quad \text{---(3)}$$

$$4c_1 + c_2 = 0 \quad \text{---(4)}$$

$\therefore v_1$ and v_2 are linearly independent.

For forming a basis on \mathbb{R}^4 ,

Two more linearly independent vectors are required.

Hence, Add Standard Basis vectors that are not in the span of v_1 and v_2

$$\text{So } v_3 = (0, 0, 1, 0)$$

$$\& v_4 = (0, 0, 0, 1)$$

$(1, 0, 0, 0) \& (0, 1, 0, 0)$
would result in Linear Dependence

Verifying the Linear Independence of all 4 vectors,

$$c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 = 0$$

$$\text{As } c_1 v_1 + c_2 v_2 = 0 \quad [\text{from (1) and (2)}]$$

And as v_3 and v_4 are standard Basis,

$$\therefore c_3 v_3 + c_4 v_4 = 0$$

\therefore Adding the above 2 equations:

$$c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 = 0$$

$\therefore v_1, v_2, v_3$ and v_4 are Linearly independent.

Check for $\mathbb{R}^4 = \text{span}(B)$

Let $x = (x_1, x_2, \dots, x_n)$ be any arbitrary vector in \mathbb{R}^4

$$(x_1, x_2, \dots, x_n) = x_1(1, 2, 3, 4) + x_2(4, 3, 2, 1) + x_3(0, 0, 1, 0) + x_4(0, 0, 0, 1)$$

$$\therefore \text{Span}(B) = \mathbb{R}^4$$

We can say, $\{(x_1 + 4x_2 + x_3), (2x_1 + 3x_2 + x_4), (3x_1 + 2x_2, 4x_1 + x_2) | x_1, x_2, x_3, x_4 \in \mathbb{R}\} = \mathbb{R}^4$

$$T(b_2) = c_1 = (1, 0, 0)$$

$$T(b_3) = c_2 = (0, 1, 0)$$

$$T(b_4) = c_3 = (0, 0, 1)$$

The rows of T are c_1, c_2, c_3 which spans \mathbb{R}^3 .

Hence, $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$

\therefore Onto Linear Transformation, $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ with

$N(T) = \{(4x, 3x, 2x, x) : x \in \mathbb{R}\}$ is given by

$$T = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

\swarrow zero column

$$\begin{aligned} \text{For } T(0, 0, 0, 1) &= T(4, 3, 2, 1) - 4T(1, 0, 0, 0) - 3T(0, 1, 0, 0) \\ &\quad - 2T(0, 0, 1, 0) \\ &= (0, 0, 0) - (4, 0, 0) - (0, 3, 0) - (0, 0, 2) \\ &= (-4, -3, -2) \end{aligned}$$

$$T(0, 0, 0, 1) = (-4, -3, -2)$$

$$T(X) = AX, \text{ where } A = \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$
$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\therefore T(X) = \{(x_1 - 4x_4, x_2 - 3x_4, x_3 - 2x_4)\}$$

⑤ Rank Nullity Theorem:

Let V and W be vector spaces over field \mathbb{F} .

T be linear transformation from $V \rightarrow W$.

Suppose that V is finite dimensional.

Prove:

$$\text{rank}(T) + \text{Nullity}(T) = \dim(V)$$

) Given:

$$N(T) = \{(4x, 3x, 2x, x) : x \in \mathbb{R}\}$$

$$T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$$

To find:

Linear Transformation, T

Solution:

$$N(T) = \{(4x, 3x, 2x, x)\}$$

$$= \text{span of } \{(4, 3, 2, 1)\}$$

The set $\{(4, 3, 2, 1)\}$ is linear independent and spans $N(T)$

\therefore forms Basis $N(T)$

$$\text{Nullity}(T) = 1$$

By Rank-Nullity Theorem, for $T: V \rightarrow W$

$$\dim(N(T)) + \dim(R(T)) = \dim(V)$$

$$\Rightarrow \dim(R(T)) = \dim(V) - \dim(N(T))$$

$$= 4 - 1$$

$$= 3$$

$$\therefore \dim(R(T)) = 3$$

As $R(T) \subseteq W$, if $\dim(R(T)) = \dim(W)$,

Then, $R(T) = W$

As $\dim(R(T)) = \dim(\mathbb{R}^3) = 3$

$$R(T) = \mathbb{R}^3$$

$\Rightarrow T$ is onto.

Basis for \mathbb{R}^4 with respect to $N(T) = \{(4, 3, 2, 1), b_2, b_3, b_4\}$

where b_2, b_3, b_4 are linearly independent and not in $N(T)$.

Let's take $b_2 = (1, 0, 0, 0)$

$b_3 = (0, 1, 0, 0)$

$b_4 = (0, 0, 1, 0)$

for $v = (4, 3, 2, 1) \in N(T); T(v) = 0$

⑥

$$P = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$$B = \{(1,1), (1,2)\}$$

Let $v_1 = (1,1)$ &
 $v_2 = (1,2)$

$$\begin{aligned} v_1' &= Pv_1 \\ &= \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} = (2,0) \end{aligned}$$

$$\begin{aligned} v_2' &= Pv_2 \\ &= \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = (3,1) \end{aligned}$$

$$B' = \{(2,0), (3,1)\}$$

$$B_1 = \{(2,1), (1,2)\}$$

Let's find a Matrix Q s.t. $[\alpha]_B = Q[\alpha]_{B_1}$

And as v_1 and v_2 must be expressed as a linear combination of B_1 ,

$$\Rightarrow v_1 = a_1 v_1' + b_1 v_2' , \quad a, b \in \mathbb{R}$$

$$\Rightarrow \begin{cases} 2a_1 + b_1 = 1 \\ a_1 + 2b_1 = 1 \end{cases} \Rightarrow \text{Solving them gives}$$

$a_1 = \frac{1}{3}$
 $b_1 = \frac{1}{3}$

$$v_2 = a_2 v_1' + b_2 v_2'$$

$$\Rightarrow \begin{cases} 2a_2 + b_2 = 1 \\ a_2 + 2b_2 = 2 \end{cases} \Rightarrow \text{Solving them gives}$$

$a_2 = 0$
 $b_2 = 1$

Proof:

Let $\{\alpha_1, \alpha_2, \dots, \alpha_k\}$ be basis for N , the Null space of T .

There are vectors $\alpha_{k+1}, \dots, \alpha_n$ in V such that $\{\alpha_1, \alpha_2, \dots, \alpha_n\}$ in V such that $\{\alpha_1, \alpha_2, \dots, \alpha_n\}$ is a basis for V .

To prove : $\{T\alpha_{k+1}, \dots, T\alpha_n\}$ is a basis for range of T .

The vectors $T\alpha_1, T\alpha_2, \dots, T\alpha_n$ certainly span range of T , since $T\alpha_j = 0$ for $j \leq k$, we see that $T\alpha_{k+1}, \dots, T\alpha_n$ span range.

To see that these vectors are linearly independent, suppose

$$c_1 T(\alpha_1) + c_2 T(\alpha_2) + c_3 T(\alpha_3) + \dots + c_n T(\alpha_n) = 0$$

$$\Rightarrow c_1 \alpha_1 + c_2 \alpha_2 + \dots + c_n \alpha_n = 0$$

And accordingly the vector $\cancel{c_{k+1}\alpha_{k+1} + \dots + c_n\alpha_n} \alpha = c_{k+1}\alpha_{k+1} + \dots + c_n\alpha_n$ is the null space of T .

Since, $\alpha_1, \alpha_2, \dots, \alpha_k$ form a basis for N , there must be scalars b_1, b_2, \dots, b_k S.T. $\alpha = b_1\alpha_1 + b_2\alpha_2 + \dots + b_k\alpha_k$

$$\text{Hence, } (b_1\alpha_1 + b_2\alpha_2 + \dots + b_k\alpha_k) - (c_{k+1}\alpha_{k+1} + c_{k+2}\alpha_{k+2} + \dots + c_n\alpha_n) = 0$$

$\because \alpha_1, \alpha_2, \dots, \alpha_n$ are linearly independent

$$\Rightarrow b_1 = b_2 = b_3 = \dots = b_k = c_{k+1} = c_{k+2} = \dots = c_n = 0$$

If $r \rightarrow \text{rank of } T$,

$T\alpha_{k+1}, \dots, T\alpha_n$ form a basis for range of T ,

i.e. $r = n - k$ $[k = \text{nullity}(T)]$

$$\Rightarrow r + k = n$$

$$\Rightarrow \text{rank}(T) + \text{Nullity}(T) = \dim(V)$$

Hence Proved

(8)

Given : $V \rightarrow \text{Vector space}$ $v_1, v_2, \dots, v_n \text{ span } V$ To prove :(i) $v_1, v_2 - v_1, v_3 - v_1, \dots, v_n - v_1$ span V .(ii) If v_1, v_2, \dots, v_n are linearly independent,Then $v_1, v_2 - v_1, v_3 - v_1, \dots, v_n - v_1$ are linearly independent.Solution :Let $\alpha \in V$

$$\Rightarrow \exists c_1, c_2, \dots, c_n \text{ S.T. } \alpha = c_1 v_1 + c_2 v_2 + c_3 v_3 + \dots + c_n v_n$$

$$\alpha = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

Add & Subtract $c_j v_1$ $\forall j = 2, 3, \dots, n$

$$\Rightarrow \alpha = (c_1 v_1 + c_2 v_2 + \dots + c_n v_n) + (c_2 v_1 + c_3 v_1 + \dots + c_n v_1)$$

$$- (c_2 v_1 + c_3 v_1 + \dots + c_n v_1)$$

$$= (c_1 + c_2 + c_3 + \dots + c_n) v_1 + c_2 (v_2 - v_1) + c_3 (v_3 - v_1)$$

$$+ \dots + c_n (v_n - v_1)$$

∴ α is a linear combination of $(v_1, v_2 - v_1, v_3 - v_1, \dots, v_n - v_1)$ $\Rightarrow (v_1, v_2 - v_1, v_3 - v_1, \dots, v_n - v_1)$ also spans V .Suppose $\{v_1, v_2, \dots, v_n\}$ is linearly independent.

$$\Rightarrow c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0 \rightarrow c_1, c_2, \dots, c_n = 0$$

 ~~$\rightarrow c_1$~~

$$\text{Let } b_1 v_1 + b_2 (v_2 - v_1) + \dots + b_n (v_n - v_1) = 0$$

$$\Rightarrow (b_1 - b_2 - \dots - b_n) v_1 + b_2 v_2 + b_3 v_3 + \dots + b_n v_n = 0$$

$$\Rightarrow b_1 = b_2 = b_3 = \dots = b_n = 0$$

$$\text{As } b_2 = 0, b_3 = 0, \dots, b_n = 0 \Rightarrow b_1 = 0$$

 $\therefore \{v_1, v_2 - v_1, v_3 - v_1, \dots, v_n - v_1\}$ is also linearly

Independent.

Hence, Proved

The transformation Matrix Φ is,

$$\Phi = \begin{bmatrix} \frac{1}{3} & 0 \\ \frac{1}{3} & 1 \end{bmatrix}$$

⑦ Given:

$$x + y + z = 0 ,$$

$$x, y, z \in V$$

$$x \neq 0, y \neq 0, z \neq 0$$

To show:

$$\text{span}\{x, y\} = \text{span}\{y, z\} = \text{span}\{z, x\}$$

Proof:

$$x = -(y+z)$$

$$y = -(z+x)$$

$$z = -(x+y)$$

As any one ~~any~~ variable x, y or z , can be expressed as a linear combination of the other two.

$$\text{i.e. } x \in \text{span}\{y, z\} \Rightarrow \text{span}\{y, z\} \supseteq \text{span}\{x, y\} \quad \textcircled{1}$$

$$z \in \text{span}\{x, y\} \Rightarrow \text{span}\{x, y\} \supseteq \text{span}\{y, z\} \quad \textcircled{2}$$

~~$$x \in \text{span}\{y, z\} \Rightarrow \text{span}\{x, y, z\} \supseteq \text{span}\{y, z\}$$~~

From $\textcircled{1}$ and $\textcircled{2}$:

$$\text{span}\{x, y\} = \text{span}\{y, z\} \quad \textcircled{3}$$

$$y \in \text{span}\{x, z\} \Rightarrow \text{span}\{x, z\} \supseteq \text{span}\{y, z\} \quad \textcircled{4}$$

Similarly,

$$x \in \text{span}\{y, z\} \Rightarrow \text{span}\{y, z\} \supseteq \text{span}\{x, z\} \quad \textcircled{5}$$

From $\textcircled{4}$ and $\textcircled{5}$:

$$\text{span}\{y, z\} = \text{span}\{x, z\} \quad \textcircled{6}$$

from $\textcircled{3}$ & $\textcircled{6}$:

$$\text{span}\{x, y\} = \text{span}\{y, z\} = \text{span}\{x, z\}$$

Hence Proved.

Solution:

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(i) LHS \Rightarrow RHS

(a) $T_0 T = 0$,

If $R(T) = N(T)$, for any $v \in V$, $T(v) \in R(T)$
 $\Rightarrow T(v) \in N(T)$

$\Rightarrow T(T(v)) = 0$ showing $T_0 T = 0$

(b) $T \neq 0$

$R(T) = N(T)$,

if $T = 0$, $R(T) = \{0\}$

$N(T) = V$

This contradicts the equality $R(T) = N(T)$,
Hence $T \neq 0$.

$\dim(V) = \text{Rank}(T) + \text{Nullity}(T)$

If $R(T) = N(T)$, $\dim(R(T)) = \dim(N(T))$

Let $r \rightarrow \text{rank of } T$

$\Rightarrow n = r + r$

$\Rightarrow r = \frac{n}{2} \Rightarrow n \text{ must be even}$

$\therefore LHS \Rightarrow RHS$

(ii) RHS \Rightarrow LHS

$T_0 T = 0$, for any $v \in V$, $T(v) \in N(T)$

$\Rightarrow R(T) \subseteq N(T) \quad \textcircled{1}$

$\dim(V) = \text{Rank}(T) + \text{Nullity}(N(T))$

As $\text{rank}(T) = \frac{n}{2}$ & $\dim(V) = \frac{n}{2}$

$\Rightarrow \text{Nullity}(T) = \frac{n}{2} \Rightarrow \text{rank}(T) = \text{Nullity}(T) \quad \textcircled{2}$

from $\textcircled{1}$ & $\textcircled{2}$:

$R(T) = N(T)$

$\therefore LHS \Rightarrow RHS$ and $RHS \Rightarrow LHS$, This tells $LHS \equiv RHS$.

\therefore Both the above statements are equivalent.

i) Given:

$AB \rightarrow$ defined

$R(A) \rightarrow$ Row space of A

$N(B) \rightarrow$ solution set of $Bx=0$

To prove:

(a) $R(AB) \subseteq R(A)$

(b) $N(AB) \supseteq N(B)$

Solution:

(a) Row space of AB contains linear combination of rows of AB . Each row in AB is a linear combination of A.

$$AB = A_1 \begin{bmatrix} B_1 \\ \vdots \\ B_n \end{bmatrix} + A_2 \begin{bmatrix} B_1 \\ \vdots \\ B_n \end{bmatrix} + \dots + A_m \begin{bmatrix} B_1 \\ \vdots \\ B_n \end{bmatrix}$$

Every vector in $R(AB)$ can be expressed as combination of rows of A,
i.e. $R(AB) \subseteq R(A)$

(b) Null space of AB is

$$N(AB) = \{x \mid ABx = 0, x \in \mathbb{R}^n\}$$

$$N(AB) = \{x \mid ABx = 0, x \in N(B)\}$$

If $x \in N(B)$, $Bx = 0 \Rightarrow ABx = A(Bx) = 0$

$$\Rightarrow x \in N(AB)$$

$$\Rightarrow N(B) \subseteq N(AB)$$

$$\Rightarrow N(AB) \supseteq N(B)$$

⑩ Given:

V: Vector space of dimension n over field f.

T: $V \rightarrow V$: Linear

To prove:

$$[R(T) = N(T)] \equiv [T \circ T = 0, T \neq 0, n \text{ is even}, \text{Rank}(T) = n]$$