

# Basis and Dimension

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**If  $S$  is a linearly independent set, then for any (finite) distinct vectors  $\alpha_1, \alpha_2, \dots, \alpha_n \in S$ ,**

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**(ii)** If  $A$  is an invertible matrix, then columns of  $A$  forms a linearly independent set ( By note (i) and Theorem 13, chapter 1).

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4. **A set  $S$  of vectors is linearly independent if and only if each finite subset of  $S$  is linearly independent if and only if for any distinct vectors  $\alpha_1, \alpha_2, \dots, \alpha_n$  of  $S$ ,  
$$c_1\alpha_1 + c_2\alpha_2 + \dots + c_n\alpha_n = 0 \implies c_1 = c_2 = \dots = c_n = 0$$**



## Problem 1

Show that  $\alpha_1 = (3, 0, -3)$ ,  $\alpha_2 = (-1, 1, 2)$ ,  $\alpha_3 = (4, 2, -2)$  and  $\alpha_4 = (2, 1, 1)$  are linearly dependent (L.D.) on  $\mathbb{R}^3$ .

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**Solution :** Find sclars  $c_1, c_2, c_3, c_4$  (at leaset one  $c_i \neq 0$ ) such that  $c_1\alpha_1 + c_2\alpha_2 + c_3\alpha_3 + c_4\alpha_4 = 0$ .

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$$2\alpha_1 + 2\alpha_2 - \alpha_3 + 0\alpha_4 = 0$$

## Problem 2

**Show that  $\epsilon_1 = (1, 0, 0)$ ,  $\epsilon_2 = (0, 1, 0)$  and  $\epsilon_3 = (0, 0, 1)$  is a linearly independent (L.I.) subset of  $F^3$ .**

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Hence  $\{\epsilon_1, \epsilon_2, \epsilon_3\}$  is a *L.I.* subset of  $F^3$ .

**Note :**

$\{\epsilon_1 = (1, 0, 0, \dots, 0, 0), \epsilon_2 = (0, 1, 0, \dots, 0, 0) \dots, \epsilon_n = (0, 0, 0, \dots, 0, 1)\}$   
is a linearly independent subset of  $F^n$ .

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# Basis

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**Note :** A vector space  $V$  is **finite dimensional** if **it has a finite basis**.

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**Show that  $\mathbb{B} =$**

$$\{\epsilon_1 = (1, 0, 0, \dots, 0, 0), \epsilon_2 = (0, 1, 0, \dots, 0, 0) \dots, \epsilon_n = (0, 0, 0, \dots, 0, 1)\}$$

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**From (a) and (b),**  $F^n = \text{span } \mathbb{B}$ .

By Claims 1 and 2,  $\mathbb{B}$  is a basis of  $F^n$

**Note:**  $\mathbb{B} = \{\epsilon_1, \epsilon_2, \dots, \epsilon_n\}$  is called the standard basis of  $F^n$ .

## Problem 3

Show that  $\mathbb{B} = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$  and  $\mathbb{B}_1 = \{(0, 1, 1), (1, 0, 1), (1, 1, 0)\}$  are basis for  $R^3$ .

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We have  $\mathbb{B} \subseteq F^{n \times 1}$ .

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$$Y = PX$$

## Problem 4 contd.

$$\implies x_1 = x_2 = \dots = x_n = 0 \implies \mathbb{B} \text{ is a L.I. set}$$

**Claim 2:**  $F^{n \times 1} = \text{Span } \mathbb{B}$

We have  $\mathbb{B} \subseteq F^{n \times 1}$ .  $\implies \text{Span } \mathbb{B} \subseteq F^{n \times 1} \text{ --- (i)}$

Let  $Y \in F^{n \times 1}$ . By Theorem 13 (Note that  $P$  is invertible),  $PX = Y$  has a solution  $X$  for each  $Y \in F^{n \times 1}$ .

$$Y = PX = x_1 P_1 + x_2 P_2 + \dots + x_n P_n$$

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From (i) and (ii),  $F^{n \times 1} = \text{Span } \mathbb{B}$ .

## Problem 4 contd.

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From (i) and (ii),  $F^{n \times 1} = \text{Span } \mathbb{B}$ . By Claims 1 and 2,  $\mathbb{B}$  (the set of all columns of  $P$ ) is a basis of  $F^{n \times 1}$ .

## Problem 5

Let  $A \in F^{n \times n}$  and let  $\{P_1, P_2, \dots, P_n\}$  be columns of  $A$ . Prove that  $A$  is invertible if and only if  $\{P_1, P_2, \dots, P_n\}$  is a L.I. set.

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**Solution :**  $A$  is invertible if and only if

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**Solution :**  $A$  is invertible if and only if  $AX = 0$  has only trivial solution  $X = 0$  (Theorem 13, chapter 1)

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**Solution :**  $A$  is invertible if and only if  $AX = 0$  has only trivial solution  $X = 0$  (Theorem 13, chapter 1) if and only if  $x_1P_1 + x_2P_2 + \dots + x_nP_n = 0$  has only trivial solution  $x_1 = x_2 = \dots = x_n = 0$

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## Note 1: ( Visit previous lecture notes)

Find the solution space of the system  $RX = 0$

$$R = \begin{bmatrix} 0 & 1 & -3 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

## Note 1: ( Visit previous lecture notes)

Find the solution space of the system  $RX = 0$

$$R = \begin{bmatrix} 0 & 1 & -3 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \left. \begin{array}{l} x_2 - 3x_3 + \frac{1}{2}x_5 = 0 \\ x_4 + 2x_5 = 0 \end{array} \right\}$$

**No. of non-zero rows of  $R$ ,  $r = 2$ , No. of variables,  $n = 5$**

$k_1 = 2, k_2 = 4 \implies$  Pivot variables  $= \{x_{k_1}, x_{k_2}\} = \{x_2, x_4\}$

No. of free variables  $= n - r = 5 - 2 = 3$ ,

Free variables  $= \{u_1, u_2, u_3\} = \{x_1, x_3, x_5\}$

$$\left. \begin{array}{l} x_2 - 3x_3 + \frac{1}{2}x_5 = 0 \\ x_4 + 2x_5 = 0 \end{array} \right\} \implies \left. \begin{array}{l} x_{k_1} + \sum_{j=1}^{n-r} C_{1j}u_j = 0 \\ x_{k_2} + \sum_{j=1}^{n-r} C_{2j}u_j = 0 \end{array} \right\} \text{ (general expression)}$$

## Note 1 contd.

$$\left. \begin{array}{l} x_2 - 3x_3 + \frac{1}{2}x_5 = 0 \\ x_4 + 2x_5 = 0 \end{array} \right\} \Rightarrow \left. \begin{array}{l} x_{k_1} + \sum_{j=1}^{n-r} C_{1j}u_j = 0 \\ x_{k_2} + \sum_{j=1}^{n-r} C_{2j}u_j = 0 \end{array} \right\} \text{general expression)}$$

**Set the free variables as :**

$$u_1 = x_1 = a, \quad u_2 = x_3 = b, \quad u_3 = x_5 = c$$

$$\Rightarrow x_2 = 3b - \frac{1}{2}c, \quad x_4 = -2c$$

**Solution set**  $S = \{(a, 3b - \frac{1}{2}c, b, -2c, c) : a, b, c \in \mathbb{R}\}$

## Note 1 contd. (back to chapter one !)

**Solution set**  $S = \{(a, 3b - \frac{1}{2}c, b, -2c, c) : a, b, c \in \mathbb{R}\}$

$$S = \left\{ a(1, 0, 0, 0, 0) + b(0, 3, 1, 0, 0) + c(0, -\frac{1}{2}, 0, -2, 1) : a, b, c \in \mathbb{R} \right\}$$

$$= \text{Span of } \left\{ (1, 0, 0, 0, 0), (0, 3, 1, 0, 0), (0, -\frac{1}{2}, 0, -2, 1) \right\}$$

**Dimension of  $S$**   $= \dim S = 3 = n - r$  **(Information for future)**

## Alternate way to find a basis of $S$

$$\left. \begin{array}{l} x_2 - 3x_3 + \frac{1}{2}x_5 = 0 \\ x_4 + 2x_5 = 0 \end{array} \right\} \text{--- (i)}$$

Note that  $\{x_2, x_4\}$  are pivot variables and  $\{x_1, x_3, x_5\}$  are free variables.

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Set  $x_1 = 1, x_3 = 0, x_5 = 0$ .

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Let  $E_1 = (1, 0, 0, 0, 0)$



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## Alternate way to find a basis of $S$

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## Alternate way to find a basis of $S$

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Clearly,  $S = \text{Span} \{E_1, E_3, E_5\}$  (See the previous slide)

Prove that  $\{E_1, E_3, E_5\}$  is a linearly independent set.



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Hence  $\{E_1, E_3, E_5\}$  is a basis of  $S$ .

Please read chapter 2, example 15 for details.

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Please read chapter 2, example 15 for details.

## Problem 5 (assignment)

Let  $W$  be set of all  $(x_1, x_2, x_3, x_4, x_5) \in \mathbb{R}^5$  which satisfies

$$2x_1 - x_2 + \frac{4}{3}x_3 - x_4 = 0$$

$$x_1 + \frac{2}{3}x_3 - x_5 = 0$$

$$9x_1 - 3x_2 + 6x_3 - 3x_4 - 3x_5 = 0$$

Find a basis of  $W$ .

(2) Find a basis of the vector space of all polynomials over the field  $F$  (see chapter 2, example 16)

## Theorem 4

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**Proof:** We have

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It is enough to prove that

if  $\{\alpha_1, \alpha_2, \dots, \alpha_n\} \subseteq V$  is an arbitrary L.I. set, then  $n \leq m$ .

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We prove by method of contradiction. Assume that  $m < n$ .



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By (i),  $\alpha_1 = A_{11}\beta_1 + A_{21}\beta_2 + \dots + A_{m1}\beta_m$

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By (i),  $\alpha_1 = A_{11}\beta_1 + A_{21}\beta_2 + \dots + A_{m1}\beta_m$

$$\alpha_2 = A_{12}\beta_1 + A_{22}\beta_2 + \dots + A_{m2}\beta_m$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m = \sum_{i=1}^m A_{ij}\beta_i, \quad j = 1, 2, \dots, n$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m = \sum_{i=1}^m A_{ij}\beta_i, \quad j = 1, 2, \dots, n$$

Consider the homogeneous system

$$x_1\alpha_1 + x_2\alpha_2 + \dots + x_n\alpha_n = 0 \text{ --- (ii)}$$

$$\implies \sum_{j=1}^n x_j\alpha_j = 0$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m = \sum_{i=1}^m A_{ij}\beta_i, \quad j = 1, 2, \dots, n$$

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$$x_1\alpha_1 + x_2\alpha_2 + \dots + x_n\alpha_n = 0 \text{ --- (ii)}$$

$$\implies \sum_{j=1}^n x_j \alpha_j = 0$$

$$\implies \sum_{j=1}^n x_j \left( \sum_{i=1}^m A_{ij} \beta_i \right) = 0$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m = \sum_{i=1}^m A_{ij}\beta_i, \quad j = 1, 2, \dots, n$$

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$$\Rightarrow \sum_{i=1}^m \left( \sum_{j=1}^n A_{ij} x_j \right) \beta_i = 0$$

$$\alpha_j = A_{1j}\beta_1 + A_{2j}\beta_2 + \dots + A_{mj}\beta_m = \sum_{i=1}^m A_{ij}\beta_i, \quad j = 1, 2, \dots, n$$

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$$x_1\alpha_1 + x_2\alpha_2 + \dots + x_n\alpha_n = 0 \text{ --- (ii)}$$

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## Theorem 4 contd.

Consider  $\sum_{j=1}^n A_{ij}x_j = 0, i = 1, 2, \dots, m \text{ --- (iii)}$

## Theorem 4 contd.

Consider  $\sum_{j=1}^n A_{ij}x_j = 0, i = 1, 2, \dots, m \text{ --- (iii)}$

## Theorem 4 contd.

Consider  $\sum_{j=1}^n A_{ij}x_j = 0, i = 1, 2, \dots, m \text{ --- (iii)}$

The system (iii) is a homogeneous linear system with  $m$  equations and  $n$  variables.

## Theorem 4 contd.

Consider  $\sum_{j=1}^n A_{ij}x_j = 0, i = 1, 2, \dots, m \text{ --- (iii)}$

The system (iii) is a homogeneous linear system with  $m$  equations and  $n$  variables. Since  $m < n$ , the system (iii) has a non-trivial solution say  $x_1^*, x_2^*, \dots, x_n^*$  (at least one  $x_j^* \neq 0$ ) such that

$$\sum_{j=1}^n A_{ij}x_j^* = 0, i = 1, 2, \dots, m \text{ --- (iv)}$$

## Theorem 4 contd.

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**Proof:** Suppose that  $\alpha_1, \alpha_2, \dots, \alpha_n$  be distinct vectors in  $S$  and that

$$c_1\alpha_1 + c_2\alpha_2 + \dots + c_n\alpha_n + b\beta = 0 - - - - - (i)$$

Then  $b = 0$ ; otherwise  $\beta = -\frac{c_1}{b}\alpha_1 - \frac{c_2}{b}\alpha_2 - \dots - \frac{c_n}{b}\alpha_n \in L(S)$ , a contradiction.

$$(i) \implies c_1\alpha_1 + c_2\alpha_2 + \dots + c_n\alpha_n = 0$$

Since  $S$  is a L.I. set,  $c_1 = c_2 = \dots = c_n = 0 = b$ . Thus  $S \cup \{\beta\}$  is a L.I. set in  $V$ .

## Theorem 5

If  $W$  is a subspace of a finite-dimensional vector space  $V$ , every linearly independent subset of  $W$  is finite and is a part of a (finite) basis for  $W$ .

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$$S_m = S_0 \cup \{\beta_1, \beta_2, \dots, \beta_m\}$$

which is basis for  $W$ .



## Example

Let  $S_0 = \{(1, 1, 1)\}$ . Find a basis for  $R^3$  which contains  $S_0$ .

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 $S_2 = S_1 \cup \{\beta_2\} = \{(1, 1, 1), (1, 1, 0), (1, 0, 0)\}$  is a L.I. set. Verify that  $L(S_2) = R^3$ . Hence,  $S_2$  is a basis for  $R^3$ .

## Corollary to Theorem 5

**Corollary 1 :** If  $W$  is a proper subspace of a finite-dimensional vector space  $V$ , then  $W$  is finite-dimensional and  $\dim W < \dim V$ .

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**Proof:** (assignment)

**Corollary 2 :** In a finite-dimensional vector space  $V$  every non-empty linearly independent set of vectors is part of a basis.

## Corollary 3 to Theorem 5

Let  $A \in F^{n \times n}$ , and suppose the row vectors of  $A$  form a linearly independent set of vectors in  $F^n$ .

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$$F^n = W = \text{span} \{\alpha_1, \alpha_2, \dots, \alpha_n\}$$

## Corollary 3 Theorem 5 contd.

Since  $\epsilon_1 = (1, 0, \dots, 0) \in F^n = \text{span } \{\alpha_1, \alpha_2, \dots, \alpha_n\}$ ,

$$\epsilon_1 = B_{11}\alpha_1 + B_{12}\alpha_2 + \dots + B_{1n}\alpha_n$$

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Since  $\epsilon_1 = (1, 0, \dots, 0) \in F^n = \text{span } \{\alpha_1, \alpha_2, \dots, \alpha_n\}$ ,

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Similarly,  $\epsilon_2 = (0, 1, \dots, 0), \dots, \epsilon_n = (0, 0, \dots, 1) \in F^n$ ,

$$\epsilon_2 = B_{21}\alpha_1 + B_{22}\alpha_2 + \dots + B_{2n}\alpha_n$$

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$$\begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \dots \\ \epsilon_n \end{bmatrix} = \begin{bmatrix} B_{11} & B_{12} & \dots & B_{1n} \\ B_{21} & B_{22} & \dots & B_{2n} \\ \dots & \dots & \dots & \dots \\ B_{n1} & B_{n2} & \dots & B_{nn} \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \dots \\ \alpha_n \end{bmatrix}$$

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$$\implies I = BA$$

Hence  $B$  is a left inverse of  $A$  and thus  $A$  is invertible.

# Sum of Subsets

**Definition:** If  $S_1, S_2, \dots, S_k$  are subsets of a vector space  $V$ , the set of all sums

$$\alpha_1 + \alpha_2 + \cdots + \alpha_k$$

of vectors  $\alpha_i$  in  $S_i$  is called the sum of the subsets  $S_1, S_2, \dots, S_k$  and is denoted by

$$S_1 + S_2 + \cdots + S_k$$

or by

$$\sum_{i=1}^k S_i$$

## Sum of Subspaces

If  $W_1, W_2, \dots, W_k$  are subspaces of  $V$ , then the sum

$$W = W_1 + W_2 + \cdots + W_k$$

is easily seen to be a subspace of  $V$  containing each subspace  $W_i$ . From this it follows, as in the proof of Theorem 3, that  $W$  is the subspace spanned by the union of  $W_1, W_2, \dots, W_k$ .

## Example 9

Let  $F$  be a subfield of the field  $C$  of complex numbers, and let  $V$  be the vector space of all  $2 \times 2$  matrices over  $F$ . Let  $W_1$  be the subset of  $V$  consisting of all matrices of the form

$$\begin{bmatrix} x & y \\ z & 0 \end{bmatrix}$$

where  $x, y, z$  are arbitrary scalars in  $F$ . Finally, let  $W_2$  be the subset of  $V$  consisting of all matrices of the form

$$\begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix}$$

where  $x$  and  $y$  are arbitrary scalars in  $F$ . Then  $W_1$  and  $W_2$  are subspaces of  $V$  (**Verify!**).

## Example 9

Also

$$V = W_1 + W_2$$

because

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & d \end{bmatrix}.$$

The subspace  $W_1 \cap W_2$  consists of all matrices of the form

$$\begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix}$$

## Dimension of $(W_1 + W_2)$

**Theorem 6:** If  $W_1$  and  $W_2$  are finite-dimensional subspaces of a vector space  $V$ , then  $W_1 + W_2$  is finite-dimensional and

$$\dim W_1 + \dim W_2 = \dim (W_1 \cap W_2) + \dim (W_1 + W_2).$$

## Dimension of $(W_1 + W_2)$

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$$\dim W_1 + \dim W_2 = \dim (W_1 \cap W_2) + \dim (W_1 + W_2).$$

**Proof:** By Theorem 5 and its corollaries,  $W_1 \cap W_2$  has a finite basis  $\{\alpha_1, \dots, \alpha_k\}$  which is part of a basis

$$\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m\} \text{ for } W_1$$

and part of a basis

$$\{\alpha_1, \dots, \alpha_k, \gamma_1, \dots, \gamma_n\} \text{ for } W_2.$$

## Proof

The subspace  $W_1 + W_2$  is spanned by the vectors

$$\alpha_1, \dots, \alpha_k, \quad \beta_1, \dots, \beta_m, \quad \gamma_1, \dots, \gamma_n$$

and these vectors form an independent set. For suppose

$$\sum x_i \alpha_i + \sum y_j \beta_j + \sum z_r \gamma_r = 0.$$

Then

$$-\sum z_r \gamma_r = \sum x_i \alpha_i + \sum y_j \beta_j$$

which shows that  $\sum z_r \gamma_r$  belongs to  $W_1$ . As  $\sum z_r \gamma_r$  also belongs to  $W_2$  it follows that

$$\sum z_r \gamma_r = \sum c_i \alpha_i$$

for certain scalars  $c_1, \dots, c_k$ .



## Proof

Because the set

$$\{\alpha_1, \dots, \alpha_k, \gamma_1, \dots, \gamma_n\}$$

is independent, each of the scalars  $z_r = 0$ . Thus

$$\sum x_i \alpha_i + \sum y_j \beta_j = 0$$

and since

$$\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m\}$$

is also an independent set, each  $x_i = 0$  and each  $y_j = 0$ . Thus,

$$\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m, \gamma_1, \dots, \gamma_n\}$$

is a basis for  $W_1 + W_2$ .

Finally

$$\begin{aligned}\dim W_1 + \dim W_2 &= (k + m) + (k + n) \\ &= k + (m + k + n) \\ &= \dim (W_1 \cap W_2) + \dim (W_1 + W_2) .\end{aligned}$$

**Verify Theorem 6 by Example 9.**