

# Invertible linear transformations

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# Invertible function

A function  $f : X \longrightarrow Y$  is invertible if there exists a function  $g : Y \longrightarrow X$  such that

- (i)  $g \circ f : X \longrightarrow X$  and
- (ii)  $f \circ g : Y \longrightarrow Y$  are identity functions.

## Onto function

A function  $f : X \longrightarrow Y$  is onto if range of  $f$ ,  $R(f) = Y$ . That is every element in  $Y$  has **at least one** pre-image under  $f$ .

## One to one (1:1) function

A function  $f : X \longrightarrow Y$  is one to one if each element in  $Y$  has **at most one** pre-image under  $f$ .

$$f(x) = f(y) \implies x = y$$

## Lemma

A linear transformation :  $V \longrightarrow W$  is **invertible** if and only if

- (1)  $T$  is 1 : 1, that is,  $T(\alpha) = T(\beta) \implies \alpha = \beta$ .
- (2)  $T$  is onto, that is,  $R(T) = W$ .

## Theorem 7 (Text book order)

Let  $V$  and  $W$  be two vector spaces over the field  $F$  and let  $T : V \longrightarrow W$  be a linear transformation. If  $T$  is invertible, then the inverse function  $T^{-1} : W \longrightarrow V$  is a linear transformation.

**Proof :** Suppose that  $T : V \longrightarrow W$  is an invertible linear transformation. Then there exists a function  $T^{-1} : W \longrightarrow V$  such that

- (i)  $TT^{-1} : W \longrightarrow W$  and
- (ii)  $T^{-1}T : V \longrightarrow V$  are identity functions.

It is enough to prove that

$$T^{-1}(c\beta_1 + \beta_2) = cT^{-1}(\beta_1) + T^{-1}(\beta_2) \text{ for all } \beta_1, \beta_2 \in W, c \in F$$

## Theorem 7 contd.

Let  $\alpha_1 = T^{-1}(\beta_1)$  and  $\alpha_2 = T^{-1}(\beta_2)$ . Since  $T$  is invertible,  $\alpha_1, \alpha_2$  are unique vectors in  $V$  such that  $T(\alpha_1) = \beta_1$  and  $T(\alpha_2) = \beta_2$ . Since  $T$  is a linear transformation,

$$T(c\alpha_1 + \alpha_2) = cT(\alpha_1) + T(\alpha_2) = c\beta_1 + \beta_2$$

$$\implies T^{-1}(c\beta_1 + \beta_2) = c\alpha_1 + \alpha_2 = cT^{-1}(\beta_1) + T^{-1}(\beta_2)$$

Hence  $T^{-1}$  is a linear transformation.

# Non-singular linear transformation

A linear transformation  $T : V \longrightarrow W$  is non-singular if

$$T(\alpha) = 0 \implies \alpha = 0$$



## Lemma 1

If  $T : V \longrightarrow W$  is a **non-singular** linear transformation, then  $N(T) = \{0\}$ .

**Proof :** Since  $T$  is a linear transformation,  $T(0) = 0$ . Hence  $0 \in N(T)$  and  $\{0\} \subseteq N(T) - - - - - (1)$ .

Let  $\alpha \in N(T) \implies T(\alpha) = 0 \implies \alpha = 0$ , since  $T$  is non-singular.  
 $\implies \alpha \in \{0\}$  and thus  $N(T) \subseteq \{0\} - - - - - (2)$ .

From (1) and (2)

$$N(T) = \{0\}$$

## Lemma 2

Let  $T : V \longrightarrow W$  be a linear transformation. Then following statements are equivalent.

- (1)  $T$  is one to one.
- (2)  $T$  is non-singular.

**Proof :** (1)  $\implies$  (2).

Suppose that  $T$  is one to one. Show that  $T$  is non-singular.

Consider  $T(\alpha) = 0 = T(0)$  (Note that  $T$  is a L.T.). Hence  $T(\alpha) = T(0)$  and  $T$  is one-one.  $\implies \alpha = 0$ .  $\implies T$  is non-singular.

(2)  $\implies$  (1).

Suppose that  $T$  is non-singular. Then  $N(T) = \{0\}$ , by previous

Lemma. Consider  $T(\alpha) = T(\beta)$ .

$\implies T(\alpha - \beta) = T(\alpha) - T(\beta) = 0$ .  $\implies \alpha - \beta \in N(T) = \{0\}$ .

$\implies \alpha - \beta = 0$ .  $\implies \alpha = \beta$ .  $\implies T$  is one to one.

## Theorem 8 (Non-singular linear transformations preserve linear independence)

Let  $T : V \longrightarrow W$  be a linear transformation. Then  $T$  is non-singular if and only if  $T$  carries each linearly independent subset of  $V$  onto a linearly independent subset of  $W$ .

**Proof :**

Case 1 : Suppose that  $T$  is non-singular. By Lemma 1,  $N(T) = \{0\}$ . Let  $S$  be a linearly independent subset of  $V$ . Let  $\alpha_1, \alpha_2, \dots, \alpha_k$  be distinct vectors in  $S$ . It is enough to show that  $\{T(\alpha_1), T(\alpha_2), \dots, T(\alpha_k)\}$  is a linearly independent subset of  $W$ . Consider

$$c_1 T(\alpha_1) + c_2 T(\alpha_2) + \dots + c_k T(\alpha_k) = 0$$

$$\implies T(c_1 \alpha_1 + c_2 \alpha_2 + \dots + c_k \alpha_k) = 0$$

## Theorem 8 contd.

Since  $N(T) = \{0\}$ ,

$$c_1\alpha_1 + c_2\alpha_2 + \dots + c_k\alpha_k = 0$$

Since  $S$  is linearly independent and  $\alpha_1, \alpha_2, \dots, \alpha_k$  be distinct vectors in  $S$ ,

$$c_1 = c_2 = \dots = c_k = 0.$$

Hence  $\{T(\alpha_1), T(\alpha_2), \dots, T(\alpha_k)\}$  is a linearly independent subset of  $W$  and it completes Case 1.

## Theorem 8 contd.

Case 2 : Suppose that  $T$  carries linearly independent subset onto linearly independent subset. Show that  $T$  is non-singular.

Consider  $T(\alpha) = 0$ . If  $\alpha \neq 0$ , then  $T$  carries a linearly independent set  $\{\alpha\}$  onto a linearly dependent set  $\{T(\alpha)\} = \{0\}$ , a contradiction.  $\implies \alpha = 0$ .  $\implies T$  is non-singular.

## Problem 1

Let  $T(x_1, x_2) = (x_1 + x_2, x_1)$  be a linear operator defined on  $F^2$ .  
Find  $T^{-1}$  if exists.

**Solution :**

$$T(x_1, x_2) = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \implies T(X) = AX$$

$$[A|I] = \left[ \begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{array} \right] \sim \left[ \begin{array}{cc|cc} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & -1 \end{array} \right] = [I|A^{-1}]$$

$$T^{-1}(Z) = A^{-1}Z = \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} \implies T^{-1}(z_1, z_2) = (z_2, z_1 - z_2)$$

## Problem 2

Find the inverse of a linear operator  $T$  on  $R^3$  defined as

$$T(x_1, x_2, x_3) = (3x_1, x_1 - x_2, 2x_1 + x_2 + x_3).$$

**Solution :**

$$T(x_1, x_2, x_3) = \begin{bmatrix} 3 & 0 & 0 \\ 1 & -1 & 0 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

## Problem 2 contd.

$$\begin{aligned} [A|I] &= \left[ \begin{array}{ccc|ccc} 3 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 & 1 & 0 \\ 2 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \\ &\sim \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{3} & -1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{array} \right] = [I|A^{-1}] \end{aligned}$$

$$T^{-1}(Y) = A^{-1}Y$$

$$T^{-1}(y_1, y_2, y_3) = \left( \frac{1}{3}y_1, \frac{1}{3}y_1 - y_2, -y_1 + y_2 + y_3 \right)$$



## Theorem 9

Let  $V$  and  $W$  be finite dimensional vector spaces over the field such that  $\dim V = \dim W$ . If  $T : V \longrightarrow W$  is a linear transformation, the following are equivalent.

- (i)  $T$  is invertible.
- (ii)  $T$  is non-singular.
- (iii)  $T$  is onto, that is,  $R(T) = W$ .

**Proof :** Let  $\dim V = \dim W = n$ .

By Rank-Nullity-Dimension Theorem,

$$\text{rank } (T) + \text{nullity } (T) = n - - - (1)$$

## Theorem 9 contd.

First we prove that  $(i) \implies (ii) \implies (iii)$ .

$T$  is invertible.  $\implies T$  is one to one.  $\implies T$  is non-singular (by Lemma 2).  $\implies N(T) = \{0\}$  (by Lemma 1).  $\implies \text{nullity}(T) = 0$ .  
 $\implies \text{rank}(T) = n$ , see (1).  $\implies \dim R(T) = \dim W$ .  
 $\implies R(T) = W$  (Reason:  $R(T) \subseteq W$  and  $\dim R(T) = \dim W$ ).  
 $\implies T$  is onto.

Next we prove that  $(iii) \implies (i)$ .

$T$  is onto.  $\implies R(T) = W$ .  $\implies \text{rank}(T) = \dim W = n$ .  
 $\implies \text{nullity}(T) = 0$ , see (1).  $\implies N(T) = \{0\}$ .

**Claim :**  $T$  is one to one.

Let  $T(\alpha) = T(\beta)$ .  $\implies T(\alpha - \beta) = 0$ .  $\alpha - \beta \in N(T) = \{0\}$ .  
 $\implies \alpha = \beta$ .  $\implies T$  is one to one. Note that  $T$  is onto (assumption) and  $T$  is one to one (above Claim). Hence  $T$  is invertible.

## Theorem 9A (Assignment)

Let  $V$  and  $W$  be finite dimensional vector spaces over the field such that  $\dim V = \dim W$ . If  $T : V \longrightarrow W$  is a linear transformation, the following are equivalent.

- (i)  $T$  is invertible.
- (ii)  $T$  is non-singular.
- (iii)  $T$  is onto, that is,  $R(T) = W$ .
- (iv) If  $\{\alpha_1, \dots, \alpha_n\}$  is a basis for  $V$ , then  $\{T(\alpha_1), \dots, T(\alpha_n)\}$  is a basis for  $W$ .
- (v) There is some basis  $\{\alpha_1, \dots, \alpha_n\}$  for  $V$  such that  $\{T(\alpha_1), \dots, T(\alpha_n)\}$  is a basis for  $W$ .