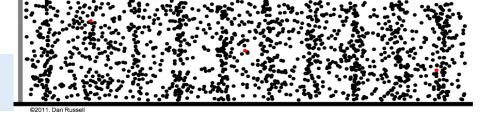
Energy associated with a wave:



A wave propagates through a medium, the particles execute SHM about their equilibrium positions, and associated with this motion is a certain amount of energy. As the wave propagates through, the energy gets transported from one end of the medium to the other. We consider the time variation of the displacement of a particle, which can be

$$\psi(x,t) = Asin(\omega t + \delta)$$

Instantaneous velocity, $v = \omega A cos(\omega t + \delta)$

Total energy of a SH oscillator, $\mathbf{E} = \mathbf{K} \cdot \mathbf{E} \cdot + \mathbf{P} \cdot \mathbf{E} \cdot = \mathbf{K} \cdot \mathbf{E} \cdot_{max}$

The wave carries energy, $\mathbf{E} = \frac{1}{2} m v^2 |_{max}$

$$E = \frac{1}{2} m\omega^2 A^2 \cos^2(\omega t + \delta) \big|_{max}$$

$$E = \frac{1}{2}m\omega^2 A^2$$

Sound wave through a gas of particle density *n*

Energy density
$$\epsilon = \frac{1}{2}mnA^2\omega^2 = \frac{1}{2}\rho A^2\omega^2$$

$$= \frac{1}{2}\rho A^2(2\pi\nu)^2 = 2\pi^2\rho A^2\nu^2$$
Speed of wave ν , dS=1

Intensity (energy/unit area), $\mathbf{l} = \epsilon . Vol = 2\pi^2 \rho A^2 v^2 v$

$$I = \frac{W}{4\pi r^2}$$

$$\frac{W}{4\pi r^2} = 2\pi^2 \rho A^2 v^2 v$$

$$\frac{1}{4\pi r^2} = \frac{W}{4\pi r^2} = \frac{A_0}{4\pi r^2} = \frac{A_0}$$

$$A = \frac{1}{r} \sqrt{\frac{W}{8\pi^2 v v^2}} = \frac{A_0}{r} \qquad \psi_s(x, t) = \frac{A_0}{r} \sin(kr - \omega t + \delta)$$

TPS

Phase and phase velocity:

A sinusoidal wave propagates through a medium is represented by,

$$\psi(x,t) = Asin(kx - \omega t + \delta)$$



Phase
$$\Rightarrow \delta$$
, Phase angle $\Rightarrow \phi = (kx - \omega t + \delta)$

$$\frac{\partial \phi}{\partial t} = -\omega$$

$$\frac{\partial \phi}{\partial x} = k$$

$$\left. \frac{\partial x}{\partial t} \right|_{\phi} = \left. \frac{\frac{\partial \phi}{\partial t}}{\frac{\partial \phi}{\partial x}} \right|_{t}$$

$$\psi(x,t) = Asin[k(x - v_p t + \delta)]$$



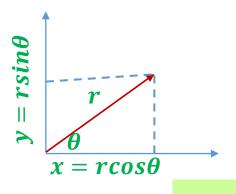
The LHS is the speed of propagation of the condition of constant phase (velocity of the wave):

Phase velocity:
$$v_p = \mp rac{\omega}{k}$$

$$\tilde{z} = x + iy$$

$$\tilde{z} = r(\cos\theta + i\sin\theta)$$

$$\tilde{z} = re^{i\theta}$$



$$Re(\tilde{z}) = rcos\theta$$

$$Re(\tilde{z}) = rcos\theta$$
 $Im(\tilde{z}) = rsin\theta$

$$\psi(x,t) = Asin(kx + \omega t + \delta) = Im\{Ae^{i(kx + \omega t + \delta)}\}$$

$$\psi(x,t) = A\cos(kx + \omega t + \delta) = Re\{Ae^{i(kx + \omega t + \delta)}\}\$$

$$\psi(x,t) = Ae^{i(kx \mp \omega t + \delta)} = Ae^{ikx}e^{i(\mp \omega t + \delta)}$$

$$r = \sqrt{x^2 + y^2}$$
 $\theta = tan^{-1}\left(\frac{y}{x}\right)$

At any instant of time, the surfaces joining all points of equal phase are known as wavefronts

If at a given time, all the surfaces on which a disturbance has constant phase form a set of planes, each generally perpendicular to the propagation direction then the wave is known as a plane wave.

To derive the expression for **a plane** that is perpendicular to a given vector \vec{k} and that passes through some point (x_0, y_0, z_0) , we write,

$$\vec{r} = x\hat{\imath} + y\hat{\jmath} + z\hat{k}$$

$$\vec{k} = k_x\hat{\imath} + k_y\hat{\jmath} + k_z\hat{k}$$

$$\vec{R} = \vec{r} - \overrightarrow{r_0} = (x - x_0)\hat{\imath} + (y - y_0)\hat{\jmath} + (z - z_0)\hat{k}$$

$$\vec{k} \cdot \vec{R} = 0 \Rightarrow \text{for } \vec{R} \text{ perpendicular to } \vec{k}$$

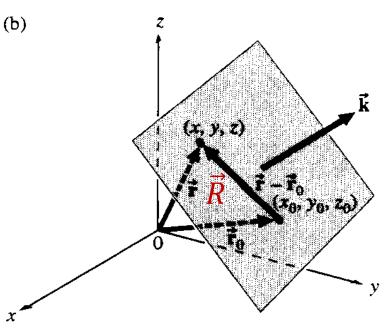
$$(x - x_0)k_x + (y - y_0)k_y + (z - z_0)k_z = 0$$

$$x_0k_x + y_0k_y + z_0k_z = xk_x + yk_y + zk_z$$

If we assume, for the fixed point $\overrightarrow{r_0}(x_0, y_0, z_0)$, $\overrightarrow{k} \cdot \overrightarrow{r_0} = constant$ (say)

$$\vec{k} \cdot \vec{r} = a$$
, constant

The plane is the locus of all points each of whose position vectors have a constant projection on \vec{k} .



$$\psi(\vec{r}) = Asin(\vec{k} \cdot \vec{r})$$

$$\psi(\vec{r}) = A\cos(\vec{k} \cdot \vec{r})$$

$$\psi(\vec{r}) = Ae^{i\vec{k} \cdot \vec{r}}$$

$$\psi(\vec{r}) = Ae^{i\vec{k}\cdot\vec{\imath}}$$

$$\psi(\vec{r}) = Asin(\vec{k} \cdot \vec{r}) \qquad \psi(\vec{r}) = Ae^{i\vec{k} \cdot \vec{r}}$$

The spatially repetitive nature of these harmonic functions can be expressed by

$$\psi(\vec{r}) = \psi\left(\vec{r} + \lambda(\vec{k}/k)\right) \qquad Ae^{i\vec{k}\cdot\vec{r}} = Ae^{i\vec{k}\cdot\vec{r}}e^{i\lambda k}$$

$$e^{i\lambda k}=1=e^{i2\pi}$$
 $\vec{k}=rac{2\pi}{\lambda}\Rightarrow wave\ number$

The disturbance on a wavefront is constant, so that after a time *dt*, if the front moves along k a distance $dr_k(r_k)$ is the projection of \vec{r} along \vec{k}), we must have

$$\psi(\vec{r},t) = \psi(r_k + dr_k, t + dt) = \psi(r_k, t)$$

$$\psi(\vec{r},t) = Ae^{i(\vec{k}\cdot\vec{r}+\omega t)} = Ae^{i(kr_k+kdr_k+\omega t+\omega t)} = Ae^{i(kr_k+kdr_k+\omega t+\omega t)} = Ae^{i(kr_k+kdr_k+\omega t+\omega t)}$$

$$kdr_k \mp \omega dt = 0 \quad \frac{dr_k}{dt} = \pm \frac{\omega}{k} = \pm v_p \quad r_1 = \hat{k}z \Rightarrow \overrightarrow{k_1} \cdot \overrightarrow{r} = kz \\ r_2 = \hat{j}y + \hat{k}z \Rightarrow \overrightarrow{k_2} \cdot \overrightarrow{r}$$

$$r_{1} = \widehat{k}z \Rightarrow \overrightarrow{k_{1}} \cdot \overrightarrow{r} = kz$$

$$r_{2} = \widehat{j}y + \widehat{k}z \Rightarrow \overrightarrow{k_{2}} \cdot \overrightarrow{r}$$

$$= k(ysin\theta + zcos\theta)$$

$$\psi_1(\vec{r},t) = A_1 sin(kz - \omega t) = A_1 e^{i(kz - \omega t)}$$

$$\psi_1(\vec{r},t) = A_1 \sin(k\{y\sin\theta + z\cos\theta\} - \omega t) = A_1 e^{i(k(x\sin\theta + z\cos\theta) - \omega t)}$$

Waves and Vibrations (PH2001)

