

# CS 302.1 - Automata Theory

Lecture 09

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# Quick Recap

**Pumping Lemma for CFL:** If  $L$  is Context Free, then there exists  $p > 0$  (pumping length), such that, for any  $w \in L$  of length  $|w| \geq p$ ,  $w$  can be split into five parts, i.e.  $w = uvxyz$  satisfying the following conditions:

- $|vy| \geq 1$
- $|vxy| \leq p$
- $uv^i xy^i z \in L, \forall i \geq 0$

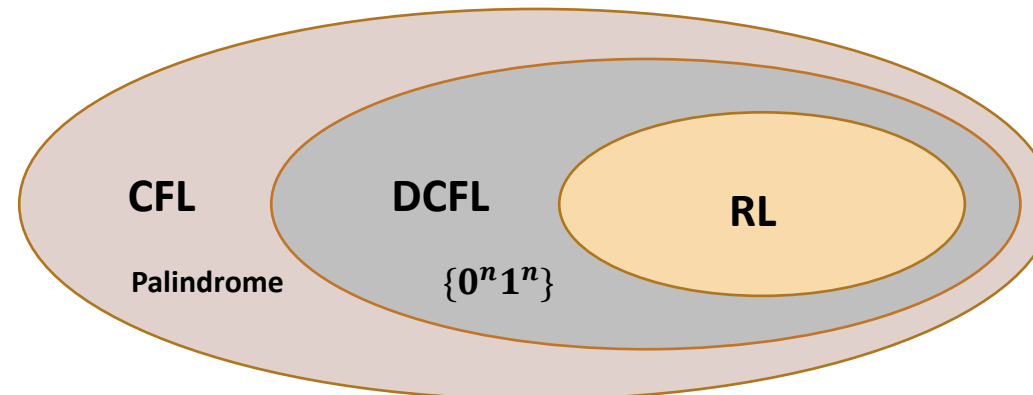
## Closure properties of CFLs

CFLs are closed under

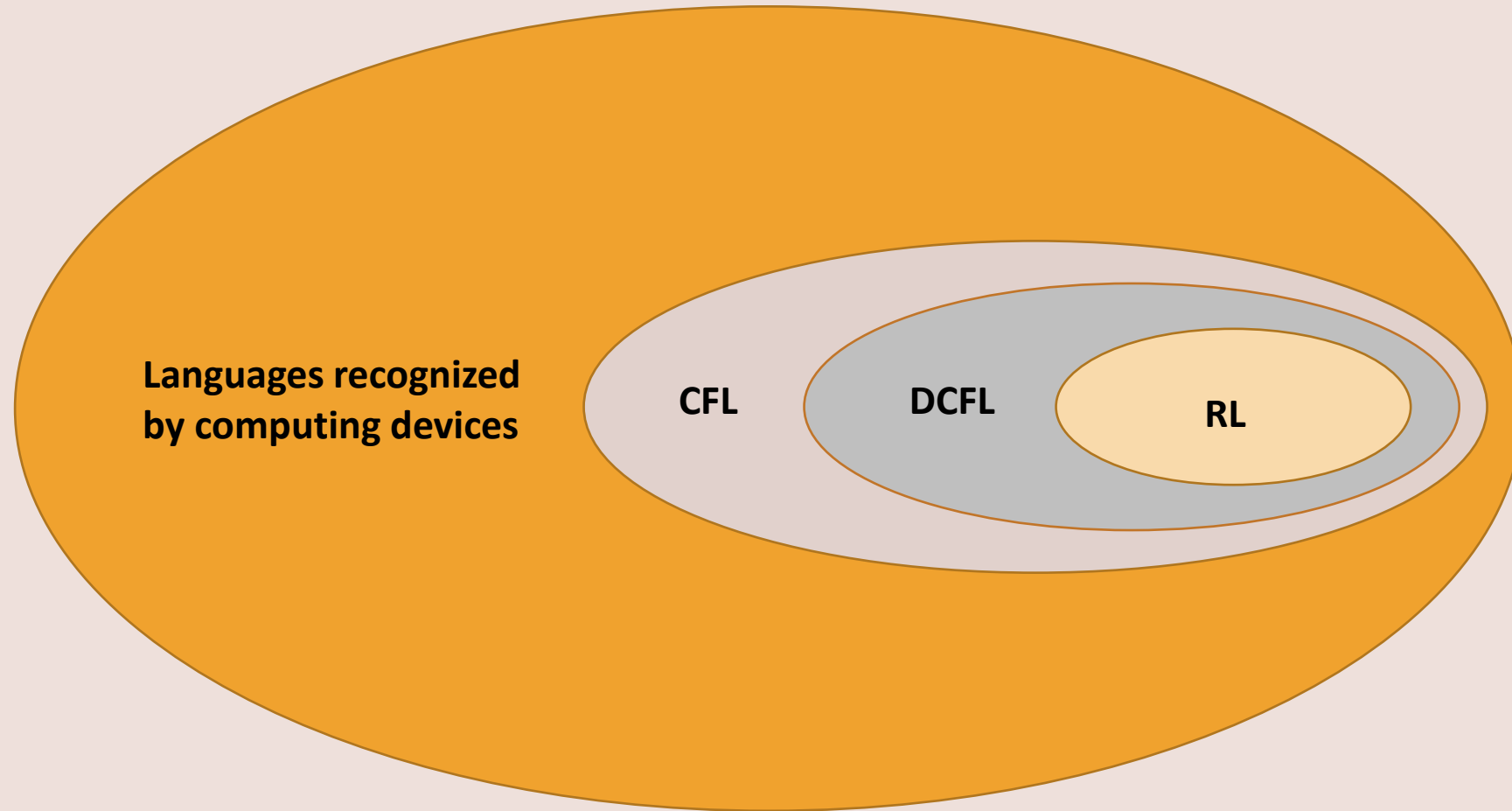
- Union
- Star
- Concatenation

CFLs are NOT closed under

- Complementation
- Intersection



**The set of all languages**



**Languages recognized  
by computing devices**

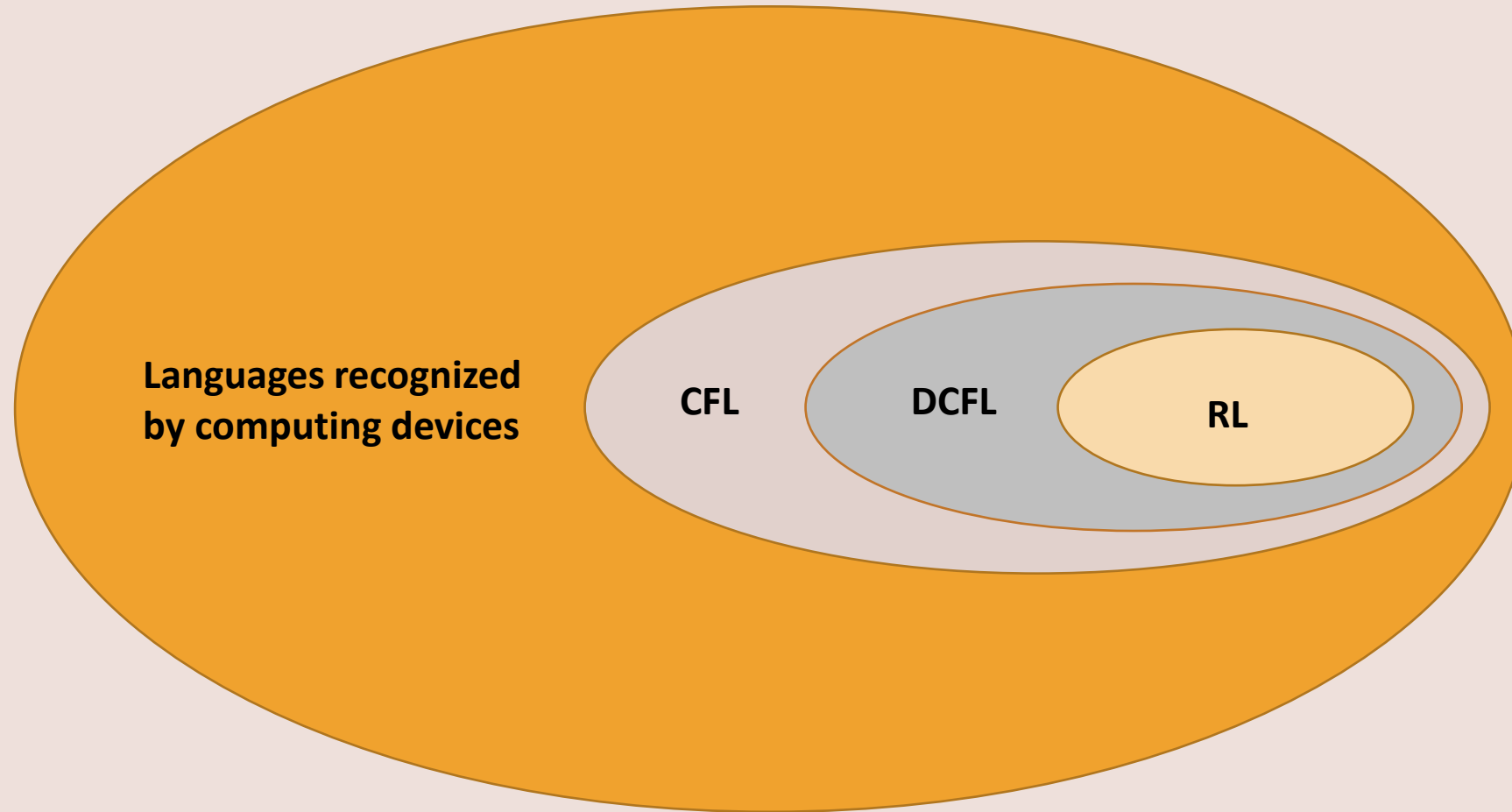
**CFL**

**DCFL**

**RL**

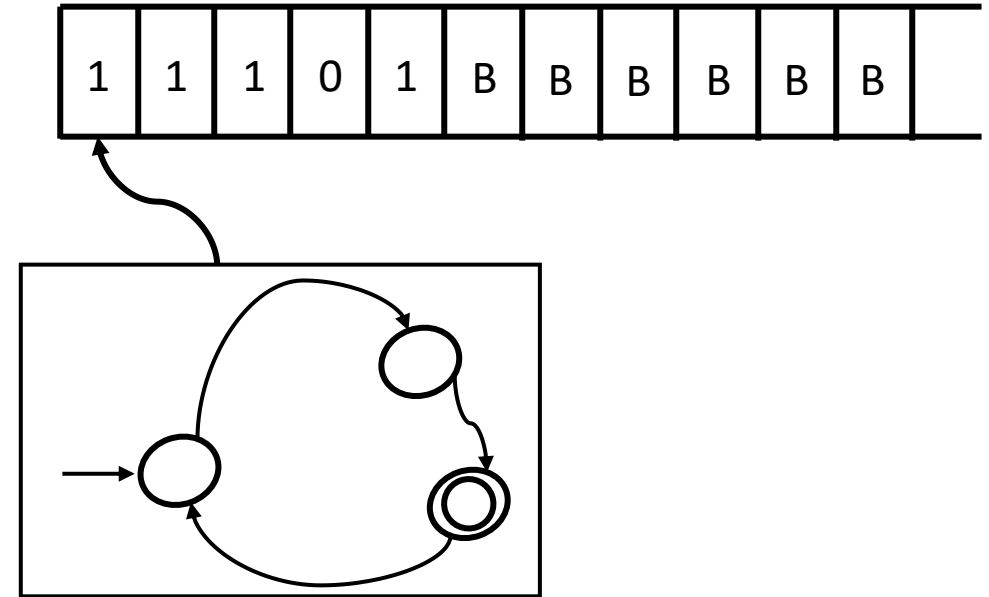
**Which languages lie here?**

**The set of all languages**



# Turing Machines

- A Turing machine is a FSM that has access to a infinite tape as its memory.
- The infinite tape contains in it, the input string followed by Blanks (indicated by B)
- The Turing machine can both read from the tape and write in it – one cell at a time, using a Read/Write head.
- The Read/Write head can move to the Left or to the Right – again one cell at a time.

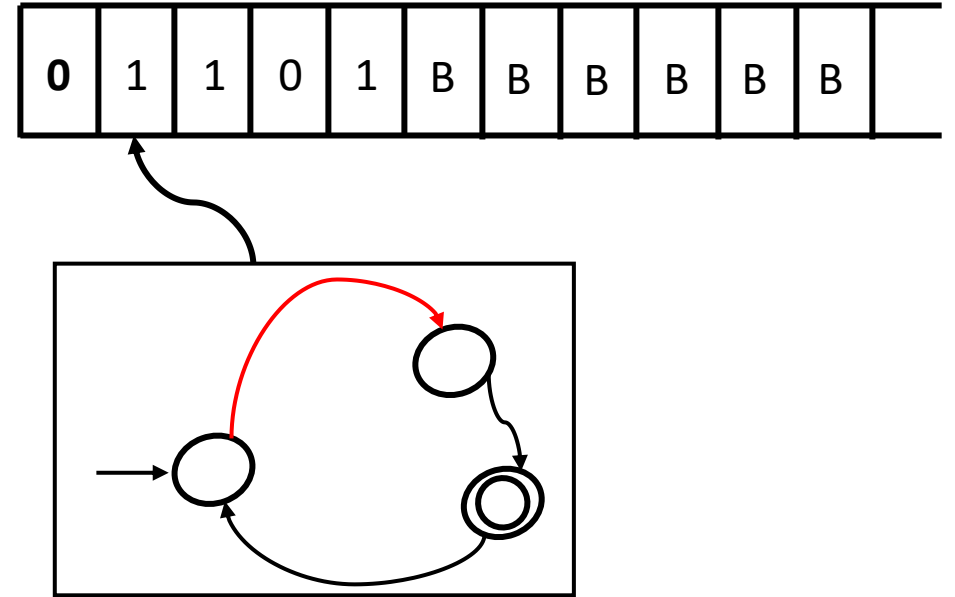


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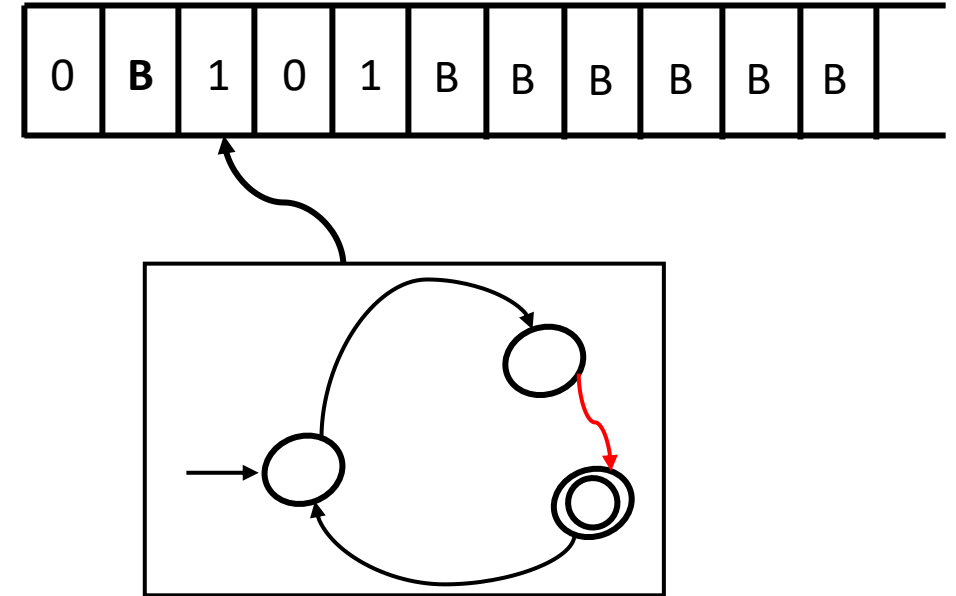


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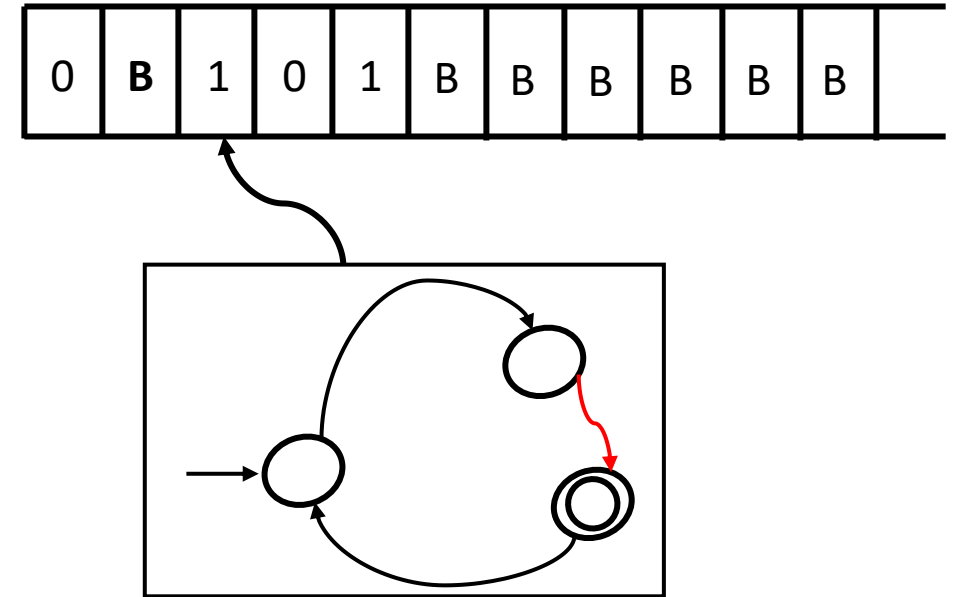


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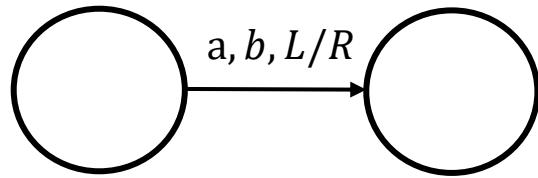
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- In a way these “added features” give TMs their power. (eg: ability to write on the tape)
- Notice: acceptance/rejection of a run is not tied to the input.
- Auxiliary computation can be performed – as much as needed, even when the input string has been scanned



# Turing Machines



Transition  $a, b, L/R$ : Read  $a$  from the tape, replace with  $b$  and move  $L/R$



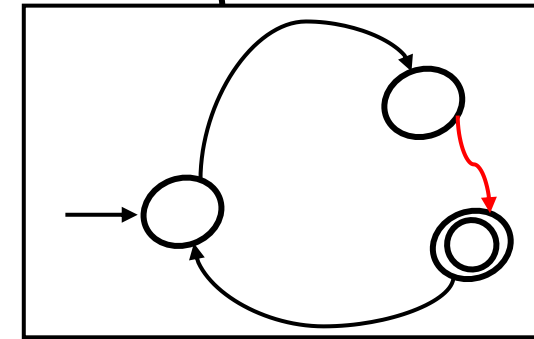
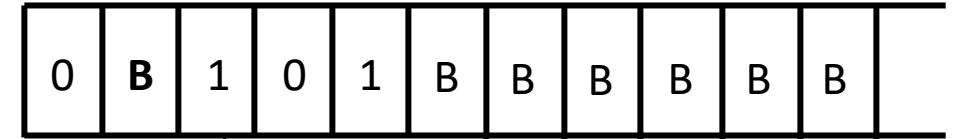
Accept state



Reject state

TM may never halt – it may loop forever

TM halts and **accepts/rejects** on reaching these states

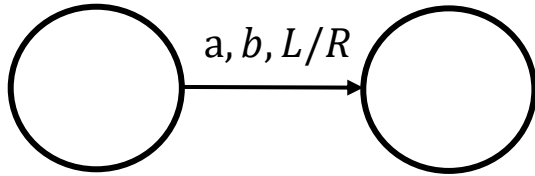


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# Turing Machines



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So, given a TM  $M$  and an input  $\omega$ ,

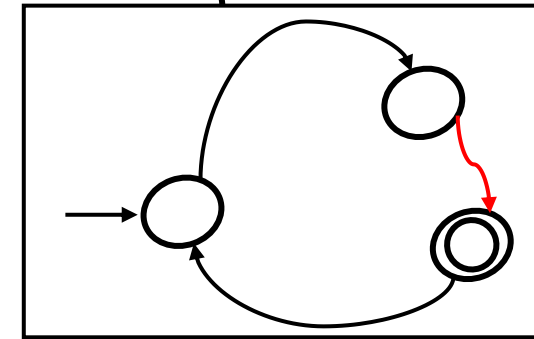
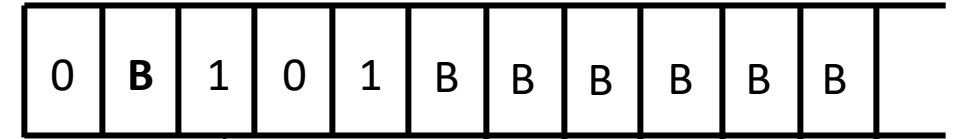
$M(\omega)$  **accepts** if  $\omega \in L(M)$

$M(\omega)$  **rejects** if  $\omega \notin L(M)$

$M(\omega)$  **runs infinitely** if  $\omega \notin L(M)$



TM halts and **accepts/rejects** on reaching these states



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Turing machines are named after **Alan Turing**. In 1936, he gave a negative answer to Hilbert's *Entscheidungsproblem* (Decision problem) – *Are all decision problems decidable?*

ON COMPUTABLE NUMBERS, WITH AN APPLICATION TO  
THE ENTSCHEIDUNGSPROBLEM

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- Turing assumed that the human brain to be a finite state machine with a finite number of states
- Consider such a human being working on a problem with a notebook, pencil and an eraser.
- The pages of the notebook are laid out on the tape – each cell consists of one page, with a finite amount of information.
- Whatever the human being does with the notebook, can be simulated on the TM: reading, writing, erasing (writing a blank), moving left or right to a new page etc.

# Turing Machines

**Example:** Let  $L = \{0^n 1^n \mid n \geq 1\}$

We will try to develop the basic idea in designing the Turing Machine for this language. Note that  $L = CFL$ .

**Idea:** An accepting run of a TM for  $L$  could look something like this:

- Mark the first 0 (by replacing it with some special symbol say  $X$ )
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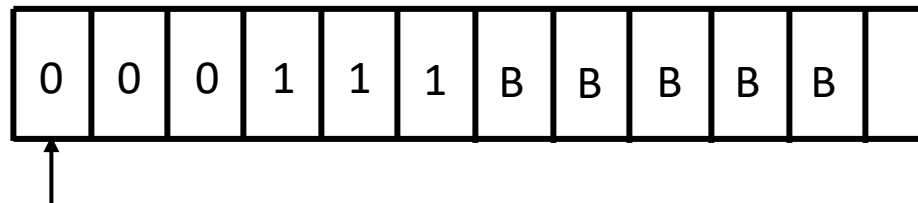
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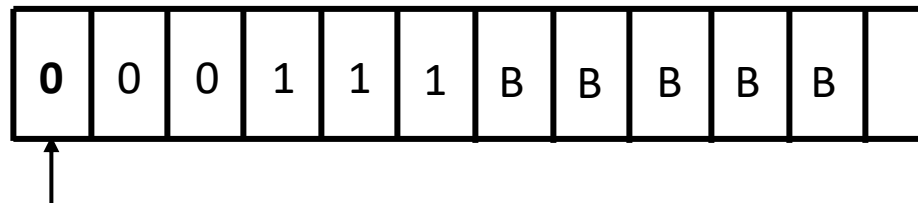
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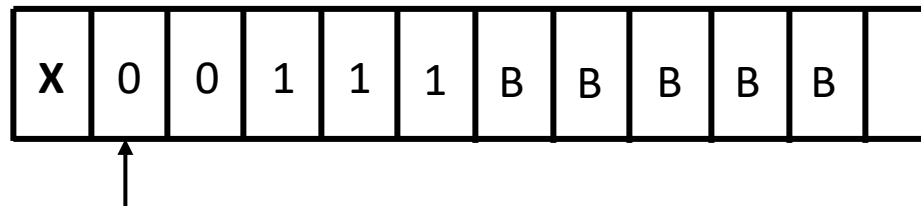
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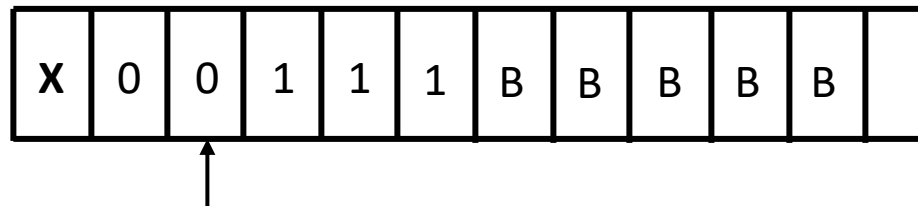
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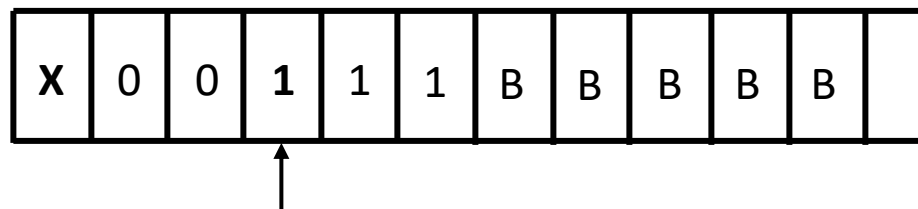
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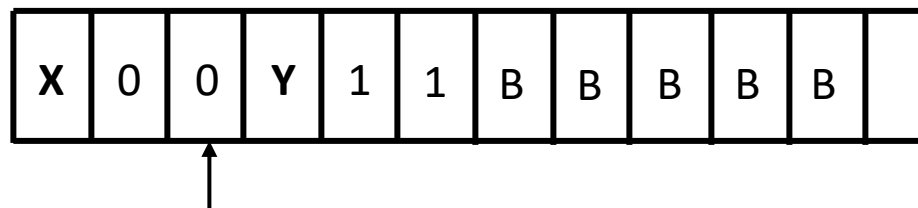
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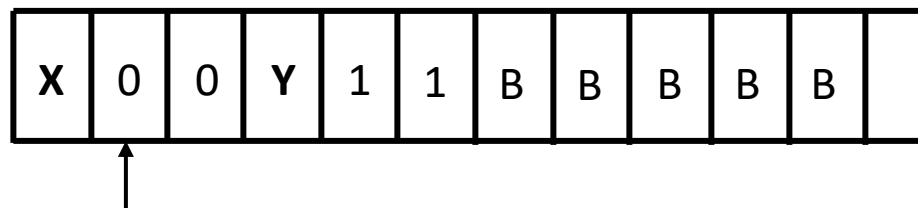
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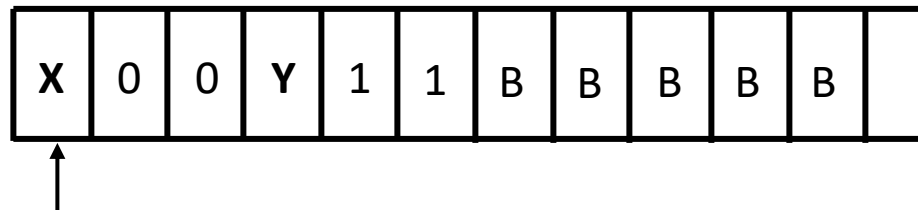
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While moving left, when an  $X$  is encountered, the head should move right until the next 0 to be marked is encountered  $\Rightarrow$  **We need rules like  $(X, X, R)$**

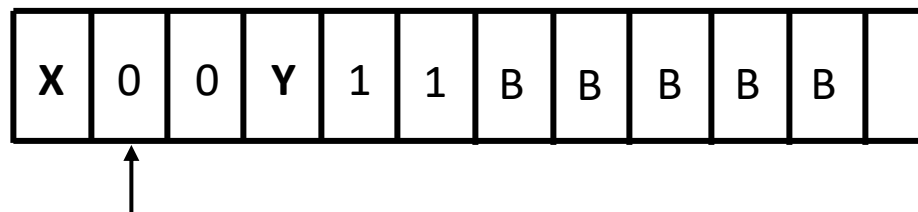
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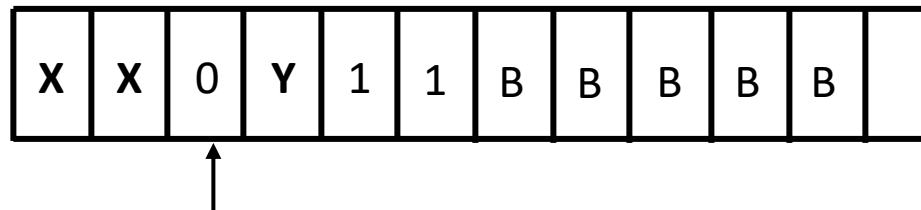
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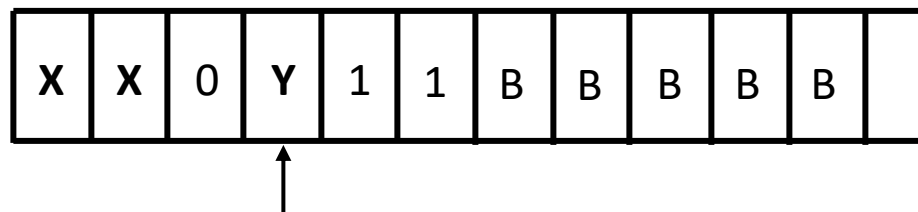
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While moving right, when a  $Y$  is encountered, the head should move right as that's where the next 1 to be marked is  
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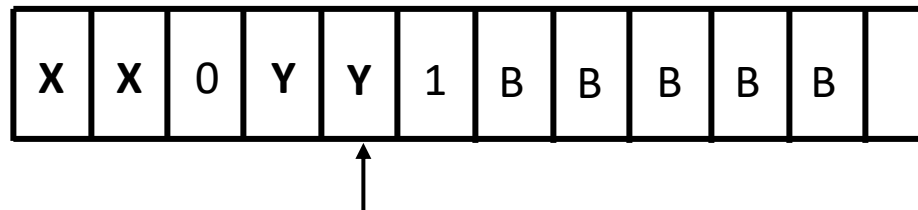
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While moving left, when a  $Y$  is encountered, the head should keep moving left as those 1's have been marked already  $\Rightarrow$  **We need rules like  $(Y, Y, L)$**

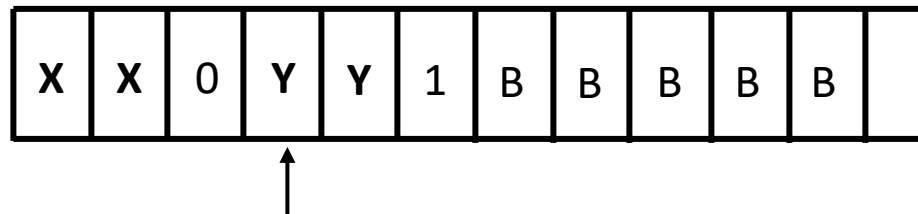
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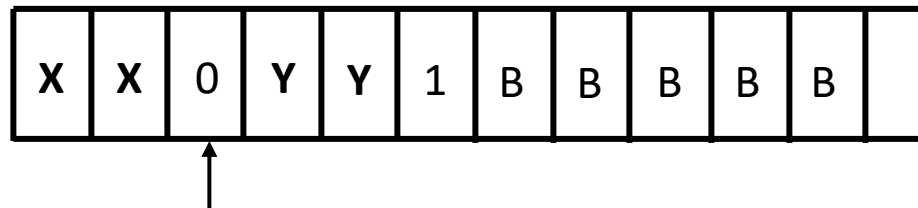
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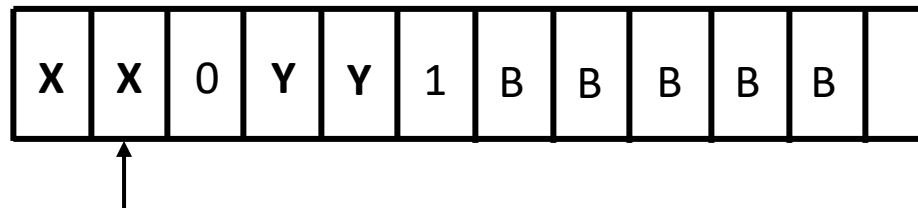
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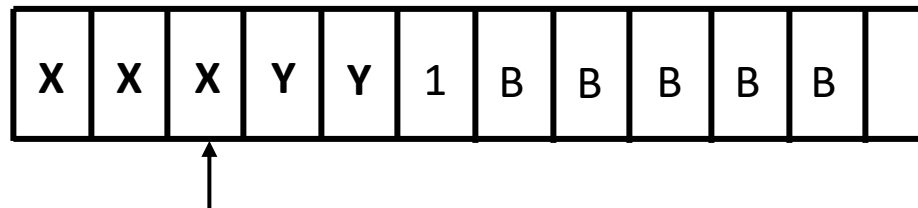
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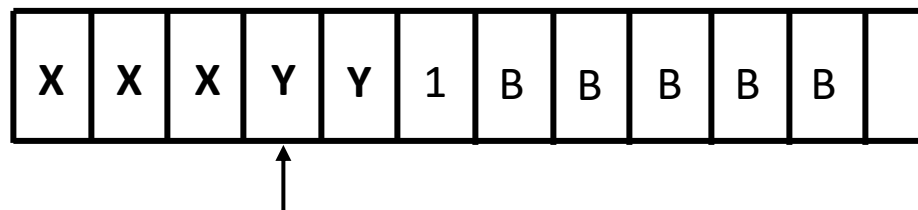
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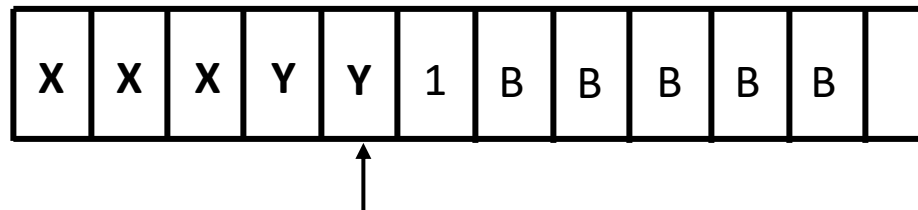
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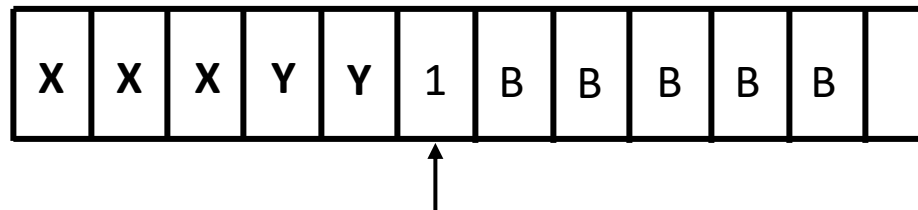
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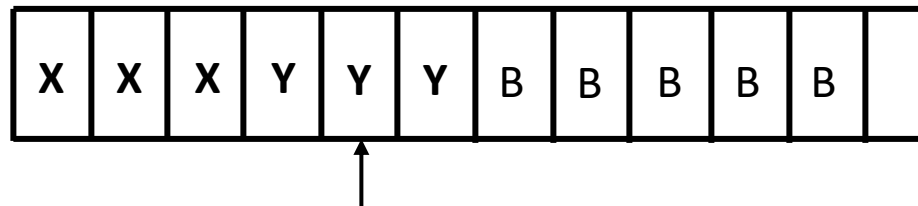
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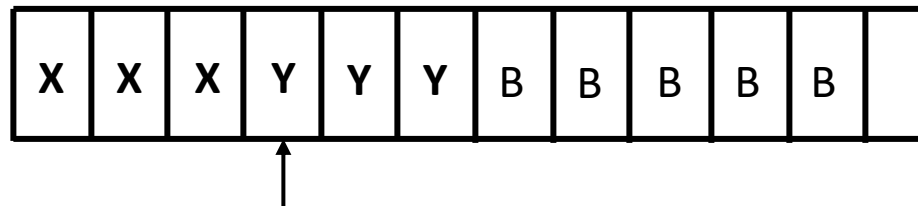
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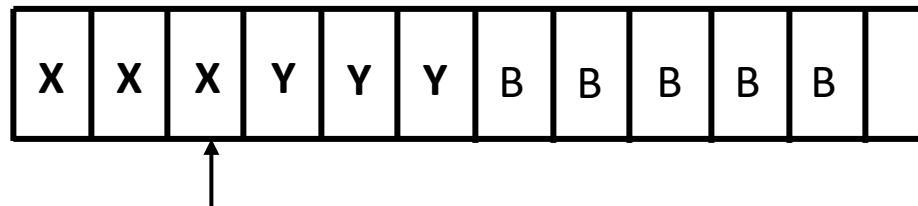
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At this stage the head should move right to look for the next 0 to mark, but finds  $Y$

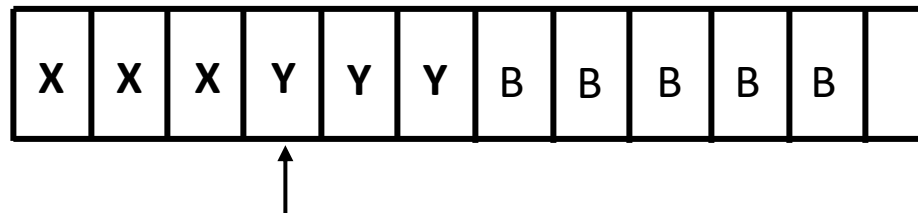
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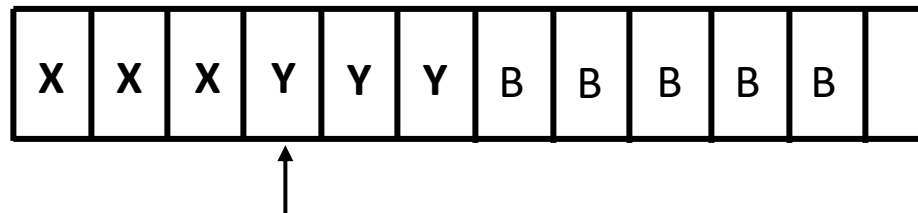
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The head keeps moving right until it finds a  $B$

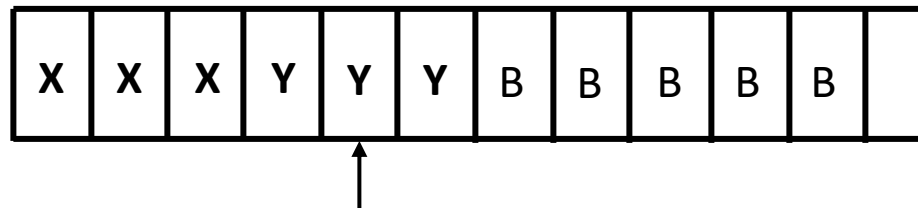
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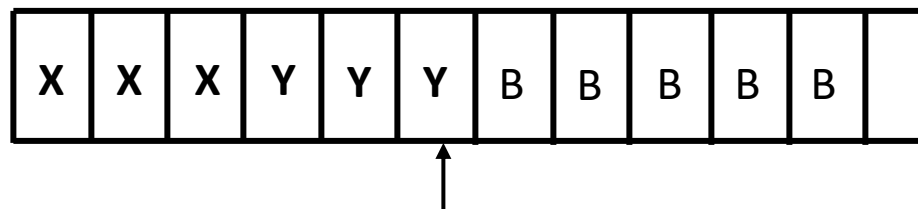
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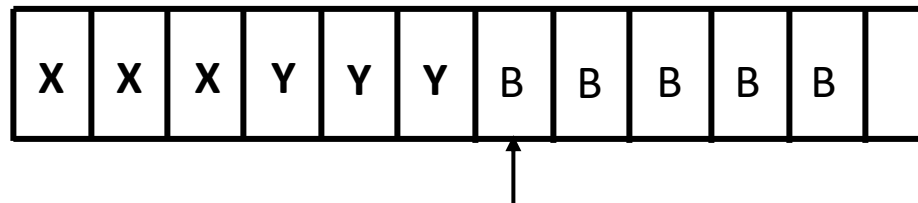
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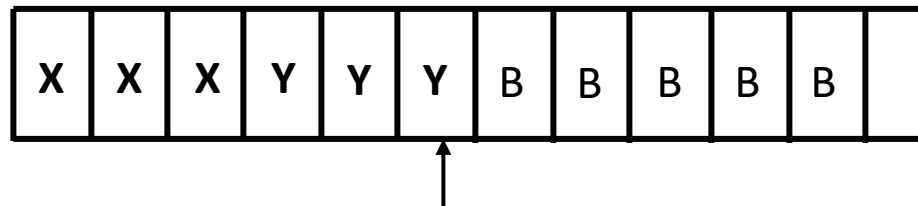
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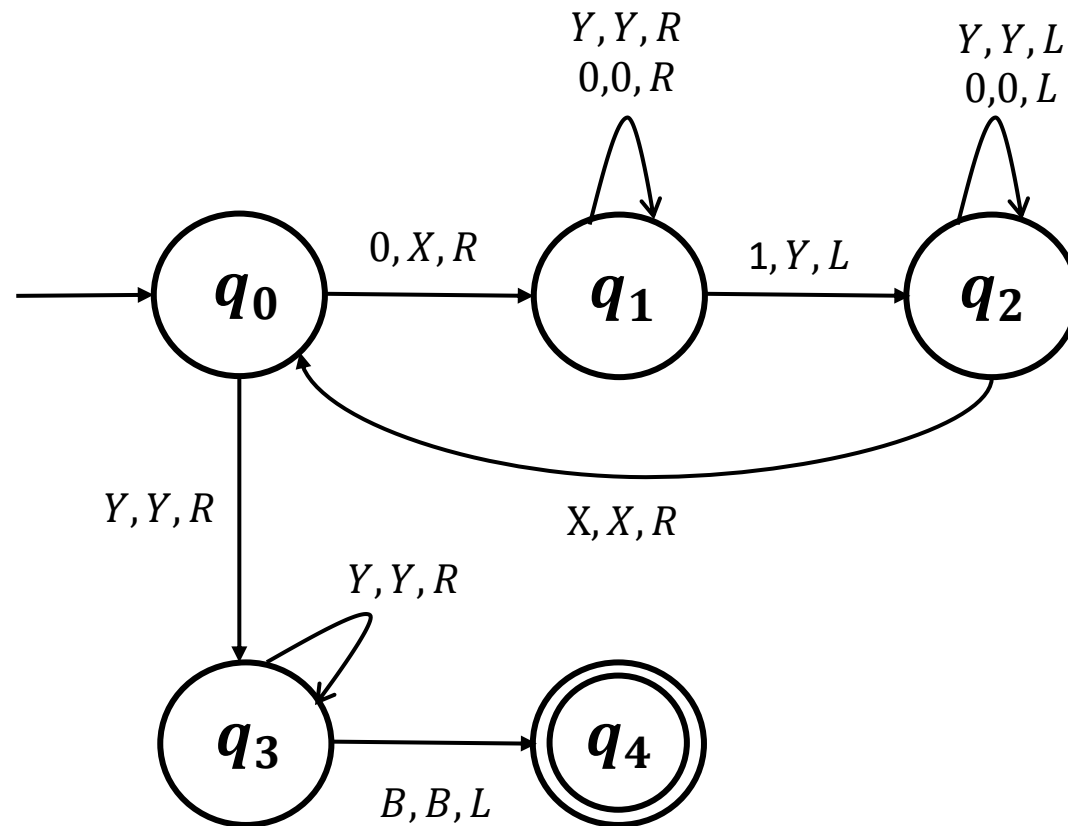
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This is when the TM decides to accept the input string.

# Turing Machines

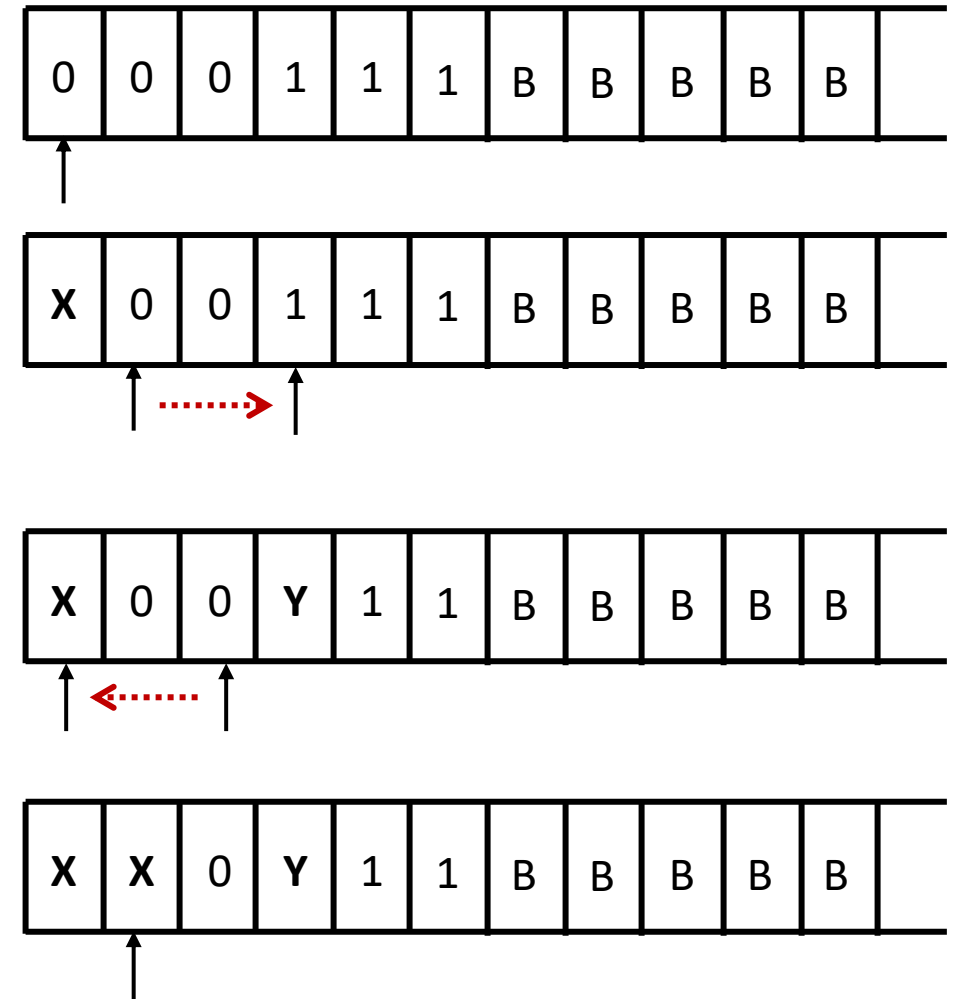
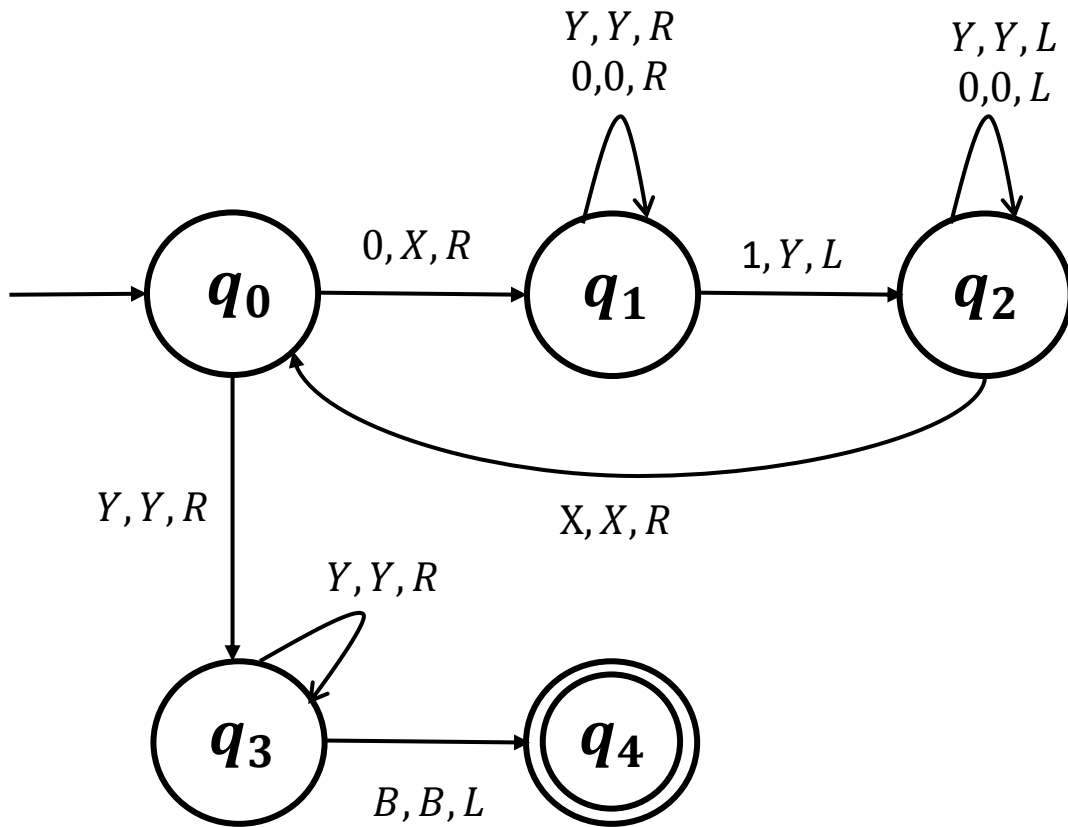
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All missing transitions lead to the reject state and the input is rejected when this state is reached.

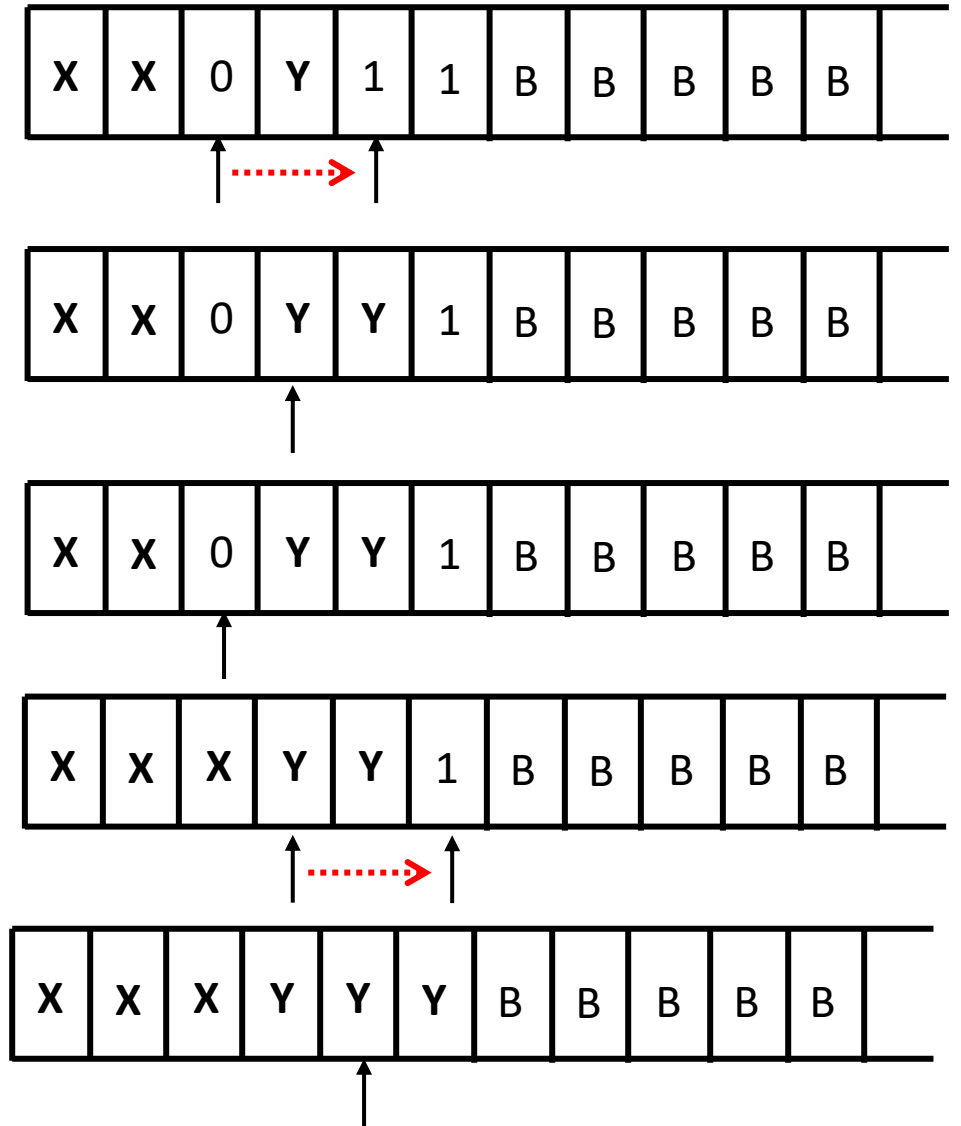
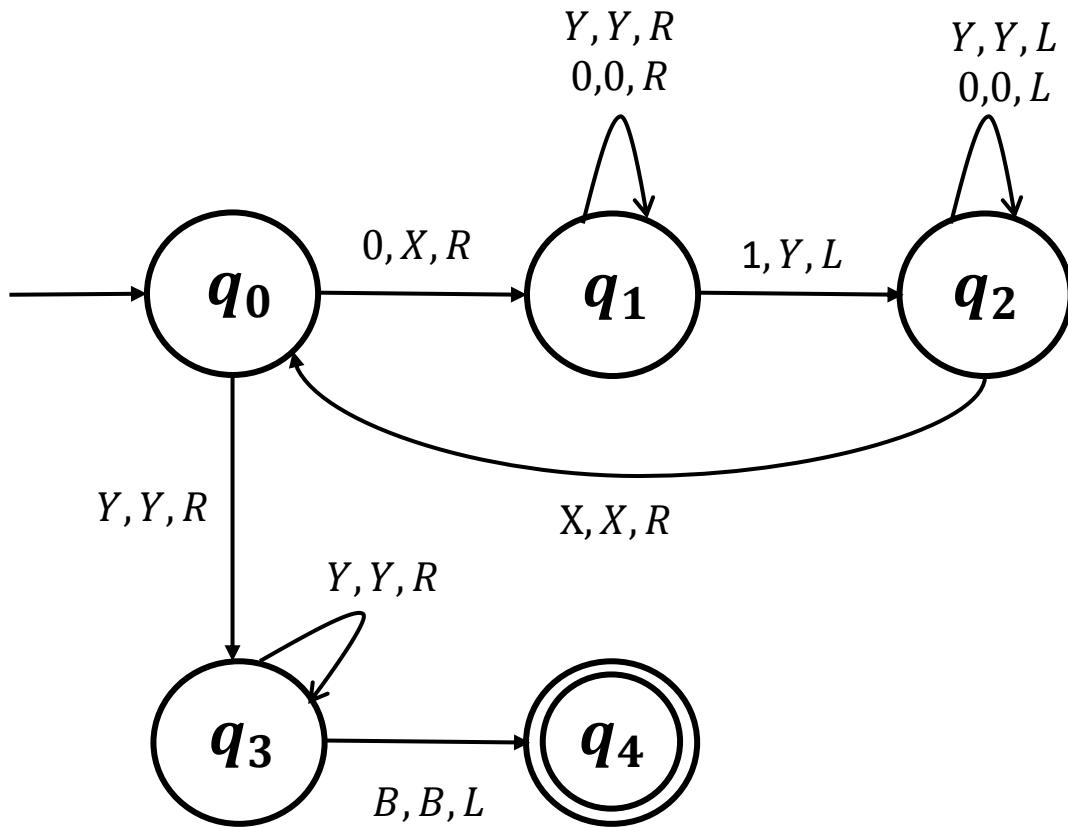
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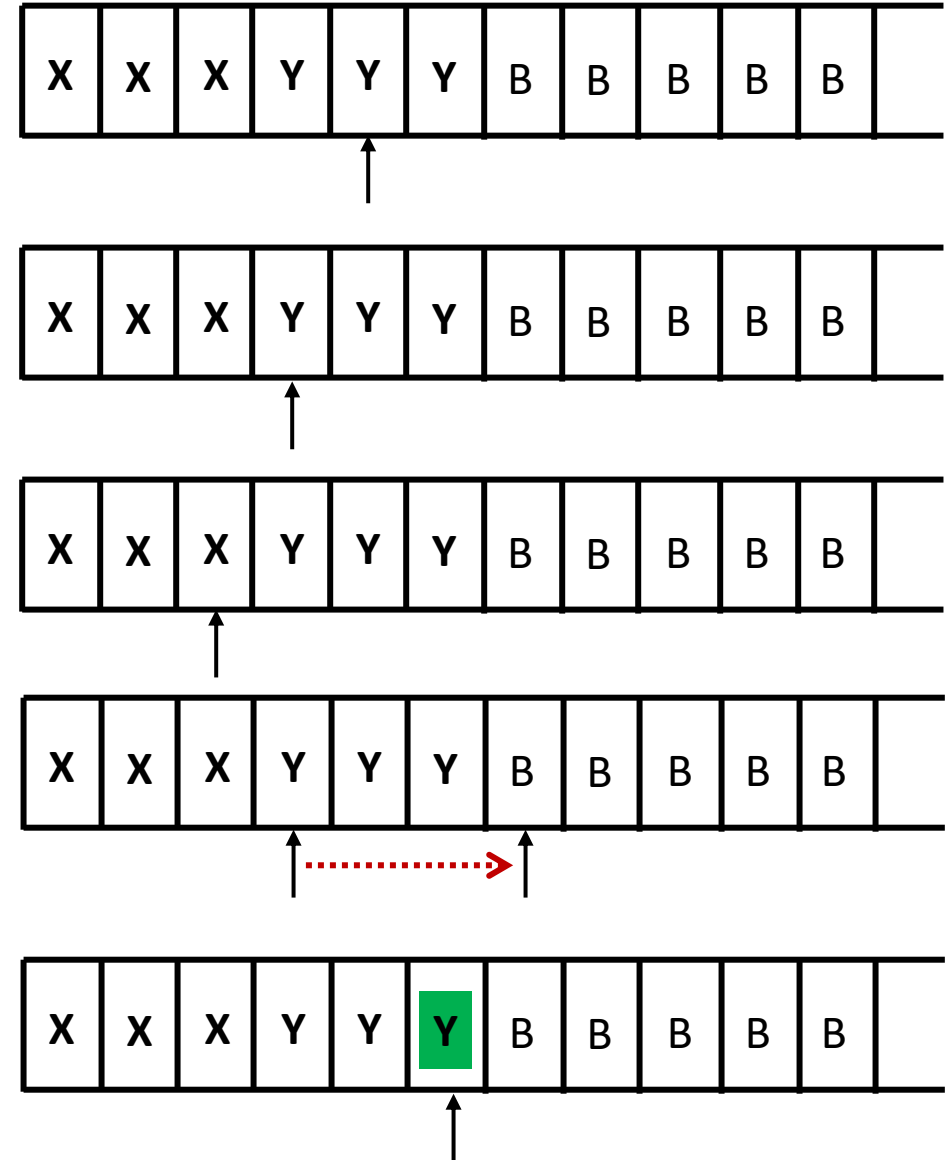
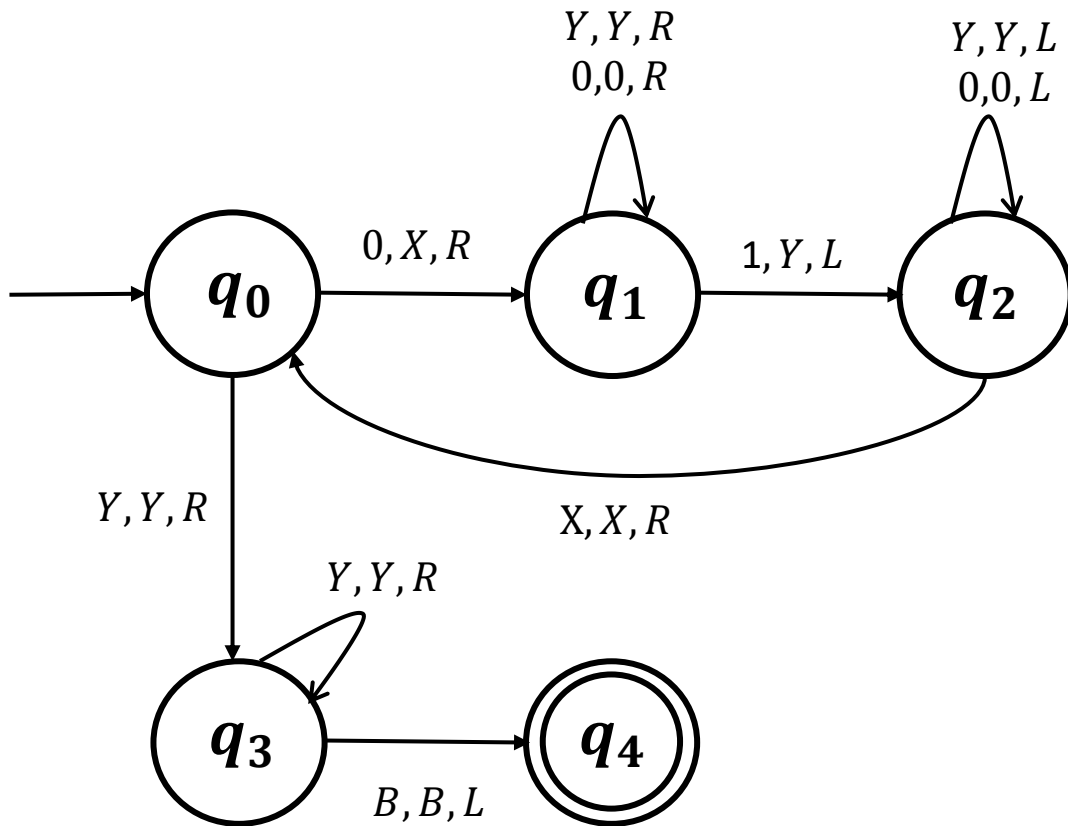
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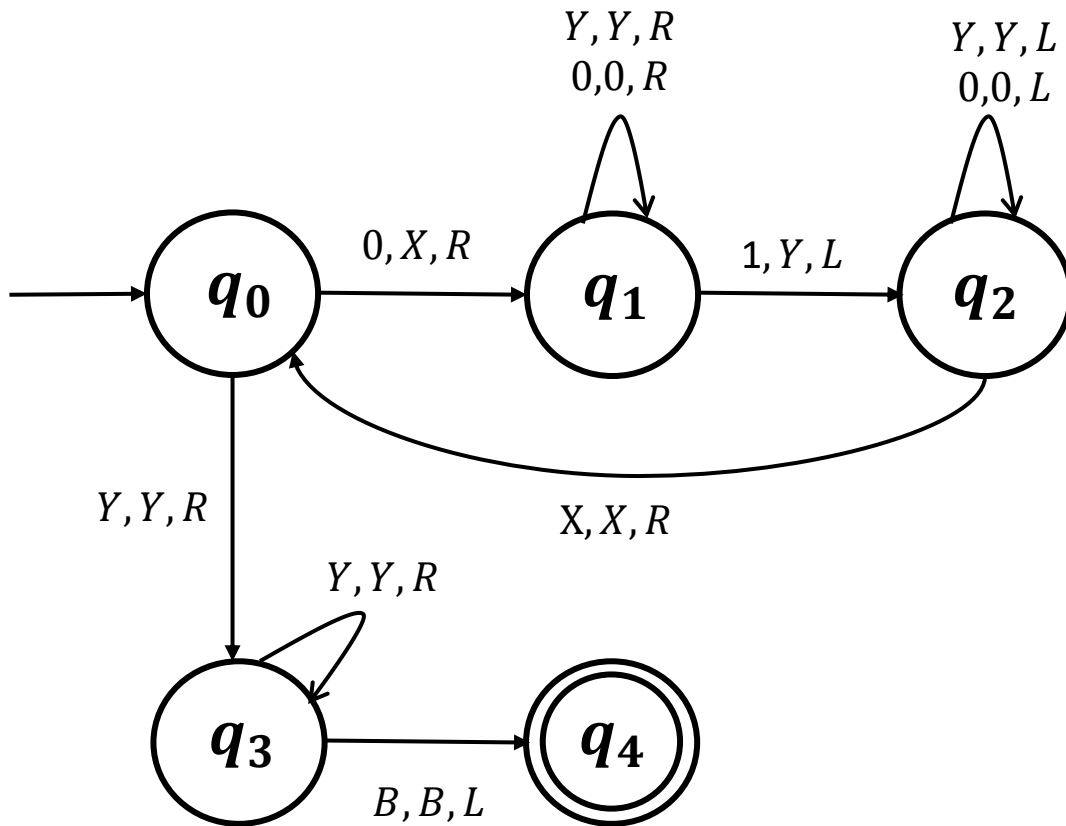
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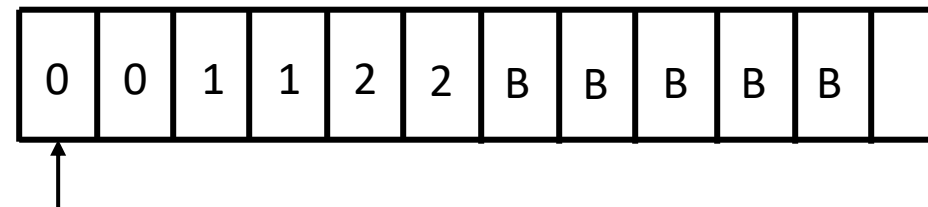


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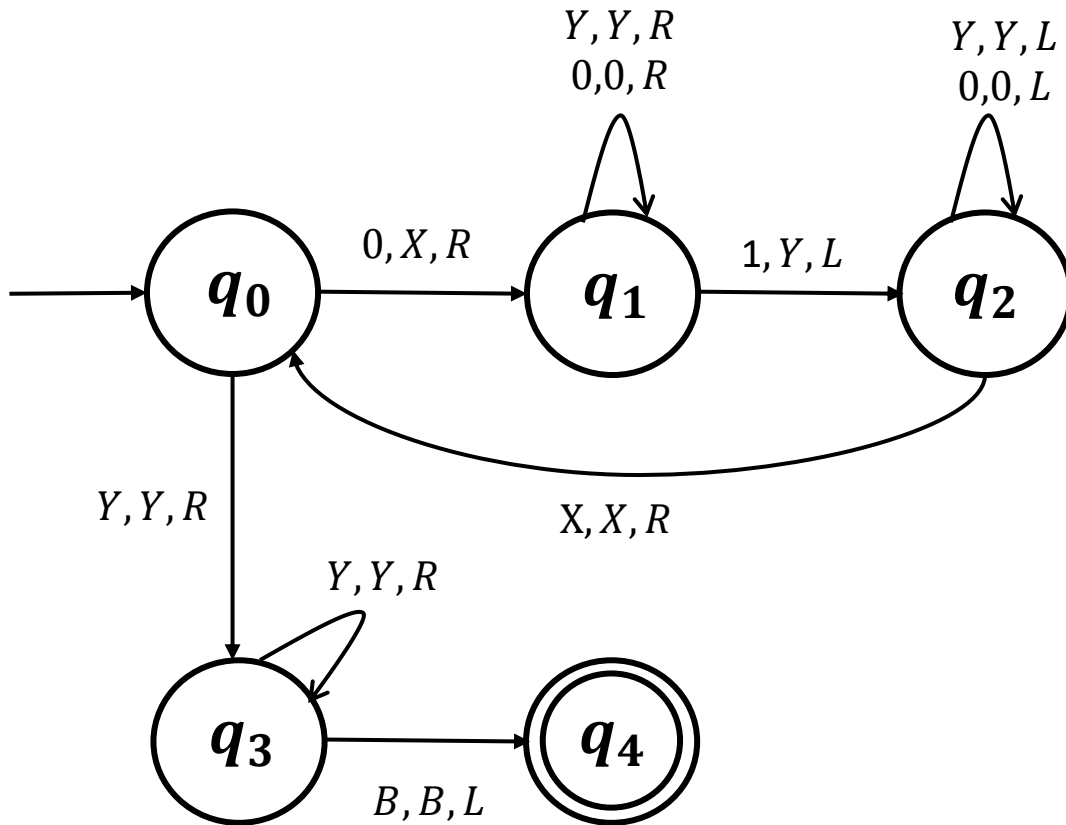


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- **Very similar to the TM for  $\{0^n 1^n\}$** , except now the FSM would count the number of 2's as well. So it marks the 2's with another symbol (say Z)

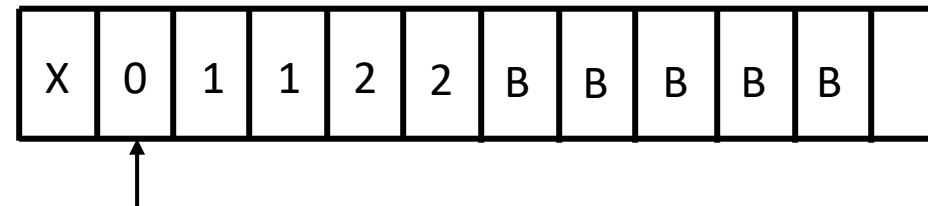


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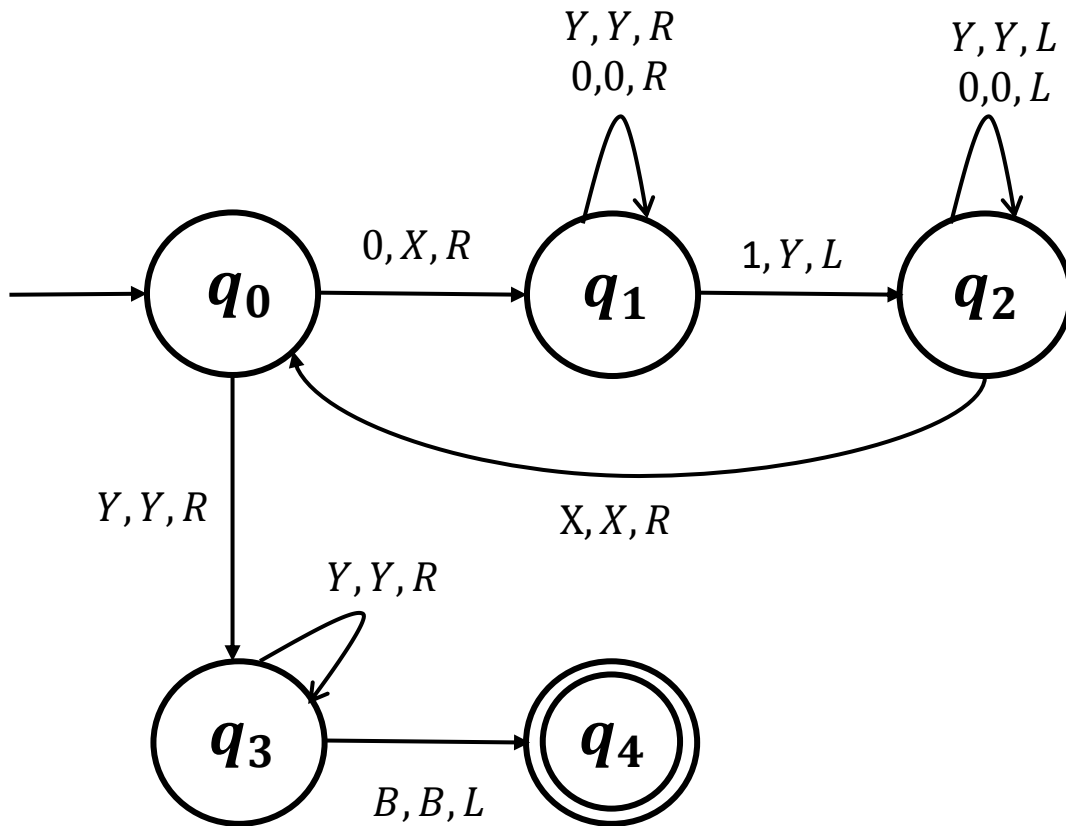


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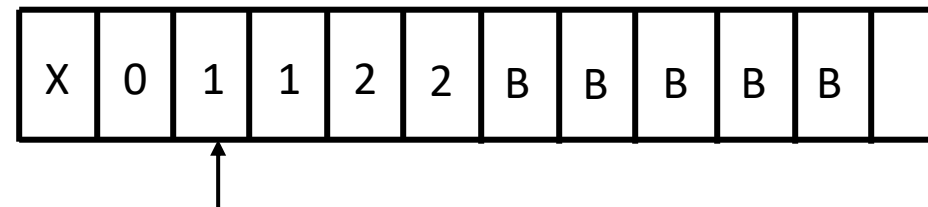


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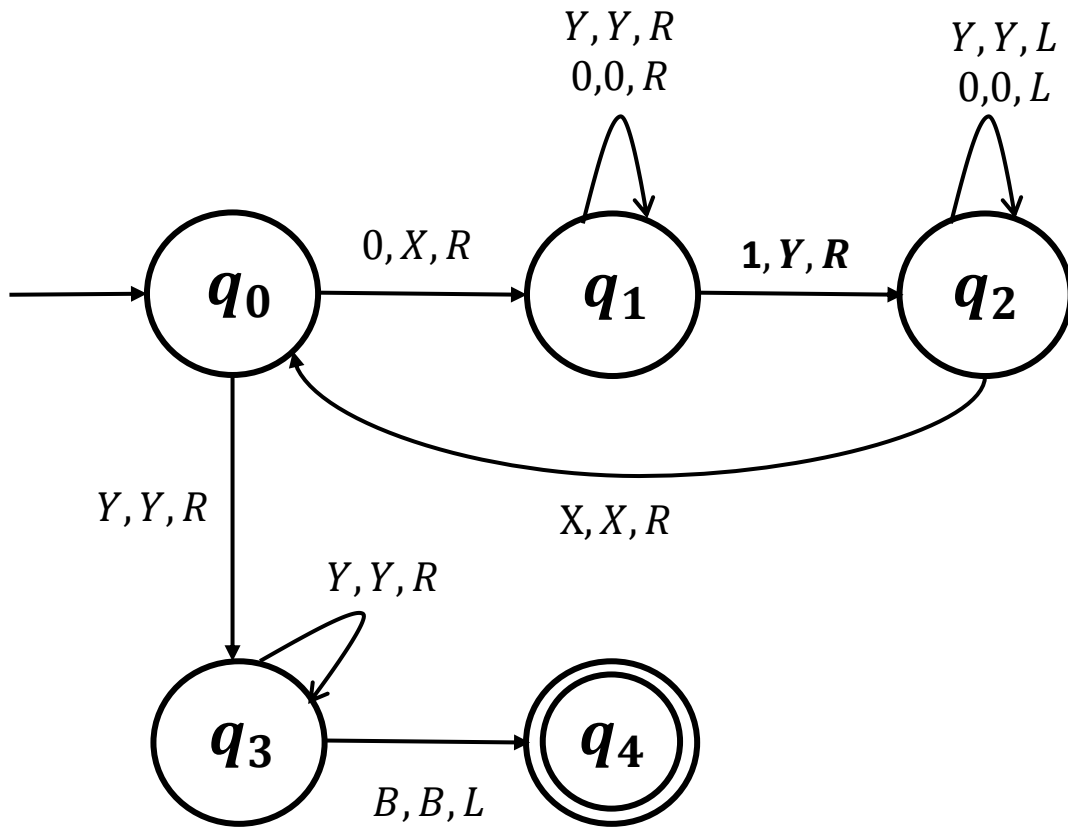
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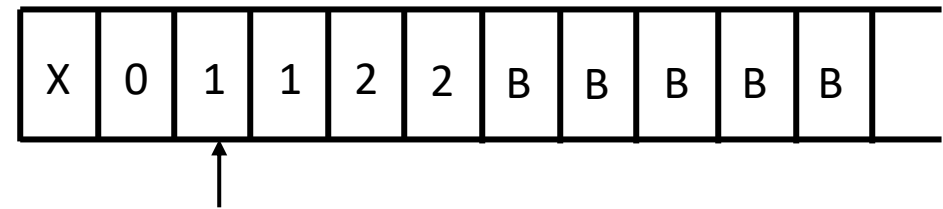


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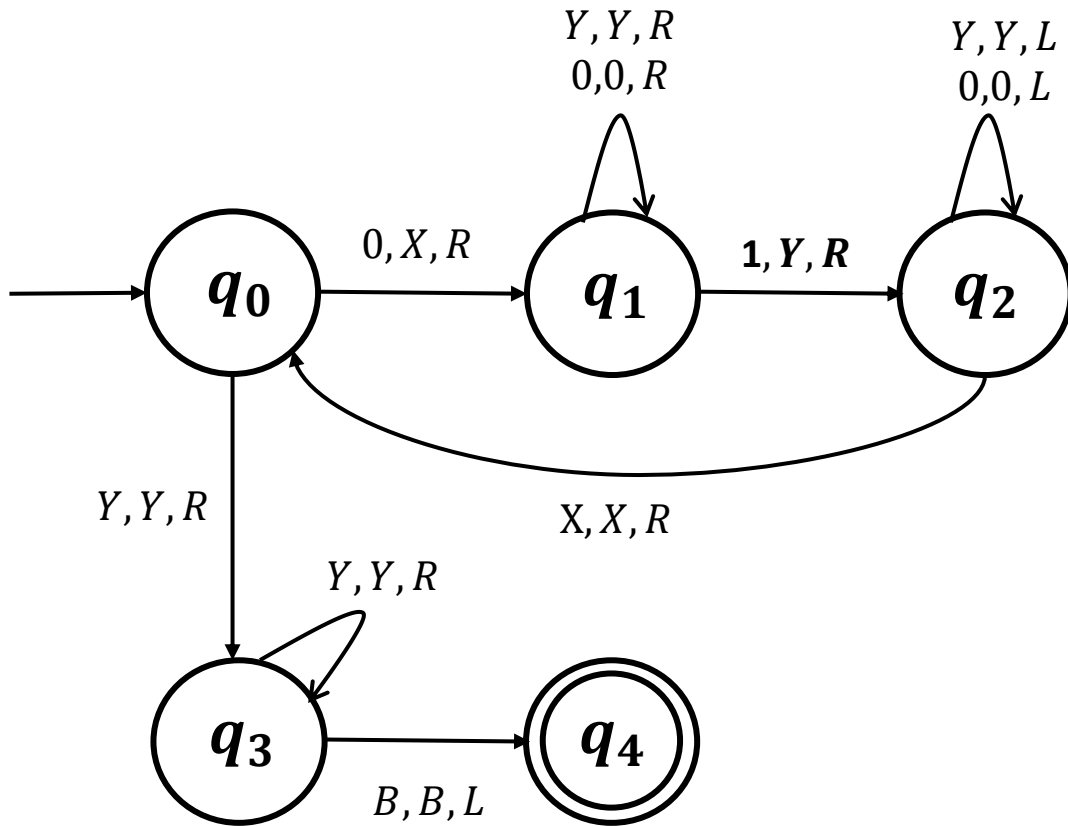


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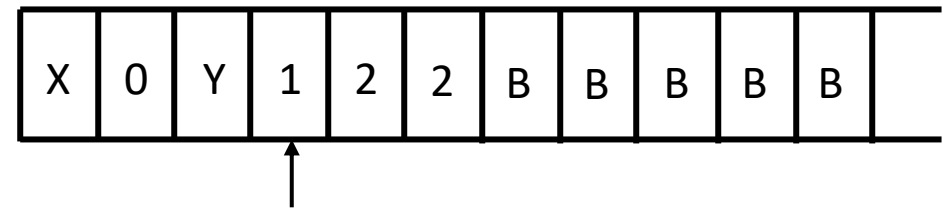


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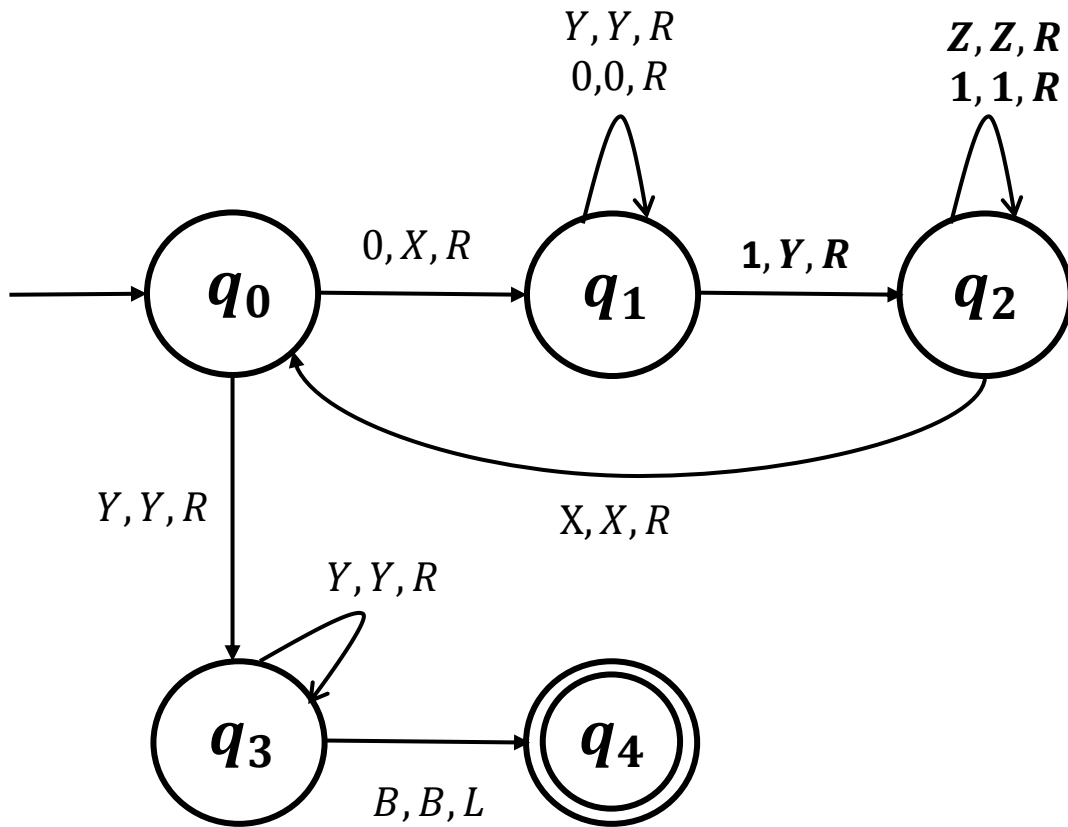


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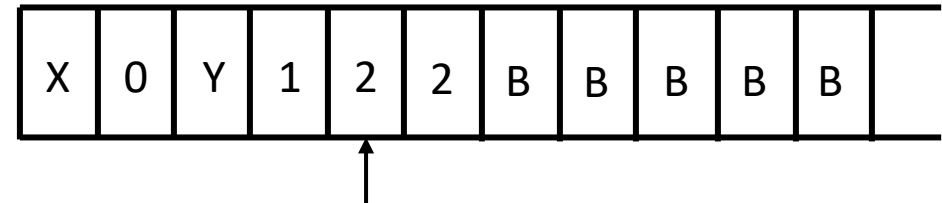


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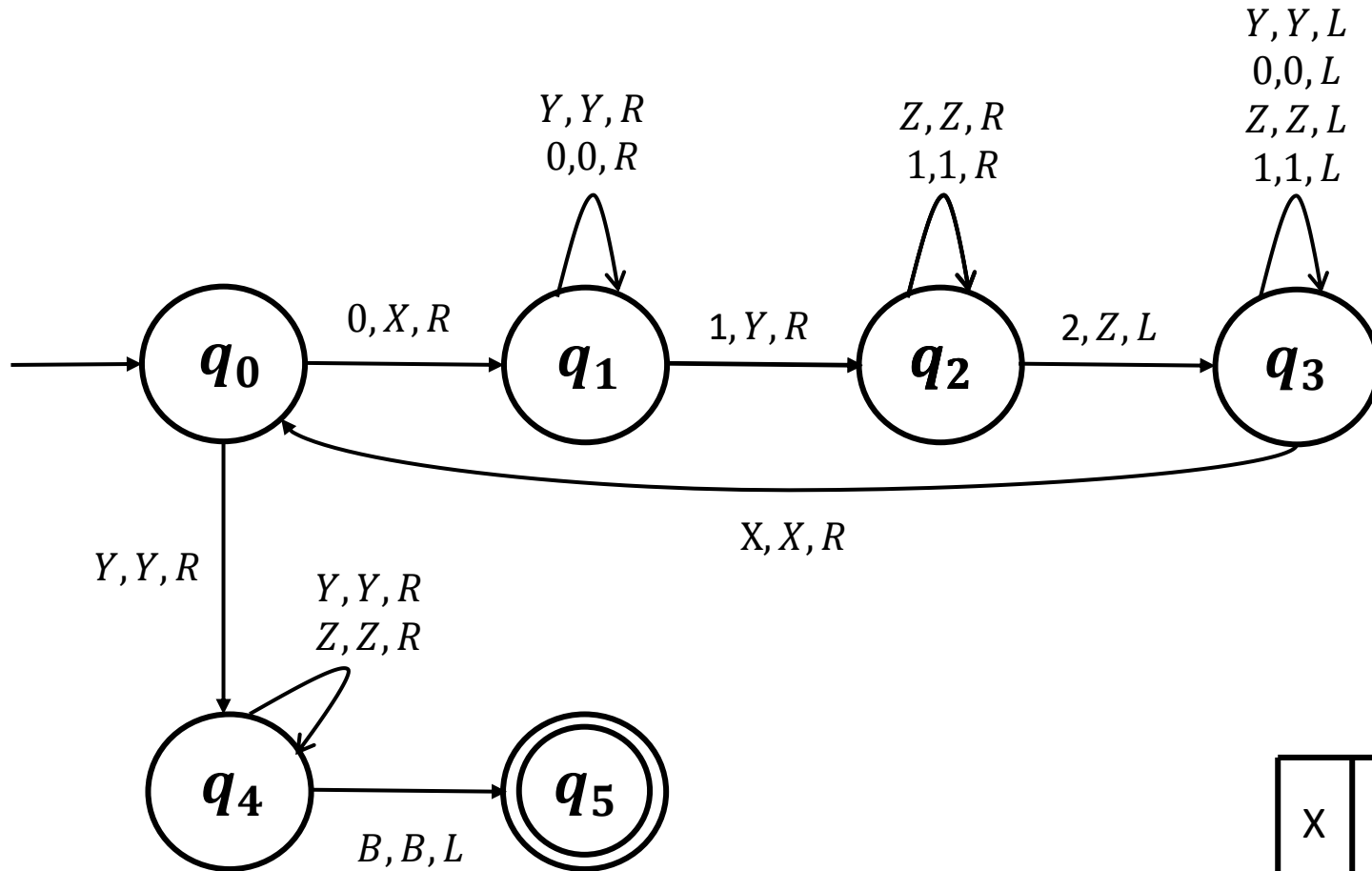


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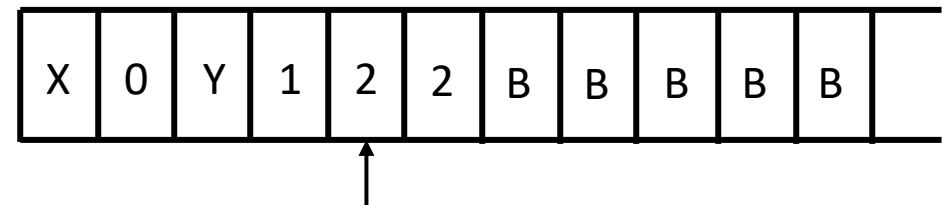


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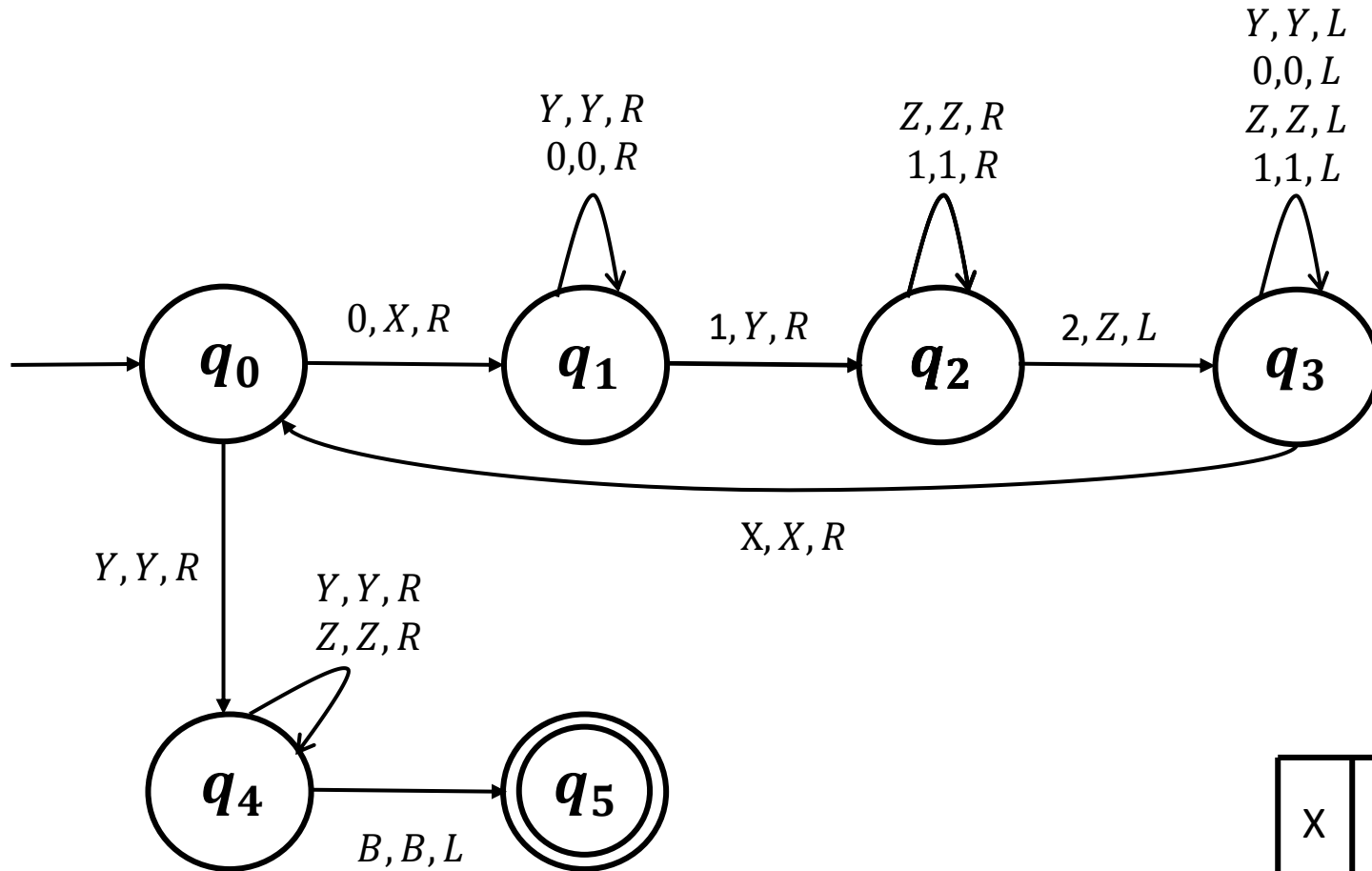


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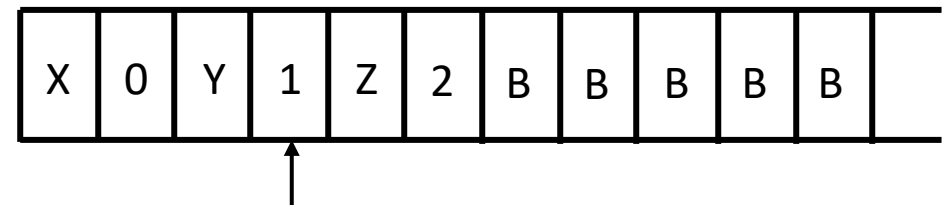


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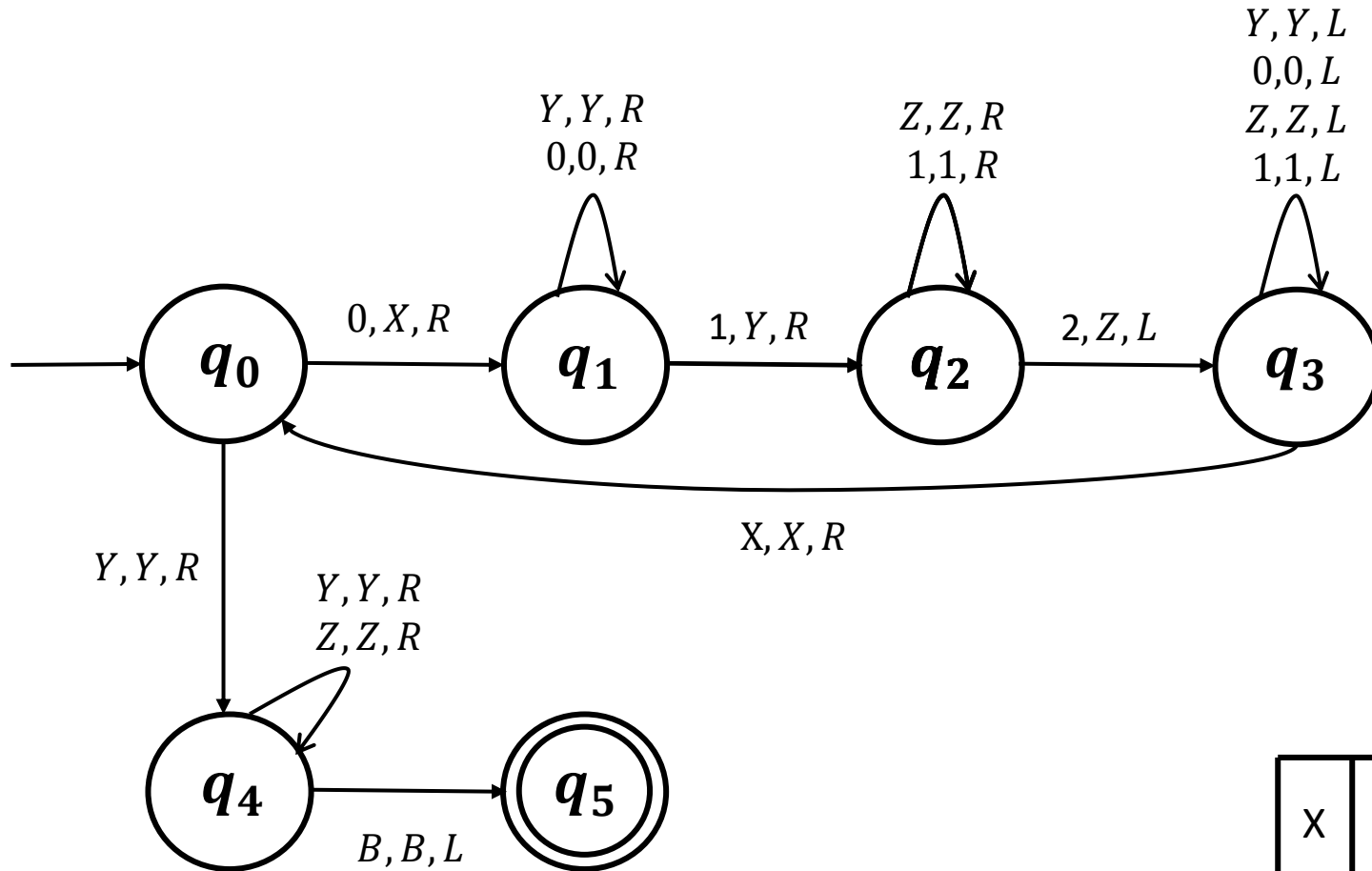


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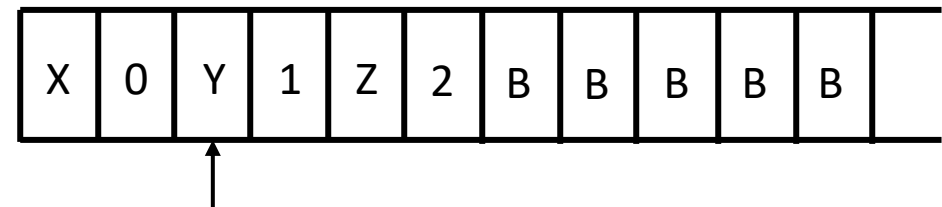


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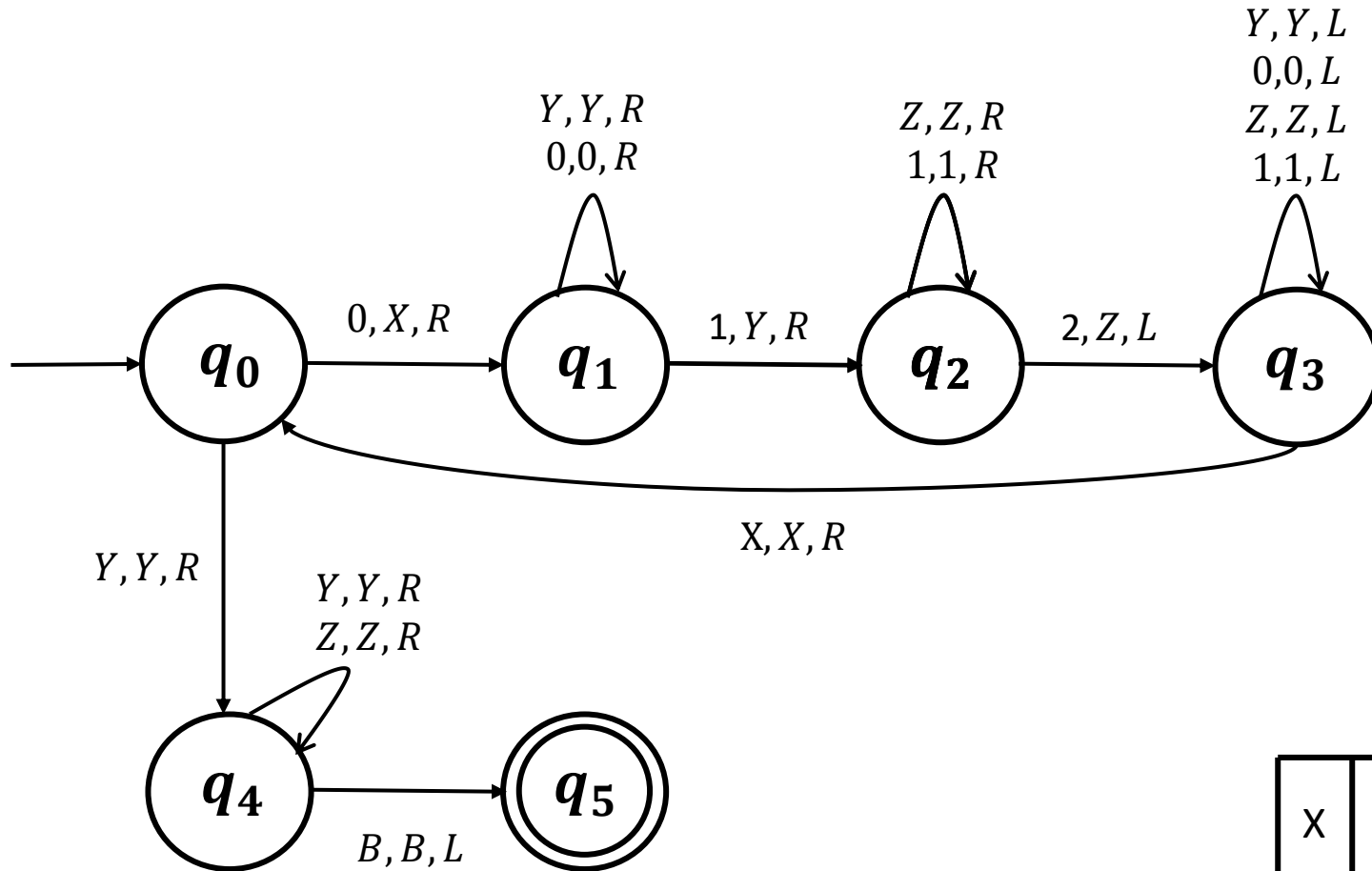


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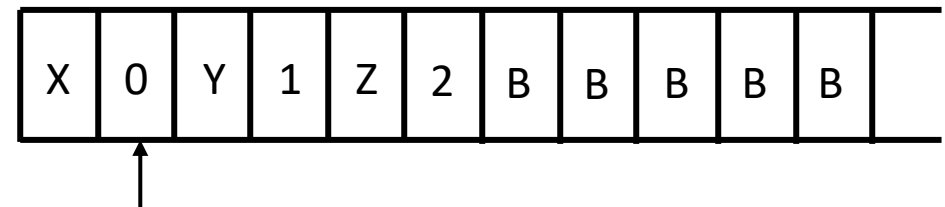


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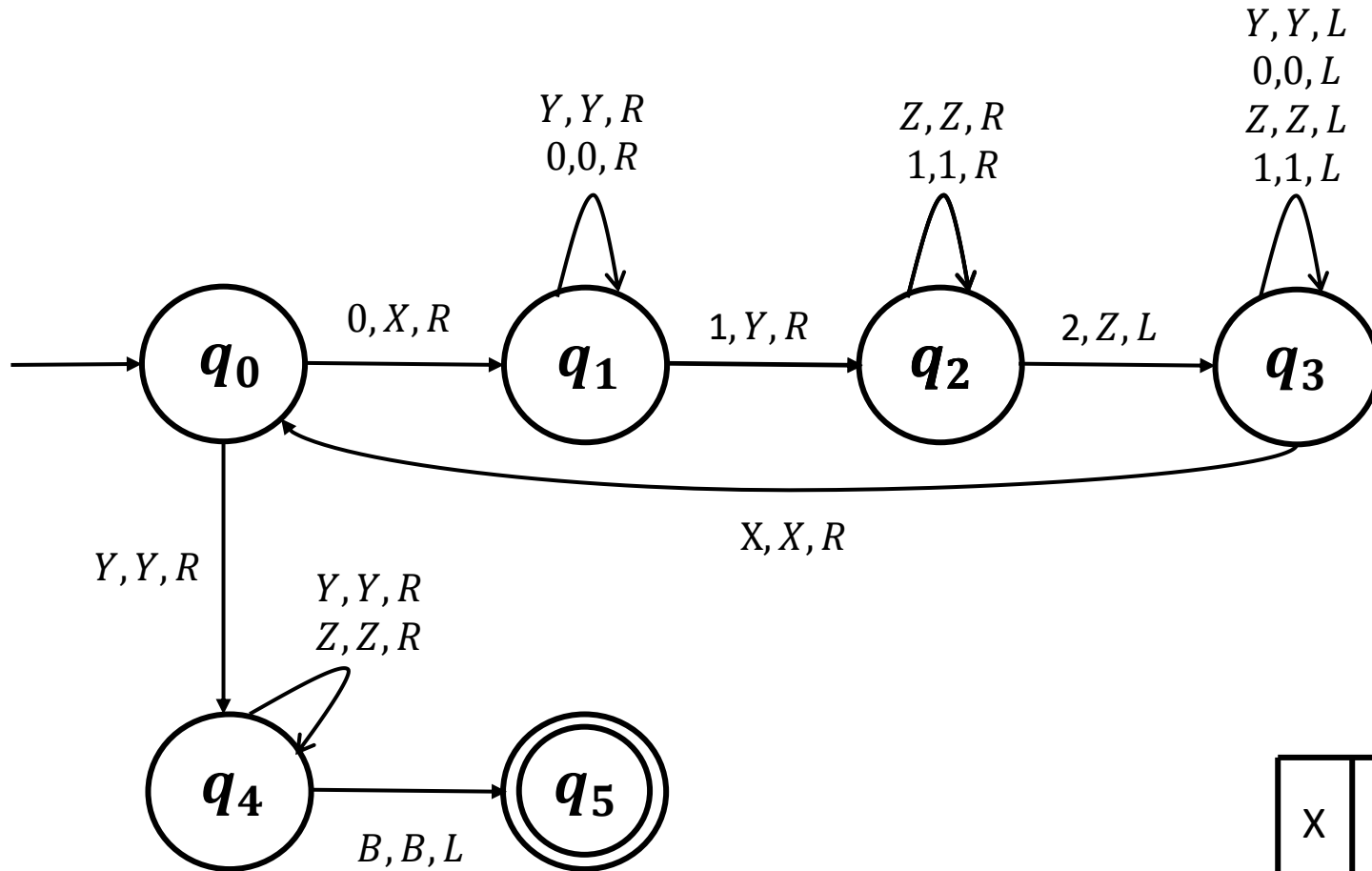


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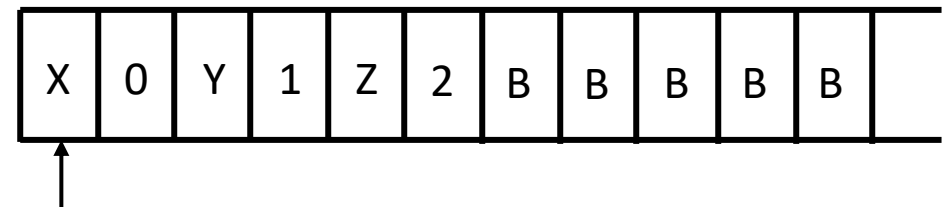


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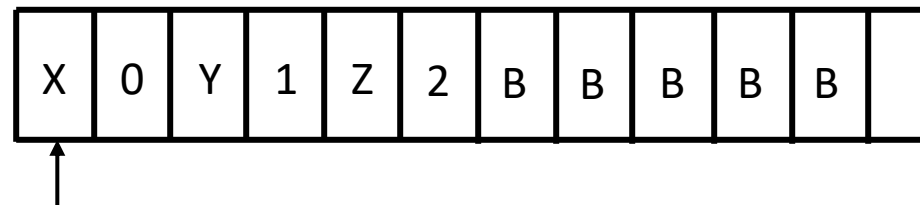
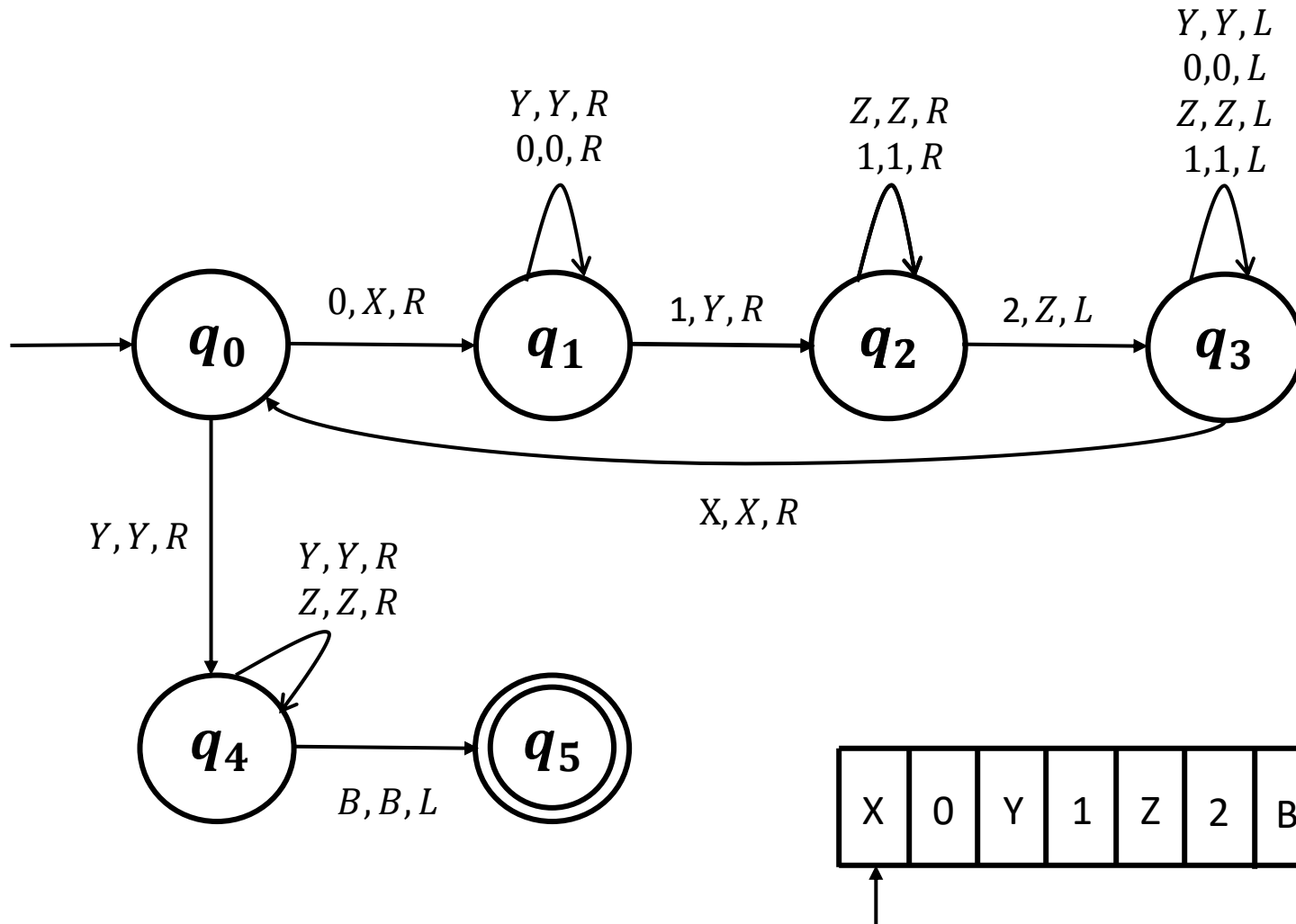
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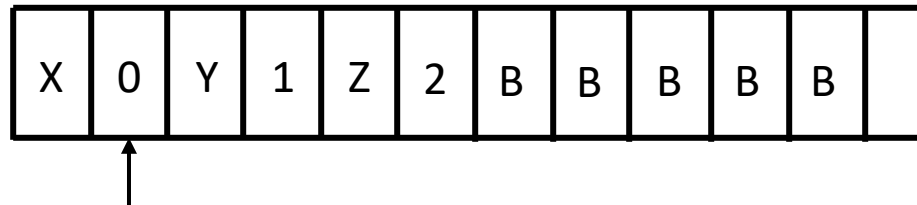
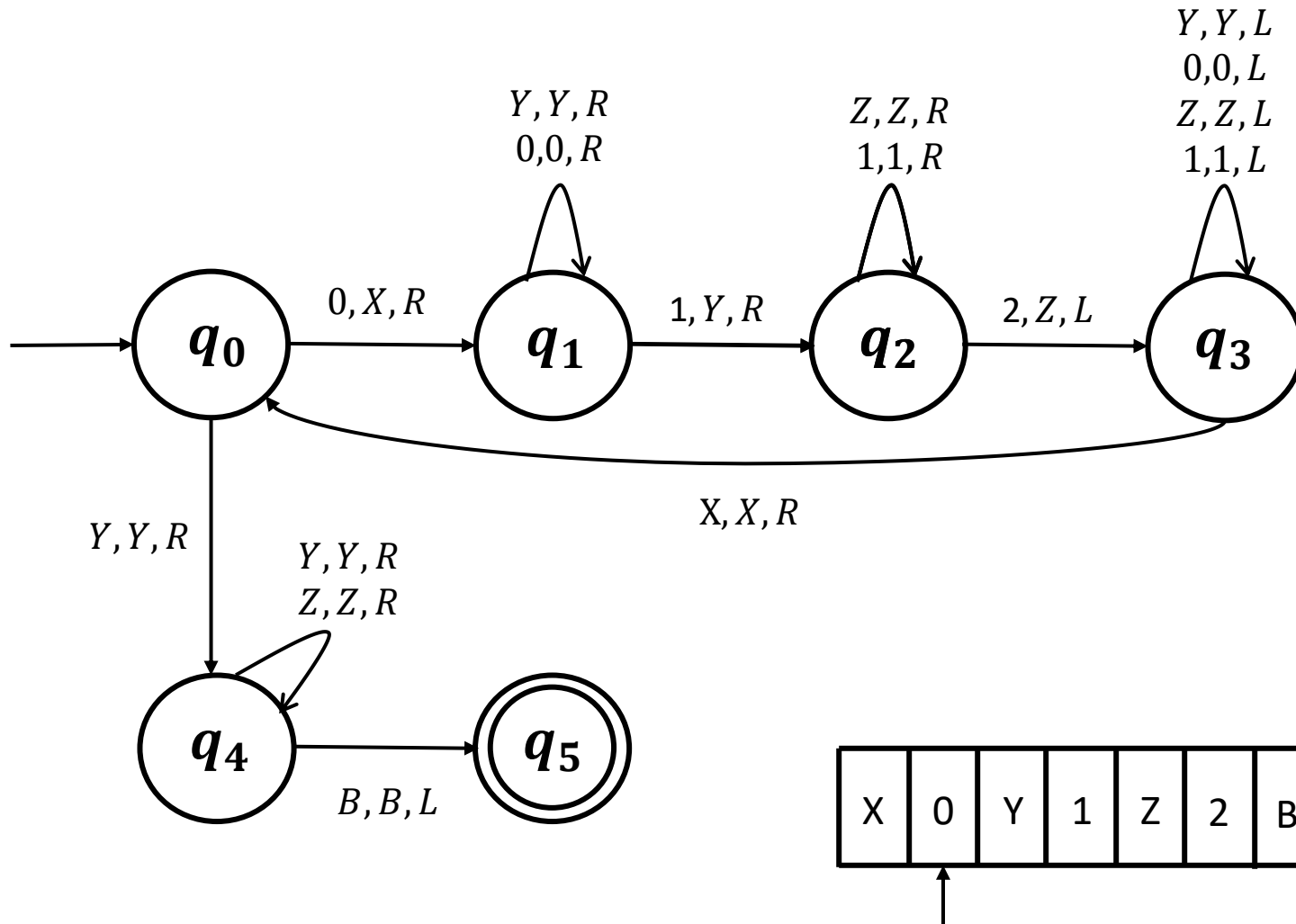
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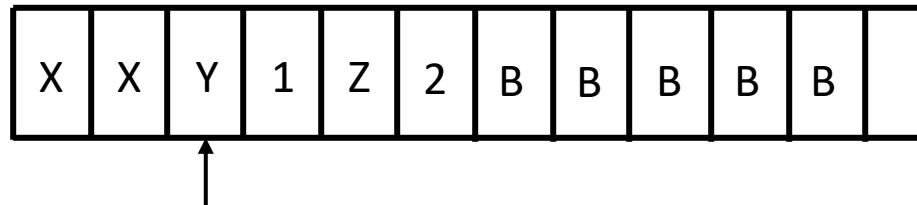
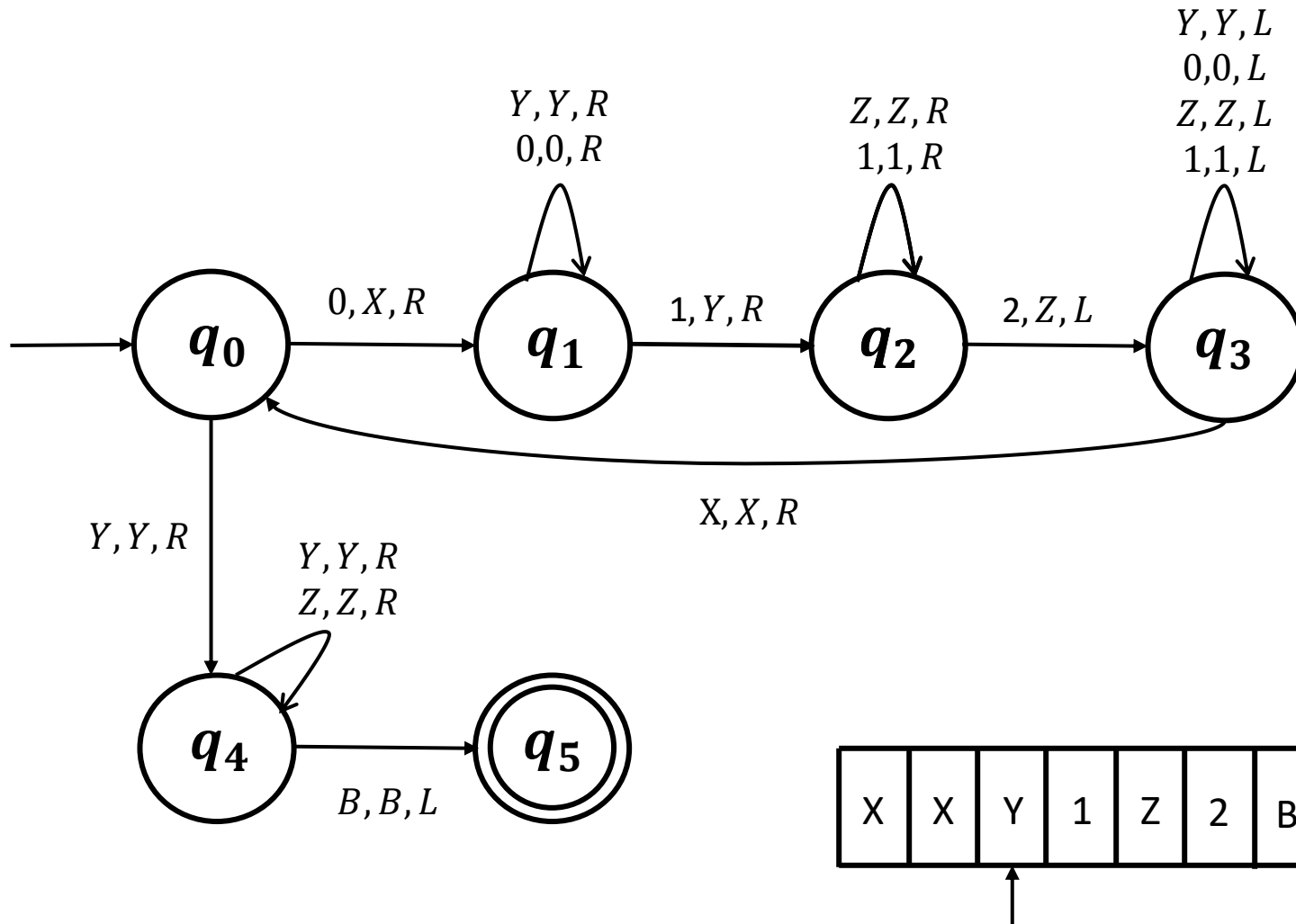
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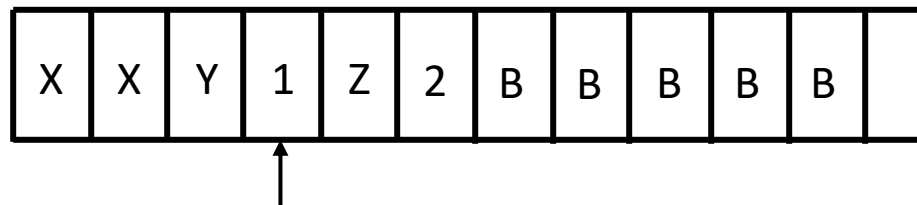
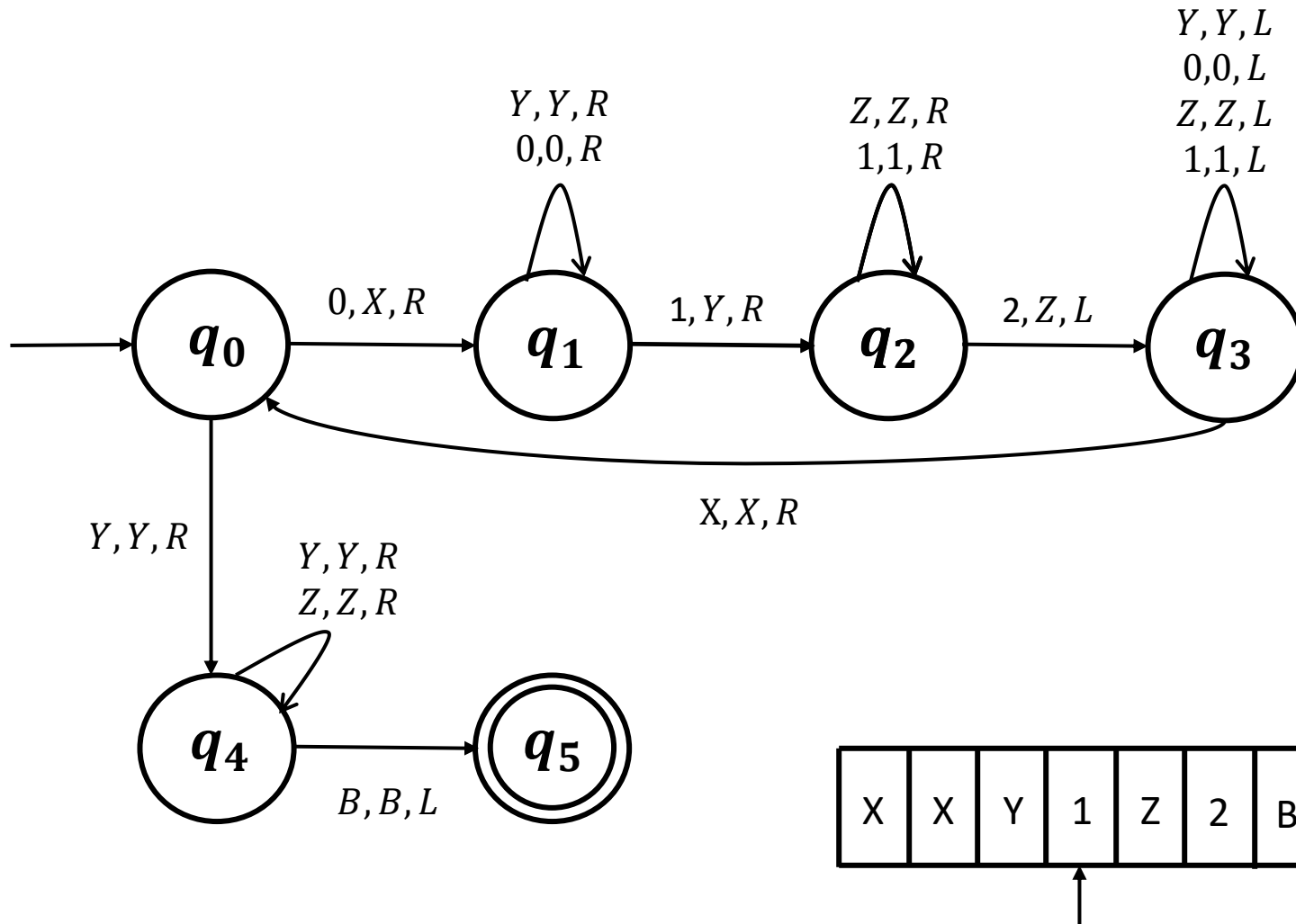
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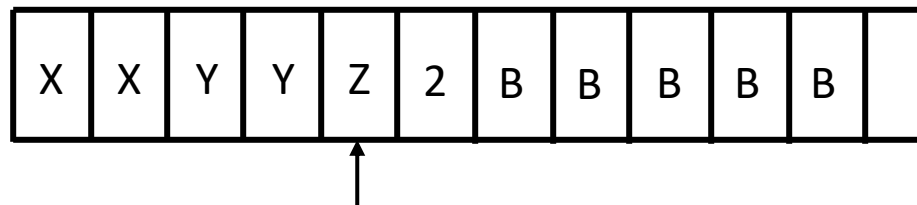
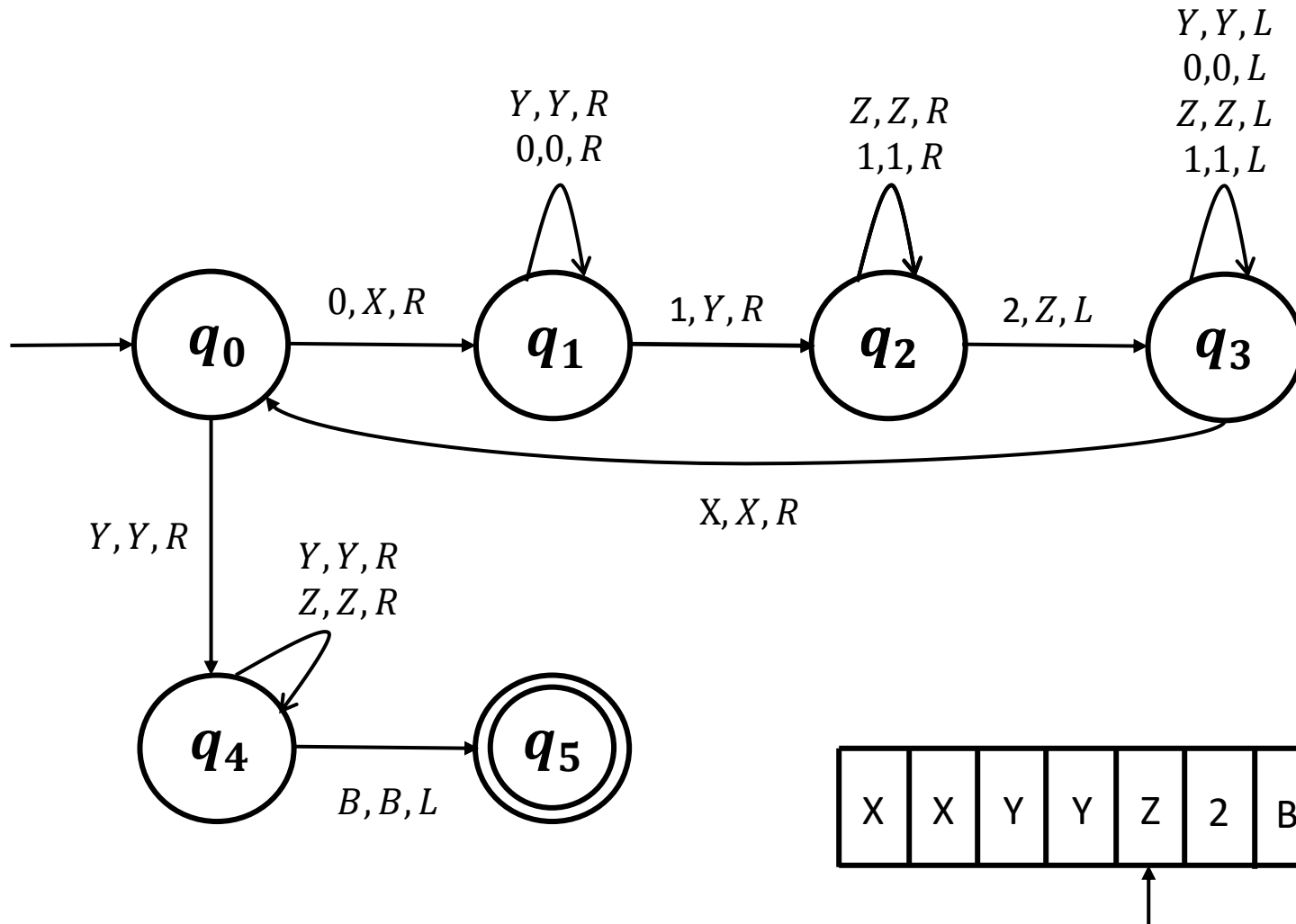
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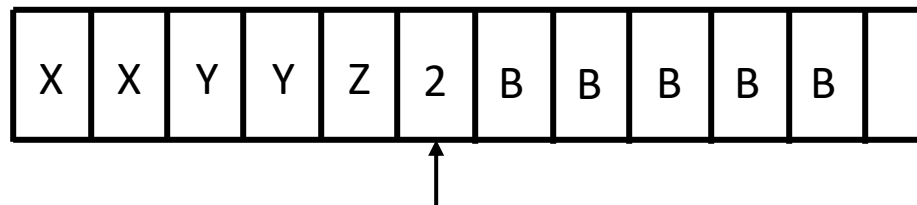
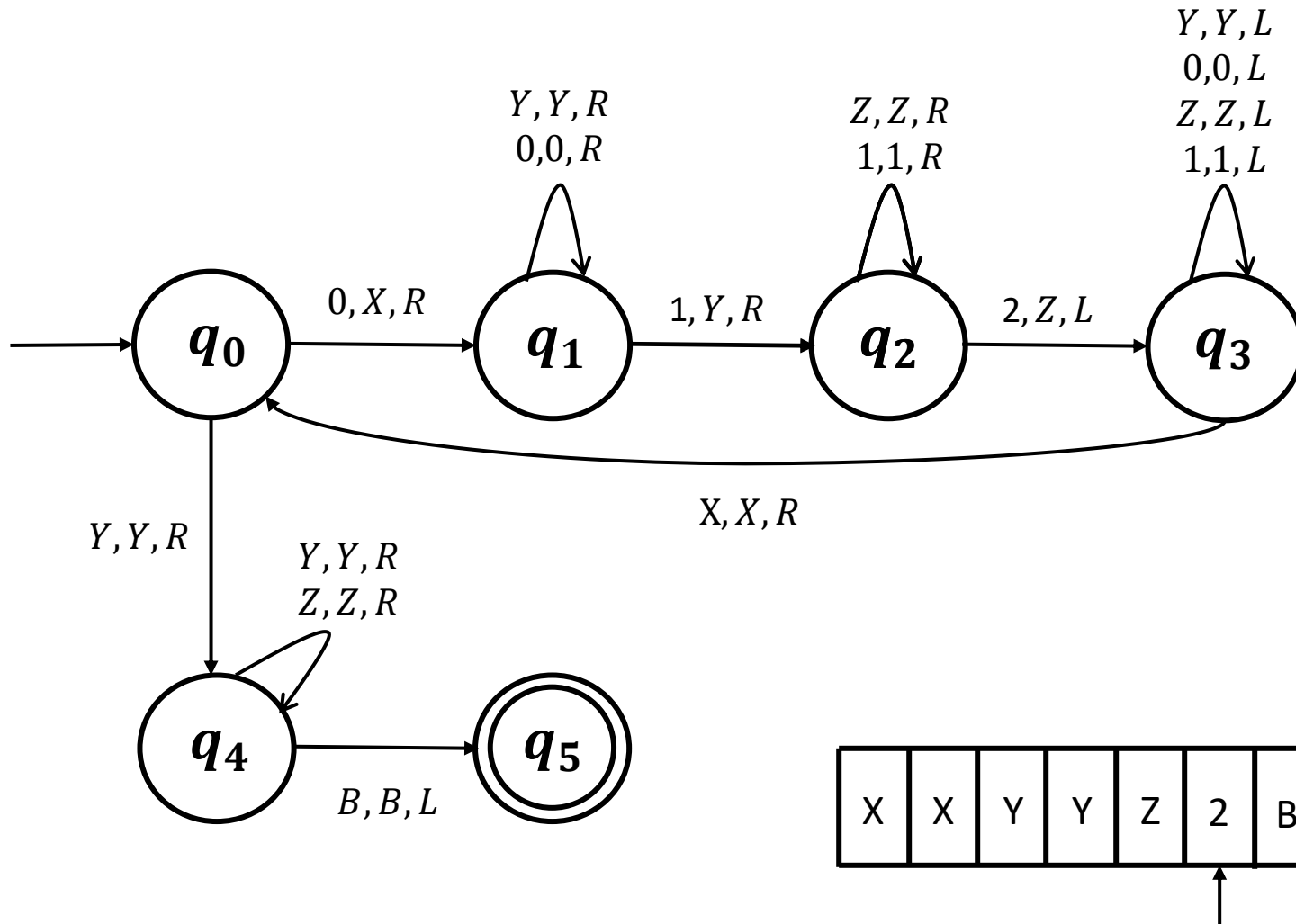
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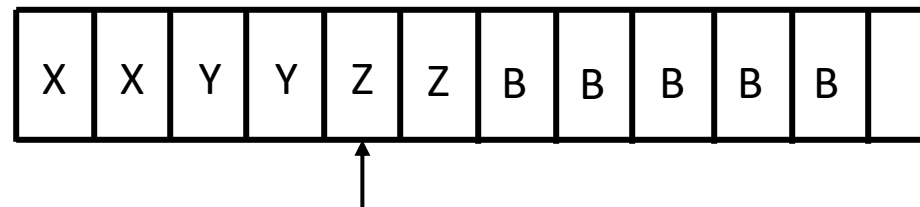
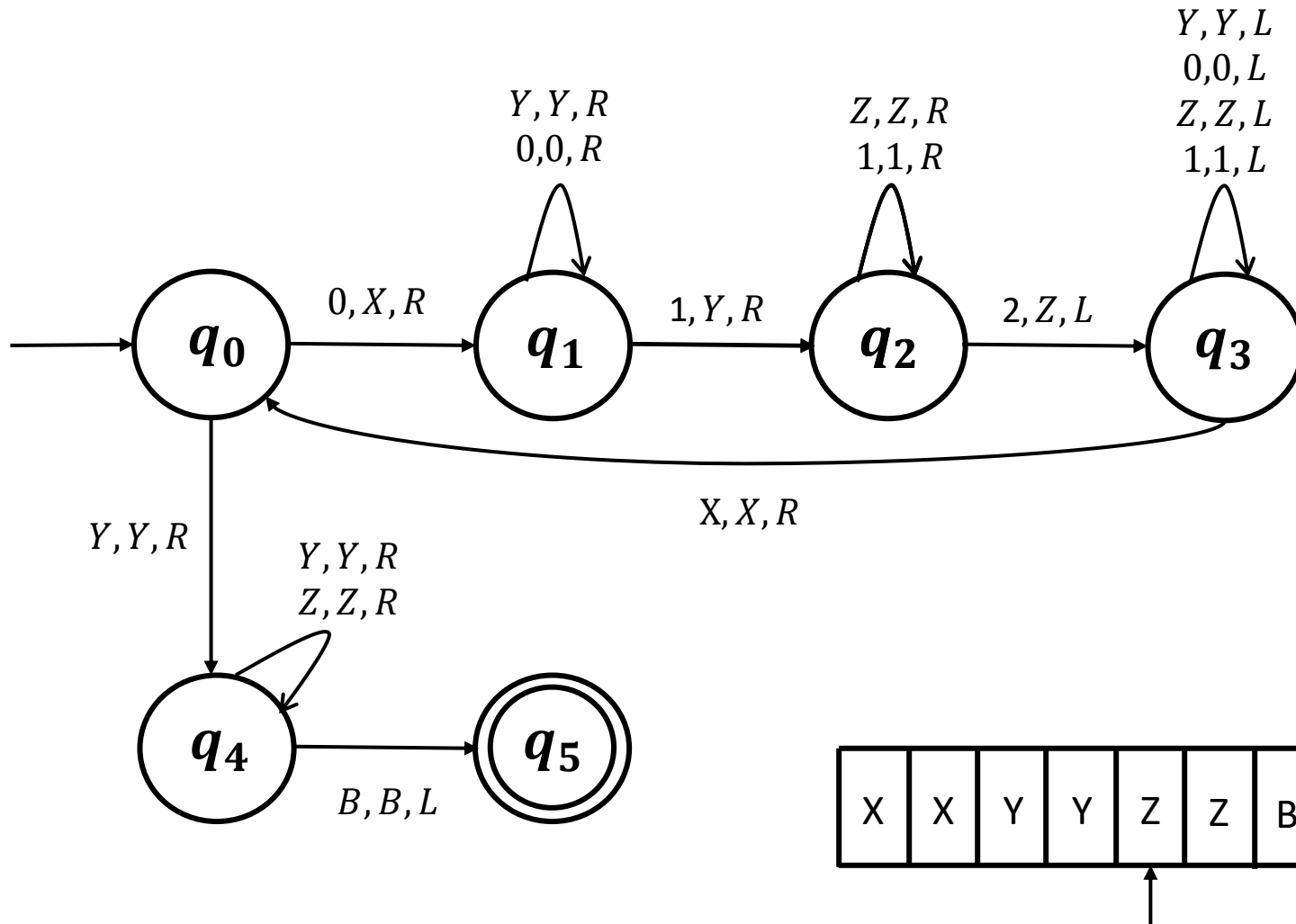
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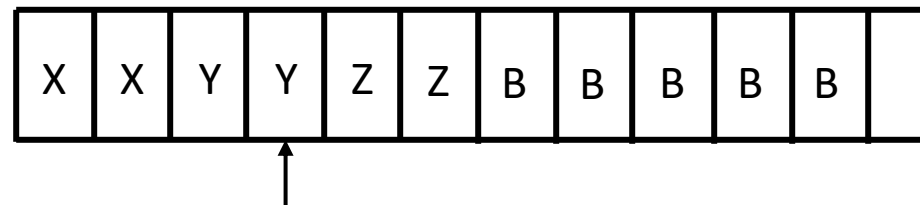
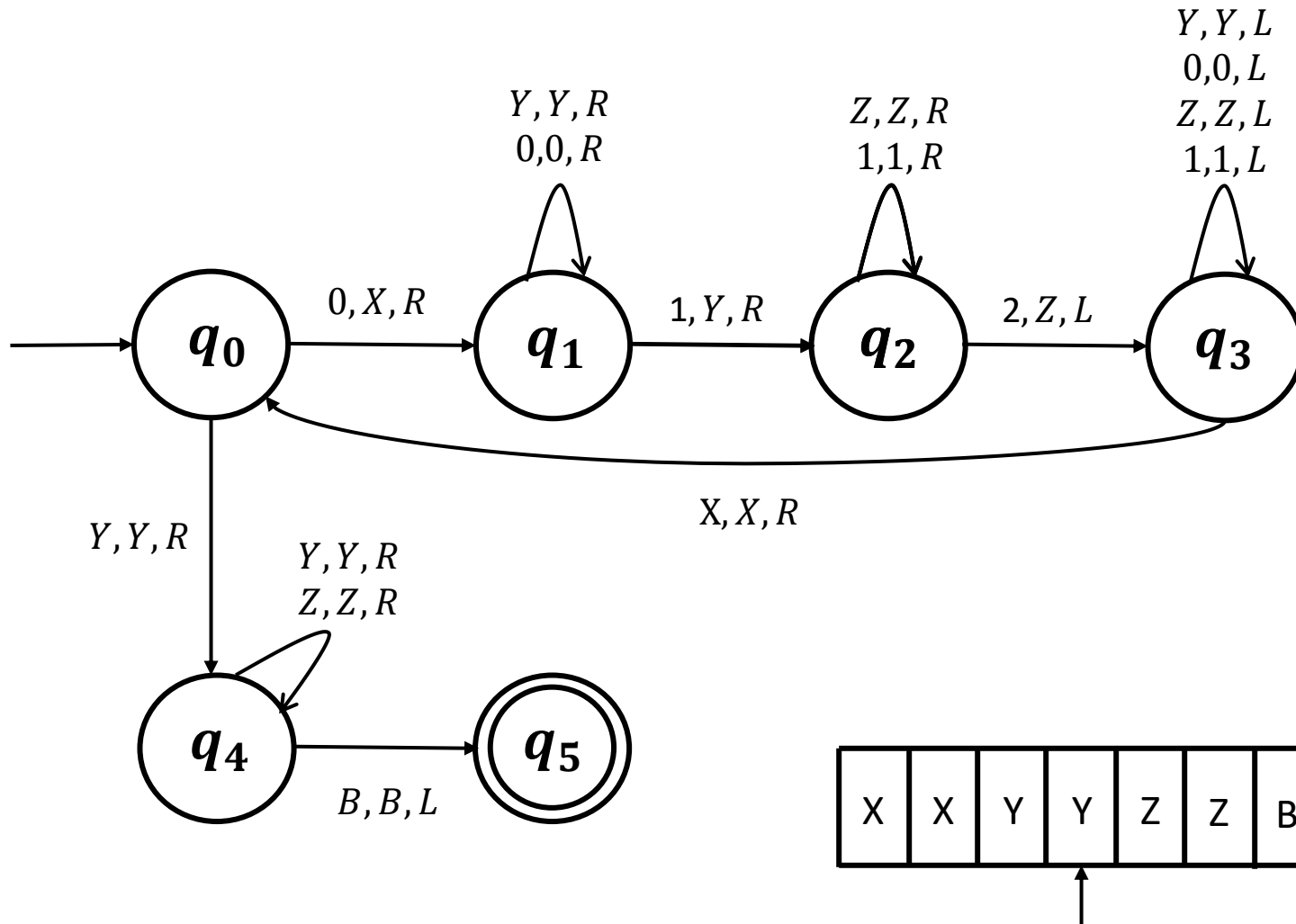
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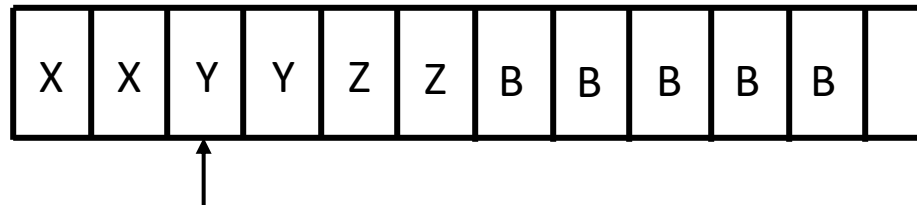
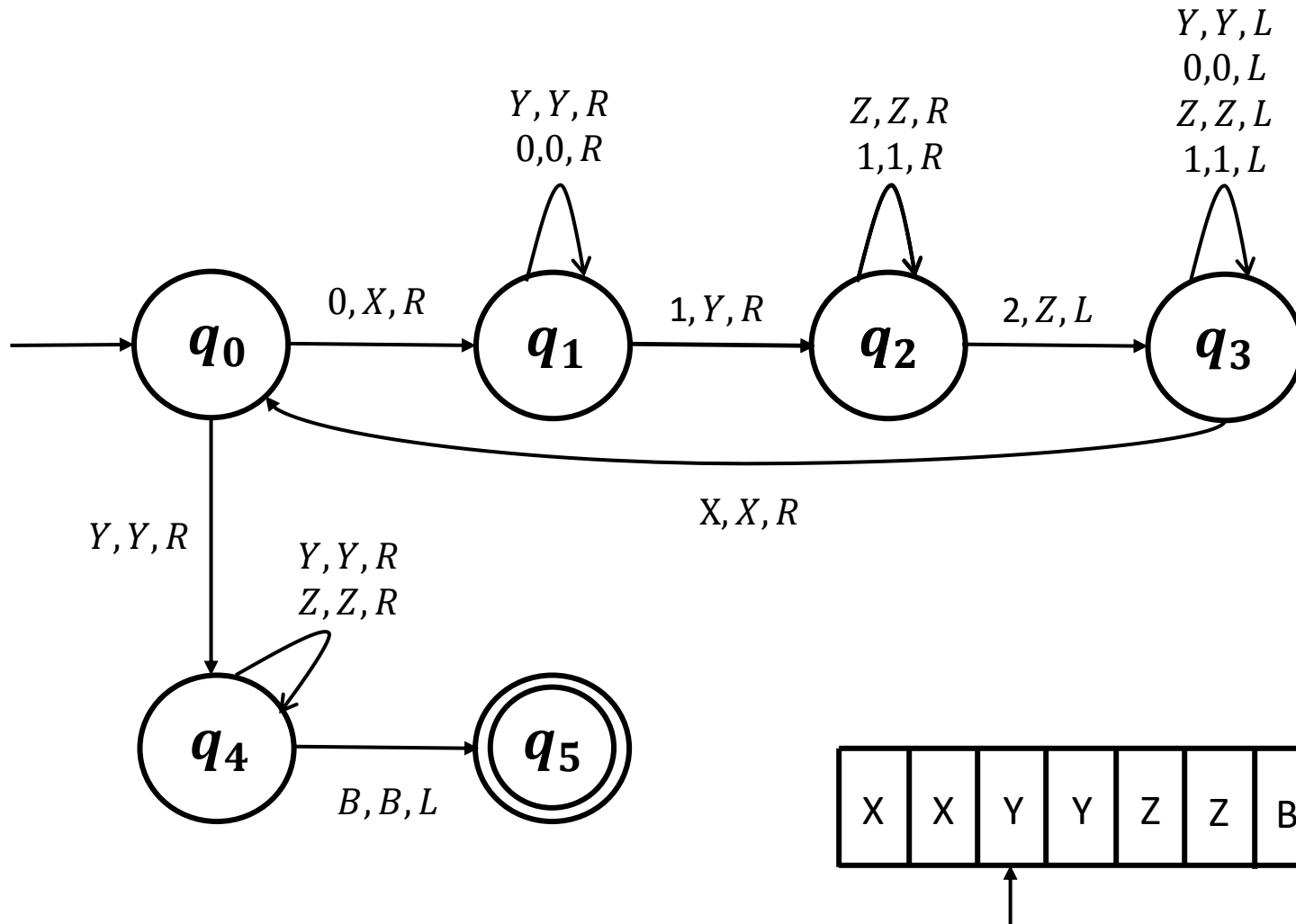


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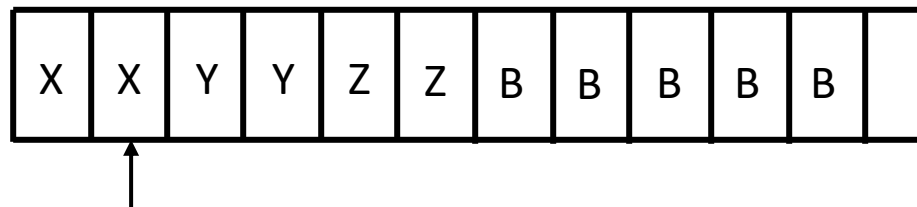
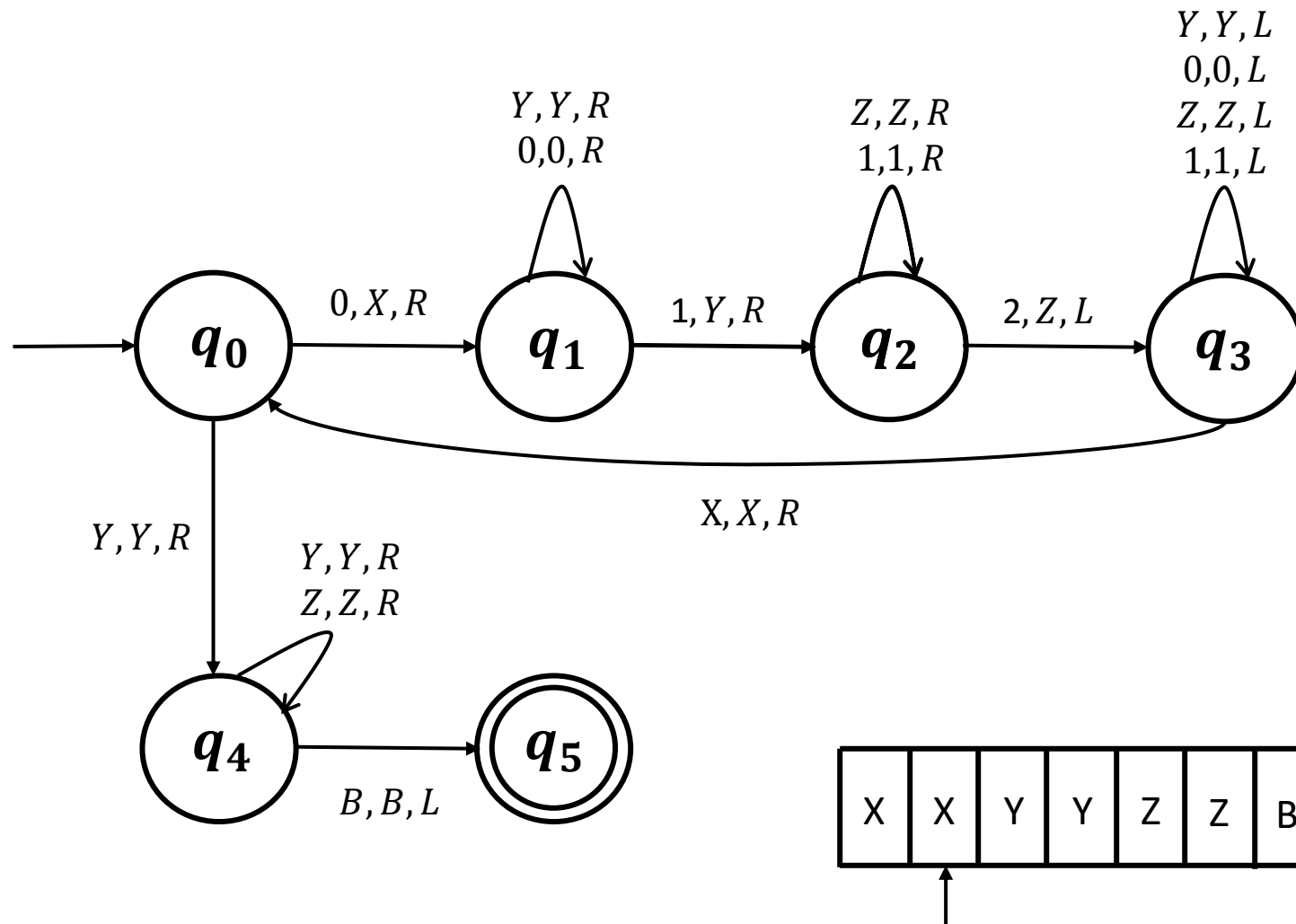
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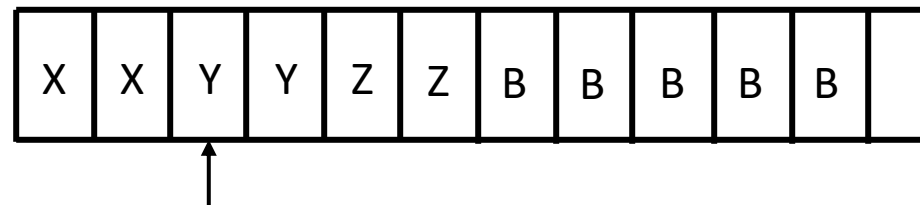
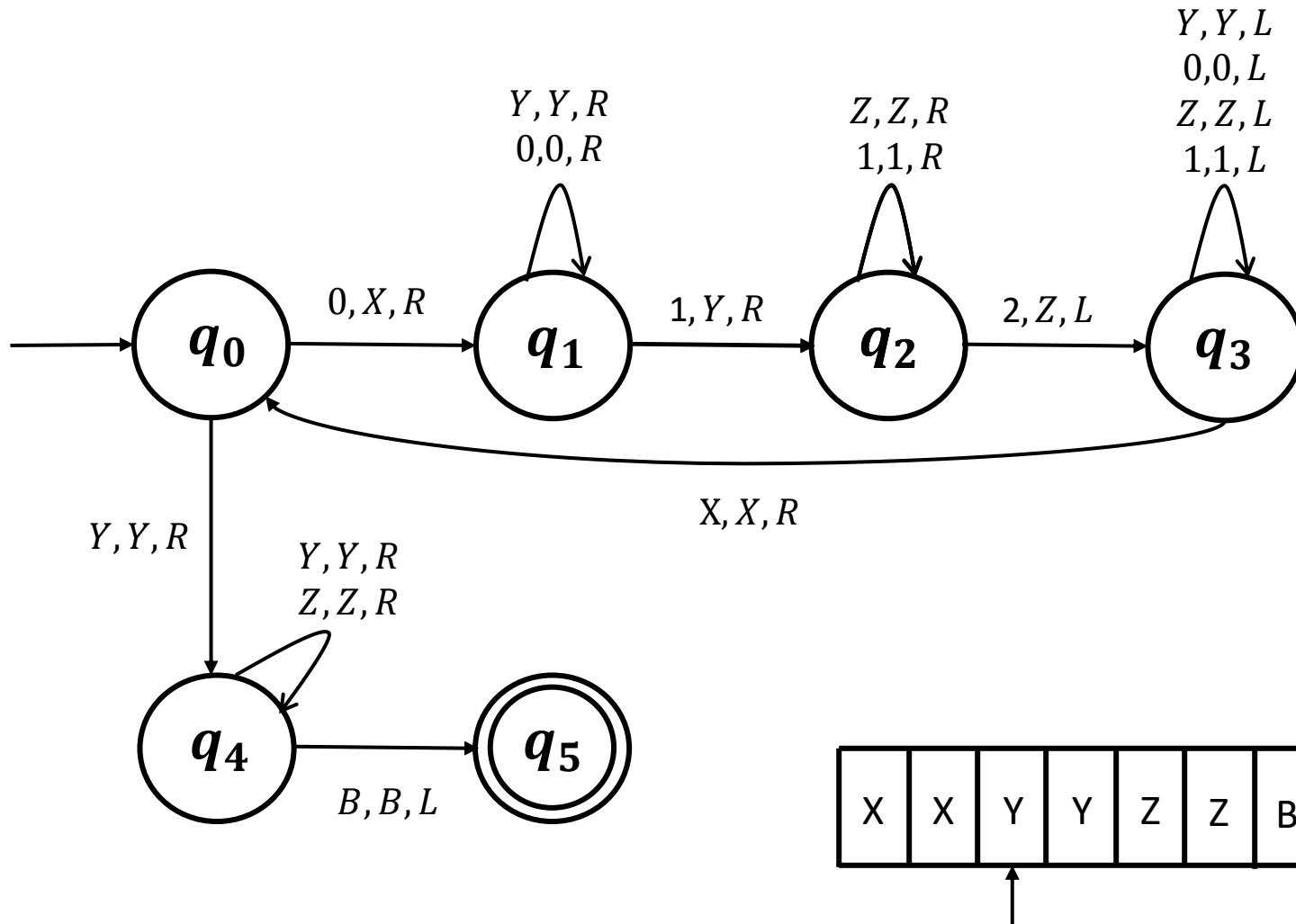
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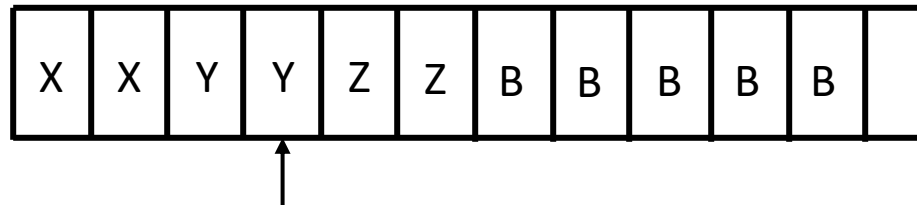
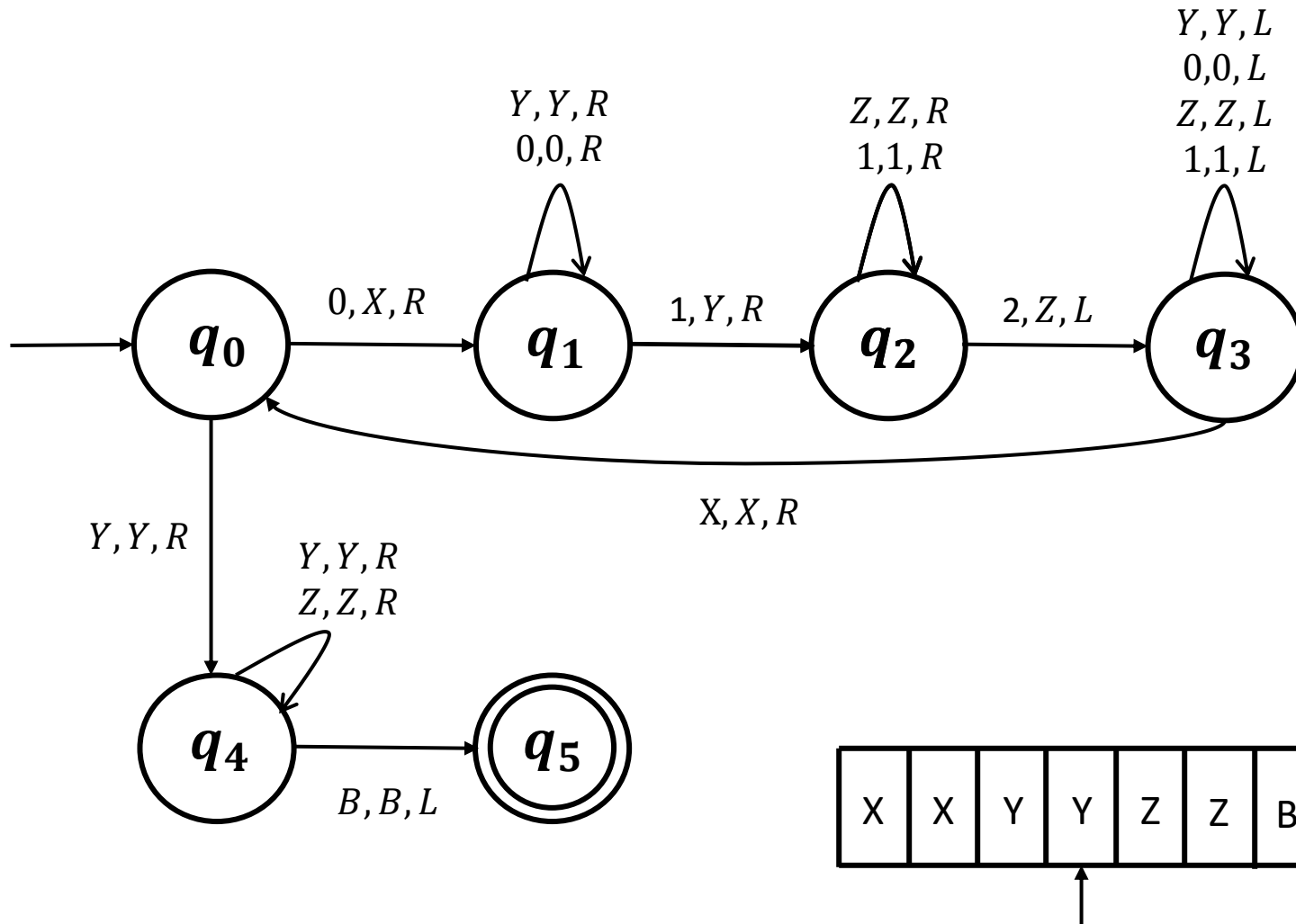
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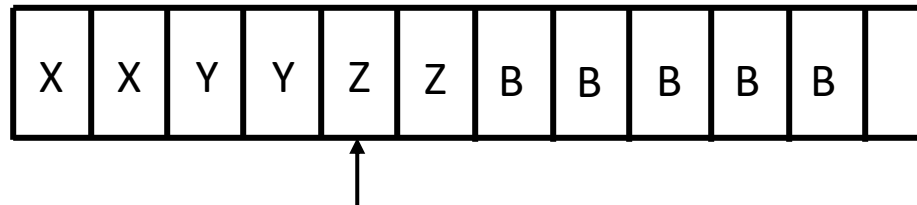
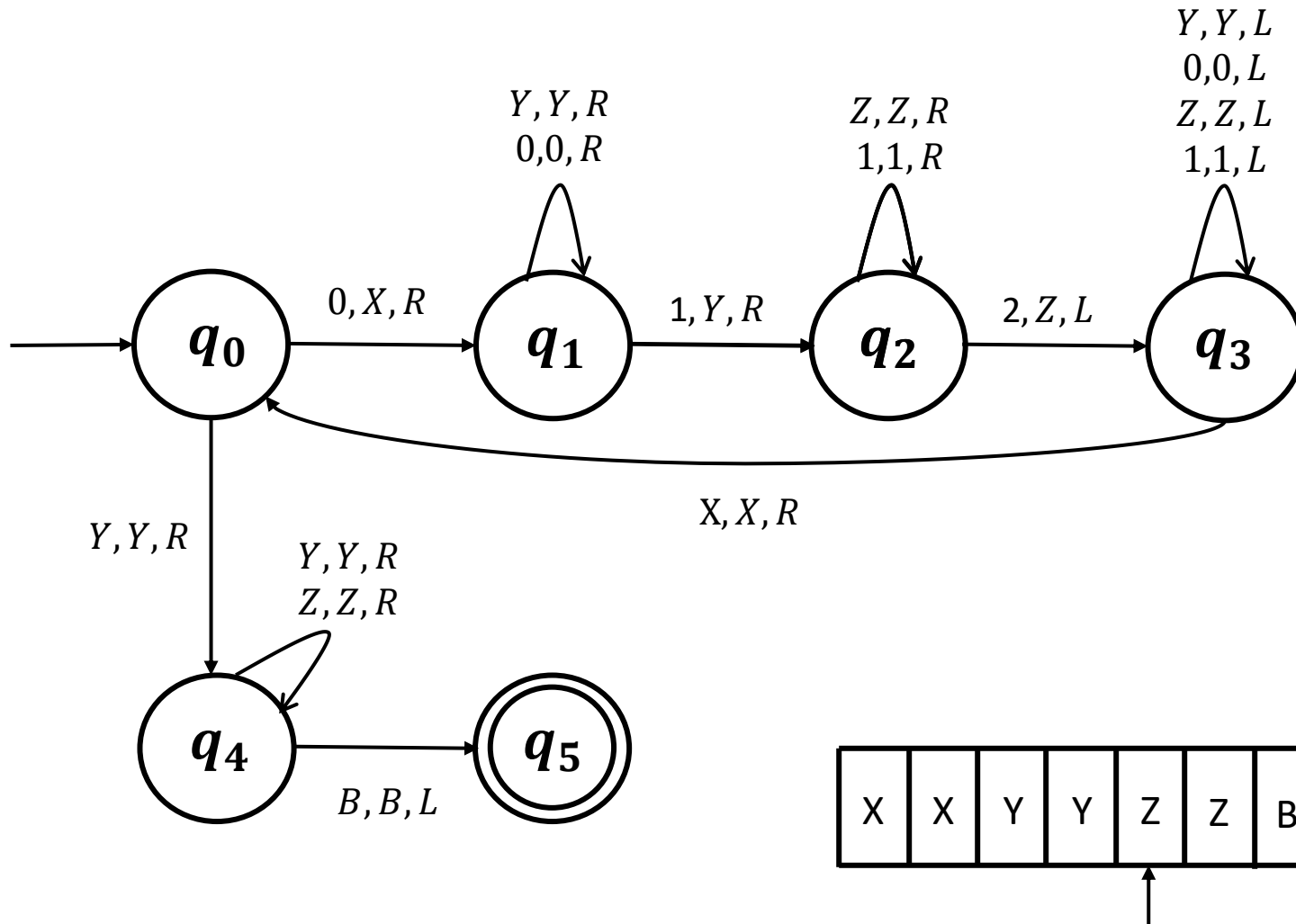
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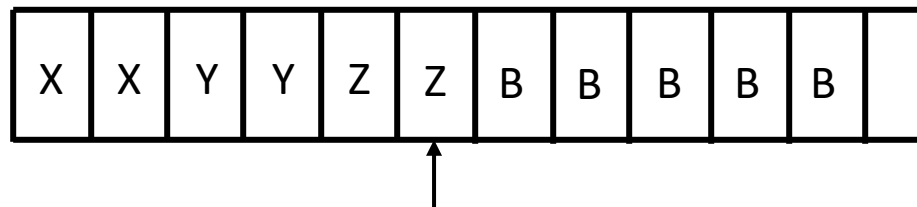
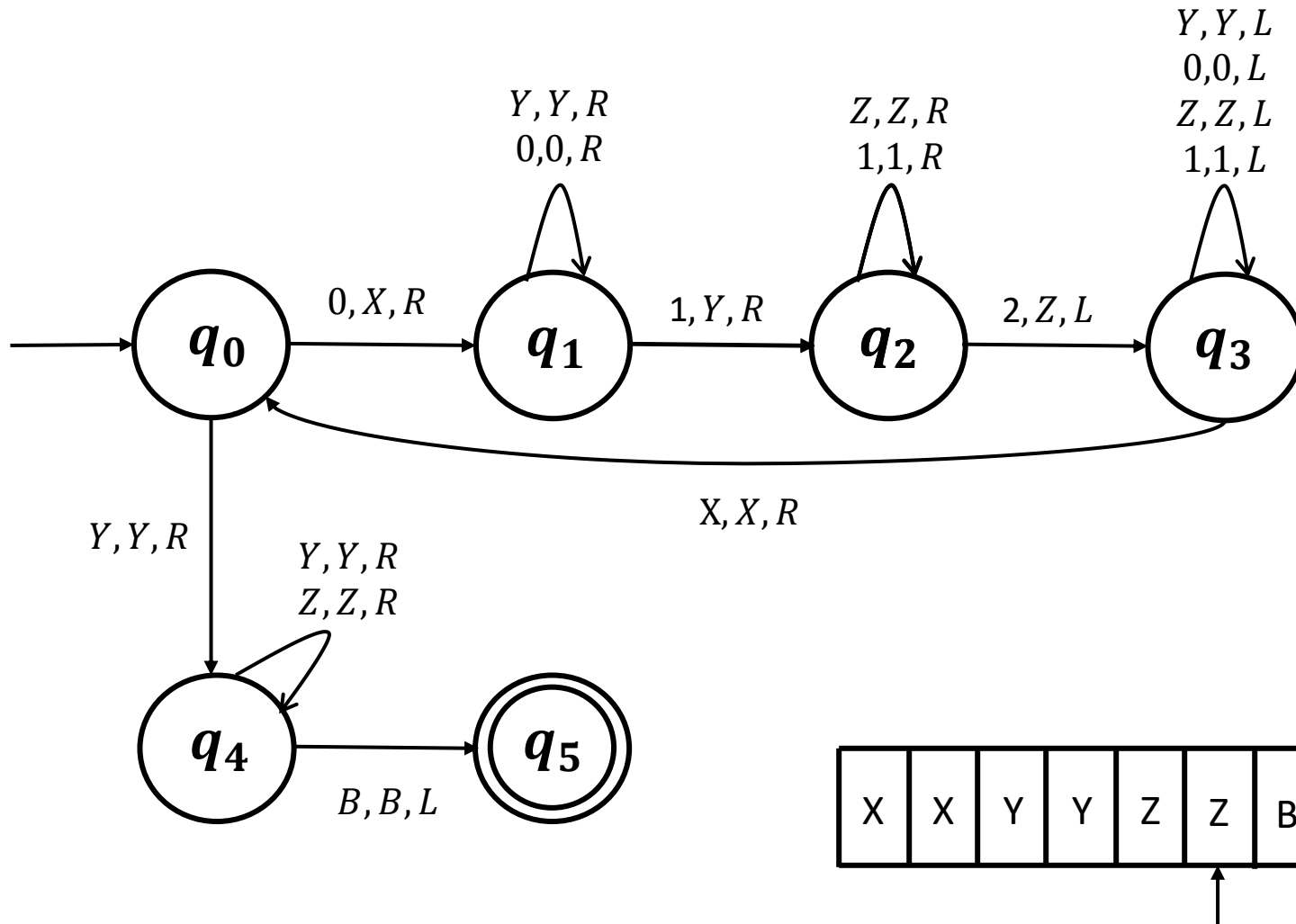
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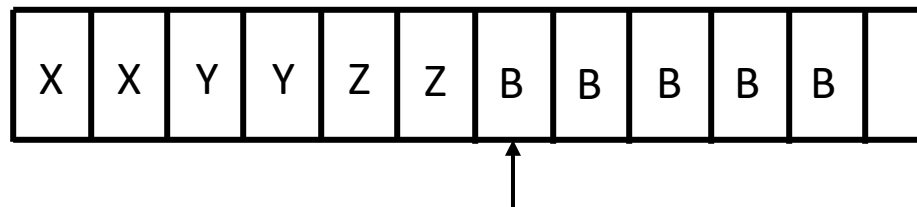
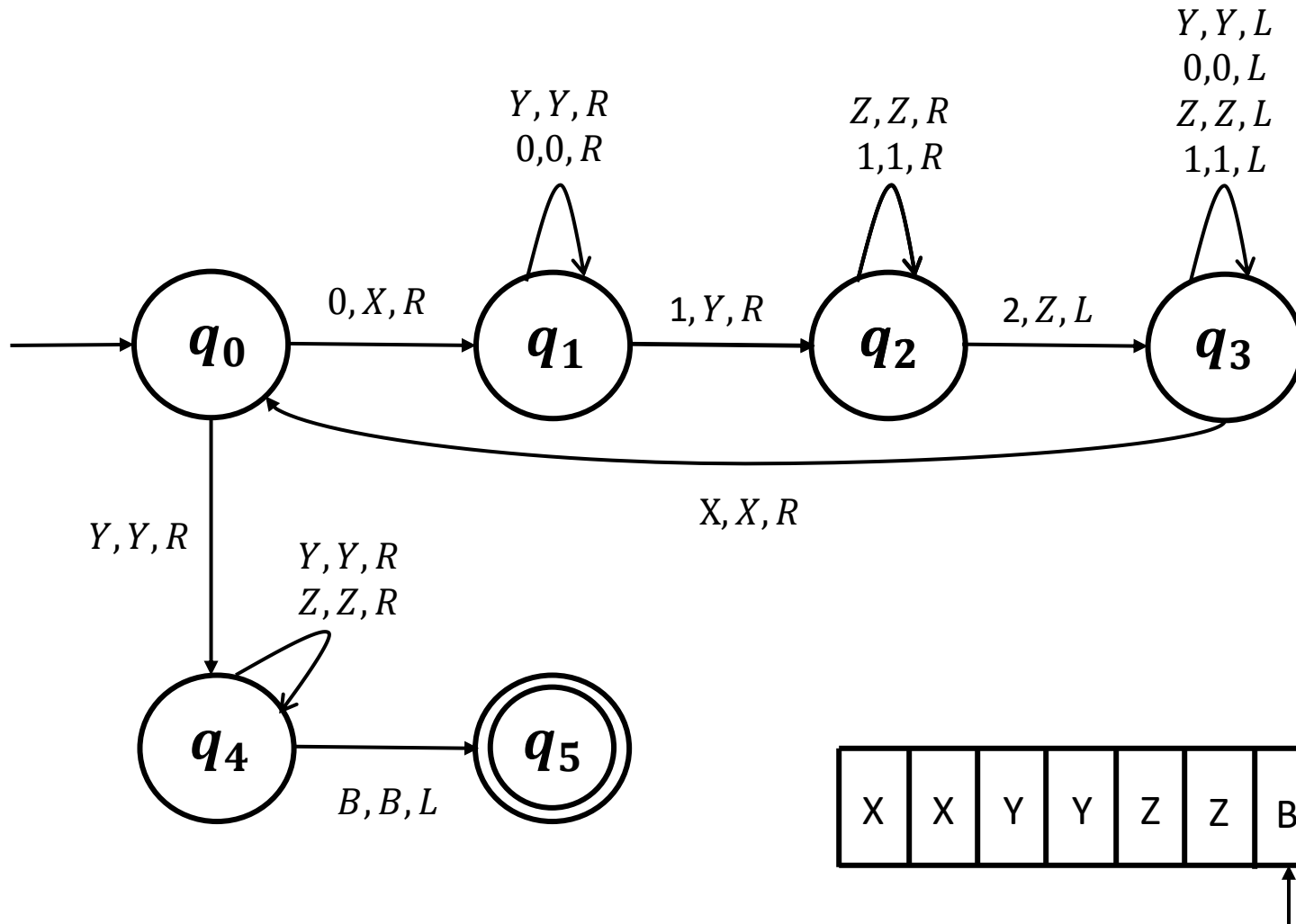
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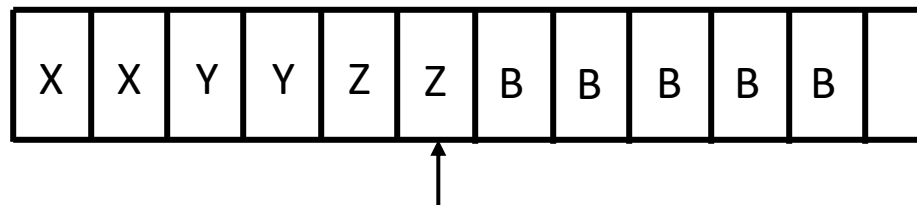
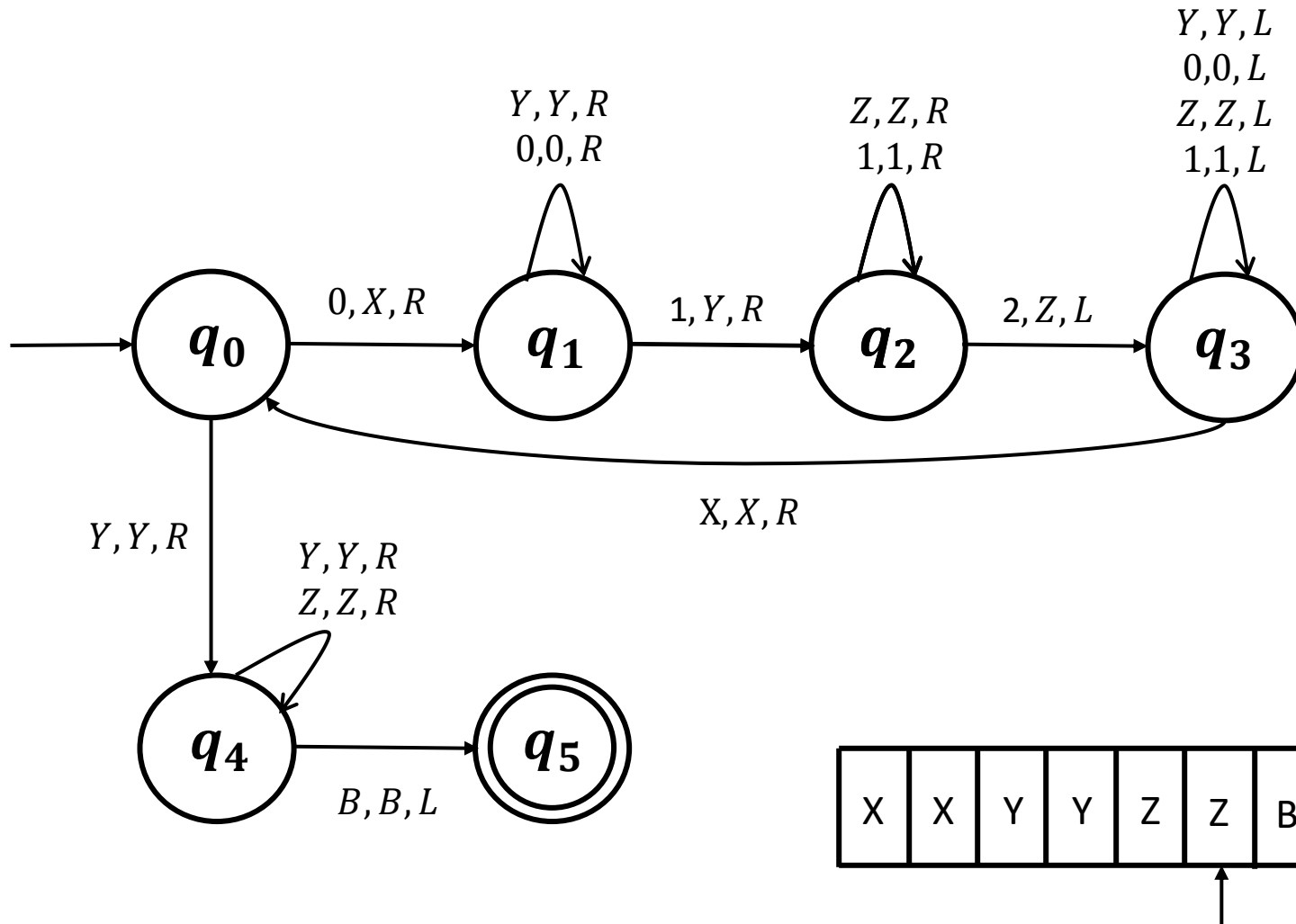
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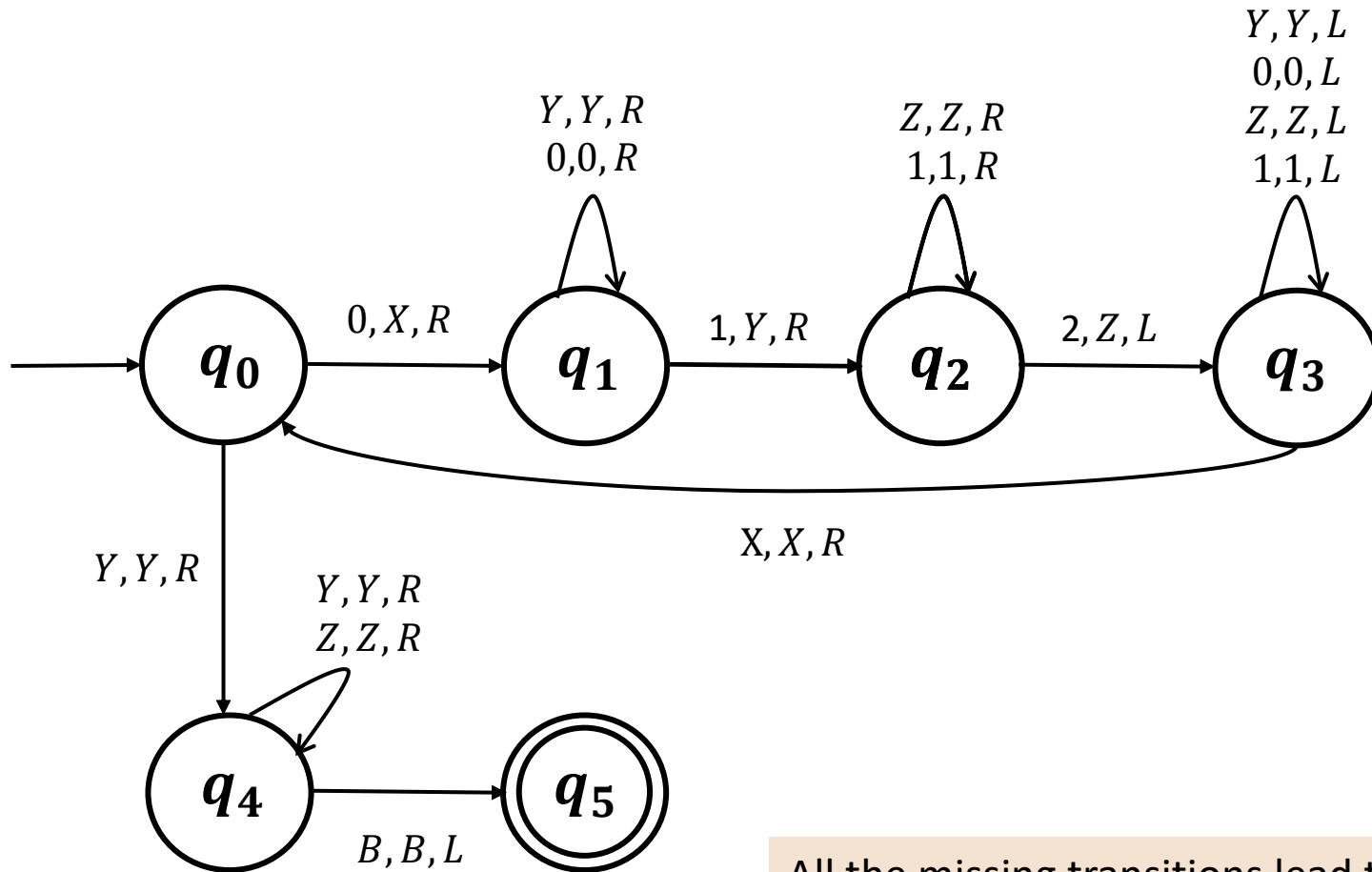


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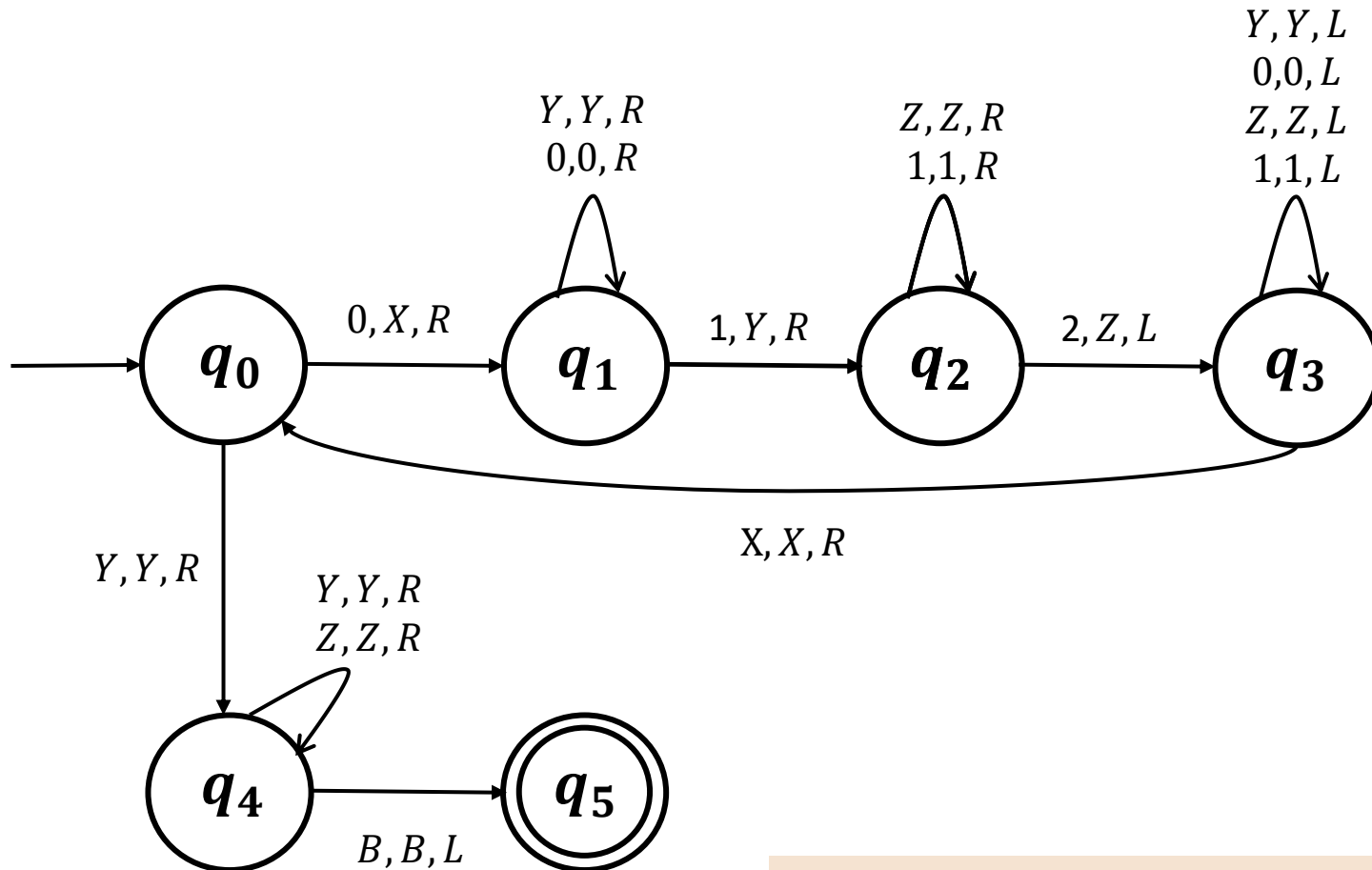


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All the missing transitions lead to a reject state and so any input not of the form  $\{0^n 1^n 2^n\}$  is rejected.

# Turing Machines

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***$CFL \subseteq \text{Language recognized by TM}$***

# Turing Machines

Formally, a Turing Machine is a 7-tuple  $(Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$  where

- $Q$  is a finite set called the **states**.
- $\Sigma$  is the set of input **alphabets** not containing the blank symbol  $B$ .
- $\Gamma$  is the **tape alphabet**, where  $B \subseteq \Gamma$  and  $\Sigma \subseteq \Gamma$ .
- $\delta: Q \times \Gamma \mapsto Q \times \Gamma \times \{L, R\}$  is the **transition function**
- $q_0 \in Q$  is the **start state**.
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**Configuration of a TM:** Combination of the current state, the current tape contents and the current head location.

Formally, it is a triple:  $(q, a, x)$ , where  $q \in Q, a \in \Gamma, x \in \mathbb{Z}_+$

At each step, the Turing machine configuration changes. We say  $C_1$  **yields**  $C_2$  if the TM changes from  $C_1$  to  $C_2$  in one step.

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A TM  **$M$**  **accepts**  **$w$**  if there exists a sequence of configurations  $C_1$  to  $C_k$ , where

- $C_1$  is the start configuration  $M$  on  $w$ .
- Each  $C_i$  yields  $C_{i+1}$ .
- $C_k$  is an accepting configuration

Language recognized a TM  $M$ :

$$L(M) = \{w | M \text{ accepts } w\}$$

**Configuration of a TM:** Combination of the current state, the current tape contents and the current head location.

At each step, the Turing machine configuration changes. We say  $C_1$  **yields**  $C_2$  if the TM changes from  $C_1$  to  $C_2$  in one step.

$X\ 0\ 0\ 1\ 1\ 1\ B\ B\ B\ B\ \dots$   
                  ↑  
                   $q_1$

**Start configuration:**

$0\ 0\ 0\ 1\ 1\ 1\ B\ B\ B\ B\ \dots$   
          ↑  
           $q_0$

**Accept configuration:**

$X\ X\ X\ Y\ Y\ Y\ B\ B\ B\ B\ \dots$   
                  ↑  
                   $q_{accept}$

**Reject configuration:**

$X\ X\ X\ Y\ Y\ 0\ B\ B\ B\ B\ \dots$   
                          ↑  
                           $q_{reject}$

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## Next Lecture

Various TM model **variants**: Robustness of the standard TM model

Thank You!