

<div>Limit Rules</div> <div>L'Hoptial: <math>\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}</math> if <b><math>\lim g(x) = \lim f(x) = 0 / \inf</math></b></div> <div>Replacement: <math>f(x) = g(x)</math> for all x, except <math>x=c</math>. <math>\lim_{x \rightarrow c} f(x) = \lim_{x \rightarrow c} g(x)</math></div> <div>Squeeze: <math>g(x) \leq f(x) \leq h(x)</math>. <math>\lim_{x \rightarrow c} g(x) = \lim_{x \rightarrow c} h(x) = L \rightarrow \lim_{x \rightarrow c} f(x) = L</math></div> <div>Exp.: <math>\lim_{x \rightarrow c} f(x)^k \leftrightarrow \exp\left(\lim(k * \ln(f(x)))\right)</math></div> <div>Polynomials: <math>\lim_{x \rightarrow \infty} \frac{P(x) = Ax^a + \dots}{Q(x) = Bx^b + \dots}</math> 0 if <math>\alpha &lt; \beta</math>, <math>\frac{A}{B}</math> if <math>\alpha = \beta</math>, infinity if otherwise</div>		<div>Series Test</div> <table><tr><td>N'th term</td><td><math>\lim_{n \rightarrow \inf} a_n</math></td><td>-</td><td>DNE!/0</td><td>0</td></tr><tr><td>Integral</td><td><math>\int_1^\infty f(x) \, dx</math></td><td>Fin. num</td><td>Inf number</td><td>(f(x) is continuous positive decreasing)</td></tr><tr><td>Comparison</td><td><math>0 \leq a_n \leq b_n</math></td><td>B conv. -&gt; a conv.</td><td>A div. -&gt; B div.</td><td></td></tr><tr><td>Ratio</td><td><math>\lim_{n \rightarrow \infty} \left  \frac{a_{n+1}}{a_n} \right </math></td><td><math>0 \leq L &lt; 1</math></td><td><math>L &gt; 1</math></td><td><math>L = 1</math></td></tr><tr><td>Root</td><td><math>\lim_{n \rightarrow \infty} \sqrt[n]{ a_n }</math></td><td><math>0 \leq L &lt; 1</math></td><td><math>L &gt; 1</math></td><td><math>L = 1</math></td></tr><tr><td>Alternating</td><td><math>\sum_{n=1}^\infty (-1)^{n-1} b_n</math></td><td><math>\lim_{n \rightarrow \infty} b_n = 0</math> <math>0 \leq b_n \geq b_{n+1}</math></td><td>-</td><td>(Note: try to show that the bn is decreasing if can)</td></tr><tr><td>Geometric Series</td><td><math>\sum_{n=1}^\infty ar^{n-1}</math></td><td><math> r  &lt; 1</math></td><td>-</td><td>-</td></tr><tr><td>P-series</td><td><math>\sum_{n=1}^\infty \frac{1}{n^p}</math></td><td><math>p &gt; 1</math></td><td><math>p \leq 1</math></td><td>-</td></tr></table>				N'th term	$\lim_{n \rightarrow \inf} a_n$	-	DNE!/0	0	Integral	$\int_1^\infty f(x) \, dx$	Fin. num	Inf number	(f(x) is continuous positive decreasing)	Comparison	$0 \leq a_n \leq b_n$	B conv. -> a conv.	A div. -> B div.		Ratio	$\lim_{n \rightarrow \infty} \left  \frac{a_{n+1}}{a_n} \right $	$0 \leq L < 1$	$L > 1$	$L = 1$	Root	$\lim_{n \rightarrow \infty} \sqrt[n]{ a_n }$	$0 \leq L < 1$	$L > 1$	$L = 1$	Alternating	$\sum_{n=1}^\infty (-1)^{n-1} b_n$	$\lim_{n \rightarrow \infty} b_n = 0$ $0 \leq b_n \geq b_{n+1}$	-	(Note: try to show that the bn is decreasing if can)	Geometric Series	$\sum_{n=1}^\infty ar^{n-1}$	$ r  < 1$	-	-	P-series	$\sum_{n=1}^\infty \frac{1}{n^p}$	$p > 1$	$p \leq 1$	-
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<div>Differentiation</div> <div>Parametric: <math>\frac{dy}{dt} = \frac{dy}{dx} \times \frac{dx}{dt} = \frac{g'(t)}{f'(t)}</math>, and, <math>\frac{d^2y}{dx^2} = \frac{g''(t)f'(t) - g'(t)f''(t)}{f'(t)^3}</math>, <math>x=f(t)</math> <math>y=g(t)</math></div> <div>Point-slope equation: <math>y - y_1 = m(x - x_1) / y = f(a) + f'(a)(x - a)</math></div> <div>Constant-power: <math>\frac{d}{dx} a^x = a^x \ln(a)</math></div>		<div>Partial Fractions</div> <div><math>\frac{P(x)}{Q(x)}</math> Where <math>P_x \geq Q_x</math></div> <div>1. Factor <math>Q(x)</math>: <math>\frac{5x-4}{x^2-x-2} = \frac{5x-4}{(x-2)(x+1)}</math></div> <div>2. Write out: <math>\frac{5x-4}{(x-2)(x+1)} = \frac{A}{(x-2)} + \frac{B}{(x+1)}</math></div> <div>3. Factor in roots and solve for A/B</div>		<div>Power Series</div> <div><math>\sum_{n=0}^\infty c_n(x-a)^n</math> Is a power series centered about a. We can check</div> <div>Power series either <b>a)</b> converge at <math>x=a</math> only, <b>b)</b> converge for all x, <b>c)</b> There is a positive R s.t. the series converges absolutely if <math> x-a &lt;R</math> &amp; diverges if <math> x-a &gt;R</math></div> <div>Radius of Convergence: <math>\lim_{n \rightarrow \infty} ( \frac{c_{n+1}}{c_n}  \text{ OR } \sqrt{ c_n }) = L</math>, <math>R = \frac{1}{L}</math>.</div>																																									
<div>Integration By Substitution</div> <div>1. Let <math>u = g(x)</math></div> <div>2. Find <math>\frac{du}{dx}</math></div> <div>3. Manipulate <math>dx = \frac{du}{u'}</math></div> <div>4. Find new bounds if necessary; sub in <math>u=g(x)</math></div> <div>5. Sub in <math>u</math>, change <math>dx</math> to <math>du</math></div> <div>6. If <math>(-1)du</math>, flip sign of integration</div> <div>You can also use <math>du = u' * dx</math></div>		<div>Integration By Parts</div> <div>1. Identify "reducible" derivative (Log, inv trig, Algebra, trig)</div> <div>2. <math>\int uv \, dx = u \int v - \int u' * (\int v \, dx) \, dx</math></div>		<div>Power Series Representation</div> <div>We can represent infinite power series as polynomial functions. Manipulate to the form of the 4 series below:</div> <div>Geometric: The geometric series <math>\sum_{n=0}^\infty ar^n = \frac{1}{1-x}</math> for <math> x &lt;1</math></div> <div>Alt. Geometric: <math>\frac{1}{1+x}</math> is equivalent to <math>\sum_{n=0}^\infty (-1)^n x^n</math>, for <math> x &lt;1</math></div> <div>Harmonic: <math>\sum_{n=1}^\infty \frac{1}{n}</math> diverges for any <math>n/x</math></div> <div>Alt. Harmonic: <math>\sum_{n=1}^\infty \frac{(-1)^{n+1}}{n}</math> converges to <math>\ln(2)</math></div>																																									
<div>Taylor &amp; Maclaurin Series</div> <div>A Taylor series centered about c: <math>\sum_{n=0}^\infty \frac{f^{(n)}(c)}{n!} * (x - c)^n</math></div> <div>A Maclaurin series is a special case of the Taylor series centered about 0: <math>\sum_{n=0}^\infty \frac{f^{(n)}(0)}{n!} x^n</math></div>		<div>PLANES AND SHIT</div> <div>Distance 2 points: <math>\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}</math></div> <div>Unit Vector: <math>\frac{u}{  u  }</math> Dot Product: <math>  u   *   v   * \cos(\theta)</math></div> <div>Cross Product: <math>  a   *   b   * \sin(\theta)</math>, remember + - det (normal to a&amp;b)</div> <div>Projection: <math>Proj_a b = \frac{b \cdot a}{  a  ^2} * a</math> Composition: <math>Comp_a b = \frac{a \cdot b}{  a  }</math></div> <div>Angle between 2 planes/normals: <math>\frac{n_1 \cdot n_2}{  n_1   *   n_2  }</math></div> <div>Line Eqn: <math>\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle</math>. 2 points to find &lt;abc&gt;</div> <div>Plane Eqn: Find 2 vectors in plane then <math>p \times q</math> to find normal. Using any point in plane sub into <math>a(x - x_0) + b(y - y_0) + c(z - z_0) + d = 0</math></div> <div>Point to Plane: <math>\frac{ ax_0 + by_0 + cz_0 - d }{\sqrt{a^2 + b^2 + c^2}}</math></div> <div>Tangent Plane: <math>z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)</math></div>		<div>Double Integrals</div> <div>Surface Area: <math>\iint \sqrt{f_x^2 + f_y^2 + 1} \, dA</math></div> <div>Type 1: <math>y=f(x)</math>, arrow pointing UP</div> <div>Type 2: <math>x = f(y)</math>, arrow pointing RIGHT</div>																																									
<div>Discriminant</div> <div><math>D = f_{xx}(a, b)f_{yy}(a, b) - [f_{xy}(a, b)]^2</math></div> <table><tr><td>D&gt;0</td><td><math>f_{xx}(a, b) &gt; 0</math></td><td>Local Min</td></tr><tr><td>D&gt;0</td><td><math>f_{xx}(a, b) &lt; 0</math></td><td>Local max</td></tr><tr><td>D&lt;0</td><td>-</td><td>Saddle Point</td></tr><tr><td>D=0</td><td>-</td><td>Inconclusive</td></tr></table> <div>Critical Point: <math>f_x(a, b)</math> AND <math>f_y(a, b) = 0</math></div>		D>0	$f_{xx}(a, b) > 0$	Local Min	D>0	$f_{xx}(a, b) < 0$	Local max	D<0	-	Saddle Point	D=0	-	Inconclusive	<div>ODE</div> <div>Separable: <math>\frac{dy}{dx} = f(x)g(y)</math> - turn into <math>\int \frac{1}{g(y)} \, dy = \int f(x) \, dx + c</math></div> <div>Reductible: <math>y' = g(\frac{y}{x})</math> - let <math>v = \frac{y}{x}</math>, then <math>y = vx</math> &amp; <math>y' = v + xv'</math>. Manipulate and get <math>v' = \frac{g(v) - v}{x}</math>. Now apply separable ODE.</div> <div>LFODE: <math>\frac{dy}{dx} + P(x)y = Q(x)</math>. Let <math>I(X) = e^{\int P(x) \, dx}</math>. Solve <math>y * I(x) = \int Q(x) * I(x) \, dx</math></div> <div>Bernoulli: <math>y' + p(x)y = Q(x) * y^n</math>. Let <math>u = y^{1-n}</math>. Then, equation is the LFODE <math>u' + (1-n)P(x)u = (1-n)Q(x)</math></div>		<div>Concavity</div> <div>Second Derivative Test: If <math>f''(c) &gt; 0</math>, then f is concave up at c. If <math>f''(c)&lt;0</math>, then concave down at c. If <math>f''(c) = 0</math>, or <math>f''(c)</math> does not exist, it is a point of inflection.</div>																													
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<div>Polar Coordinates</div> <div><math>R = \{(r, \theta) : 0 \leq a \leq r \leq b, \alpha \leq \theta \leq \beta\}</math></div> <div><math>\iint f(x, y) \, dA = \int_\alpha^\beta \int_a^b f(r * \cos(\theta), r * \sin(\theta)) * r \, dr \, d\theta</math></div>		<div>Extrema tests</div> <div>Critical Values: If c is not an endpoint, and <math>f'(c) = 0</math> or <math>f'(c)</math> DNE</div> <div>FDT abs extrema: Find critical points. Evaluate function at critical points. By EVT, highest/lowest value is abs max/min</div> <div>FDT loc extrema: Find critical points. If f' changes from positive to negative at c, local maximum. (respectively for neg-pos)</div> <div>SDT: Find critical points. If <math>f''(c) &lt; 0</math>, local max. <math>f''(c) &gt; 0</math>, local minimum. =0 inconclusive</div>		<div>Extrema Theorems</div> <div>Extreme value theorem states that on <math>[a, b]</math>, f has absolute extrema</div> <div>Rolle's theorem states on <math>(a, b)</math>, if <math>f(a)=f(b)</math> anywhere in the interval (including end point <math>a, b</math>), there is at least on c such that <math>f'(c) = 0</math>.</div>																																									
<div>General Stuff</div> <div>Equation of sphere: <math>(x - h)^2 + (y - k)^2 + (z - l)^2 = r^2</math>, where <math>c=(h, k, l)</math>, radius = r</div> <div>Reciprocal Identities:</div> <div><math display="block">\csc(\theta) = \frac{1}{\sin(\theta)}</math><math display="block">\sec(\theta) = \frac{1}{\cos(\theta)}</math><math display="block">\cot(\theta) = \frac{1}{\tan(\theta)}</math></div> <div>For finding bounds of double integration, try subbing <math>z=0</math> so you can find relation between x and y.</div>		<div>Functions of Several Variables</div> <div>Arc length curves: <math>y=f(x) \rightarrow \int_a^b \sqrt{1 + f'(x)^2} \, dx</math></div> <div>Arc length: <math>\langle f, g \rangle \rightarrow \int_a^b \sqrt{f'(t)^2 + g'(t)^2} \, dt</math> where f/g represent x/y axes.</div> <div>Chain Rule: <math>z = f(x, y)</math>, <math>x=g(s, t)</math>, <math>y=h(s, t)</math>: <math>\frac{dz}{dt} = \frac{df}{dx} * \frac{dx}{dt} + \frac{df}{dy} * \frac{dy}{dt}</math> (resp. s)</div> <div>Implicit D: <math>\frac{dz}{dx/y} = - \frac{F_x/y(x, y, z)}{F_z(x, y, z)}</math></div> <div>Directional D: <math>D_u f = \nabla f(x, y) * u = \langle f_x, f_y \rangle \cdot u</math></div> <div>Level Surface to Tangent Plane: <math>\nabla F(x_0, y_0, z_0) \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0</math></div>				<div>Volume of Solids</div> <div>X-axis rotation - Disk method wrt to x (<math>\uparrow</math>), shell wrt to y (<math>\rightarrow</math>).</div> <div>Y-axis rotation - Disk method wrt y (<math>\rightarrow</math>), shell wrt x (<math>\uparrow</math>).</div>																																							

<b>Limits Tips</b> <b>Limits</b> need to converge to 1 number to exist. If not dividing by 0 or invalid, just sub in the value <b>Substitute</b> trigonometric values if can and use squeeze: $-5 \leq 3 \sin(g(x)) - 2 \cos(h(x)) \leq 5$	<b>Differentiation RULES</b> <b>Constant Rule:</b> $d/dx \ c = 0$ <b>Constant multiple:</b> $d/dx \ cu = c \ du/dx \ u$ <b>Sum Rule:</b> $d/dx \ (u + v) = d/dx \ u + d/dx \ v$ <b>Product Rule:</b> $d/dx(uv) = du/dx * v + dv/dx * u$ <b>Quotient Rule:</b> $\frac{d}{dx} \frac{u}{v} = \frac{\frac{du}{dx} * v - u * \frac{dv}{dx}}{v^2}$ $ f(x)  \neq  f'(x) $ . Open abs value to $-f(x)$ and $f(x)$ first		<b>Fundamental Theorem of Calculus 1</b> If f is a function and G is the antiderivative of F (that is, $G' = f$ ): $\int_a^b f(x) \, dx = G(b) - G(a)$ $\int_a^b G'(x) \, dx = G(b) - G(a)$	<b>Fundamental Theorem of Calculus 2</b> If $g(x) = \int_{h(x)}^{u(x)} f(t) \, dt$ , <b>THEN</b> $g'(x) = f(u(x)) * u'(x) - f(h(x)) * h'(x)$ IF f is continuous on $[a,b]$ , f is differentiable on $(a,b)$
<b>Differentiability</b> If f' is differentiable at a point, then: $\lim_{h \rightarrow 0} \frac{f(x)_0 + h - f(x_0)}{h}$ or $\lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}$ exist and are equal to the derivative at the point. For piecewise functions, if they are differentiable, then $f(a)=f(b)$ (no sharp spikes) and their limits are equal at the "meeting point" of the piecewise fnc	<b>Natural Logarithm Rules</b> $\ln(a) = x \rightarrow a = e^x$ $\ln(ab) = \ln(a) + \ln(b)$ $\ln\left(\frac{a}{b}\right) = \ln(a) - \ln(b)$ $\ln(a^n) = n * \ln(a)$ $\ln(1) = 0$ $\ln(e) = 1$	<b>Integration</b> Don't be stupid - $dx/dy$ directly corresponds to the axis <b>Trigonometry Stuff</b> $\sin(0) = 0, \sin(\pi) = 0, \sin\left(\frac{\pi}{2}\right) = 1$ $\cos(0) = 1, \cos(\pi) = -1, \cos\left(\frac{\pi}{2}\right) = 0$ $\sin(\theta) = \frac{opp}{hypotenuse}$ $\cos(\theta) = \frac{adj}{hypotenuse}$ $\tan(\theta) = \frac{opp}{adj} = \frac{\sin(\theta)}{\cos(\theta)}$	<b>Optimization problems</b> Problems where you're trying to make something as <u>large/small</u> as possible 1. <i>Read the problem:</i> Write down the givens, and what you're optimizing for 2. <i>Draw a picture</i> , label any part important 3. <i>Introduce Variables:</i> List every relation as an equation/algebra, and identify which is the unknown variable 4. <i>Test Critical points and unknowns:</i> Find critical points E.g. An open top box is made by cutting squares from a 12-by-12 sheet and bent up. How large should the squares cut from the corners be to make the box hold as much as possible? From problem diagram: $V(x) = x * (12 - 2x)^2$ , where x is the size of the corner cut. Find critical point by taking derivative (basic), and then check which is the maximum point and sub into original equation	
<b>Implicit Differentiation</b> Apply $d/dx$ to every term off the equation. Treat y as a function of x, and apply chain rule: $\frac{d}{dx} y = \frac{dy}{dx}$ Solve for $dy/dx$ by collecting all the terms <b>Power rule:</b> $\frac{d}{dx} y^n = ny^{n-1} \frac{dy}{dx}$ <b>Product Rule:</b> $\frac{d}{dx} u(x) y(x) = u'(x) y + u(x) \frac{dy}{dx}$ <b>Chain Rule:</b> $\frac{d}{dx} f(y) = f'(y) \frac{dy}{dx}$ Example:		<b>Figuring out bounds</b> Let's say you did some discriminant/differentiation stuff and you get an equation like: $x=y+1$ How do you find out the values that hold true for this? <b>Sub it into</b> the original equation and solve!	<b>ODE problems</b> Look for <i>rates of change</i> , these usually indicate ODE. 1. <i>Read the problem:</i> Find the rates given, create them if required 2. <i>Identify the type of ODE</i> 3. <i>Solve the ODE</i> 4. <i>Find constant:</i> Using initial value given in question 5. <i>Finish:</i> Calculate some value using the equation if needed Example: In an oil refinery, a storage tank contains 10,000L of gas that initially has 50kg of additive dissolved in it. Gasoline containing 0.2kg/l of additive is pumped into the tank at a rate of 200L/min. The solution is pumped out at a rate of 220L/min. How much of the additive is in the tank 20mins after the pumping begins? Let y be kgs of additive in tank at time t. When $y=50, t=0$ . The number of liters of gasoline and additive in the solution is given: $V(t) = 10,000L + (200L/min - 220L/min) * t \, mins$ $= (10,000 - 20t)L$	
<b>Imposing restrictions</b> Let's say a question gives you a function of several variables $f(x,y,z) = w = xyz^2$ . Additionally, $f(x,y,z)$ must fulfill the constraint equation $2x^3z^3 - xyz = 1$ . You are tasked to find the exact value of $dw/dx$ when $(x,y,z)=(1,1,1)$ . Lastly, you must regard w as a function of variables x and y only. Firstly, you perform implicit differentiation on the constraint equation, treating z as a non-variable: $\frac{d}{dx} (2x^3z^3 - xyz)$ $= 6x^3z^3 + 6x^3z^2 \frac{dz}{dx} - yz - xy \frac{dz}{dz} = 0$ $- xy \frac{dz}{dz} = 0$ $= \frac{dz}{dx} = -\frac{z}{x}$ Then, we differentiate the original equation wrt to x, treating z as a function of x and y: $\frac{dw}{dx} = yz^2 + 2xyz \frac{dz}{dx}$ Finally, we sub in (1,1,1) in the differentiated constraint equation to find	<b>Interchanging bounds of integration</b> $\int_0^4 \int_{\sqrt{x}}^2 g(x) \, dy \, dx$ let's say you have this integral, and want to interchange the bounds of integration. The best way is to draw a graph of sqrt x and observe how y and x change. However, you could also try this: Write out the bounds: $[0 \leq x \leq 4] \text{ and } [\sqrt{x} \leq y \leq 2]$ Write out y in terms of x: $[x \leq y^2 \leq 4]$ Combine the bounds: $[0 \leq x \leq y^2 \leq 4]$ Separate and swap: $[0 \leq y^2 \leq 4] \text{ and } [0 \leq x \leq y^2]$ Always double-check, though.		<p>With this, we can model how much additive comes in and out of the tank:</p> $\text{Rate out} = \frac{y(t)}{V(t)} * \text{outflow} = \frac{y}{10,000 - 20t} * 200 = \frac{220y}{10,000 - 20t} \, kg/min$ <p>Rate in = <math>0.2 \, kg/l * 200l = 40kg/min</math></p> <p>We can model a differential equation:</p> $\frac{dy}{dt} = 40 - \frac{220y}{10,000 - 20t} \, kg/min$ <p>In standard form:</p> $\frac{dy}{dt} + \frac{220}{10,000 - 20t} * y = 40$ <p>This is a LFODE so we get the integrating factor:</p> $I(x) = e^{\int P \, dt} = e^{\int \frac{220}{10,000 - 20t} dt}$ $= e^{-11 * \ln(10,000 - 20t)} = (10,000 - 20t)^{-11}$ <p>Follow the steps for LFODE and multiply both sides and integrate:</p> $(10,000 - 20t)^{-11} * \left( \frac{dy}{dt} + \frac{220}{10,000 - 20t} * y \right) = 40 (10,000 - 20t)^{-11}$ <p>Skiping a few steps we get:</p> $y = 0.2 (10,000 - 20t) + C (10,000 - 20t)^{11}$ <p>From this, we solve the initial value problema and get C. Done.</p>	
<b>Maclaurin Series tiny example</b> Find the maclaurin series for $\frac{1}{1-3x}$ This is the geometric series, where $u=3x$ . Hence, $\sum_{n=0}^{\infty} (3x)^n$ Then, to find the 6th derivative of the function $\frac{1}{1-3x}$ evaluated at 0, we take: $c_n = \frac{f^{(n)}(0)}{n!}$ , which when rearranged: $f^{(6)}(0) = 6! * 3^6$				

