

ASSIGNMENT 4: TRANSFORMATION AND BARYCENTRIC COORDINATES

EXERCISE 1

TASK 1

$$P_i = [1, 1]^T \quad p = [1.5, 2.5]^T \quad u = p - P_i$$

$$R_{90} = \begin{bmatrix} \cos(90) & -\sin(90) & 0 \\ \sin(90) & \cos(90) & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \cos(90) & -\sin(90) & 0 \\ \sin(90) & \cos(90) & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & 0 & +x \\ 0 & 1 & +y \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

TASK 2

Representation in Homogeneous Coordinates: $P_i = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad p = \begin{bmatrix} 1.5 \\ 2.5 \\ 1 \end{bmatrix} \quad u = \begin{bmatrix} 0.5 \\ 1.5 \\ 0 \end{bmatrix}$

ROTATION:

We get the following results:

$$P_{i_rotation} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

$$P_{rotation} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1.5 \\ 2.5 \\ 1 \end{bmatrix} = \begin{bmatrix} -2.5 \\ 1.5 \\ 1 \end{bmatrix}$$

$$U_{rotation} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.5 \\ 1.5 \\ 0 \end{bmatrix} = \begin{bmatrix} -1.5 \\ 0.5 \\ 0 \end{bmatrix}$$

TRANSLATION

We get the following results based on the rotation:

$$P_{i_translate} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$P_{rotation} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -2.5 \\ 1.5 \\ 1 \end{bmatrix} = \begin{bmatrix} -1.5 \\ -0.5 \\ 1 \end{bmatrix}$$

$$U_{rotation} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1.5 \\ 0.5 \\ 0 \end{bmatrix} = \begin{bmatrix} -1.5 \\ 0.5 \\ 0 \end{bmatrix}$$

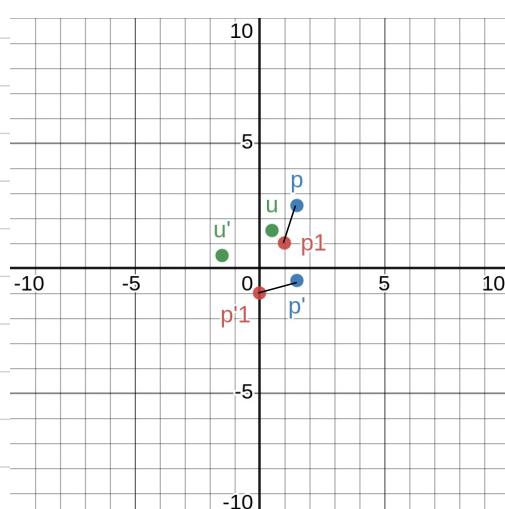
Converting Homogeneous coordinates to Cartesian coordinates:

$$P'_i = \begin{bmatrix} 0 \\ -1 \end{bmatrix} \quad P' = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} \quad U' = \begin{bmatrix} -1.5 \\ 0.5 \end{bmatrix}$$

Confirming if this is true: $U' = P' - P'_i$

$$\begin{bmatrix} -1.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} - \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} -1.5 \\ 0.5 \end{bmatrix}$$



TASK 3

$$P_i' = \begin{bmatrix} 0 \\ -1 \end{bmatrix} \quad P_j' = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} \quad U' = \begin{bmatrix} -1.5 \\ 0.5 \end{bmatrix}$$

Representation in Homogeneous Coordinates:

$$P_i' = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \quad P_j' = \begin{bmatrix} 1.5 \\ -0.5 \\ 1 \end{bmatrix} \quad U' = \begin{bmatrix} -1.5 \\ 0.5 \\ 0 \end{bmatrix}$$

$$S = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing the scaling:

$$P_i'' = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$$

$$P_j'' = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1.5 \\ -0.5 \\ 1 \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \\ 1 \end{bmatrix}$$

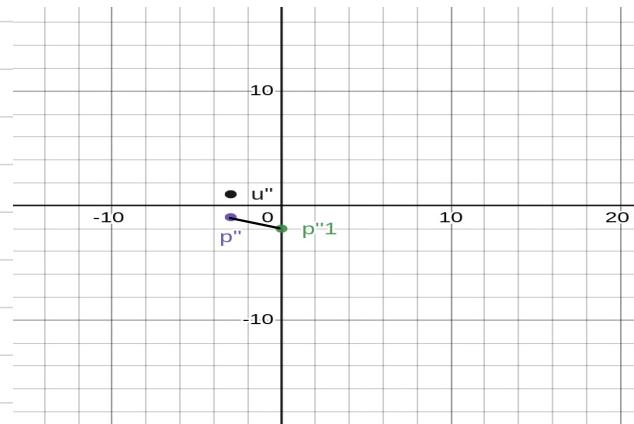
$$U'' = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1.5 \\ 0.5 \\ 0 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix}$$

Converting it back to cartesian product:

$$P_i'' = (0, -2)$$

$$P_j'' = (-3, -1)$$

$$U'' = (-3, 1)$$



TASK 4

The inverse transformation matrices are as follows:

Rotation (Clockwise)

$$R_{90}^{-1} = \begin{bmatrix} \cos 90^\circ & \sin 90^\circ & 0 \\ -\sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \cos(90) & \sin(90) & 0 \\ -\sin(90) & \cos(90) & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ tx & ty & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 2 & 1 \end{bmatrix}$$

$$S^{-1} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & s_z \end{bmatrix} = \begin{bmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

EXERCISE 2:

First we need to find the area of the whole triangle. We have the following points for the triangle:

$$P_1 = (6, 0, 4) \quad P_2 = (2, 0, 0) \quad P_3 = (2, 4, 4)$$

Hence we do the follow:

$$\begin{aligned} \overrightarrow{P_1 P_2} &= \langle 2-6, 0-0, 0-4 \rangle = \langle -4, 0, -4 \rangle \\ \overrightarrow{P_1 P_3} &= \langle 2-6, 4-0, 4-4 \rangle = \langle -4, 4, 0 \rangle \end{aligned}$$

Now doing cross product of $\overrightarrow{P_1 P_2}$ and $\overrightarrow{P_1 P_3}$:

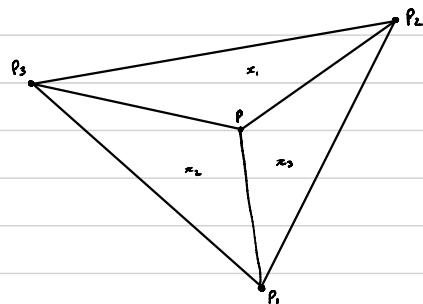
$$\begin{aligned} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -4 & 0 & -4 \\ -4 & 4 & 0 \end{vmatrix} &= \begin{vmatrix} 0 & -4 \\ 4 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} -4 & -4 \\ -4 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} -4 & 0 \\ -4 & 4 \end{vmatrix} \vec{k} \\ &= [0 - (-16)] \vec{i} - [0 - (-16)] \vec{j} + [-16 - 0] \vec{k} \\ &= 16 \vec{i} - 16 \vec{j} - 16 \vec{k} \end{aligned}$$

$$\therefore \overrightarrow{P_1 P_2} \times \overrightarrow{P_1 P_3} = \langle 16, -16, -16 \rangle$$

$$\begin{aligned} \|\overrightarrow{P_1 P_2} \times \overrightarrow{P_1 P_3}\| &= \sqrt{16^2 + (-16)^2 + (-16)^2} \\ &= \sqrt{768} \end{aligned}$$

$$\text{Area of the triangle} = \frac{\sqrt{768}}{2} = 13.856 \text{ or } 8\sqrt{3}$$

Lets assume that P is in the triangle. Hence we should get the area for the following sub-triangles (x_1, x_2, x_3) :



Finding area of x_1 , we need the following points:

$$P_3 = (2, 4, 4) \quad P_2 = (2, 0, 0) \quad P = (4, 1, 3)$$

$$\begin{aligned} \overrightarrow{P_3 P_2} &= \langle 2-2, 0-4, 0-4 \rangle = \langle 0, -4, -4 \rangle \\ \overrightarrow{P_3 P} &= \langle 4-2, 1-4, 3-4 \rangle = \langle 2, -3, -1 \rangle \end{aligned}$$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & -4 & -4 \\ 2 & -3 & -1 \end{vmatrix} = \begin{vmatrix} -4 & -4 \\ -3 & -1 \end{vmatrix} \vec{i} - \begin{vmatrix} 0 & -4 \\ 2 & -1 \end{vmatrix} \vec{j} + \begin{vmatrix} 0 & -4 \\ 2 & -1 \end{vmatrix} \vec{k}$$

$$= (-4-12)\vec{i} - (0-(-8))\vec{j} + (0-6)\vec{k}$$

$$= -8\vec{i} - 8\vec{j} + 8\vec{k}$$

$$\frac{\|\overrightarrow{P_2P_3} \times \overrightarrow{P_3P}\|}{\|\overrightarrow{P_2P_3} \times \overrightarrow{P_3P}\|} = \frac{<-8, -8, 8>}{\sqrt{(-8)^2 + (-8)^2 + (8)^2}}$$

$$= \sqrt{192}$$

$$x_1 = \frac{\sqrt{192}}{2} = 6.928 \text{ or } 4\sqrt{3}$$

$$\Delta_1(x_1) = \frac{4\sqrt{3}}{8\sqrt{3}} = \frac{1}{2}$$

Finding area of x_2 we need the following points:

$$P_1 = (6, 0, 4) \quad P_3 = (2, 4, 4) \quad P = (4, 1, 3)$$

$$\overrightarrow{P_1P_3} = <(2-6), (4-0), (4-4)> = <-4, 4, 0>$$

$$\overrightarrow{P_1P} = <(4-6), (1-0), (3-4)> = <-2, 1, -1>$$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -4 & 4 & 0 \\ -2 & 1 & -1 \end{vmatrix} = \begin{vmatrix} 4 & 0 \\ 1 & -1 \end{vmatrix} \vec{i} - \begin{vmatrix} -4 & 0 \\ -2 & -1 \end{vmatrix} \vec{j} + \begin{vmatrix} -4 & 4 \\ -2 & 1 \end{vmatrix} \vec{k}$$

$$= (-4-0)\vec{i} - (4-0)\vec{j} + (-4+8)\vec{k}$$

$$= -4\vec{i} - 4\vec{j} + 4\vec{k}$$

$$\frac{\|\overrightarrow{P_1P_3} \times \overrightarrow{P_1P}\|}{\|\overrightarrow{P_1P_3} \times \overrightarrow{P_1P}\|} = \frac{<-4, -4, 4>}{\sqrt{(-4)^2 + (-4)^2 + (4)^2}}$$

$$= \sqrt{48}$$

$$x_2 = \frac{\sqrt{48}}{2} = 3.464 \text{ or } 2\sqrt{3}$$

$$\Delta_2(x_2) = \frac{2\sqrt{3}}{8\sqrt{3}} = \frac{1}{4}$$

Finding area of x_2 we need the following points:

$$P_2 = (2, 0, 0) \quad P_1 = (6, 0, 4) \quad P = (4, 1, 3)$$

$$\overrightarrow{P_2P_1} = <(6-2), (0-0), (4-0)> = <4, 0, 4>$$

$$\overrightarrow{P_2P} = <(4-2), (1-0), (3-0)> = <2, 1, 3>$$

$$\begin{vmatrix} 1 & 0 & 1 \\ 4 & 0 & 4 \\ 2 & 1 & 3 \end{vmatrix} = \begin{vmatrix} 0 & 4 \\ 1 & 3 \end{vmatrix} \bar{i} - \begin{vmatrix} 4 & 4 \\ 2 & 3 \end{vmatrix} \bar{j} + \begin{vmatrix} 4 & 0 \\ 2 & 1 \end{vmatrix} \bar{k}$$

$$\begin{aligned}
 &= (0 - 4) \bar{i} - (12 - 8) \bar{j} + (4 - 0) \bar{k} \\
 &= -4 \bar{i} - 4 \bar{j} + 4 \bar{k} \\
 \overrightarrow{P_2 P_1} \times \overrightarrow{P_2 P} &= \langle -4, -4, 4 \rangle \\
 \|\overrightarrow{P_2 P_1} \times \overrightarrow{P_2 P}\| &= \sqrt{(-4)^2 + (-4)^2 + 4^2} \\
 &= \sqrt{48} \\
 x_3 &= \frac{\sqrt{48}}{2} = 3.464 \text{ or } 2\sqrt{3} \\
 \alpha_3(x_3) &= \frac{2\sqrt{3}}{8\sqrt{3}} = \frac{1}{4}
 \end{aligned}$$

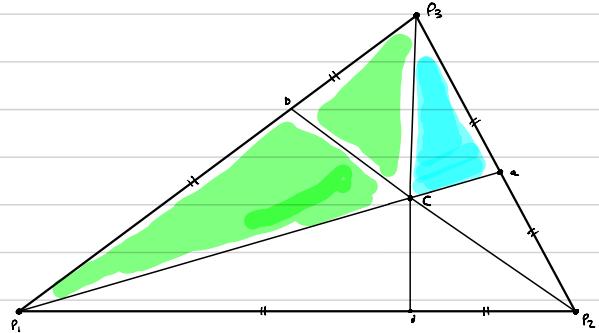
Hence, finally we have gotten the Barycentric coordinates. If we add the Barycentric coordinates we get the following :

$$\frac{1}{2} + \frac{1}{4} + \frac{1}{4} = 1$$

Also since they are positive we get to know that our assumption is correct. Hence P is inside the triangle

EXERCISE 3

Let's visualize the triangle :



$$\text{lets assume } 2 \overrightarrow{P_1 C} = \overrightarrow{c}$$

\therefore that means the area of $P_1 P_2 C$ is twice as big as $P_3 C a$. Hence let x be area for $P_3 C a$.

$$x = \frac{(P_3 - C) \times (C - a)}{2} \quad \text{--- (1)}$$

Then area for $P_1 P_2 C$ is as :

$$2x = \frac{(P_3 - C) \times (P_1 - C)}{2} \quad \text{--- (2)}$$

Now coming back to our assumption we would substitute $2(C - a)$ in (2) :

$$2x = \frac{(P_3 - C) \times 2(C - a)}{2}$$

$$2x = (P_3 - C) \times (C - a)$$

$$x = \frac{(P_3 - C) \times (C - a)}{2}$$

which equals to x .

EXERCISE 4

We know that the x would always need to be 1.

Also we know the following as well:

$$y = mx + b \quad b = 0$$

$$y = mx$$

$$m = \frac{y}{x}$$

so y' is now equal to m . In the cartesian coordinates we want $\begin{bmatrix} 1 \\ m \end{bmatrix}$.

If convert this to the homogenous coordinates we would get the following:

$$\begin{bmatrix} 1 \\ m \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{y}{x} \end{bmatrix} \Rightarrow \begin{bmatrix} x \\ y \\ x \end{bmatrix}$$

Hence after the transformation we need above.

$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ x \end{bmatrix}$$

Therefore the transformation matrix is as follows:

$$m = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$