



AUTOSAR Introduction

The vision, the partnership and current features in a nutshell

Presenter

Occasion (Meeting, Conference, etc.)

20 Jan 2020

Location @ Host

BMW
GROUP



DAIMLER



TOYOTA

VOLKSWAGEN
AKTIENGESELLSCHAFT

Agenda

- > Introduction of the AUTOSAR Partnership
- > Challenges in the automotive industry
- > Architecture and recent features
- > Smart solutions based on AUTOSAR
- > Processes and quality
- > Outlook

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> Introduction of the AUTOSAR Partnership

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AUTOSAR Introduction

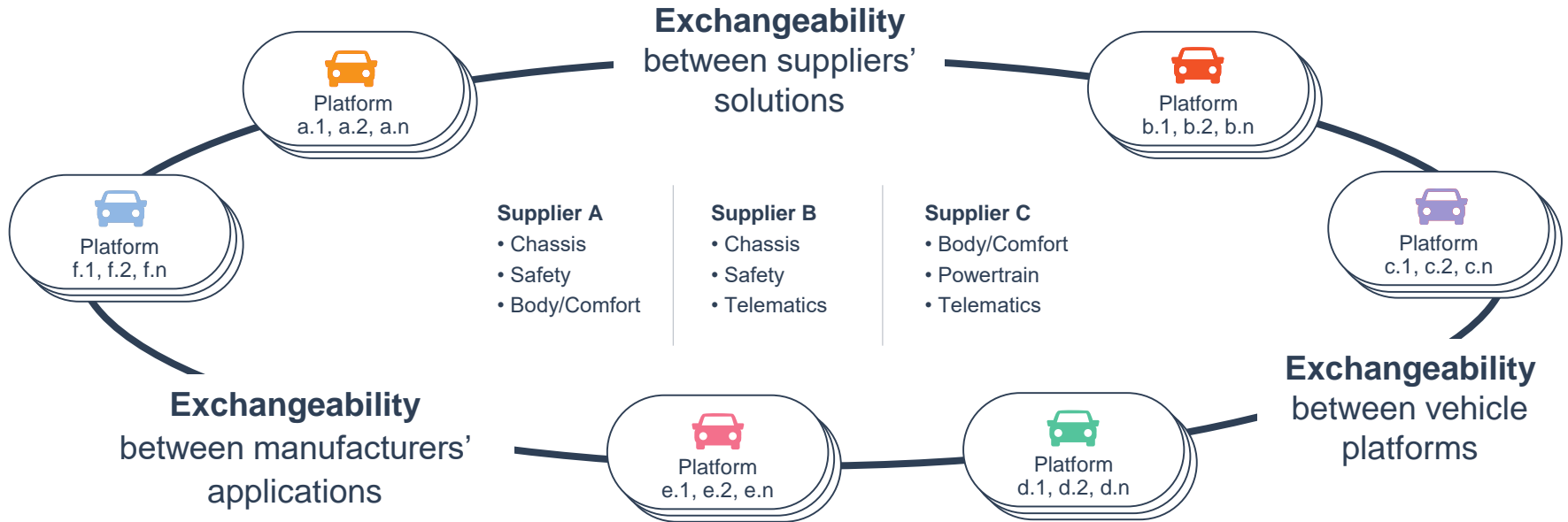


(AUTomotive Open System ARchitecture)

is a worldwide development partnership of car manufacturers, suppliers and other companies from the electronics, semiconductor and software industry.

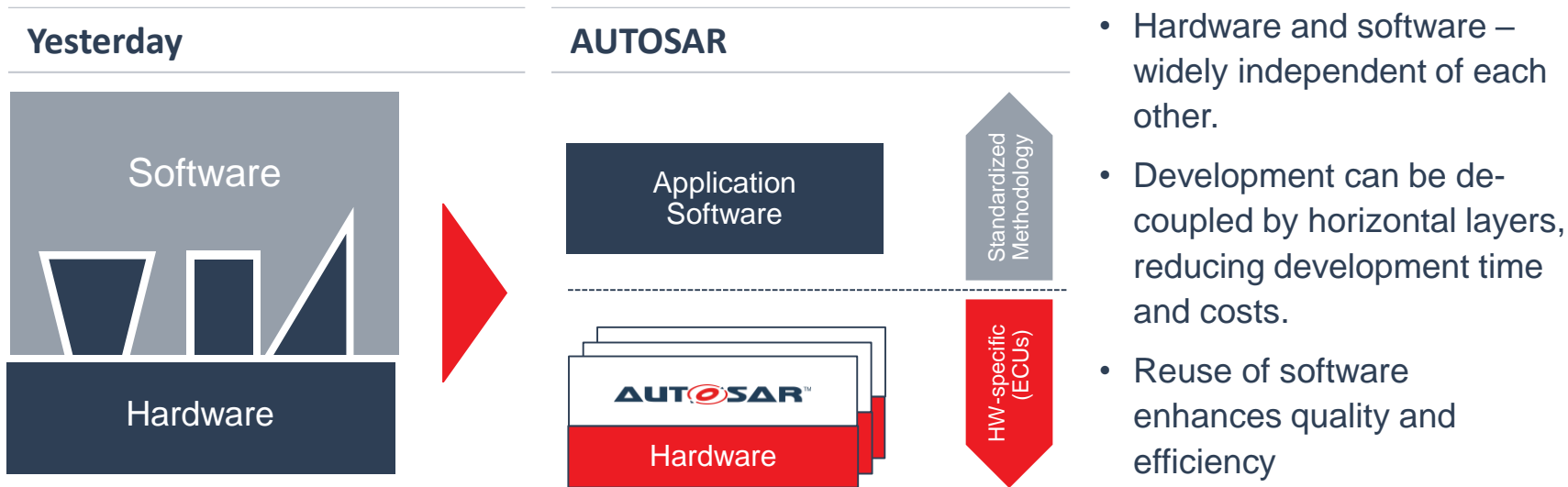
AUTOSAR Vision

AUTOSAR aims to improve complexity management of integrated E/E architectures through increased reuse and exchangeability of SW modules between OEMs and suppliers.

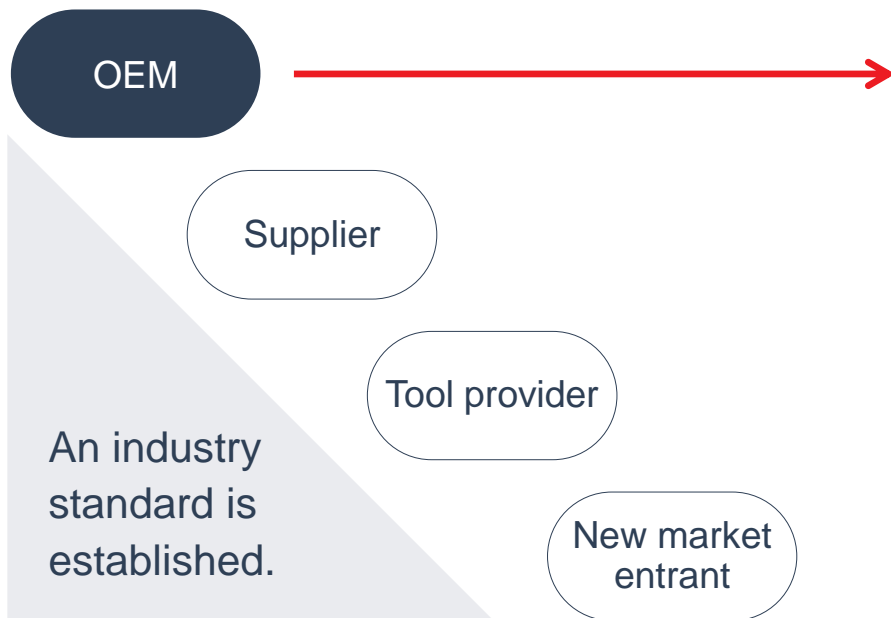


Aims and benefits of using AUTOSAR

AUTOSAR aims to standardize the software architecture of **Electronic Control Units (ECUs)**. AUTOSAR paves the way for innovative electronic systems that further improve performance, safety and environmental friendliness.

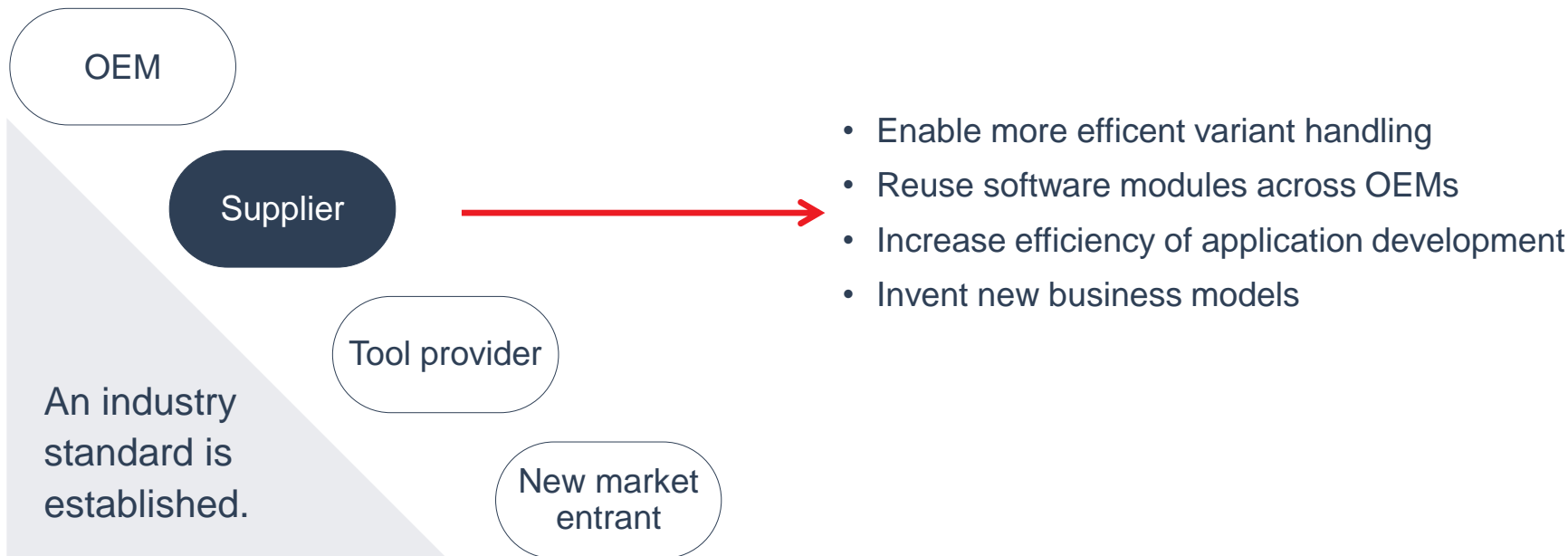


Exploitation of the standard provides significant benefits

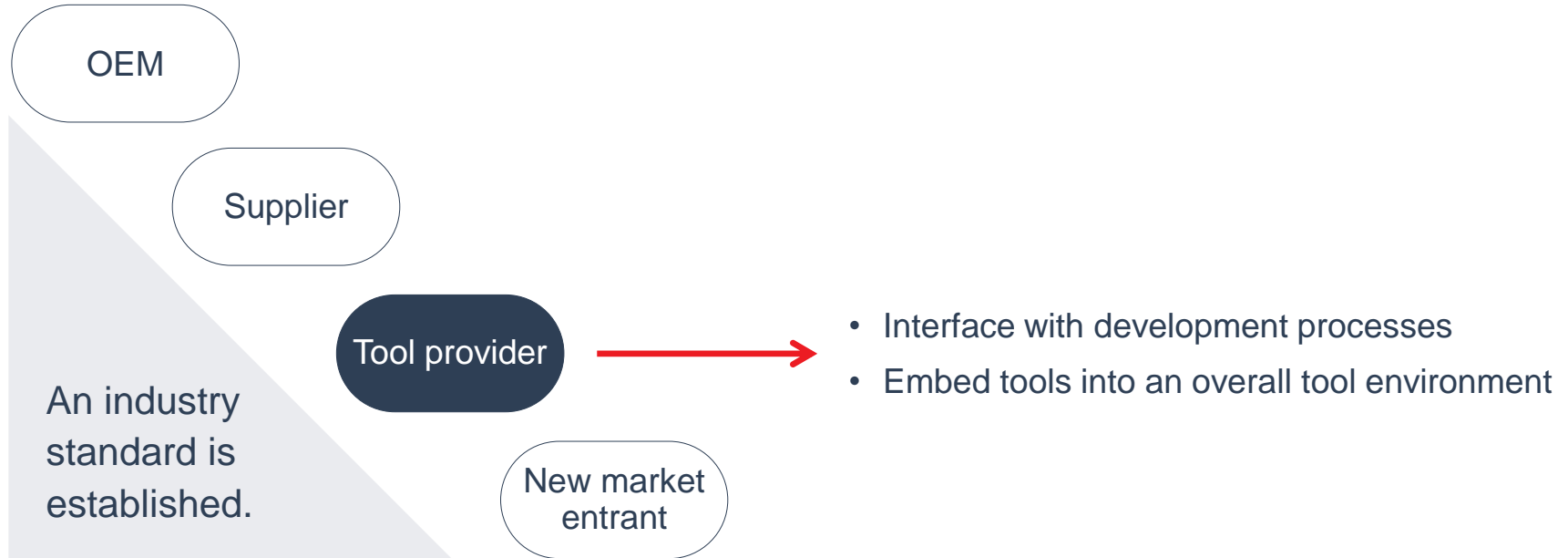


- Establish development distribution among suppliers
- Compete on innovative functions with increased design flexibility
- Simplify software and system integration
- Reduce overall software development costs

Exploitation of the standard provides significant benefits



Exploitation of the standard provides significant benefits



Exploitation of the standard provides significant benefits



The 280 AUTOSAR Partners



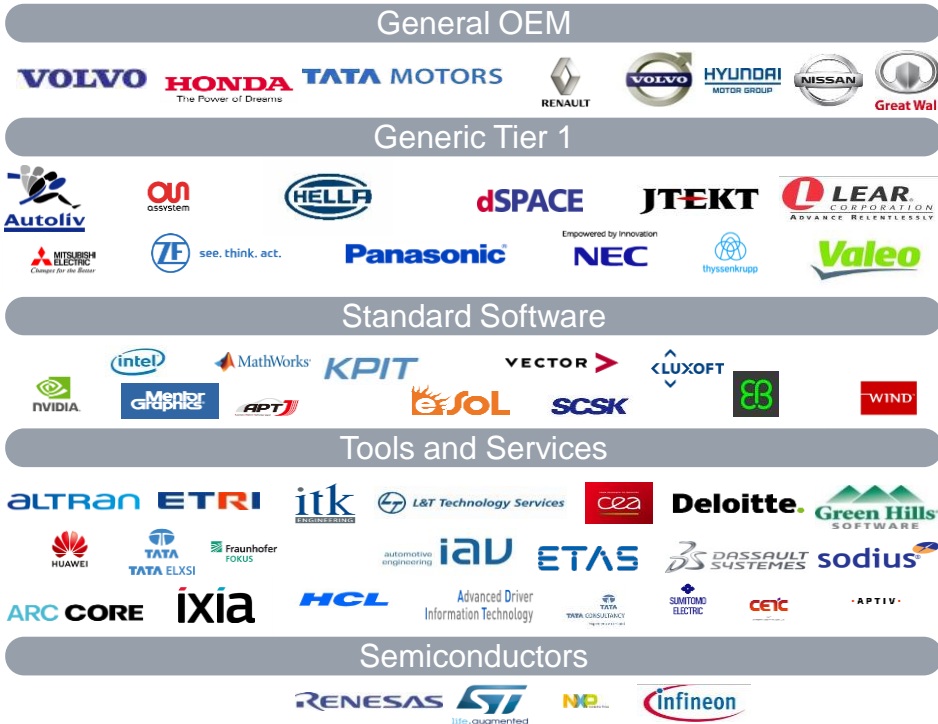
9 Core Partners



2 Strategic Partners



58 Premium Partners



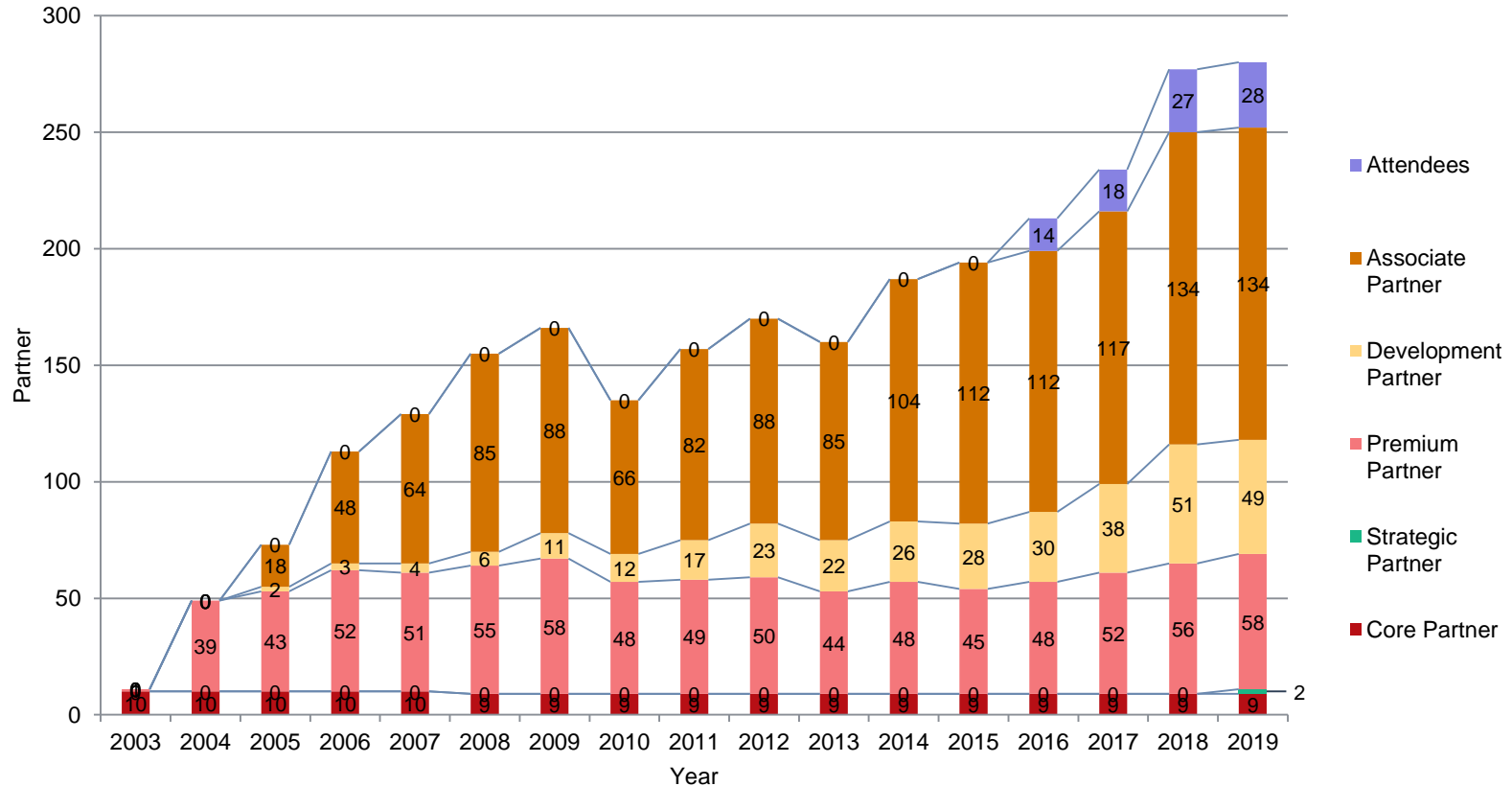
49 Development Partners



134 Associate Partners
28 Attendees

History and current state – Total: 280

Info

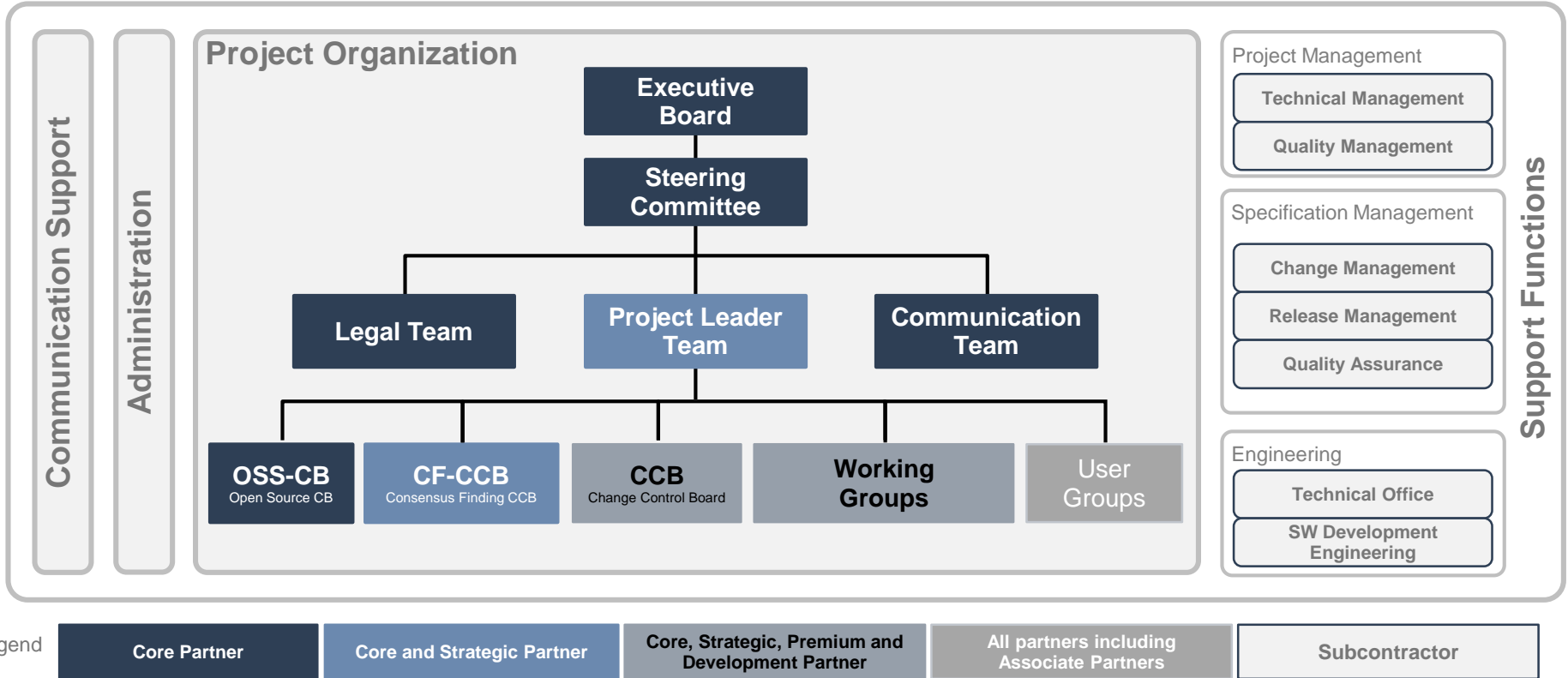


Geographical distribution of partners

Info



AUTOSAR Organization



Working Group organization

Project Leader Team

Cross-standard Working Groups (FO, CP, AP)

WG-A
Architecture Team

WG-MT
Methodology and Templates

WG-SEC
Automotive Security

WG-SAF
Functional Safety

WG-IVC
In-Vehicle COM

WG-AIF
Application Interfaces

WG-V2X
Vehicle to X

WG-DIA
Diagnostics

WG-RES
Resources

WG-UCM
Update & Conf. Management

WG-VAL
Validation

Classic Platform Working Groups (CP)

WG-CP-RTE
Runtime Environment

WG-CP-MCBD
Multicore BSW Distr.

WG-CP-LIB
Libraries

WG-CP-MCL
MCAL and NVRAM

Adaptive Platform Working Groups (AP)

WG-AP-EMO
Execution Man. & OS

WG-AP-DI
Demonstrator Integration

WG-AP-ST
System Tests

WG-AP-PER
Persistency

WG-AP-CCT
Central Coding Team

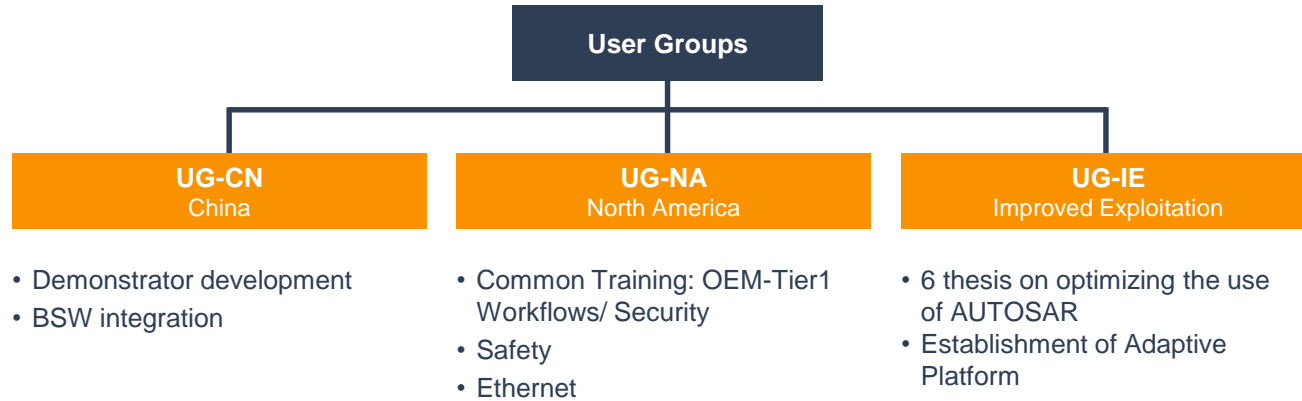
WG-AP-CLD
Cloud Services

Legend:

Lead Working Group

Working Group

User Group Structure



Groups, Boards and Task Forces

Group	Type	Initiated by	Main Tasks	Coaching	Contact person	Reporting to
Lead WG	Permanent	PL Team	<ul style="list-style-type: none"> - Technical supervision of WGs and concept groups - Harmonization of technical content - Assignment of concepts to WGs 	PL Coach	WG Speaker	PL Team
WG	Permanent	PL Team	<ul style="list-style-type: none"> - Expert statements - Responsibility for documents and code development - Assessment of concepts 	PL Coach	WG Speaker	PL Team
Subgroup	Permanent	WG	WG substructure for a dedicated branch of WG content	-	Subgroup Speaker	WG
Control Board	Permanent	PL Team	Controlling task within AUTOSAR processes (e.g. CM, QM, SDE or RM) such as CCB, CF-CCB and OSS-CB	PL Team	CM, QM or RM	CM, QM or RM
Concept Group	On demand (project-based)	CP/SP/PP/DP	Creation and processing of a concept or a set of concepts according to concept process Responsibility for concept validation	-	Concept Owner(s)	Lead WG, WG, PL Team; cf. concept handling process
Task Force	On demand (project-based)	WG or PL Team	Dedicated task with defined due date	-	TF Speaker	WG or PL Team
UG	On demand (project-based)	PP/DP/AP	Creation of documents or implementations based on existing releases	PL or SC Team	UG Speaker	PL-Team

AUTOSAR Deliverables

Legend



Released as an own standard



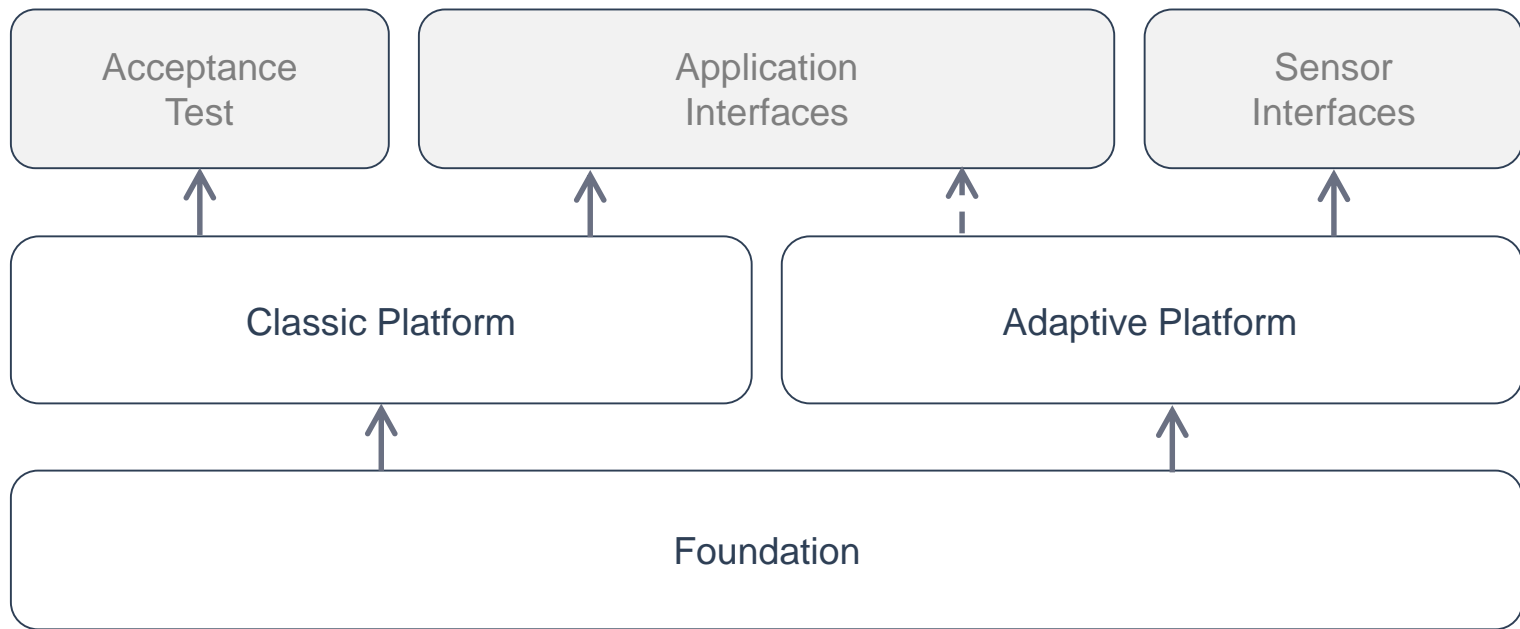
Released as part of the standard it is extending



A extends B



A planned to extend B



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Challenges – selected main drivers



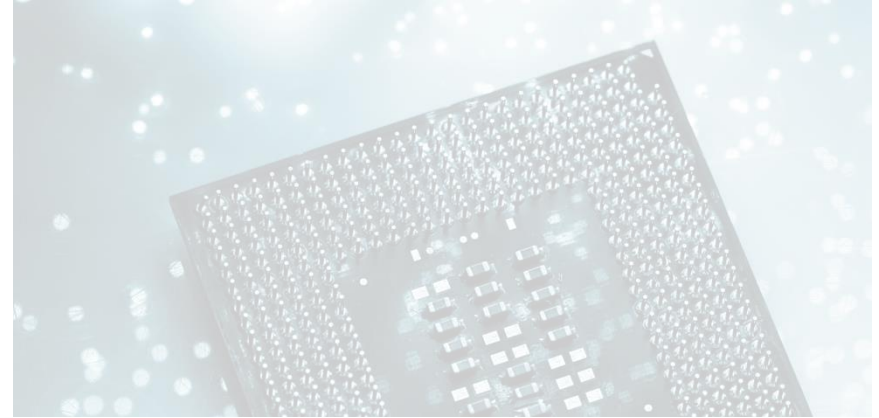
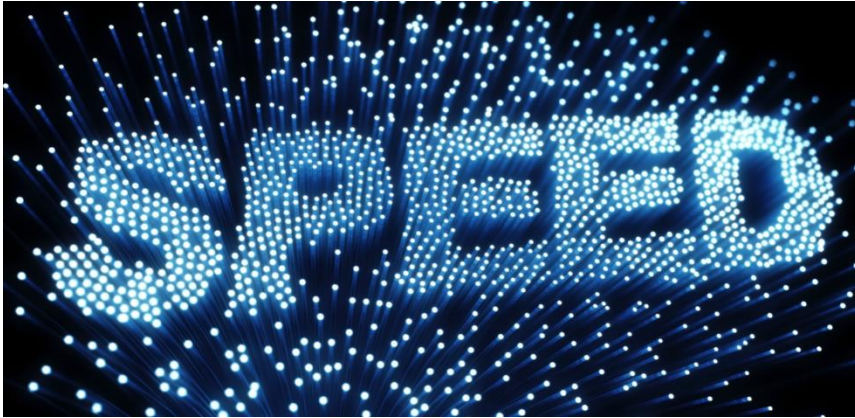
➤ Highly automated driving

Challenges – selected main drivers



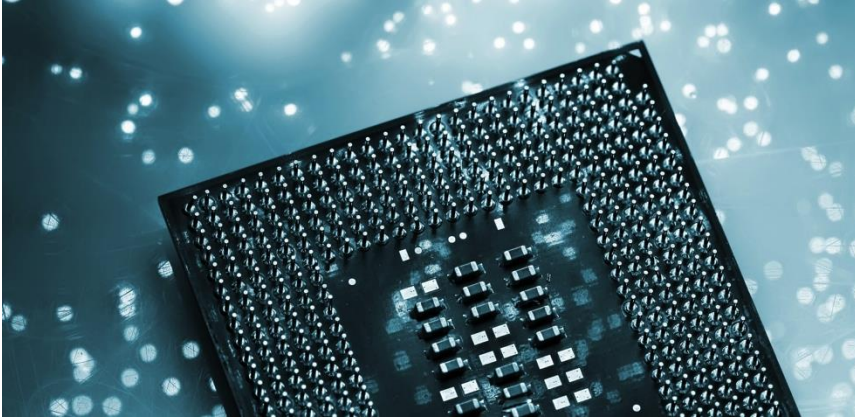
- Car-2-X applications
- Internet of Things and cloud services

Challenges – selected main drivers



➤ Increasing data rates

Challenges – selected main drivers



- New processor technologies

Challenges – selected main drivers



➤ Trust

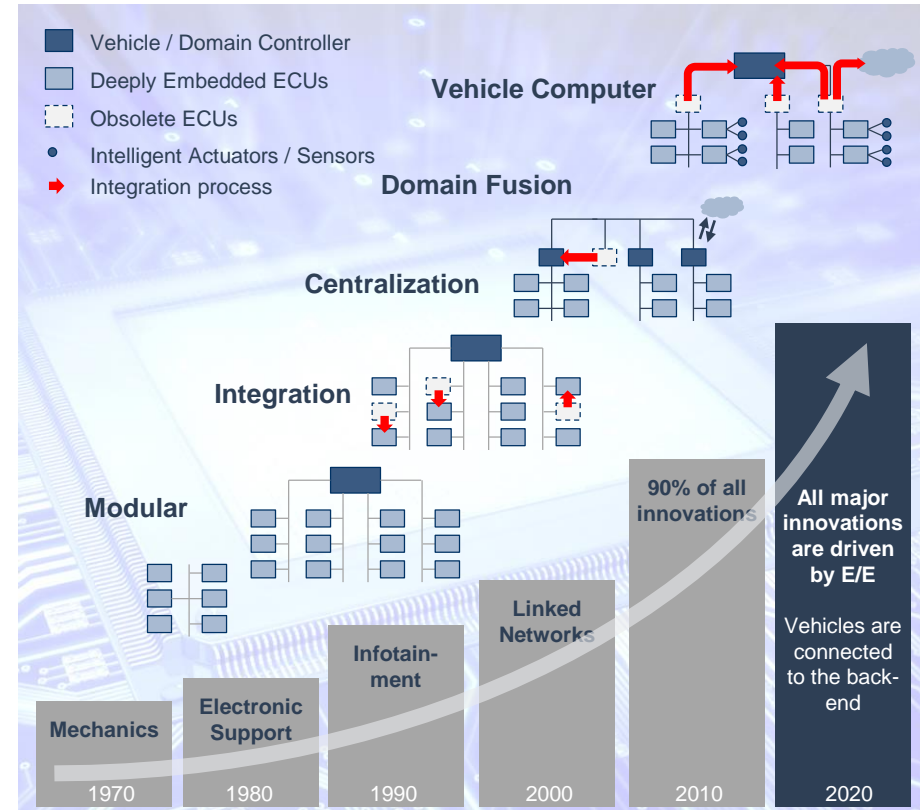
Challenges – Driving changes in E/E Architectures

New types of in vehicle computers are required to fulfill the needs of

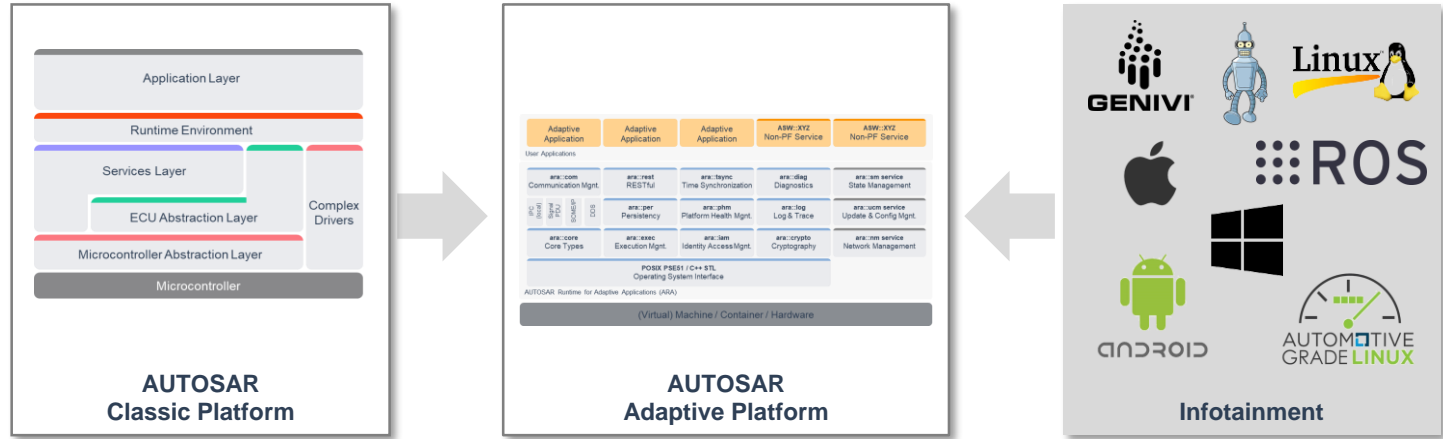
- **performance**,
- **flexibility** and
- **connectivity**

But

- **backwards compatibility** with existing solutions,
 - fulfillment of increasing requirements for **safety** and **security**
- is **a must** as well.



AUTOSAR's answer to the upcoming challenges

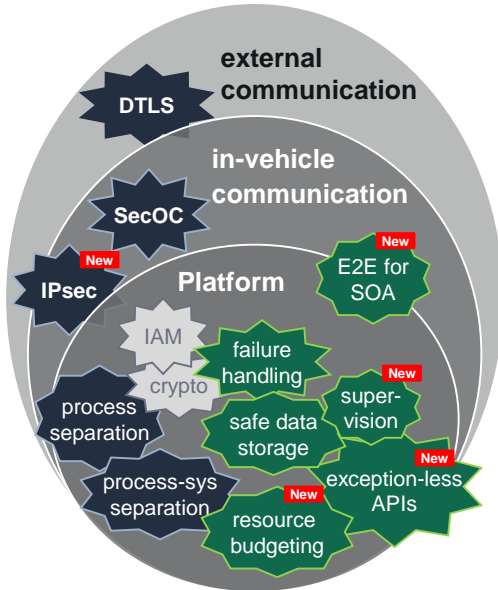


Real time Requirements	High, in the range of micro-sec	Mid, in the range of milli-sec	Low, in the range of sec
Safety Criticality	High, up to ASIL-D	High, at least ASIL-B	Low, QM
Computing power	Low, ~ 1000 DMIPs	High, > 20.000 DMIPs	High, ~ 10.000 DMIPs

AUTOAR Adaptive Platform

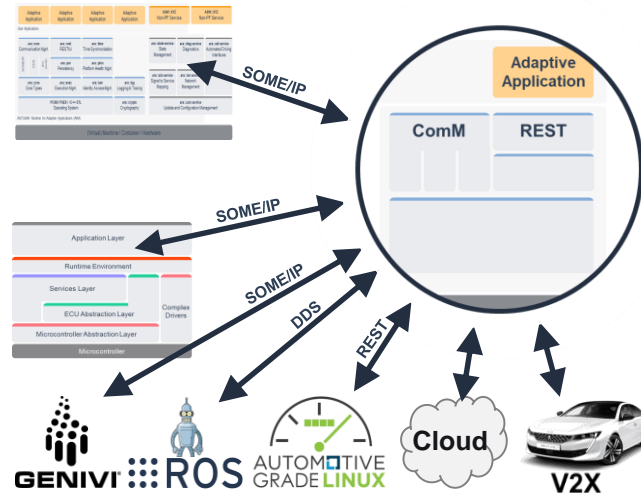
The 3 Pillars of the Adaptive Platform ...

I – Safe & Secure

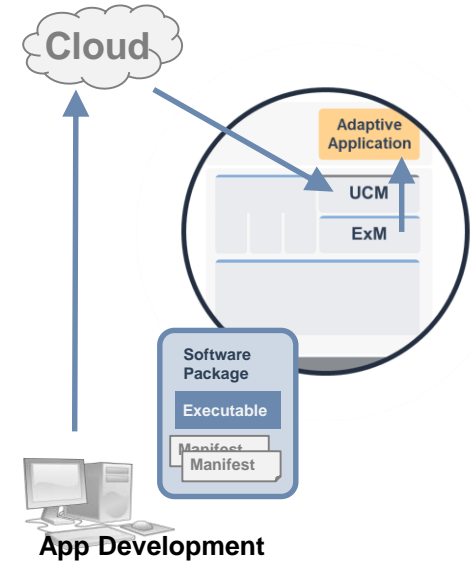


II – Connected

Service-Oriented Communication



III – Dynamic & Updateable



... are the prerequisite for ADAS applications

Strengthen and Extend Pillars of AUTOSAR

AUTOSAR USP

Strengthen Safety & Security

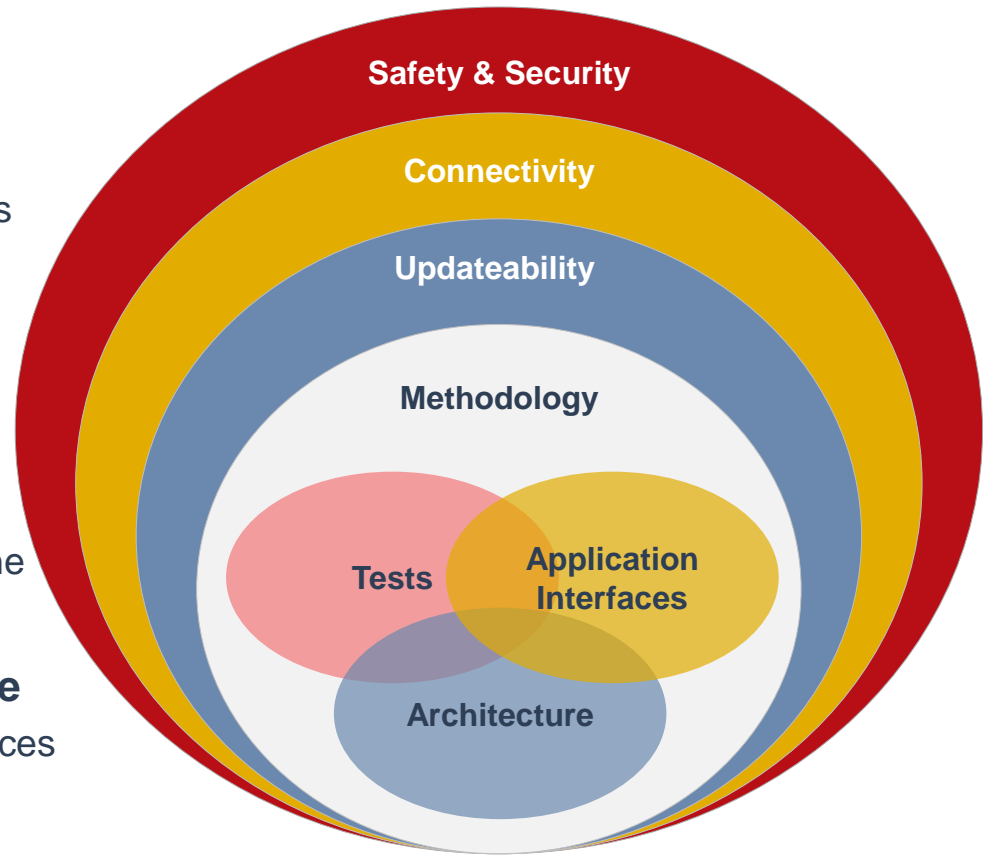
- ➔ Support standard failure and attack scenarios
- ➔ Extend test and verification
- ➔ Improve processes

Strengthen connectivity

- ➔ Extend standard cloud services
- ➔ Think about AUTOSAR App store
- ➔ Enable connectivity to smart phones and zone ECUs

Develop flexible updates during life time

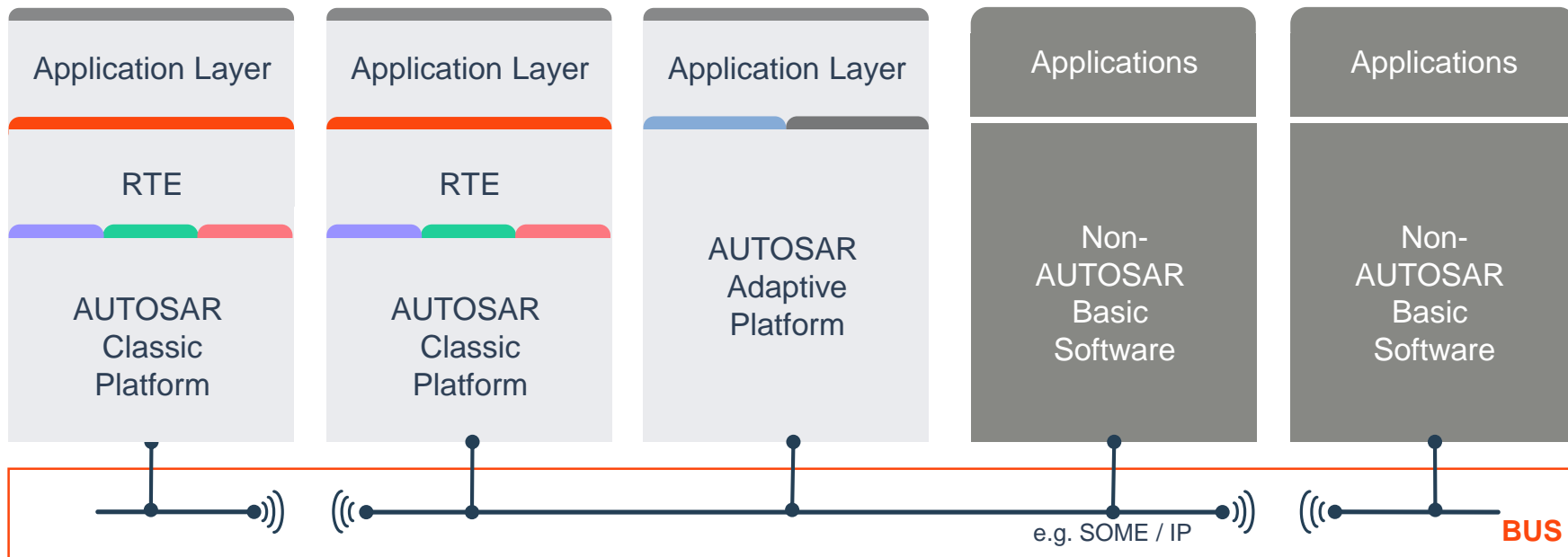
- ➔ Improve modularity e.g. define cluster interfaces
- ➔ Provide means for system description



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AUTOSAR in a Vehicle Network



Common Bus Interface Specification

AUTOSAR Foundation

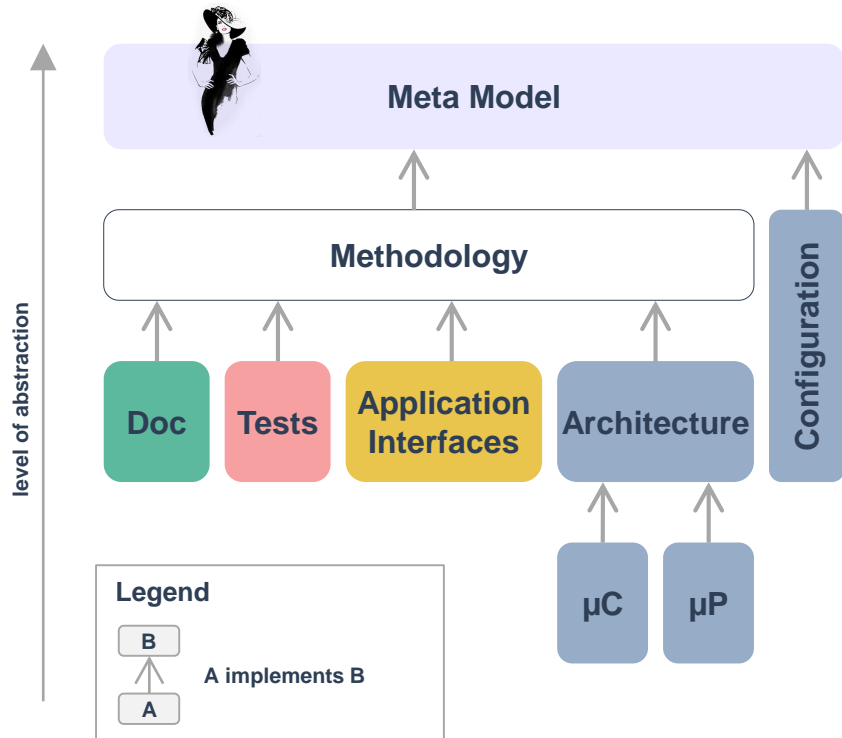
Common Features

The Foundation **assures compatibility** of the different AUTOSAR standards and therefore **contains** all **common artifacts** such as ...



AUTOSAR Foundation

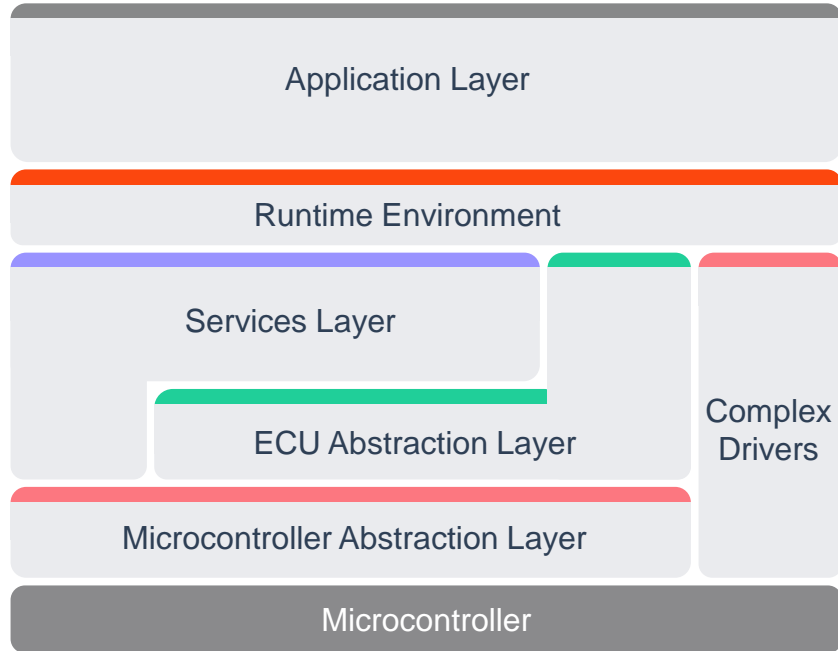
The Methodology, derived out of the Meta Model, ...



- ... provides means to describe the AUTOSAR **architecture** with all its **interfaces**
- ... defines **exchange formats** and description **templates** (e.g. manifest) to enable
 - a seamless integration of the complete vehicle E/E architecture,
 - the automatized configuration of the μ C- and μ P-software stacks and
 - the seamless integration of application software
- ... supports means to **ensure safety** and **security** of the system
- ... provides templates to **document the standard**

AUTOSAR Classic Platform

Layered Software Architecture (1/2)

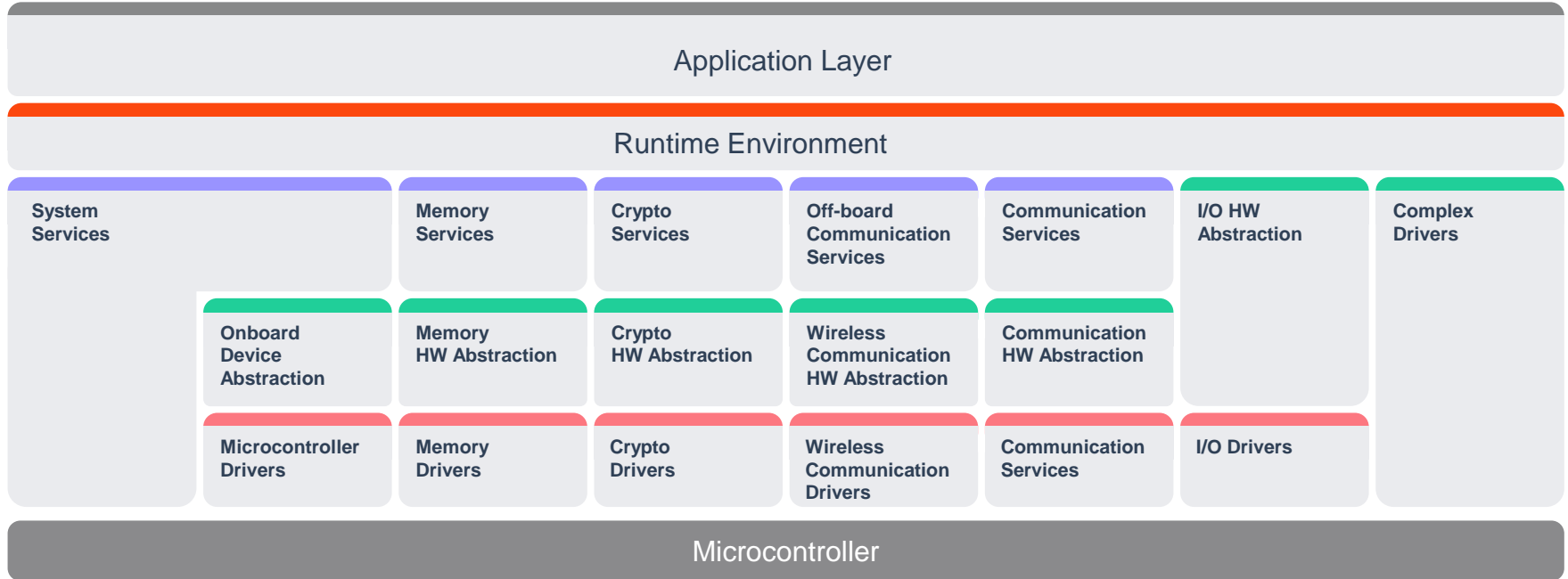


The layered architecture of the classic platform basically supports

- Hardware abstraction
- Scheduling of runnables and tasks (OS)
- Communication between applications on the same hardware and over the network
- Diagnosis and diagnostic services
- Safety- and
- Security Services

AUTOSAR Classic Platform

Layered Software Architecture (2/2)



AUTOSAR Adaptive Platform

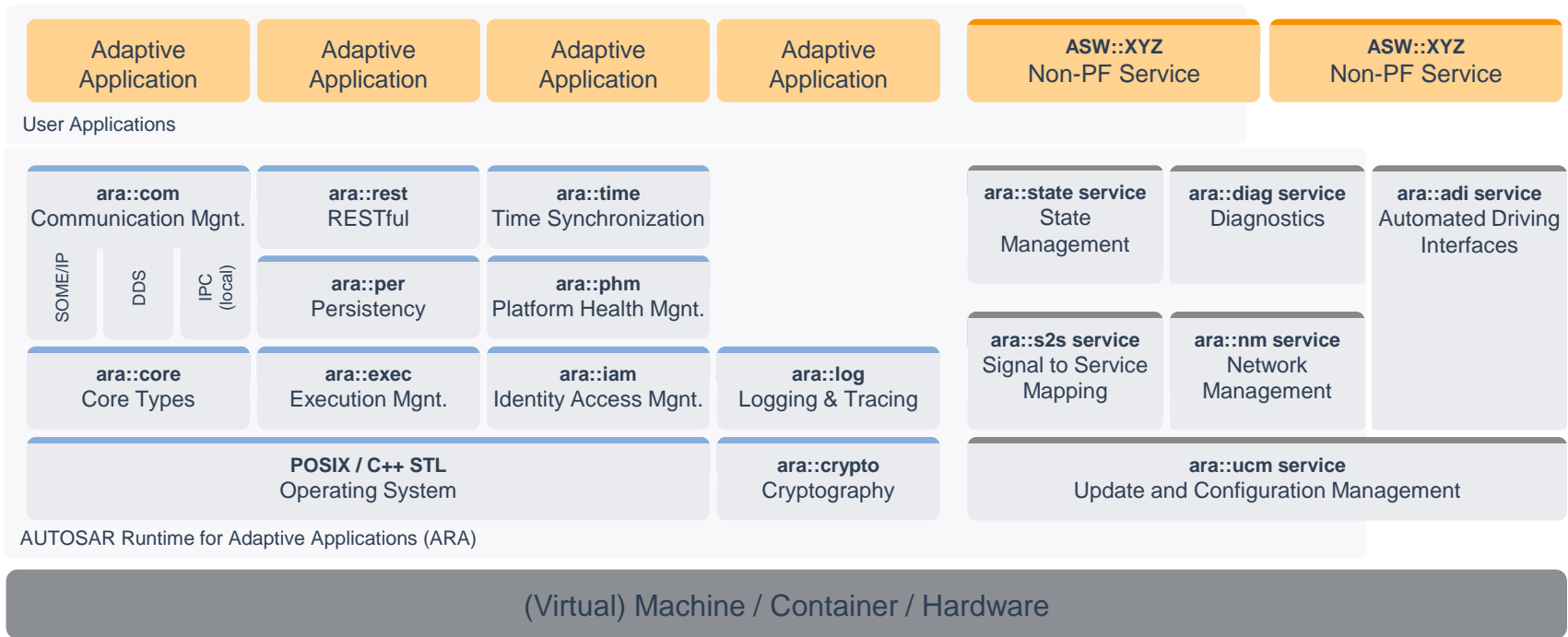
Logical view

Legend

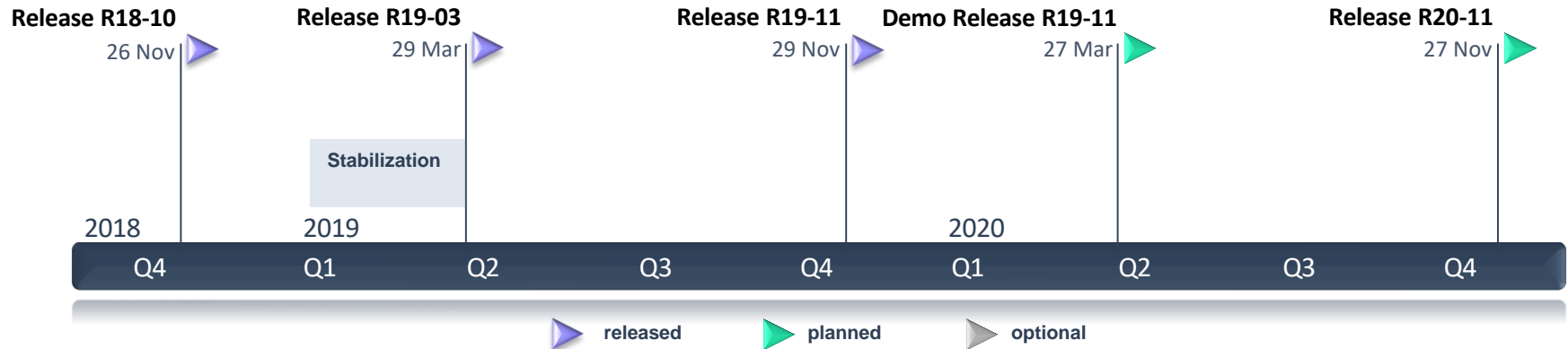
SERVICE
Non-PF Service

SERVICE
Func. Cluster

API
Func. Cluster



AUTOSAR AP and CP Features

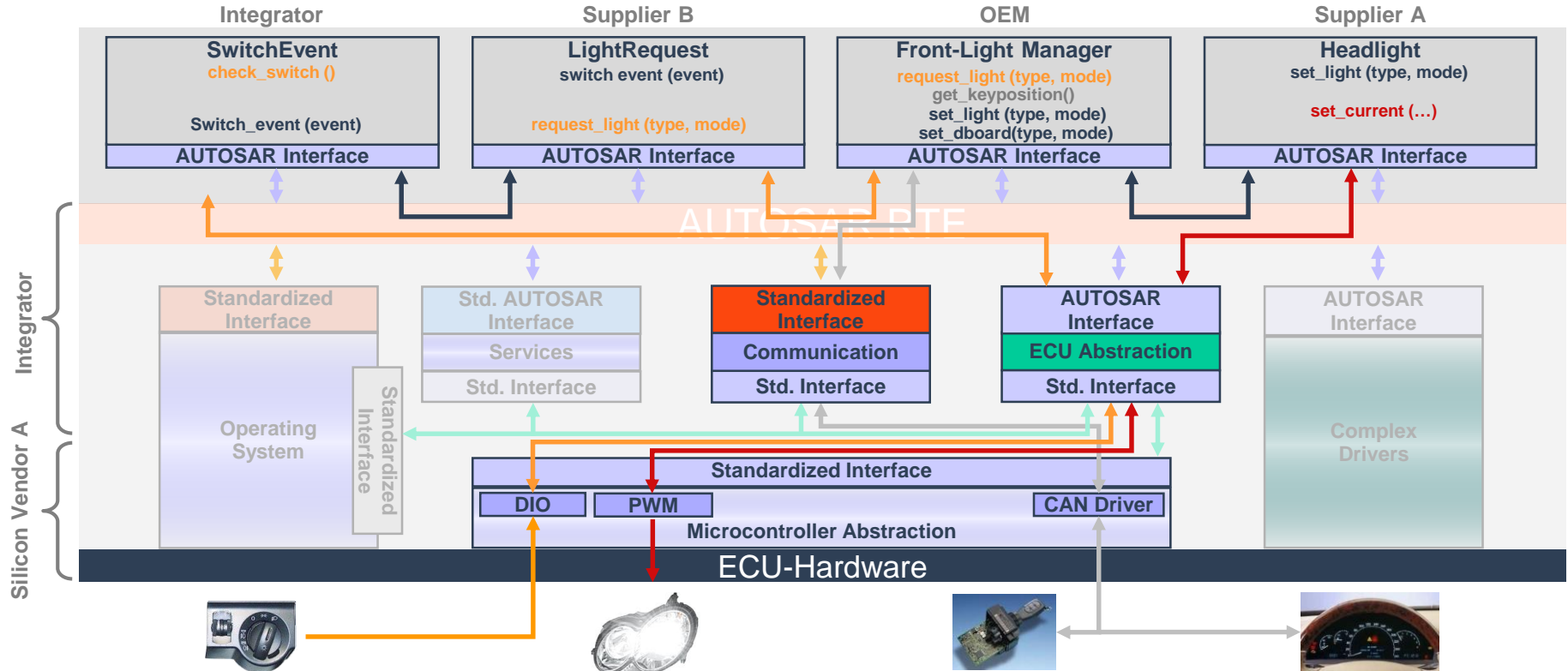


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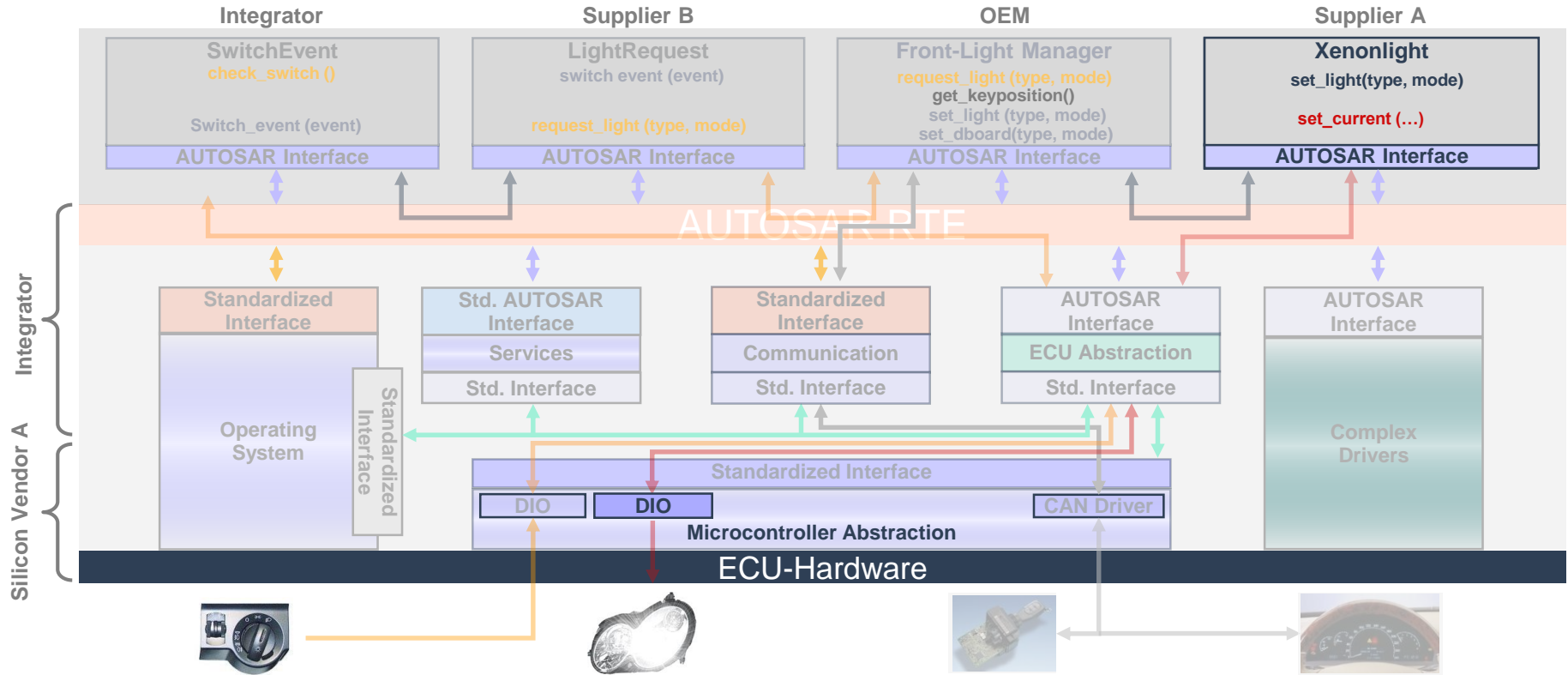
Software Architecture – AUTOSAR Defined Interfaces

Use Case ‘Front Light Management’: Exchange Type of Front Light



Software Architecture – AUTOSAR Defined Interfaces

Use Case ‘Front Light Management’: Exchange Type of Front Light



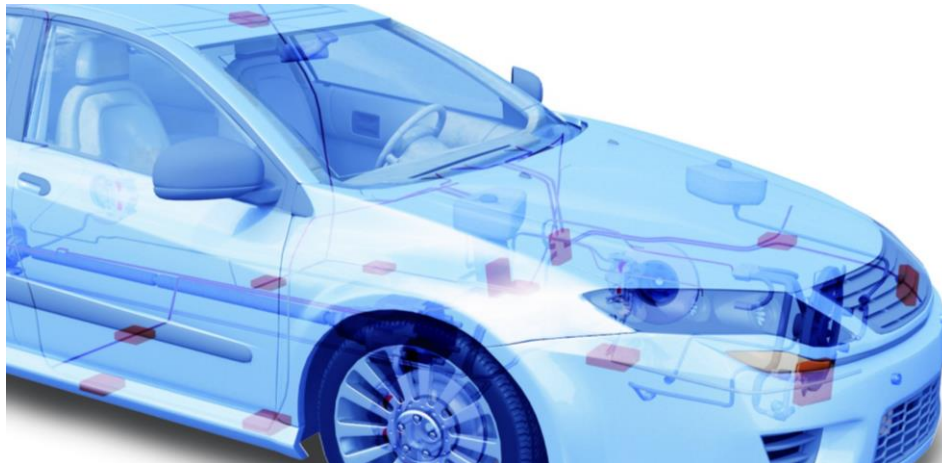
Distribution ECUs

SwitchEvent
switch_event (event)
AUTOSAR Int.

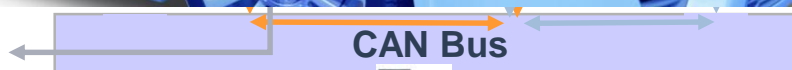
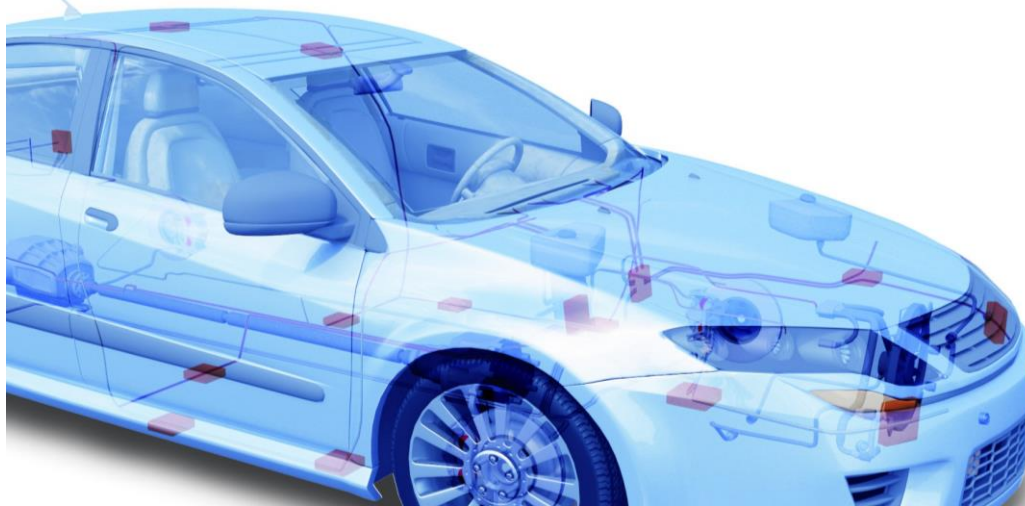
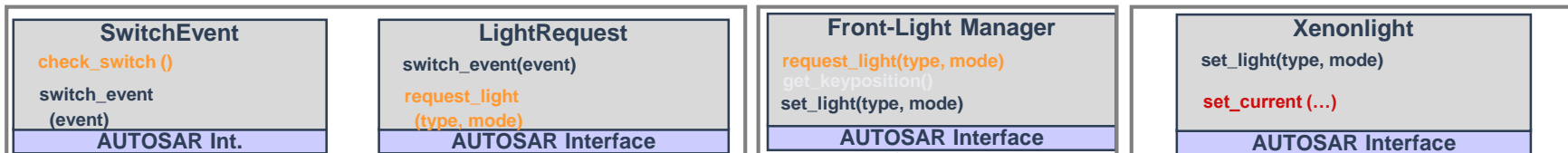
LightRequest
switch_event(event) request_light (type, mode)
AUTOSAR Interface

Front-Light Manager
request_light(type, mode) set_light(type, mode)
AUTOSAR Interface

Xenonlight
set_light(type, mode) set_current (...)
AUTOSAR Interface

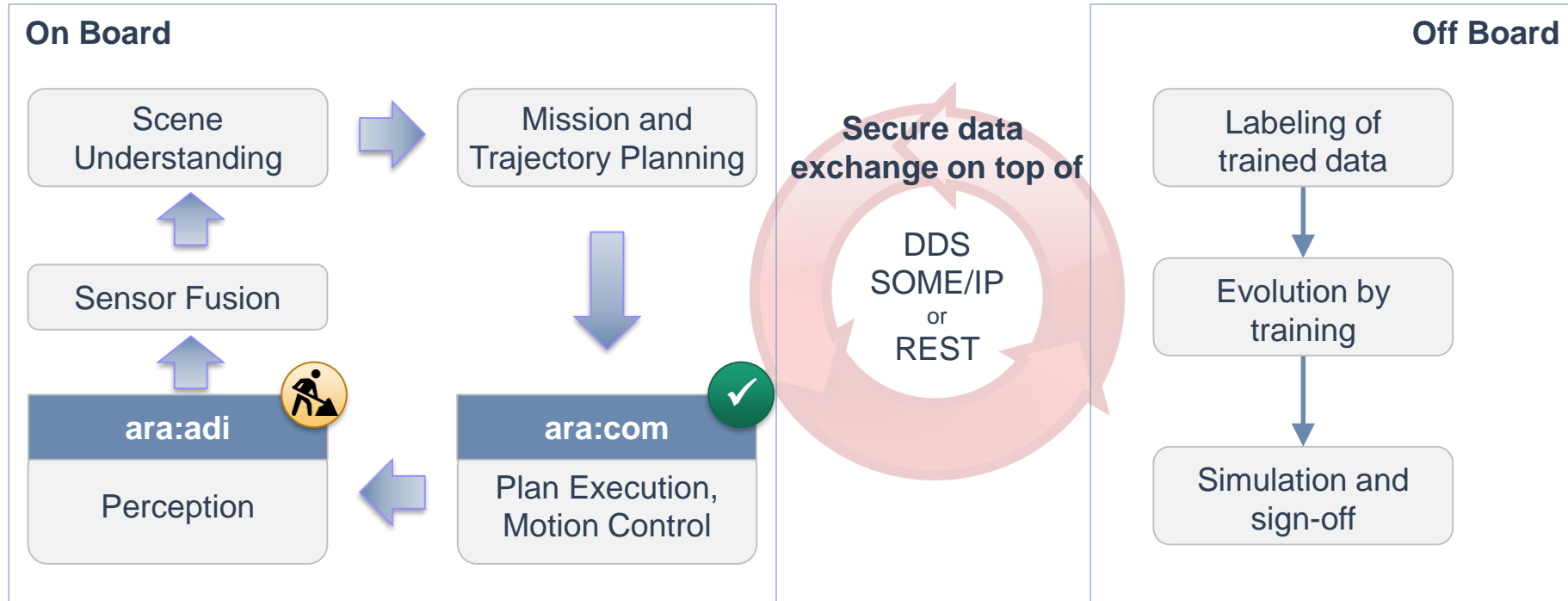


Distribution on ECUs – ‘Front-Light Management’

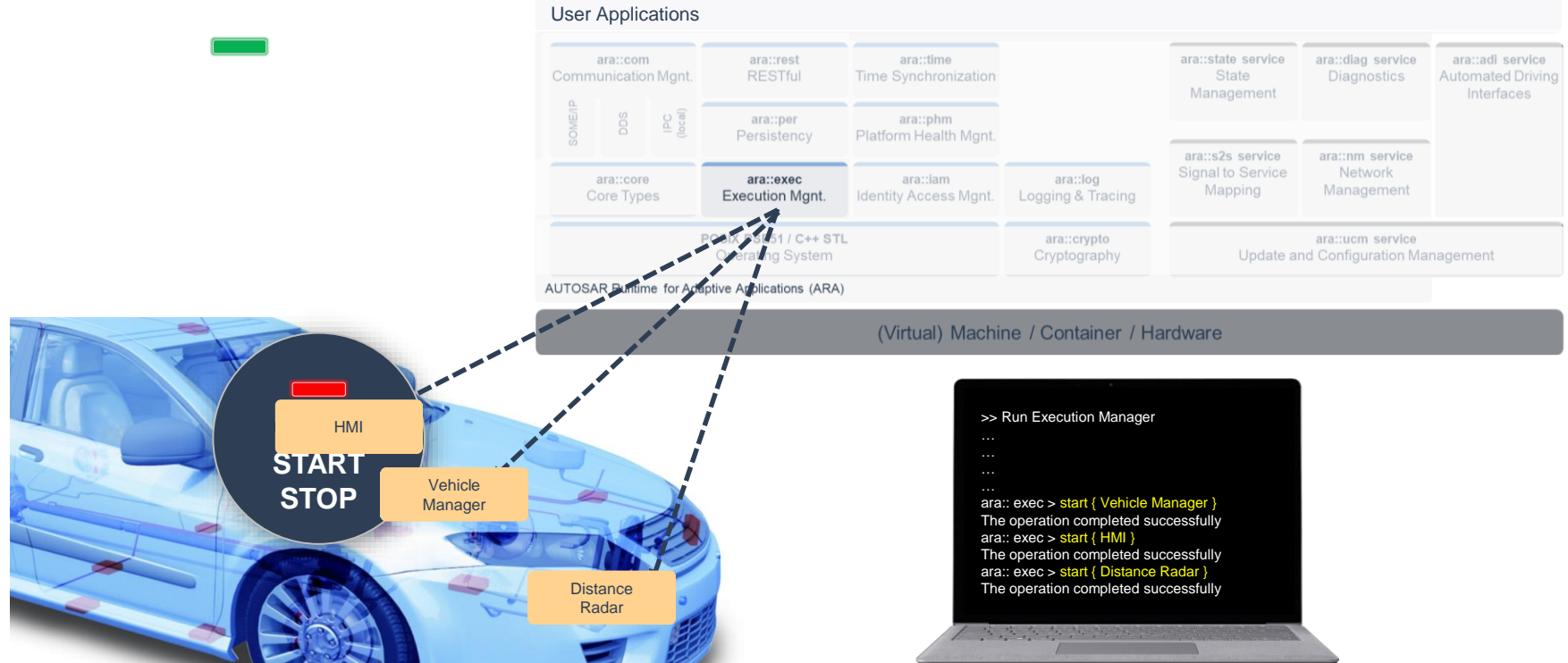


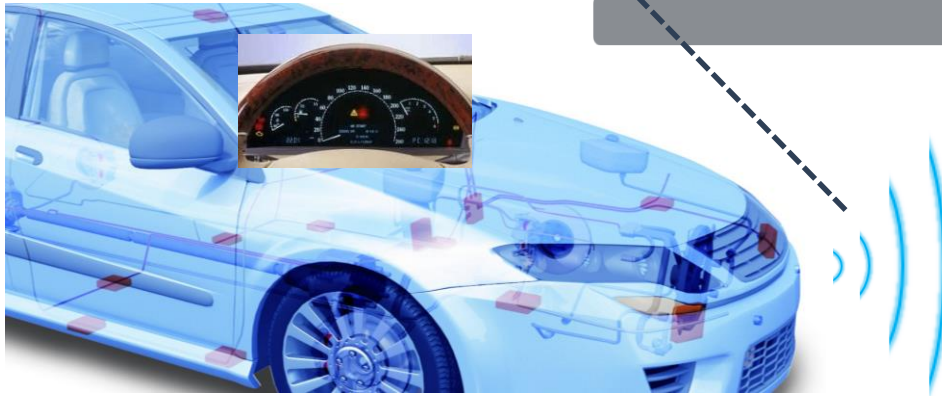
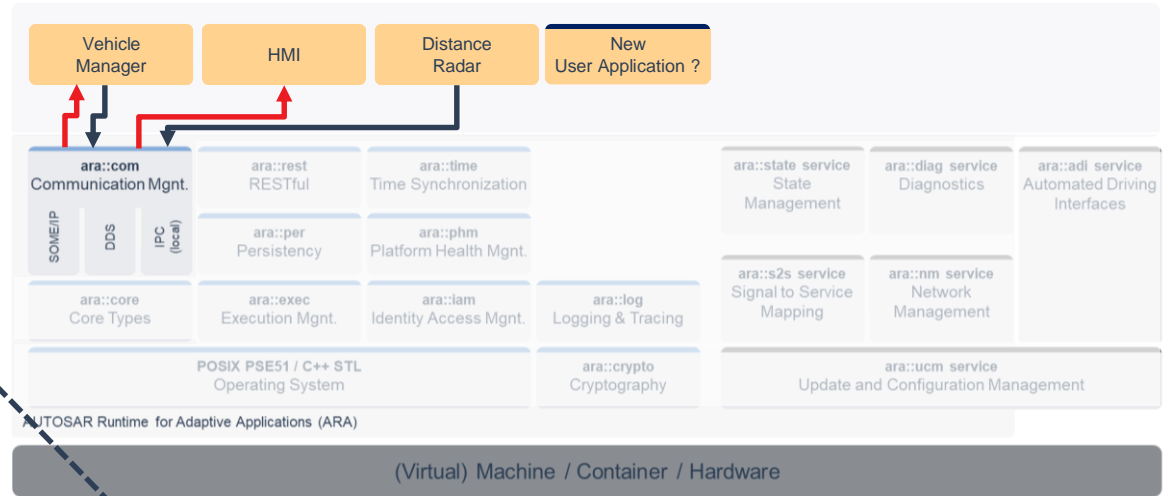
AUTOSAR Platform Application

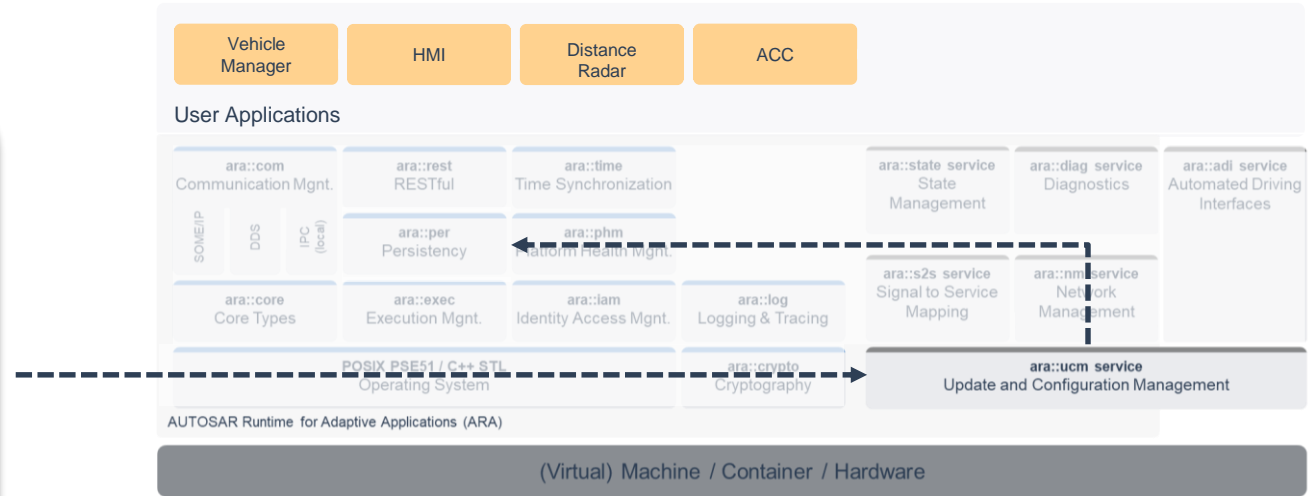
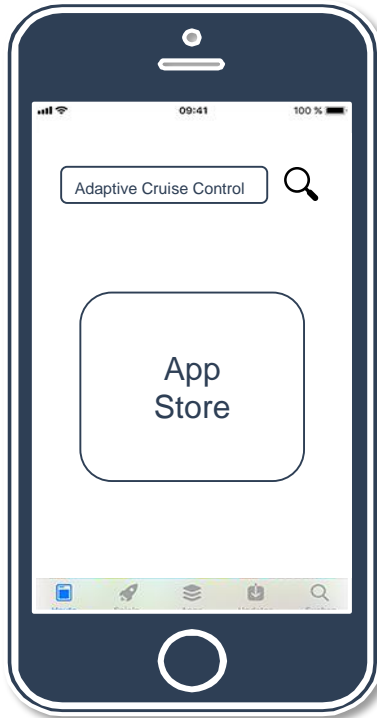
Continuous improvement cycle for ADAS systems

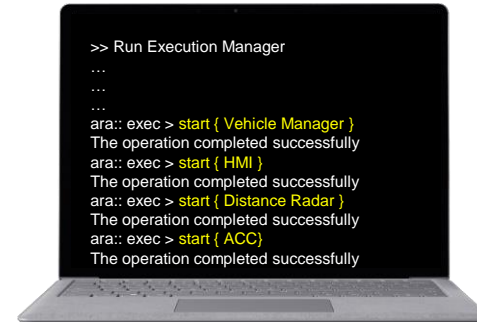
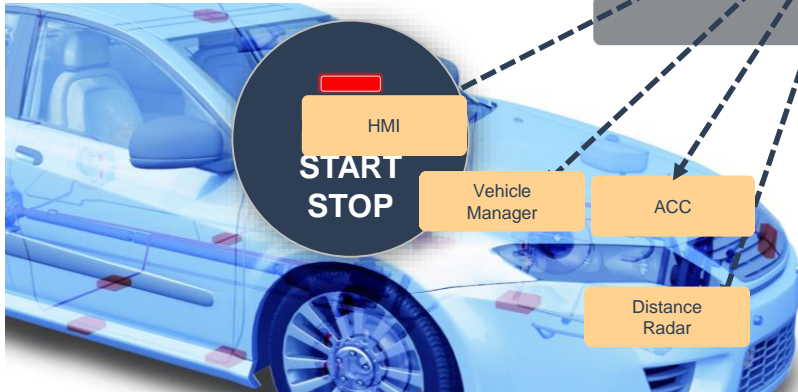
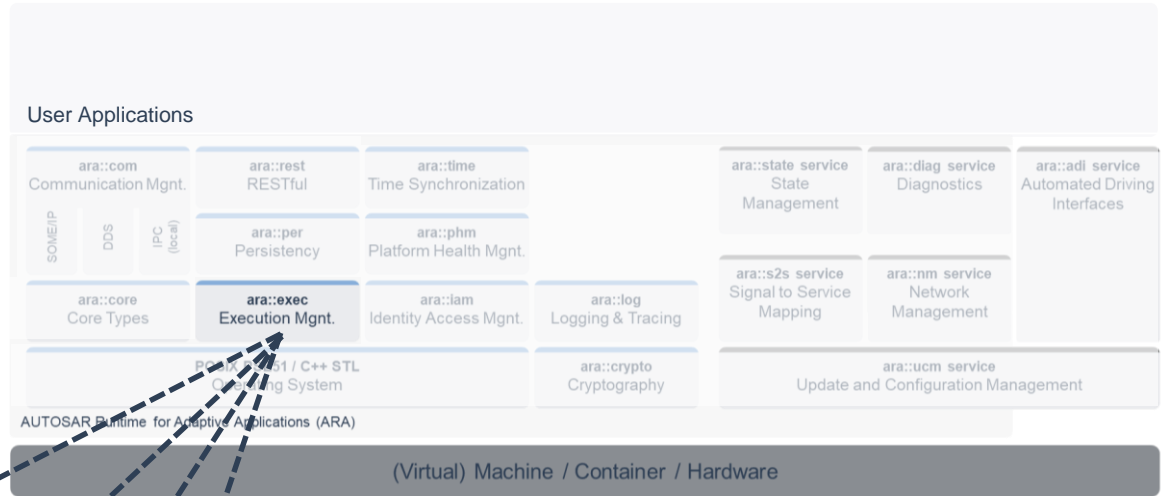


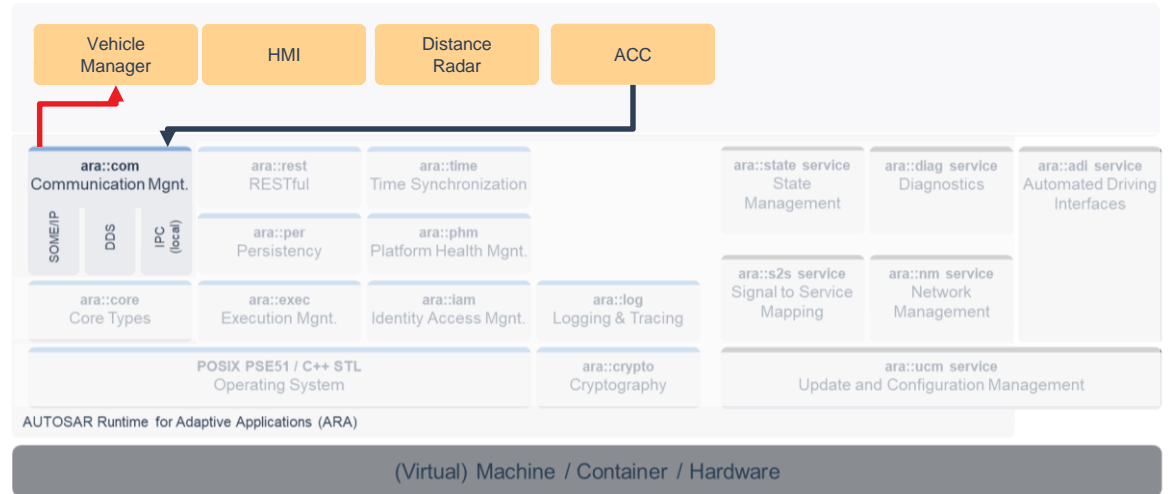
AUTOSAR Platform Application

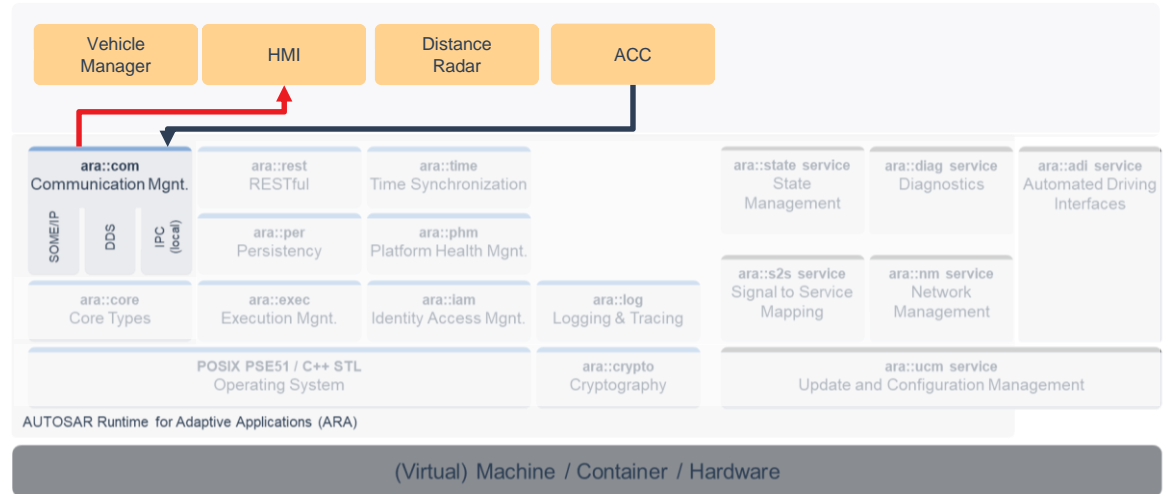


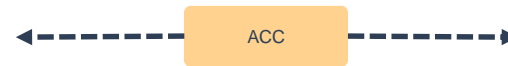
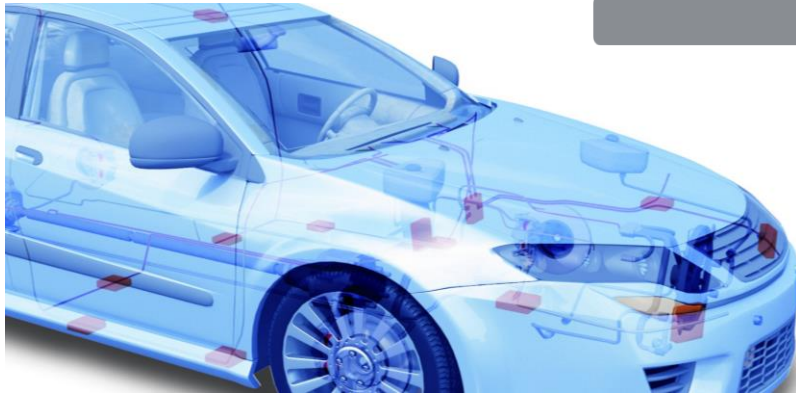
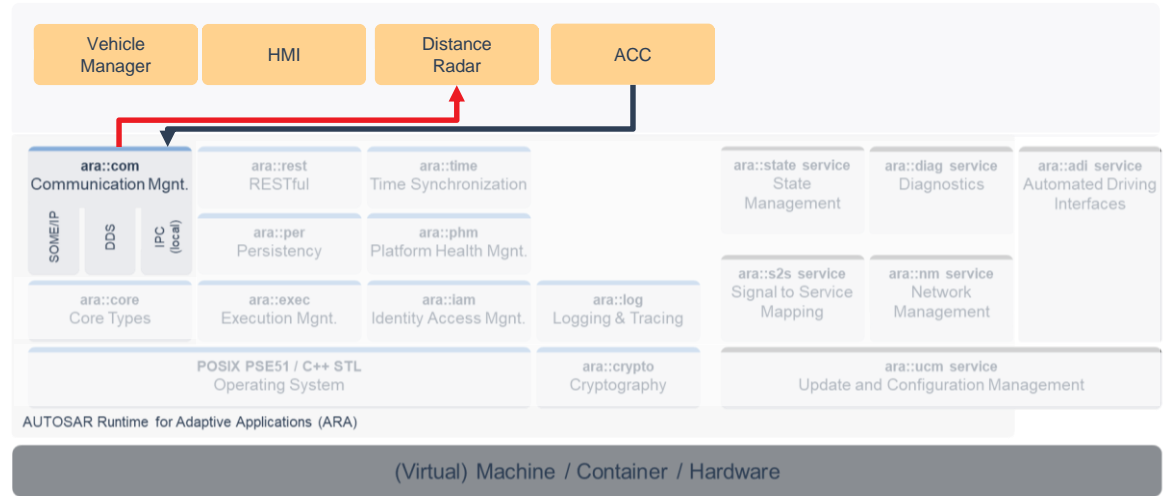












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AUTOSAR Adaptive Platform development approach

Specification

Identify needs & use-cases:

- 1) Concepts
- 2) Features
- 3) Requirements



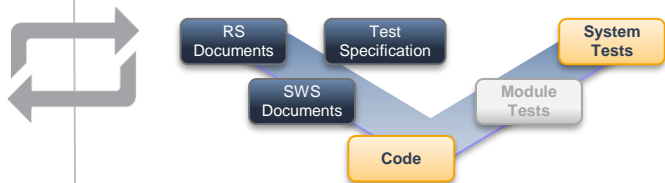
Quality:

- TF-ARC approval
- Cross team review
- Lifecycle :
preliminary → draft → valid

Implementation

Gain speed:

- 1) Spec validation
- 2) Reduce room for spec interpretation
- 3) Training / dissemination of AP



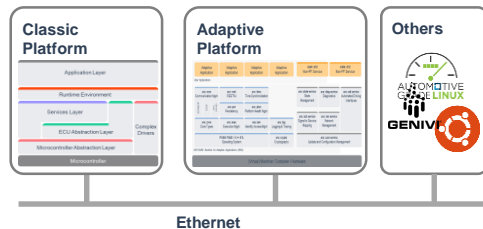
Attracting environment for coders:

- Appealing technology (C++, Yocto, Git, ...)
- Modern use case (ADAS EBA)
- Handy documentation (Wiki)
- Peer programming sessions

Demonstration

Gain trust:

- 1) Advertises the progress
- 2) Highlights some specific features



Show AUTOSAR interoperability

- of classic and adaptive platforms
- but also with others

Best tradeoff between commercial cooperation & compatibility between different vendors

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Timeline to full automation

AUTOSAR – a faithful ADAS companion

