1

EECS 16A Designing Information Devices and Systems I Discussion 2C

1. Steady and Unsteady States

(a) You're given the matrix M:

$$\mathbf{M} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{bmatrix}$$

Which generates the next state of a physical system from its previous state: $\vec{x}[k+1] = \mathbf{M}\vec{x}[k]$. (\vec{x} could describe either people or water.) Find the eigenspaces associated with the following eigenvalues:

- i. span(\vec{v}_1), associated with $\lambda_1 = 1$
- ii. span(\vec{v}_2), associated with $\lambda_2 = 2$
- iii. span(\vec{v}_3), associated with $\lambda_3 = \frac{1}{2}$

Answer:

i. $\lambda = 1$:

$$\begin{bmatrix} \mathbf{M} - \mathbf{I} & \vec{0} \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\vec{v}_1 = \alpha \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \alpha \in \mathbb{R}$$

ii.
$$\lambda = 2$$

$$\begin{bmatrix} \mathbf{M} - 2\mathbf{I} & \vec{0} \end{bmatrix} = \begin{bmatrix} \frac{-3}{2} & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -3 & 0 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\vec{v}_2 = \beta \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}, \beta \in \mathbb{R}$$

iii.
$$\lambda = \frac{1}{2}$$

$$\begin{bmatrix} \mathbf{M} - \frac{1}{2}\mathbf{I} & \vec{0} \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & \frac{1}{2} & -2 & 0 \\ 0 & 0 & \frac{3}{2} & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$
$$\vec{v}_3 = \gamma \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \gamma \in \mathbb{R}$$

(b) Define $\vec{x} = \alpha \vec{v}_1 + \beta \vec{v}_2 + \gamma \vec{v}_3$, a linear combination of the eigenvectors. For each of the cases in the table, determine if

$$\lim_{n\to\infty}\mathbf{M}^n\vec{x}$$

converges. If it does, what does it converge to?

α	β	γ	Converges?	$\lim_{n\to\infty}\mathbf{M}^n\vec{x}$
0	0	$\neq 0$		
0	$\neq 0$	0		
0	$\neq 0$	$\neq 0$		
$\neq 0$	0	0		
$\neq 0$	0	$\neq 0$		
$\neq 0$	$\neq 0$	0		
$\neq 0$	$\neq 0$	$\neq 0$		

Answer:

$$\mathbf{M}^{n}\vec{x} = \mathbf{M}^{n}(\alpha\vec{v}_{1} + \beta\vec{v}_{2} + \gamma\vec{v}_{3})$$

$$= \alpha\mathbf{M}^{n}\vec{v}_{1} + \beta\mathbf{M}^{n}\vec{v}_{2} + \gamma\mathbf{M}^{n}\vec{v}_{3}$$

$$= 1^{n}\alpha\vec{v}_{1} + 2^{n}\beta\vec{v}_{2} + \left(\frac{1}{2}\right)^{n}\gamma\vec{v}_{3}$$

α	β	γ	Converges?	$\lim_{n\to\infty}\mathbf{M}^n\vec{x}$
0	0	$\neq 0$	Yes	$\vec{0}$
0	$\neq 0$	0	No	-
0	$\neq 0$	$\neq 0$	No	-
$\neq 0$	0	0	Yes	$\alpha \vec{v}_1$
$\neq 0$	0	$\neq 0$	Yes	$\alpha \vec{v}_1$
$\neq 0$	$\neq 0$	0	No	-
$\neq 0$	$\neq 0$	$\neq 0$	No	-

2. Polynomials as a Vector Space

Let \mathbb{P}_2 be the set of polynomials of degree of at most two (that is, $p(t) = at^2 + bt + c$).

(a) Give a basis for \mathbb{P}_2 .

Answer:

The standard basis would be $\{t^2, t, 1\}$, but any three linearly independent quadratics, where {constant, linear, quadratic} terms all appear at least once, is acceptable.

(b) Consider the linear transformations

$$T_1(f(t)) = 2f(t)$$

$$T_2(f(t)) = f'(t)$$

For each, find the transformation matrix with respect to the basis from part (a).

Answer:

Using the ordered standard basis $\{t^2, t, 1\}$,

$$\mathbf{A}_1 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$\mathbf{A}_2 = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

(c) Suppose that $\{x_0, x_1, x_2\}$ form a basis for \mathbb{P}_2 and that the following polynomials have the corresponding coordinates in this basis.

$$(1,1,1) \Rightarrow 2t^2 + 3t$$
$$(1,0,-1) \Rightarrow t+1$$
$$(0,2,0) \Rightarrow 4t+2$$

Find the basis vectors x_0, x_1, x_2 .

Answer:

Solving the system of equations:

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & -1 \\ 0 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2t^2 + 3t \\ t+1 \\ 4t+2 \end{bmatrix}$$

yields the solution:

$$x_0 = t^2 + t, x_1 = 2t + 1, x_2 = t^2 - 1$$