

## Resample

**Resample [flags] waveName [, waveName]...**

The Resample operation resamples *waveName* by interpolating or up-sampling (set by /UP=*upSample*), lowpass filtering, and decimating or down-sampling (set by /DOWN=*downSample*).

Lowpass filtering is specified with /N and /WINF or with /COEF=*coefsWaveName*.

The sampling frequency (1/DimDelta) of a resampled output wave *waveName* is changed by the ratio of *upSample/downSample*. For example, if *upSample*=4 and *downSample*=3, then the final sampling rate is 4/3 of the original value.

Straight interpolation can be accomplished by setting *upSample* to the interpolation factor and *downSample*=1, in which case the sample rate is multiplied by *upSample*. Deltax(*waveName*) will be proportionally smaller. Linear interpolation is accomplished by setting *numReconstructionSamples*=3 and *windowKind*=None.

For decimation only, set *upSample*=1 and *downSample* to the decimation factor. The sample rate is divided by *downSample*, and deltax(*waveName*) will be proportionally larger.

Use **RatioFromNumber** to choose appropriate values for *upSample* and *downSample*, or use /SAME=*sWaveName* or /RATE=*sampRate*. See **Resampling Rates Example** for details.

When using /COEF=*coefsWaveName*, the filter coefficients should implement a low-pass filter appropriate for the *upSample* and *downSample* values or aliasing (filtering errors) will result. See **Advanced Externally-Supplied Low Pass Filter Example** for details.

### Resampling Rates Flags

The *upSample* and *downSample* values define how much interpolation and decimation to perform. They can be set directly with /UP and /DOWN or indirectly with /SAME or /RATE

/DOWN=*downSample* Down-samples or decimates the filtered result by this integer factor after up-sampling and lowpass filtering. The default is 1 (no down-sampling).

For example, /DOWN=3 places only every third value in the output wave.

Down-sampling divides the sampling rate of the filtered data by a factor of *downSample*. The DimDelta(*waveName, dim*) value is multiplied by the same factor.

/RATE=*sampRate* Converts the output *waveName* to the specified sampling rate frequency (normally Hz).

The necessary *upSample* and *downSample* values for each *waveName* are computed internally as if you had executed:

```
RatioFromNumber (deltax (waveName) * sampRate)
upSample = V_numerator
downSample = V_denominator
```

/RATE returns V\_numerator and V\_denominator set to these automatically-determined values for the last *waveName*.

/SAME=*sWaveName*

Converts the output *waveName* to the same sampling rate as *sWaveName*, 1/DimDelta(*sWaveName, dim*). The necessary *upSample* and *downSample* values are computed internally as if you had executed:

```
Variable dd = DimDelta (waveName, dim)
RatioFromNumber dd/DimDelta (sWaveName, dim)
upSample = V_numerator
downSample = V_denominator
```

/SAME returns V\_numerator and V\_denominator set to these automatically-determined values for the last *waveName*.

## Resample

/UP= <i>upSample</i>	Up-samples or interpolates the input by this integer factor. The default is 1 (no up-sampling). For example, /UP=4 inserts three extra points between each input point (producing 4 times as many values) before the lowpass filtering and down-sampling occurs. Up-sampling multiplies the sampling rate of the input data by a factor of <i>upSample</i> , though no additional signal information is created. The DimDelta( <i>waveName</i> , <i>dim</i> ) value is divided by the same factor.
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### Internal Sinc Reconstruction Filter Flags

If /COEF=*coefsWaveName* is not specified, Resample computes a windowed sinc filter from /N, /DOWN, /UP, and /WINF flag values.

If /COEF=*coefsWaveName* is specified, then *coefsWaveName* supplies the filter, and /N and /WINF are ignored. See **Externally-Supplied Low Pass Filter Flags**.

/COEF	Replaces the first <i>waveName</i> with coefficients generated by <i>downSample</i> , <i>upSample</i> , <i>numReconstructionSamples</i> , and <i>windowKind</i> , a windowed sinc impulse response. When resampling multiple <i>waveNames</i> with different filters (because /RATE or /SAME were specified and the multiple <i>waveNames</i> had different sampling rates), the filter used to resample the last <i>waveName</i> is returned.
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### /N=*numReconstructionSamples*

Specifies the number of input values used to created the up-sampled values (default is 21).  
The value of *numReconstructionSamples* must be odd.

The size of the computed filter is (*numReconstructionSamples*-1) \* *upSample* + 1.

Bigger is better: 15 is usually on the low side for yielding reasonably accurate results, and although 101 will nearly always give very good results, it will be slow.

Use /COEF to output the impulse response, and the FFT to display the frequency response of the interpolator:

```
Make/O coefs  
Variable numReconstructionSamples= 51, upSample= 5  
Resample/COEF/N= (numReconstructionSamples) /UP=(upSample) coefs  
Variable evenNum= 2*floor( (numpnts(coefs)+1) /2)  
FFT/OUT=3/PAD={evenNum} /DEST=coefs_FFT coefs  
Display coefs_FFT
```

Bigger is also slower: the filtering is computed in the time-domain, and execution time is linearly related to

*upSample/downSample* \* *numReconstructionSamples*.

### /WINF=*windowKind*

Applies the window, *windowKind*, to the computed filter coefficients. If /WINF is omitted, the Hanning window is used. For no coefficient windowing, use /WINF=None, though this is discouraged unless you want linear interpolation, in which case it should be paired with /N=3.

Windows alter the frequency response of the filter in obvious and subtle ways, enhancing the stop-band rejection or steepening the transition region between passed and rejected frequencies. They matter less when *numReconstructionSamples* is large.

Choices for *windowKind* are:

Bartlett, Blackman367, Blackman361, Blackman492, Blackman474, Cos1, Cos2, Cos3, Cos4, Hamming, Hanning, KaiserBessel20, KaiserBessel25, KaiserBessel30, Parzen, Poisson2, Poisson3, Poisson4, Riemann and None.

See **FFT** for window equations and details.

**Externally-Supplied Low Pass Filter Flags****/COEF=coefsWaveName**

Identifies the wave, *coefsWaveName*, containing filter coefficients that implement a low-pass filter with a cutoff frequency of the lesser of  $0.5/upSample$  and  $0.5/downSample$ , where 0.5 corresponds to the Nyquist frequency of the up-sampled data.

For example, if *upSample*=2, then the filter must contain the classic “half-band” filter, which stops the higher half of the frequencies and passes the lower half. If *upSample*=10, then the filter must pass only the lowest 1/10th of the frequencies.

For *downSample > upSample*, the low-pass filter’s cutoff frequency must be  $0.5/downSample$ . This prevents the decimation from introducing aliasing to the resampled data.

To avoid shifting the output with respect to the input, *coefsWaveName* must have an odd length with the “center” coefficient in the middle of the wave.

The length of *coefsWaveName* must be  $1+upSample*n$ , where *n* is any even integer.

**Note:** Instead of using /N=*numReconstructionSamples* with /COEF=*coefsWaveName*, *numReconstructionSamples* is computed from *upSample* and the number of points in *coefsWaveName*:

*numReconstructionSamples*= $1+(\text{numptns}(\text{coefsWaveName})-1)/upSample$ .

Coefficients are usually symmetrical about the middle point, but this is not enforced.

*coefsWaveName* must not be a destination *waveName*.

*coefsWaveName* must be single- or double-precision numeric and one-dimensional.

**Data Range Flags****/DIM=d**

Specifies the wave dimension to resample.

For *d*=0, 1, ..., resampling is along rows, columns, etc.

The default is /DIM=0, which resamples each individual column (each one a channel, say left and right) in a multidimensional *waveName* where each row comprises all sound samples at a particular time.

To resample in multiple dimensions, execute the command once for each dimension. For example, use /DIM=0 followed by another command with /DIM=1 to resample a two-dimensional wave in each direction.

**E=endEffect**

Determines how to handle the ends of the resampled wave(s) (*w*) when fabricating missing neighbor values.

*endEffect*=0: Bounce method. Uses *w[i]* in place of the missing *w[-i]* and *w[n-i]* in place of the missing *w[n+i]*.

*endEffect*=1: Wrap method. Uses *w[n-i]* in place of the missing *w[-i]* and vice versa.

*endEffect*=2: Zero method (default). Uses 0 for any missing value.

*endEffect*=3: Repeat method. Uses *w[0]* in place of the missing *w[-i]* and *w[n]* in place of the missing *w[n+i]*.

**Parameters**

*waveName* can be a wave with any number of dimensions. Only one dimension is resampled. Use multiple Resample calls to resample across multiple dimensions.

Without /DIM, resampling is done along the row (first) dimension for each column. That is, each column is resampled as if it were a separate one-dimensional wave. This allows multichannel audio to be resampled to another frequency.

If /DIM=1, then resampling proceeds across all the columns of each row.

## Resample

If /COEF is specified without *coefsWaveName*, then the first *waveName* is overwritten by the filter coefficients instead of being resampled.

### Details

The filtering convolution is performed in the time-domain. That is, the FFT is not employed to filter the data. For this reason the coefficients length (/N or the length of *coefsWaveName*) should be small in comparison to the resampled waves.

Resample should not be used on data that contains NaNs; use **Smooth/M=NaN** to replace NaN values with a local median, or use **MatrixOp zapNaNs** to remove them.

Resample assumes that the middle point of *coefsWaveName* corresponds to the delay=0 point. The “middle” point number = trunc((numpnts(*coefsWaveName*)-1)/2). *coefsWaveName* usually contains the two-sided impulse response of a filter, an odd number of points, and implements a low-pass filter whose cutoff frequency is the lesser of 0.5/*upSample* and 0.5/*downSample* (0.5 corresponds to the Nyquist frequency = 1/2 sampling frequency).

When /COEF creates a coefficients wave it sets the wave’s X scaling *deltax* property to the *deltax* of the input wave multiplied by the /DOWN factor and divided by the /UP factor. It also sets the *x0* property so that the zero-phase (center) coefficient is located at *x=0*.

### Simple Examples

```
// Interpolation by factor of 4, default filter  
Resample/UP=4 data  
  
// Interpolation by factor of 7, linear interpolation  
Resample/UP=7/N=3/WINF=None data  
  
// Decimation by factor of 3, default filter  
Resample/DOWN=3 data  
  
// Match sampling rates, default filter  
Resample/SAME=dataAtDesiredRate dataAtWrongRate1, dataAtWrongRate2,...  
  
// Resample waves to 10 KHz sampling rate  
Resample/RATE=10e3 dataAtWrongRate1, dataAtWrongRate2,...  
  
// Interpolate an image by a factor of 2  
Resample/UP=2 image           // default is /DIM=0, resample rows  
Resample/UP=2/DIM=1 image      // resample across columns
```

**Note:** Interpolating by a factor of two does not produce an image with twice as many rows and columns. The new number of rows = (original rows-1)\**upSample* +1, and a similar computation applies to columns.

### Resampling Rates Example

Suppose we have an audio wave sampled at 44,100 Hz and we wish to resample it to a higher 192,000 Hz frequency.

We can use /RATE= 192000 and let Resample determine the correct values (provided *waveName* has its X scaling set properly to reflect sampling at 44100 Hz), but let’s compute *upSample* and *downSample* ourselves.

Because the sampling rate = 1/*deltax(wave)*, we can recast the /SAME formula to RatioFromNumber (*desiredSamplingRate/currentSamplingRate*):

- RatioFromNumber/V (192000 / 44100)  
V\_numerator= 640; V\_denominator= 147;  
ratio= 4.3537414965986;  
V\_difference= 0;

Then *upSample*=640 and *downSample*=147.

The 44100 Hz input data will be interpolated by 640 to 28,224,000 Hz.

The result is low-pass filtered with a “cutoff frequency” of 1/640th of the interpolated Nyquist frequency = (28224000/2)/640 = 22,050 Hz, the same as the input signal’s original Nyquist frequency.

The result will be decimated by 147 to 192,000 Hz, which is the desired output sampling frequency.

**Note:** If *downSample* had been greater than *upSample*, then the low-pass filter's cutoff frequency would have been  $1/\text{downSample}$ th of the interpolated Nyquist frequency =  $(28224000/2)/\text{downSample}$ . This prevents the decimation from introducing aliasing to the resampled data.

```
Resample/UP=640/DOWN=147 sound           // convert 44.1 KHz to 192 KHz
```

### Advanced Externally-Supplied Low Pass Filter Example

You can generate an appropriate filter by executing commands like these:

```
// Compute a filter for after the input is upsampled
// to restore the frequency content to the original range.
Variable fc = min(0.5 / upSample, 0.5 * upSample / downSample)
// Transition width, small widths need big n
Variable tw= fc/10
// Set end of pass band
Variable f1= fc-tw/2
// Set start of stop band
Variable f2= fc+tw/2
// Use bigger values of n to make the filter smoother
Variable nReconstruct= 31
Variable n= (nReconstruct-1)*upSample+1           // odd = no phase shift
// Create a wave to hold the coefficients; it gets resized to n
Make/O/N=0 coefsWaveName
FilterFIR/COEF/LO={f1,f2,n} coefsWaveName
```

However, FilterFIR does not create windowed sinc lowpass filters that have the endearing property that the original input values are unaltered in the filtered output, though only if *upSample* > *downSample*. This is called a "Nyquist filter" or "Kth-band filter" in the literature.

If *upSample* > *downSample*, you can enforce the Nyquist criterion by "zeroizing" the designed filter by setting every *upSample*th value to 0 except the center one.

```
// coefsWaveName length must be 1+upSample*n, where n is any even integer
Function Zeroize(w, upSample)
    Wave w                      // coefsWaveName
    Variable upSample             // upSample value

    Variable n= DimSize(w,0)
    Variable centerP= floor((n-1)/2)          // if n=101, centerP= 50
    Variable i
    for (i=0; i<n; i+=upSample)
        if( i != centerP )
            w[i] = 0
        endif
    endfor
End
```

Resample zeroizes the internally-generated low pass filter when *upSample* > *downSample*.

Additionally, the FilterFIR command generates a low-pass filter whose gain needs to be multiplied by *upsample*:

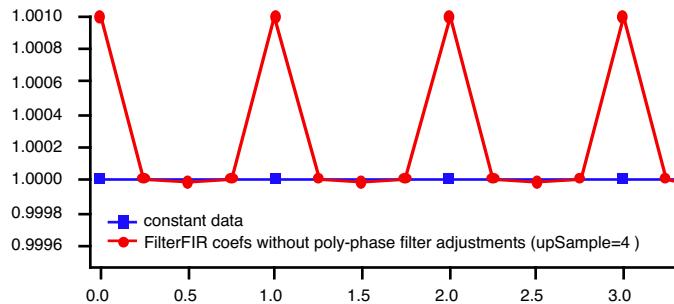
```
coefsWaveName *= upSample
```

When designing an externally supplied filter, you should also consider the filter's "polyphase" nature; *coefsWaveName* is actually a set of *upSample* interleaved filters, each with its own response. It makes sense to adjust these filters to produce consistent responses. If you don't, the results will contain ringing with a period of *upSample*/*downSample*. This is most apparent when *downSample* is 1.

Using the filter we've designed so far with *upSample*=4, here's the output of a constant-input wave:

```
Make/O constantData= 1
Resample/COEF=coefsWaveName/UP=4 constantData
```

## Resample

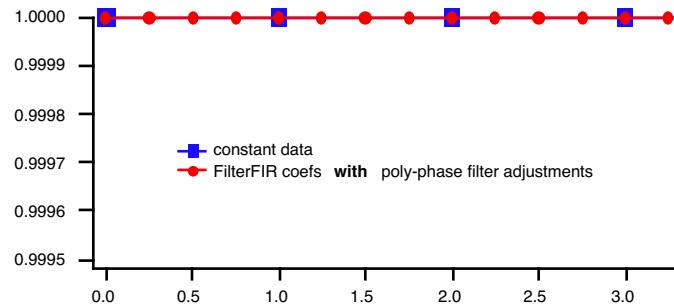


The graph shows that the filter response at 0 Hz for the first of 4 filters is 1.0010, the second and fourth filter's responses are very close to 1.0, and the third filter's response at 0 Hz is a little less than 1.0.

These variations can be eliminated by normalizing the sum of each polyphase filter to 1.0:

```
Function PolyphaseNormalize(w, upSample)
    Wave w                                // coefsWaveName
    Variable upSample                      // upSample value

    Variable n= DimSize(w,0)
    Variable filt
    // for each filter (0..upSample-1)
    for (filt=0; filt<upSample; filt+=1)
        Variable total=0
        Variable pt
        // compute total for this filter
        for (pt=filt; pt<n; pt+=upSample)
            total += w[pt]
        endfor
        // divide by total to normalize total to 1
        for (pt=filt; pt<n; pt+=upSample)
            w[pt] /= total
        endfor
    endfor
End
```



Now the filter is ready to be used to filter data:

```
Resample/COEF=coefsWaveName/UP=(upSample)/DOWN=(downSample) dataWave
```

You can see that designing an externally-supplied lowpass filter is much more complicated than using the internal sinc reconstruction filter, which does all this zeroizing, scaling, and polyphase normalization for you.

### References

Mintzer, F., On half-band, third-band, and Nth band FIR filters and their design, *IEEE Trans. on Acoust., Speech, Signal Process.*, ASSP-30, 734-738, 1982.

### See Also

[RatioFromNumber](#), [FilterFIR](#), [interp](#), [Interp2D](#), [Interpolate2](#), [ImageInterpolate](#), [Loess](#), [Smooth](#), [Multidimensional Decimation](#)