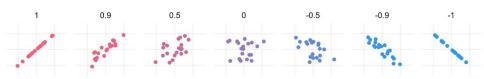
### COMS20017 - Algorithms & Data

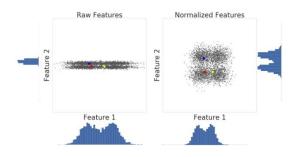


## September 2025 Majid Mirmehdi

with some slides from Rui Ponte Costa & Dima Damen

\*/tinystats@ithub.io/teacups-giraries-aird-statistics/U5\_cicrelation.html

### This lecture



- Data acquisition
- Data characteristics: distance measures
- Data characteristics: summary statistics
- > Data normalisation and outliers

### Mean and Variance

For one-dimensional data  $\mathbf{x} = \{x_1, ..., x_n\}$ ,

Mean: [average]

$$\mu = \frac{1}{N} \sum_{i} x_{i}$$

Variance: [spread]

$$\sigma^2 = \frac{1}{N-1} \sum_i (x_i - \mu)^2$$

Standard Deviation:

$$\sigma = \sqrt{\frac{1}{N-1} \sum_{i} (x_i - \mu)^2}$$

### Mean and Covariance

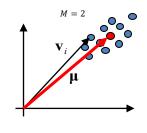
For multi-dimensional data:

e.g. M dimensions with  $\{v_1, ..., v_N\}$ , i.e there are N vectors/datapoints where each vector has M elements.



Computed independently for each dimension

$$\mu = \frac{1}{N} \sum_{i} \mathbf{v}_{i}$$



#### Covariance:

Gives spread and how variables change together

$$\mathbf{C} = \frac{1}{N-1} \sum_{i} (\mathbf{v}_i - \mathbf{\mu})^2$$

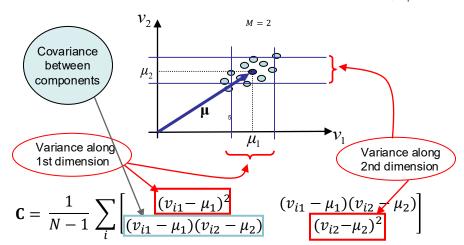
$$\mathbf{C} = \frac{1}{N-1} \sum_{i} (\mathbf{v}_{i} - \boldsymbol{\mu})^{\mathrm{T}} (\mathbf{v}_{i} - \boldsymbol{\mu})$$

$$\mathbf{C} = \frac{1}{N-1} \sum_{i} \begin{bmatrix} (v_{i1} - \mu_1)^2 & (v_{i1} - \mu_1)(v_{i2} - \mu_2) \\ (v_{i1} - \mu_1)(v_{i2} - \mu_2) & (v_{i2} - \mu_2)^2 \end{bmatrix}$$

*N* when the population mean is known, *N-1* when not!

### Mean and Covariance

$$\mu = \frac{1}{N} \sum_{i} \mathbf{v}_{i}$$

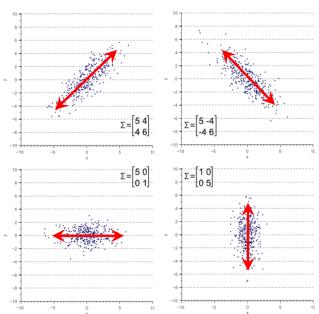


### **Covariance Matrix**

$$\mathbf{C} = \frac{1}{N} \sum_{i} \begin{bmatrix} (v_{i1} - \mu_1)^2 & (v_{i1} - \mu_1)(v_{i2} - \mu_2) \\ (v_{i1} - \mu_1)(v_{i2} - \mu_2) & (v_{i2} - \mu_2)^2 \end{bmatrix} \longrightarrow \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

## Spread and Covariance

- The shape of the data is defined by the covariance matrix.
- Diagonal spread is captured by the covariance, while axis-aligned spread is captured by the variance.



#### Covariance Matrix

In three dimensions,

$$\mathbf{C} = \frac{1}{N} \sum_{i} \begin{bmatrix} (v_{i1} - \mu_{1})^{2} & (v_{i1} - \mu_{1})(v_{i2} - \mu_{2}) & (v_{i1} - \mu_{1})(v_{i3} - \mu_{3}) \\ (v_{i1} - \mu_{1})(v_{i2} - \mu_{2}) & (v_{i2} - \mu_{2})^{2} & (v_{i2} - \mu_{2})(v_{i3} - \mu_{3}) \\ (v_{i1} - \mu_{1})(v_{i3} - \mu_{3}) & (v_{i2} - \mu_{2})(v_{i3} - \mu_{3}) & (v_{i3} - \mu_{3})^{2} \end{bmatrix}$$

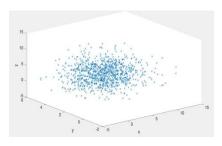
#### A Covariance matrix is always:

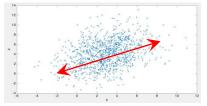
- square
- symmetric
- variances on the diagonal
- covariance between each pair of dimensions in non-diagonal elements

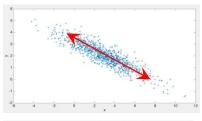
## Covariance Matrix example

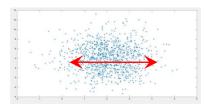
For the covariance matrix,

$$\mathbf{c} = \begin{bmatrix} 5 & -2 & 2 \\ -2 & 1 & 0 \\ 2 & 0 & 7 \end{bmatrix}$$









### Correlation

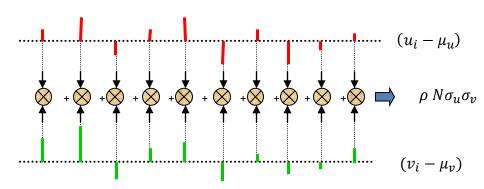
- We are often interested in the degree of similarity between two sequences in terms of their variation (independent of their absolute values)
- Correlation of two sequences u and v of length N

$$\rho = \frac{1}{N\sigma_u \sigma_v} \sum_{i=0}^{N-1} (u_i - \mu_u) (v_i - \mu_v)$$

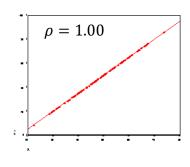
Division by variance product  $\sigma_u\sigma_v$  normalises measure to be independent of absolute value and is unitless  $\rightarrow$  captures similarity in variation (or *structure*).

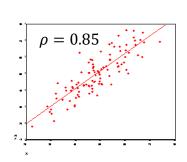
# Example: Correlating Coefficient for Two Sequences

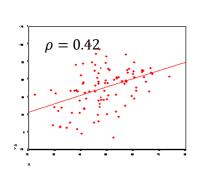
$$\rho = \frac{1}{N\sigma_u \sigma_v} \sum_{i=0}^{N-1} (u_i - \mu_u) (v_i - \mu_v)$$

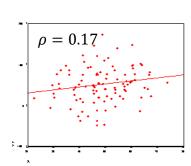


# **Correlation Example**









## Correlation – shifting similarity

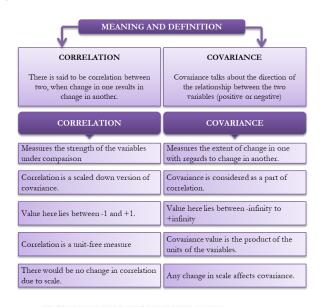
- Sometimes sequences are similar after applying a shift.
- Can be measured with cross-correlation

$$\rho = \frac{1}{N\sigma_u \sigma_v} \sum_{i=0}^{N-1} (u_i - \mu_u)(v_{i-j} - \mu_v)$$

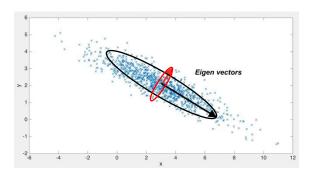


'most likely shift' given by position j of maximum value in cross-correlation

### Self Study: Correlation and Covariance



- Eigenvectors and eigenvalues define the principal axes and spread of points along directions
- Major axis eigenvector corresponding to larger eigenvalue (i.e. larger variance)
- Minor axis eigenvector corresponding to smaller eigenvalue (i.e. smaller variance)
- These can be represented using major and minor axes of ellipses



#### **Definition**

For a square matrix **C**, if there exists a non-zero column vector **v** where

$$\mathbf{C}v = \lambda v$$

then,

 $v \rightarrow \text{ eigenvector of matrix } C$  $\lambda \rightarrow \text{ eigenvalue of matrix } C$ 

e.g. 
$$\mathbf{C} = \begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix}$$
 ,  $v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ ,  $\lambda_1 = 1$ 

▶ To calculate eigenvectors of a square matrix, solve  $\mathbf{C}v = \lambda v$ 

$$\longrightarrow$$
  $|\mathbf{C} - \lambda \mathbf{I}| = 0$ 

where

- ► *I* is the identity matrix
- |C| is the determinant of the matrix

For 2  $\times$  2 matrices, there are two eigenvalues  $\lambda_1$ ,  $\lambda_2$ 

$$\mathbf{C} - \lambda \mathbf{I} = \begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} -\lambda & -1 \\ 2 & 3 - \lambda \end{bmatrix}$$

$$|\mathbf{C} - \lambda \mathbf{I}| = \lambda^2 - 3\lambda + 2 = (\lambda - 1)(\lambda - 2)$$

$$\lambda_1 = 1$$
 and  $\lambda_2 = 2$ 

After the eigenvalues are found, the eigenvectors can be calculated

For  $\lambda_1 = 1$ 

$$\begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} \tag{2}$$

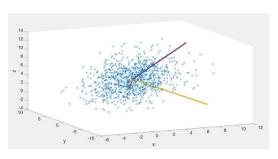
► This simplifies to:

▶ If we set  $v_{12} = 1$ , then we get the eigenvector:

$$\begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \tag{4}$$

▶ Verify that this is indeed a valid eigenvector by calculating  $\mathbf{C}v = \lambda v$ 

## 3D example



ightharpoonup Eigenvalues ightharpoonup  $\lambda_1 = 0.08$   $\lambda_2 = 4.52$   $\lambda_3 = 8.40$ 

$$\lambda_1 = 0.08$$

$$\lambda_2 = 4.52$$

$$\lambda_3 = 8.40$$

► Eigenvectors → 
$$v_1 = \begin{bmatrix} -0.42 \\ -0.90 \\ 0.12 \end{bmatrix}$$
  $v_2 = \begin{bmatrix} 0.71 \\ -0.40 \\ 0.57 \end{bmatrix}$   $v_3 = \begin{bmatrix} 0.57 \\ -0.15 \\ 0.01 \end{bmatrix}$ 

$$v_1 = \begin{bmatrix} -0.42 \\ -0.90 \\ 0.12 \end{bmatrix}$$

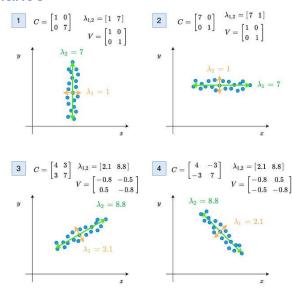
$$v_2 = \begin{bmatrix} 0.71 \\ -0.40 \\ -0.57 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 0.57 \\ -0.15 \\ 0.81 \end{bmatrix}$$

 $\triangleright$  Principal/Major axis is  $v_3$  (corresponding to the largest eigenvalue)

## Eigenvalue and Variance

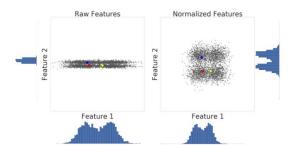
If the covariance matrix of the data is a diagonal matrix, i.e the covariances are zero, the variances are equal to the eigenvalues.



V = eigenvectors

 $\lambda = eigenvalues$ 

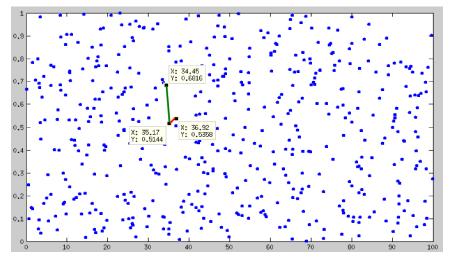
### **Next**



- Data acquisition
- > Data characteristics: distance measures
- Data characteristics: summary statistics
- > Data normalisation and outliers

### Data Characteristic - Data Normalisation

- Note the difference in magnitude between the two dimensions below!
- Data may need to be normalised before distance is calculated



### Data Characteristic - Data Normalisation

Methods for normalisation:

1. Rescaling 
$$x' = \frac{x - \min(x)}{\max(x) - \min(x)}$$

rescales the range of features to [0, 1]

2. Standardisation (also known as z-score)

$$x' = \frac{x - \mu}{\sigma}$$

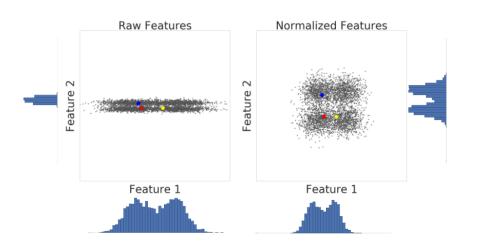
makes the values of each feature in the data have zero-mean and unit-variance

3. Scaling to unit length

$$x' = \frac{x}{\|\mathbf{x}\|}$$

scales components of feature vector so that the complete vector has length one

## Normalisation Example



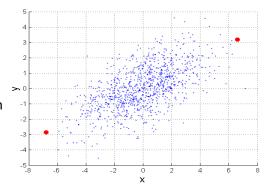
### Brief return to Distance Measures

**Mahalanobis Distance** is a measure of distance between a data vector and a set of data, or a variation that measures the distance between two vectors from the same dataset:

$$mahalanobis(a,b) = \sqrt{(a-b)^T (\Sigma)^{-1} (a-b)}$$
 where  $cov(X,Y) = (\Sigma) = \frac{1}{N-1} \sum_{i=1}^{N} (x_i - \bar{x})(y_i - \bar{y})$ 

Warning:  $\Sigma$  is the covariance matrix of the input data D

For red points, the Euclidean distance is 14.7, and the Mahalanobis distance is 6.



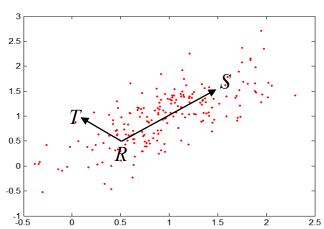
### Brief return to Distance Measures

#### Mahalanobis Distance example:

Given R = (0.5,0.5), S = (1.5,1.5), T = (0.0,1.0), find the Mahalanobis distance RS and RT.

$$\sum = \begin{bmatrix} 0.3 & 0.2 \\ 0.2 & 0.3 \end{bmatrix}$$

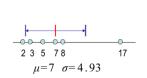
$$RS = 2$$
$$RT = \sqrt{5}$$

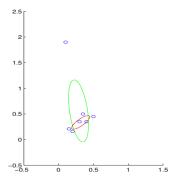


### **Data Characteristics - Outliers**

- Mean, variance and covariance can provide concise description of 'average' and 'spread', but not when outliers are present in the data
- outliers: An outlier is an observation that lies an abnormal distance from other values in a random sample from a population.
- usually due to fault in measurement and not always easy to remove



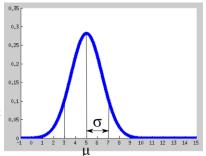




## Normal or Gaussian Distribution (Reminder)

For a normal distribution  $N(\mu, \sigma^2)$  in one dimension, the probability density function (pdf) can be calculated as:

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

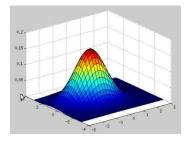


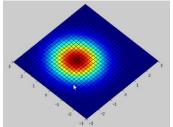
68% of data within  $1\sigma$  of  $\mu$  92% within  $2\sigma$  of  $\mu$  99% within  $3\sigma$  of  $\mu$ 

## Normal Distribution - Multi-dimensional (reminder)

For multi-dimensional normal distribution  $N(\mu, \Sigma)$ , the probability density function (pdf) can be calculated as

$$p(\mathbf{x}) = \frac{1}{2\pi \|\mathbf{\Sigma}\|^{1/2}} \exp(-\frac{1}{2}(\mathbf{x} - \mathbf{\mu})^T \mathbf{\Sigma}^{-1}(\mathbf{x} - \mathbf{\mu}))$$





**WARNING:**  $\Sigma$  here is the capital letter of  $\sigma$  and represents the covariance matrix. It is NOT the summation sign!

## Some of the topics next in COMS20017

- Least Squares and Regression
- Clustering data
- Classification of data
- The Fourier transform
- Principal Components Analysis
- Convolutions