

NB learned Parameters θ (mean) and σ (variance)

```
[67]: X_train_val.columns
```

```
[67]: Index(['area', 'perimeter', 'length_kernel', 'width_kernel',  
        'length_of_kernel_groove'],  
        dtype='object')
```

```
[68]: # mean ['area', 'perimeter', 'length_kernel', 'width_kernel', 'length_of_kernel_groove']  
gnb.theta_
```

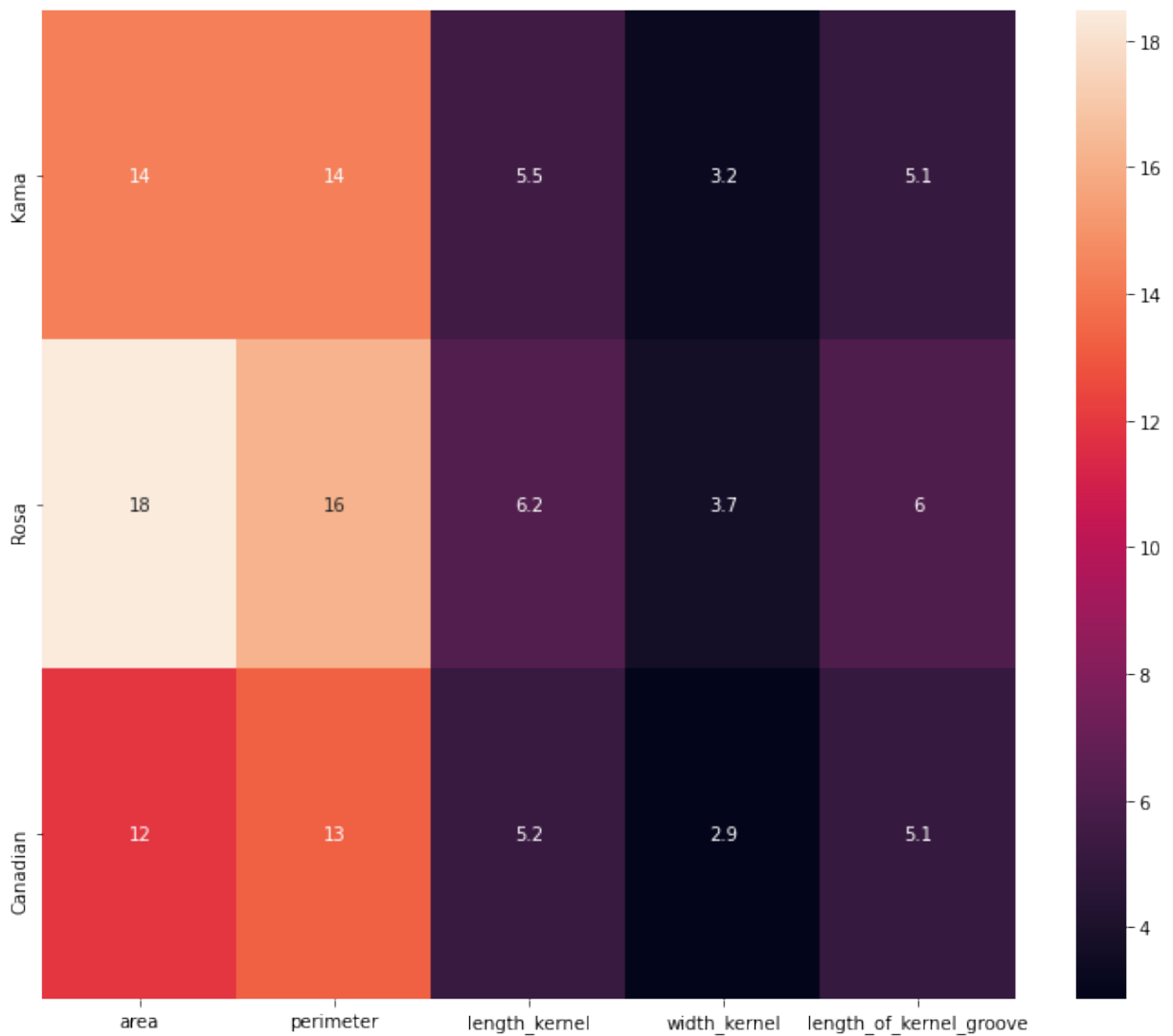
```
[68]: array([[14.31229984, 14.30681863,  5.51372596,  3.24076923,  5.07336077],  
        [18.47509091, 16.20672727,  6.18145455,  3.68961818,  6.04552727],  
        [11.92980392, 13.26666667,  5.23572549,  2.86598039,  5.11607843]])
```

```
[69]: # variance  
      ↪ ['area', 'perimeter', 'length_kernel', 'width_kernel', 'length_of_kernel_groove']  
gnb.sigma_
```

```
[69]: array([[1.1553264 , 0.2751547 , 0.0466526 , 0.03198691, 0.05833384],  
        [1.91794499, 0.33493838, 0.05771701, 0.03350129, 0.04885654],  
        [0.47804898, 0.11106144, 0.01841267, 0.01965065, 0.02661811]])
```

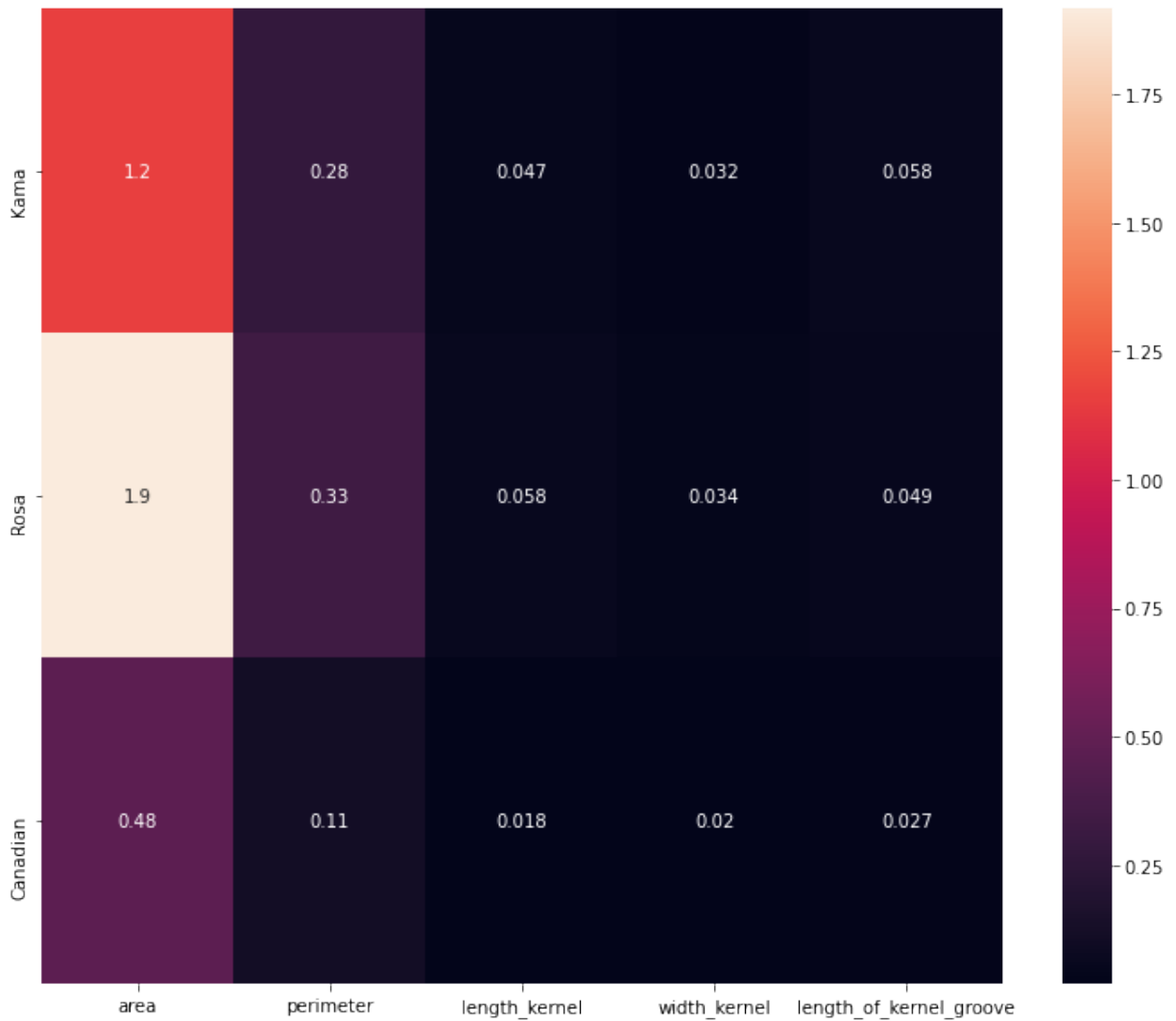
```
[70]: x_axis_labels =  
      ↪ ['area', 'perimeter', 'length_kernel', 'width_kernel', 'length_of_kernel_groove'] #  
      ↪ labels for x-axis  
y_axis_labels = ['Kama', 'Rosa', 'Canadian'] # labels for y-axis  
  
# create seaborn heatmap with required labels  
fig, ax = plt.subplots(figsize=(12,10))  
sns.heatmap(gnb.theta_, ticklabels=x_axis_labels,  
            ↪ yticklabels=y_axis_labels, annot=True)
```

```
[70]: <matplotlib.axes._subplots.AxesSubplot at 0x20c7435f7f0>
```



```
[71]: # create seaborn heatmap with required labels
fig, ax = plt.subplots(figsize=(12,10))
sns.heatmap(gnb.sigma_, xticklabels=x_axis_labels,
            yticklabels=y_axis_labels,annot=True)
```

```
[71]: <matplotlib.axes._subplots.AxesSubplot at 0x20c78e26af0>
```



[CM6]

Seeds Dataset :

In Decision tree, we observe maximum accuracy of 91% at maximum depth of 5 on the training set with 10 fold cross validation. The model gives an accuracy of 92.65% on the test set.

In Random Forest, we observe maximum accuracy of 92.95% at the maximum depth of 5 and 50 independent trees on the training set with 10 fold cross validation. The model also gives an accuracy of 92.65% on the test set.

In Gradient Tree Boosting, we observe maximum accuracy of 94.25% with 150 trees on the training set with 10 fold cross validation. The model also gives an accuracy of 92.65% on the test set.

In Naive Bayes Classifier, we observe maximum accuracy of 90.4% with a variance smoothing parameter $1e-10$. The model gives an accuracy of 92.5% on the test set. We notice that the accuracy for variance smoothing parameters $1e-10$, $1e-9$, $1e-5$, $1e-3$ is same and then decreases for $1e-1$. Laplace smoothing is a smoothing technique that helps tackle the problem of zero probability in the Naïve Bayes machine learning algorithm. We see that the smoothing parameter doesn't have a major impact here as all the features are numeric in the dataset.

Comparing the classifiers, we notice that Decision tree approaches has better performance on the training set than Naive Bayes, But we observe similar performance on the test set. This can be attributed to small size of the dataset. Decision tree is a discriminative model, whereas Naive bayes is a generative model. Also, Naive bayes is computationally faster when compared to Decision tree approaches.

From the NB learned parameters of ‘theta_’ (mean) and ‘sigma_’ (variance) , and comparing this to the single Decision Tree model, We observe:

- A feature can be considered good separator, if the mean of the feature for distinct classes are far apart, and if the variance of the features are low indicating the values are closer to the mean.
- the learned parameter ‘theta_’ (mean) of feature ‘length_of_kernel_groove’ is similar for Class 1(Kama) & 3(Canadian) (5.1) and different from Class 2 (Rosa) (6). Also ‘sigma_’ (variance) is very low for this feature indicating all the values are spaced close to the mean. Thus this feature ‘length_of_kernel_groove’ can be used to distinguish Class 2 (Rosa) effectively. This is observed in the decision tree classifier as well, where the splitting rule ‘length_of_kernel_groove’ ≤ 5.57 successfully separates Class 2 (Rosa) from rest of the dataset.
- Similarly the parameter ‘theta_’ (mean) of feature ‘perimeter’ is relatively different for Classes 1(Kama) & 3(Canadian). Also ‘sigma_’ (variance) is low for this feature indicating all the values are spaced close to the mean. Thus this feature can distinguish between Classes 1(Kama) & 3(Canadian) considerably. This is observed in the decision tree classifier as well, where the splitting rule ‘perimeter’ ≤ 13.80 separates Classes 1(Kama) & 3(Canadian) to a good extent.
- Similarly the learned parameters of feature ‘area’ and ‘width_kernel’ are relatively different for Classes 1(Kama) & 3(Canadian). Thus these features can distinguish between Classes 1(Kama) & 3(Canadian) decently. This is observed in the decision tree classifier as well, where the features are used to separate Classes 1(Kama) & 3(Canadian).

[]: