

GRAPH ALGORITHMS

Graph Generation - Static vs. Dynamic Traversals

Depth First Search

- Algorithm**
- Properties and Time Complexity**
- Applications**

Breadth First Search

GRAPH GENERATION

- Graph generation can be static or dynamic :
 - If the graph on which an algorithm is to be applied is already available then it is static
 - If the graph can change during execution - i.e. insertions / deletions may happen - then it is dynamic
- Examples
 - Traffic networks
 - Set of states in program execution
 - World Wide Web (web pages and hyperlinks)

GRAPH TRAVERSAL

- Given a graph G , a traversal is a systematic procedure for exploring G by examining its vertices (and edges)
 - E.g. web spider / crawler
 - E.g. find operation in Unix/Linux
 - E.g. A broadcast in a network
- Depth First Search (DFS) in an undirected graph:
 - A traversal which explores one path completely before exploring another would be “depth” first.
 - “Backtrack” to explore the next path
 - i.e. consider a branch not taken in exploring the previous path

DEPTH FIRST SEARCH

- Outline:

- Start at a given “root” vertex v and recursively visit adjacent vertices;
- If you encounter an explored edge or an explored vertex then backtrack;
 - Keep track of explored edges and vertices

DEPTH FIRST SEARCH

- DFS(G, v) // v is “visited”
 - for each vertex u that is adjacent to v such that (v, u) is “unexplored”
 - if u is “not visited”
 - mark u as “visited”
 - label (v, u) as “discovery edge” (or as “tree edge”)
 - DFS(G, u)
 - else
 - mark (v, u) as “back edge”

DEPTH FIRST SEARCH - PROPERTIES

- Claim DFS1:
 - DFS(G, v) visits all vertices in the connected component of v
- Definition : Connected Component
 - A connected component $G' = V', E'$ of a graph $G = V, E$, is such that
 - V' is a subset of V
 - E' is a subset of E
 - and between any pair of vertices u and v in V' , there is a path in E' .

DEPTH FIRST SEARCH - PROPERTIES

○ Claim DFS2:

- The discovery edges marked in $\text{DFS}(G,v)$ form a “spanning tree” of the connected component of v .
 - The spanning tree is referred to as the “DFS tree”
 - The edges are referred to as “tree edges”

○ Definition: Spanning Tree

- Given a connected graph $G = (V,E)$, a spanning tree T is a tree (V,E') such that E' is a subset of E .
 - Note that a tree is connected by definition.

DEPTH FIRST SEARCH - IMPLEMENTATION

- Assume an adjacency lists representation for G .
 - $\text{DFS}(G, v)$ // v is “visited”
 - for each vertex u that is adjacent to v such that (v, u) is “unexplored”
 - if u is “not visited”
 - mark u as “visited”
 - label (v, u) as “discovery edge” (or as “tree edge”)
 - $\text{DFS}(G, u)$
 - else
 - mark (v, u) as “back edge”
- Space Complexity:**
“visited”, “explored” bits
Recursion / backtracking
- **$O(d(w))$ time per vertex w**
 - **Total time:**
 - **$\sum_{w \text{ in } G'} d(w)$ where G' is the connected component of root**
 - **i.e. $O(m)$ where $m = |E'|$ and $G' = (V', E')$**

DFS

○ Theorem:

- A DFS traversal of G can be performed in $O(|V|+|E|)$ time.

dft(G) { // DFS traversal – G may not be connected

Let $(V,E)=G$.

for $j = 1$ to $|V|$ {

if (j is “not visited”) { mark j as “visited”; dfs(G,v); }

}

}

ALGORITHMS USING DFS

- Corollary:

- $O(|V|+|E|)$ time DFS-based algorithms exist for the following problems:
 - Test whether G is connected
 - Find the connected components of G
 - Find a spanning forest of G
 - Find a path between two vertices of G , if it exists
 - Find a cycle in G if it exists

BREADTH FIRST SEARCH (BFS)

- Traverse level-by-level
 - Discovery edges
 - Cross edges
 - BFS Tree – Spanning Tree
- BFS – outline
 - Start with a root vertex and at level 0
 - Maintain a FIFO queue
 - Insert all vertices at a level into the queue
 - Discover edges from current level to next level
 - Traverse until queue is empty