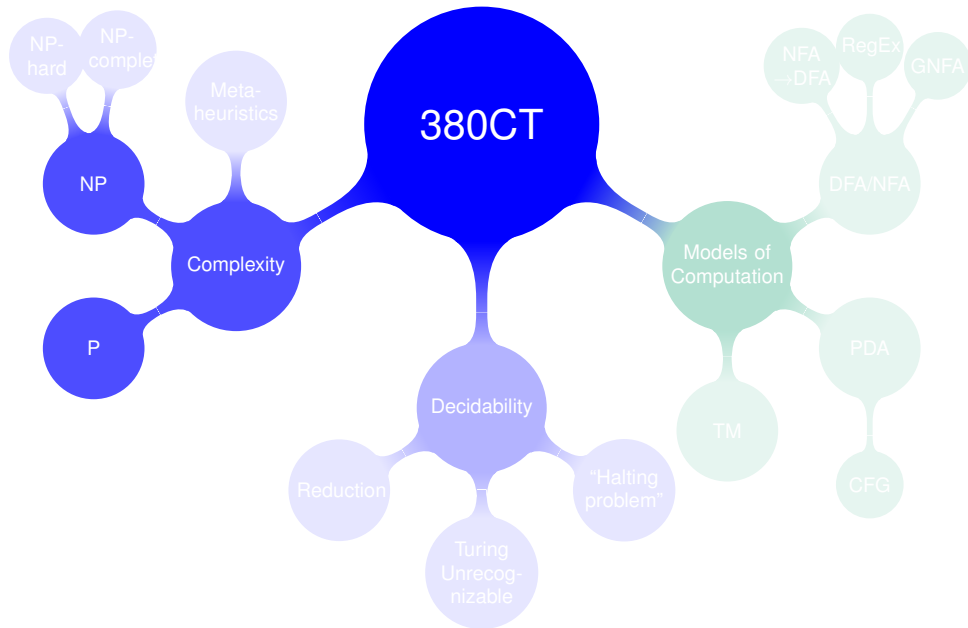


Complexity

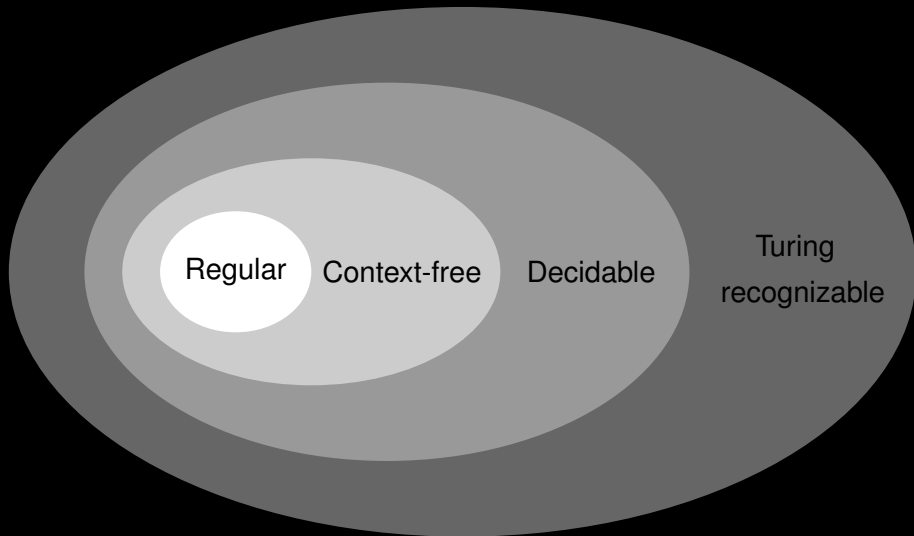
Dr Kamal Bentahar

School of Engineering, Environment and Computing
Coventry University

21/11/2014



The “computation universe” discovered so far...



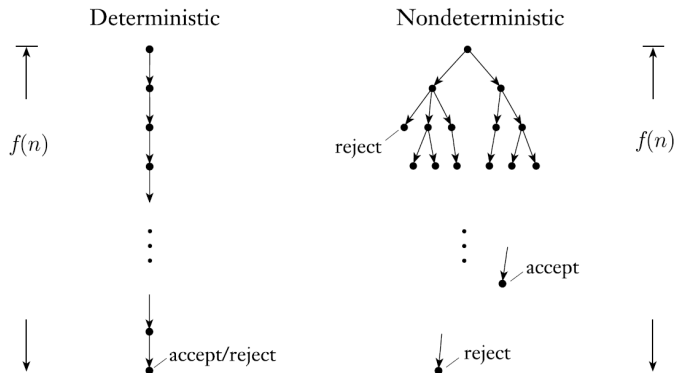
- ▶ Being **decidable** means that an **algorithm** exists to decide the problem.
- ▶ However, the algorithm may still be *practically* ineffective because of its **time** and/or **space** cost.

Running time / Time complexity

The **running time** or **time complexity** of a TM that always halts is the maximum number of steps $f(n)$ that it makes on any input of length n .

For nondeterministic TMs consider **all the branches** of its computation.

We say that it runs in time $f(n)$; and that it is an $f(n)$ -time TM.



Big-O notation cheat-sheet

- 1.
2. $\log n$
3. n
4. $n \log n$
5. n^2
6. $n^2 \log n$
7. n^3
8. 2^n
9. 3^n
10. $n!$
11. n^n

constant, does not depend on n
think of this as n^ϵ for a “small” ϵ

think $n \times n^\epsilon = n^{1+\epsilon}$

think $n^{2+\epsilon}$

Big-O notation cheat-sheet

- ▶ Constant $O(1)$
- ▶ Polynomial $O(n), O(n^2), \dots, O(n^k), \dots$ ($k \geq 1$)
- ▶ Exponential $O(2^n), O(3^n), \dots, O(b^n), \dots$ ($b > 1$)
- ▶ Factorial $O(n!)$
- ▶ $O(n^n)$

“Tricks”:

$$\begin{aligned}n^k \log n &\sim n^k n^\epsilon = n^{k+\epsilon} \\ n! &\sim n^n / e^n \quad \text{where } e = 2.718 \dots\end{aligned}$$

$$2013 \quad O(1)$$

$$n + 5 \quad O(n)$$

$$543n + n^3 + 13 \quad O(n^3)$$

$$4n^2 + 2784n + 10^{74} \quad O(n^2)$$

$$n^{578} + 4685 + 2^n \quad O(2^n)$$

$$n + n \log n + 35 \quad O(n \log n)$$

$$n^2 + n \log n + 35 \quad O(n^2)$$

$$n^2 + n^2 \log n + 35 \quad O(n^2 \log n)$$

$$n^{86754} + n! \quad O(n!)$$

Review

Big-O

P

Examples

NP

Examples

P vs NP

Formal definition of big-O notation

Big-O notation

Let f and g be functions

$$f, g: \mathbb{N} \rightarrow \mathbb{R}^+$$

Say that $f(n) = O(g(n))$ if positive integers c and n_0 exist such that for every integer $n \geq n_0$,

$$f(n) \leq cg(n).$$

We say that $g(n)$ is an **(asymptotic) upper bound** for $f(n)$.

[Review](#)[Big-O](#)[P](#)[Examples](#)[NP](#)[Examples](#)[P vs NP](#)

Time complexity class

Interesting observation:

Complexity relationships among TM variants

Let $t(n)$ be a function, where $t(n) \geq n$. Then every $t(n)$ time multi-tape TM has an equivalent $O(t^2(n))$ time single-tape TM.

Time complexity class

Let $t: \mathbb{N} \rightarrow \mathbb{R}^+$ be a function.

Define the **time complexity class**

$$TIME(t(n)),$$

to be the collection of all languages that are decidable by an $O(t(n))$ time TM.

Review

Big-O

P

Examples

NP

Examples

P vs NP

The class **P**

The class **P**

P is the class of languages that are decidable in polynomial time on a deterministic (single-tape) TM.

$$\mathbf{P} = \text{TIME}(1) \cup \text{TIME}(n) \cup \text{TIME}(n^2) \cup \text{TIME}(n^3) \cup \dots$$

P examples – path between two nodes in a graph

$PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t \}.$

A polynomial time algorithm for PATH

On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.

Review

Big-O

P

Examples

NP

Examples

P vs NP

P examples – relatively prime numbers

$$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}.$$

E : Euclidean algorithm for computing the *greatest common divisor*

On input $\langle x, y \rangle$, where x and y are natural numbers in binary:

1. Repeat until $y = 0$:
2. $x \leftarrow x \bmod y$
3. Exchange x and y .
4. Output x .

Algorithm that solves RELPRIME, using *E* as a subroutine:

On input $\langle x, y \rangle$, where x and y are natural numbers in binary:

1. Run *E* on $\langle x, y \rangle$.
2. If the result is 1, *accept*. Otherwise, *reject*."

The class **NP** – Solution vs Verification

- ▶ Solving: **finding/searching** for a solution.
- ▶ Verifying: **confirming** that a proposed solution is correct.

For example, given a candidate example of a tour around England, we just need to check if it

- ▶ contains all the required cities
- ▶ uses no city more than once
- ▶ finishes at its starting point
- ▶ uses only valid routes

[Review](#)[Big-O](#)[P](#)[Examples](#)[NP](#)[Examples](#)[P vs NP](#)

The class NP

Complexity

Verifiers

A verifier for a language L is an algorithm V , where

$$L = \{w \mid V \text{ accepts } \langle w, c \rangle \text{ for some } \textit{certificate} \text{ string } c\}.$$

- ▶ A **polynomial time verifier** runs in polynomial time in the length of w .
- ▶ A language is **polynomially verifiable** if it has a polynomial time verifier.

The class NP

NP is the class of languages that have polynomial time verifiers.

Review

Big-O

P

Examples

NP

Examples

P vs NP

The class **NP**

Nondeterministic Polynomial time complexity class

$\text{NTIME}(t(n)) = \{\text{Language decided by an } O(t(n)) \text{ time nondeterministic TM}\}.$

$$\mathbf{NP} = \text{NTIME}(1) \cup \text{NTIME}(n) \cup \text{NTIME}(n^2) \cup \text{NTIME}(n^3) \cup \dots$$

NP examples – the subset sum problem

Complexity

$$\text{SUBSETSUM} = \{ \langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \\ \text{and for some } \{y_1, \dots, y_\ell\} \subseteq \{x_1, \dots, x_k\}: y_1 + \dots + y_\ell = t \}.$$

Verifier: “On input $\langle S, t \rangle, c$:

1. Test whether c is a collection of numbers that sum to t .
2. Test whether S contains all the numbers in c .
3. If both pass, *accept*. Otherwise, *reject*.”

Alternatively, polynomial time NDTM: “On input $\langle S, t \rangle$:

1. Non-deterministically select a subset c of the numbers in S .
2. Test whether c is a collection of numbers that sum to t .
3. If the test passes, *accept*. Otherwise, *reject*.”

Review

Big-O

P

Examples

NP

Examples

P vs NP

Hamiltonian paths

A **Hamiltonian path** in a directed graph is a path that goes through each node exactly once.

$HAMPATH = \{ \langle G, s, t \rangle \mid \text{Directed graph } G \text{ has a Hamiltonian path from } s \text{ to } t \}.$

NP examples – cliques in a graph

Cliques

A **clique** in an undirected graph is a subgraph, wherein every two nodes are connected by an edge.

A **k -clique** is a clique that contains k nodes.

$$CLIQUE = \{ \langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique} \}.$$

Verifier for **$CLIQUE$** : “On input $\langle \langle G, k \rangle, c \rangle$:

1. Test whether c is a subgraph with k nodes in G .
2. Test whether G contains all edges connecting nodes in c .
3. If both pass, *accept*. Otherwise, *reject*.”

Alternatively, polynomial time NDTM: “On input $\langle G, k \rangle$, where G is a graph:

1. Nondeterministically select a subset c of k nodes of G .
2. Test whether G contains all edges connecting nodes in c .
3. If yes, accept; otherwise, reject.”

P

Polynomial-time

Class of languages that are decidable in polynomial time.

$$\mathbf{P} = \bigcup_{k \geq 0} \text{TIME}(n^k).$$

Review

Big-O

P

Examples

NP

Examples

P vs NP

NP

Nondeterministic Polynomial time

Class of languages that have polynomial time verifiers.

$$\mathbf{NP} = \bigcup_{k \geq 0} \text{NTIME}(n^k).$$

P = NP?

