

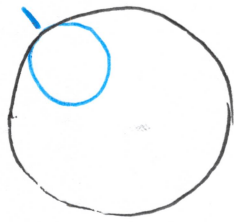
set turntable based on joystick, ~~and~~ with a
more turntable to rotate

Turntable rotates towards the angle from origin created by the joystick
Possible PID loop control if it is helpful - see about VEX Robotics
builtin PID control also

<https://www.vexforum.com/index.php/6465-a-pid-controller-in-a-robot-c/>
where the master is the joystick (unless the joystick is hovering around $x=0, y=0$,
then it should stop).

also, for multiple - tasking:

<https://www.vexforum.com/index.php/6146-robot-c-programming-tips/p2#p53786>



when - is more than the error

