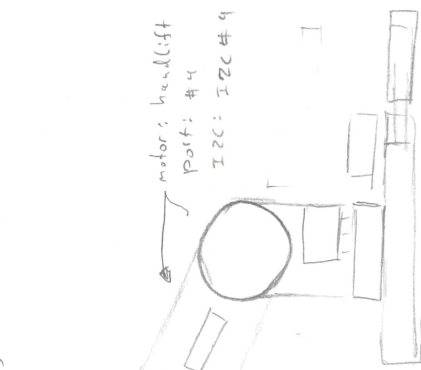


motor: elbow lift
Port: #3
I2C: I2C #3

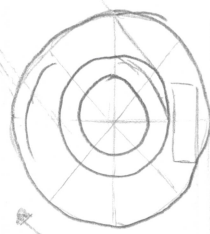


motor: hand Rotation
Port: #5
I2C: I2C #5

motor: hand lift
Port: #4
I2C: I2C #4

motor: base lift
Port: #2
I2C: I2C #2

motor: base Rotation
Port: #1
I2C: I2C #1



★ This is technically only a 4 DOF bot -
the rotation of the claw doesn't technically count.