



Title: Computing and AI

Code: CS101

Total Marks: 25

Instructor: Dr. Khurram Khan

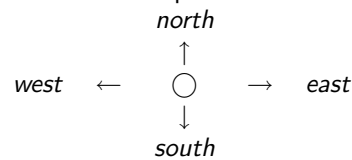
Project

Deadline: 27/12/2023

Q No 01

This project simulates a robot wandering around and trying to avoid bumping into anything. This is a typical robot behavior called *obstacle avoidance*. The robot has 4 *distance* sensors that point in 4 directions:

Each sensor returns a value between 0 and 100. The smaller the value, the closer the robot is to an object. The bigger the value, the further the robot is from an object. In order to avoid obstacles, the robot should always move in the direction of the sensor with the largest value.



Below is part of an obstacle avoiding robot simulation program. Your job is to fill in the missing pieces.

```
#include <stdlib.h>
#include <sys/time.h>
#include <iostream>
#include <string>
using namespace std;

// function prototypes
int senseDistance();
void getSensors( int sensors[] );
void printSensors( int sensors[], string labels[] );
int furthest( int sensors[] );

// main function
int main() {
    int sensors[4];           // array of four distance sensors
    string labels[4];         // array of labels for each sensor
    int dir;                  // indicates which direction to go next
    srand( time( NULL ) );    // initialize the random number generator
    labels[0] = "north";      // initialize the sensor labels
    labels[1] = "west";
    labels[2] = "south";
    labels[3] = "east";
    for ( int i=0; i<5; i++ ) { // simulate 5 moves by the robot
        getSensors( sensors ); // get values for all the sensors
        printSensors( sensors, labels ); // print out the sensor values
        dir = furthest( sensors ); // find the direction that is furthest from an obstacle
        cout << "moving " << labels[dir] << endl; // 'go'
    }
} // end of main()
```

1. Create a file called **avoid.cpp** and type in the code above. You need to type in all the comments :-)

2. Complete the function `senseDistance()`, which should return a random integer between 0 and 100.
3. Complete the function `getSensors()`, which should assign a distance value to each element in the `sensors[]` array, by calling `senseDistance()` to get the distance value for each sensor.
4. Complete the function `printSensors()`, which should print out the value of each sensor, preceded by its label. For example, if `sensors[0] = 93`, `sensors[1] = 80`, `sensors[2] = 73` and `sensors[3] = 28`, then the output might look like this:

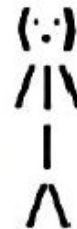
```
sensors = [north=93] [west=80] [south=73] [east=28]
```

Make sure that you use the `labels` array and don't hardcode any labels when printing out the sensor values (i.e., output "north" by using `labels[0]`).
5. Complete the function `furthest()`, which should return the *index* of the entry in the `sensors` array that has the largest value. For example, given the value of `sensors[]` shown above, the output from `furthest()` should be 0 because `sensors[0]` is 93, which is larger than the other elements in the `sensors[]` array.

Q No 02

In this task you have to develop the game "Hang the Man". The concept of the game is, computer will think of any country/city, it will display underscores which will be equivalent to the length of the country/city name the computer has thought of.

For example in case computer thinks China then it will display-----
 The user may enter any character as his option. If the chosen character is not in the name of city/country user loses 1 chance out of 8 possible chances of mistake and one component of human body is displayed per mistake (see the snap below). Otherwise, the chosen character is replaced in the underscore.



Note: You must NOT use any built in function for string processing.

Constraints:

1. Once a character is chosen, it cannot be chosen again.
2. Maximum number of mistakes is 11 {i.e., when the body is completed}.
3. Display the number of chances left for the user
4. Clear the screen and display latest data on each iteration of user input.
5. At the end, show the result, i.e., win/lose with the correct answer that will be the name of the city/country.

Submission instructions

- You will be upload zip folder with regnumber of group members e.g 2020345-2020456-project.