

MT-102:

(Primary) ✓ DEMIS G ZILL; 10th Edition
ERWIN KREYSZIG; 10th Edition.

Chapter 7 :-

$$A = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \quad B = \begin{bmatrix} a & b & c & d \end{bmatrix}$$

(column matrix (row matrix or
or column vector))

Only square matrix's inverse is possible.

① Symmetric Matrix

If A (a square) matrix $= A^T$

$$A = A^T$$

$$A^T = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 0 \end{bmatrix}$$

$$B^T = \begin{bmatrix} 0 & -1 & 3 \\ 1 & 0 & 2 \\ -3 & -2 & 0 \end{bmatrix} = -B.$$

To check if it is skew symmetric ; pick the
non-diagonal entities that are negative
of each other.

③ Upper triangular Matrix :-

$$\begin{bmatrix} 0 & 4 & 2 \\ 0 & 0 & 6 \\ 0 & 0 & 0 \end{bmatrix}; \begin{bmatrix} 1 & 4 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}; \begin{bmatrix} 1 & 4 & 2 \\ 0 & 3 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

(a short tick to check if it is symmetric ;
pick the non-diagonal or triangular terms
and check if they are same).

* If vice versa for the lower diagonal matrix.
(square matrix that can have non-zero
entities only on & above-the main diagonal)

(2) Skew-Symmetric:

A square matrix B is skew symmetric if
 $B^T = -B$.

(4)

Diagonal Matrix :- (square)

Non zero entities only on the main diagonal.

$$\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$$

(5) Identity Matrix :- (square)

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(A.I = I.A = A)
Property of a identity during multiplication of with a given matrix.

"APPLICATIONS OF MATRIX MULTIPLICATION"

PROBLEM:-

PC1086 PC1186

A = $\begin{bmatrix} 12 & 16 \\ 3 & 4 \end{bmatrix}$ Raw components.

$\begin{bmatrix} 5 & 6 \\ 5 & 6 \end{bmatrix}$ Labour
Miscellaneous

$$B = \begin{bmatrix} 3 & 8 & 6 & 9 \\ 6 & 2 & 4 & 3 \end{bmatrix} \begin{array}{l} \text{PC 1086} \\ \text{PC 1186} \end{array}$$

'A' shows cost per computer & shows production figures for a year.
'B'

Find Matrix that shows the cost per quater for raw materials, labour, & miscellaneous

Quater.

$$AXB \Rightarrow \begin{bmatrix} ① & ② & ③ & ④ \end{bmatrix} \begin{array}{l} \text{Raw components} \\ \text{Labour} \\ \text{Miscellaneous} \end{array}$$

hence if we multiply AxB we will get AB of (3×4) that will satisfy the demands as highlighted above

Result :-

$$AXB = \begin{bmatrix} (12 \times 3) + (16 \times 6) & 128 & 136 & 156 \\ 3 & 3 & 32 & 34 \\ 51 & 52 & 54 & 63 \end{bmatrix}$$

singular matrix $|A|=0$; no solution. $A^{-1} = \frac{adj A}{|A|}$

Step/Out

7.3: Linear System of Equations.

m equations with n unknowns.

$$\begin{array}{l} (1) \quad a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ (2) \quad a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ (3) \quad a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{array}$$

Conversion into a matrix.

$$\left[\begin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \\ \vdots \\ x_n \end{array} \right] = \left[\begin{array}{c} b_1 \\ b_2 \\ \vdots \\ b_m \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{array} \right]$$

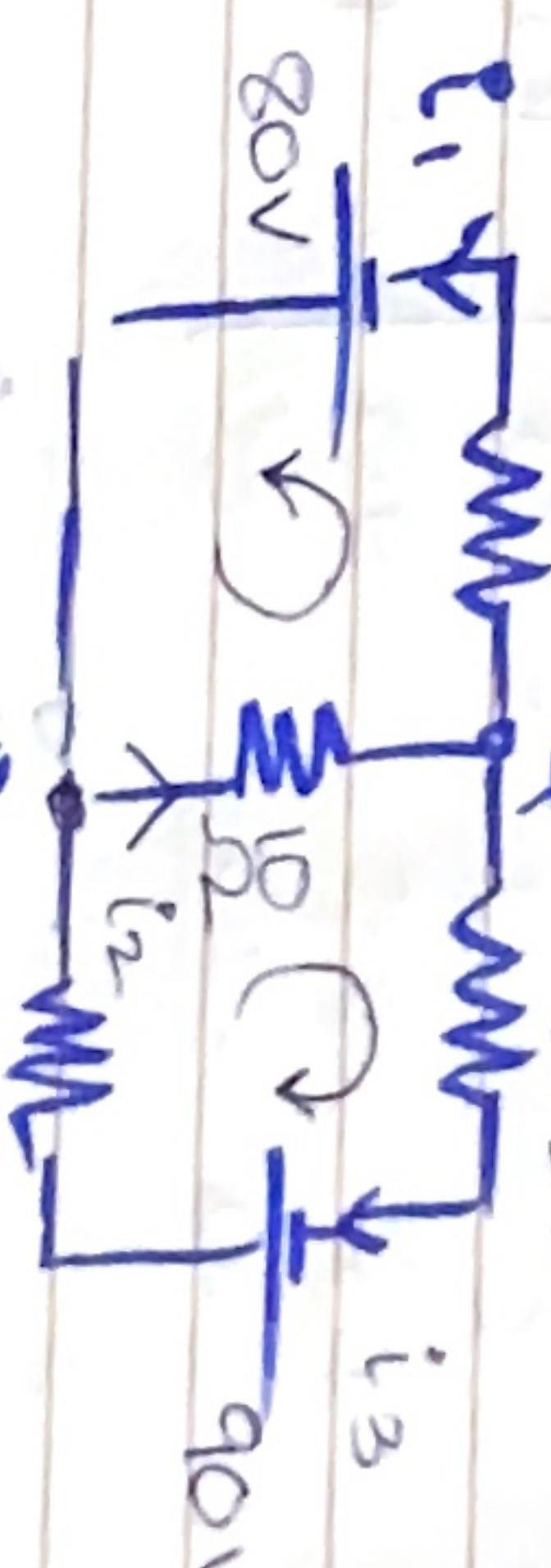
Steps:-

Create a augmented Matrix.

$$\tilde{A} = [A : B]$$

Perform row operations to make an upper triangle matrix.

Ex:- ELECTRICAL NETWORK:-



$$\text{Node } P: -i_2 + i_3 + i_1 = 0 \quad \text{---(1)}$$

$$\text{Node } Q: -i_1 + i_2 - i_3 = 0 \quad \text{---(2)}$$

The only method left to solve these

(rectangular system) of equations is through "Gauss Elimination".

$$10i_2 + 10i_3 + 15i_1 = 90V$$

$$10i_1 + 25i_3 = 90 \quad \text{---(3)}$$

$$10i_2 + 20i_1 = 80V \quad \text{---(4)}$$

Making equation matrix system.

$$A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 0 & 10 & 25 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 90 \\ 80 \end{bmatrix}, X = \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix}$$

* The pivoted row ^{entry} will have no change ever.

$$\sim = \begin{bmatrix} 1 & -1 & 1 & : & 0 \\ -1 & 1 & -1 & : & 0 \\ 0 & 10 & 25 & : & 90 \end{bmatrix}$$

first value =
first diagonal
and first pivot

$$\sim = \begin{bmatrix} 1 & -1 & 1 & : & 0 \\ 0 & 30 & -20 & : & 20 \\ 0 & 0 & 95 & : & 190 \end{bmatrix}$$

move the zeros ↓ - 1 row 1 → R3 - R1
down makes 3rd row
and make 3rd row a pivot through column

Back Substitution

$$0 = 0 \quad * \checkmark$$

$$95i_3 = 190 \Rightarrow i_3 = 2$$

$$30i_2 - 20i_3 = 80$$

$$i_2 = \frac{190}{95} = 2 \text{ Ans!}$$

$$30i_2 - 20(2) = 80$$

$$30i_2 - 40 = 80 \Rightarrow i_2 = \frac{120}{30} = 4 \text{ Ans!}$$

zeros been have been converted

$$1 \quad -1 \quad 1 \quad : \quad 0$$

$$0 \quad 0 \quad 0 \quad : \quad 0$$

$$0 \quad 10 \quad 25 \quad : \quad 90$$

$$R_2 \leftrightarrow R_4$$

$$i_1 - i_2 + i_3 = 0$$

$$i_1 - (4) + 2 = 0$$

$$i_1 - 2 = 0$$

$$i_1 = 2 \text{ Ans!}$$

Now make no 2nd diag repivot 2nd entry

$$a^{01} \quad \begin{bmatrix} 1 & -1 & 1 & : & 0 \\ 0 & 30 & -20 & : & 80 \\ 0 & 10 & 25 & : & 90 \end{bmatrix} \quad 3R_3 - R_2$$

zero in diag is not change entry is somehow help w/ it somehow

$$0 \quad 0 \quad 0 \quad : \quad 0$$

Now '10' in the highlighted position is the only value that needs to be zero in order to be a upper triangle.

$$\begin{bmatrix} 1 & -1 & 1 & : & 0 \\ 0 & 30 & -20 & : & 20 \\ 0 & 0 & 95 & : & 190 \end{bmatrix}$$

Stochastic Matrix:-

Stochastic Matrix is a square matrix with all the entries non-negative and the column entries sum up to become 1. ↳

MARKOV'S PROCESS:-

a process for which the probability of occurring a newer state / entering a newer state / leaving a newer state occupied depends upon the last state occupied.

For a markov process a matrix must be a stochastic matrix. If x_0 is the last / initial stage then any later stage (x_f) is given by

$$x_f = P x_0 \rightarrow \begin{matrix} \text{initial / last} \\ \text{stage} \\ \text{achieved} \end{matrix} \quad \begin{matrix} \text{stochastic} \\ \text{matrix} \end{matrix} \quad \begin{matrix} \text{after} \\ \text{(a probability)} \\ \text{change} \end{matrix}$$

CASES :

COLUMN STOCHASTIC MATRIX

In it the square matrices

matrix has row

entries summing

equal to one.

Example 13:-

Suppose that 2004 state of land used in a city of 60 mi^2 built up area of $20\% + 5 = 25\%$.

- C. commercial area 20% .
- I. Industrial " 20% .
- R. Residential " 55% . \Rightarrow

Find the states in 2009, 2014, 2019 assuming that the transition probabilities for 5 years intervals are given by matrix A. From

$$A = \begin{bmatrix} 0.7 & 0.1 & 0 \\ 0.2 & 0.9 & 0.2 \\ 0.1 & 0 & 0.8 \end{bmatrix} \begin{matrix} C \\ I \\ R \end{matrix}$$

Now as the probability of newer state is required we use the markov's process. The matrix A is stochastic (column wise), thus the x_0 is given as.

$$x_0 = \begin{bmatrix} 25\% \\ 20\% \\ 55\% \end{bmatrix}; \text{ By method } x_f = P x_0$$

Such case has such case has row
a column matrix matrix for x_0 .

Such case has row
matrix for x_0 .

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$$\Rightarrow \begin{bmatrix} 0.1 & 0.1 & 0 \\ 0.2 & 0.9 & 0.2 \\ 0.1 & 0 & 0.8 \end{bmatrix} \times \begin{bmatrix} 28 \\ 20 \\ 55 \end{bmatrix}$$

Therefore fire at 2014 is

$$19.5$$

Ans!

Similarly using

$$34.0$$

$$46.5$$

(a) again 2009,

then 2014, 2019

be predicted.

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system with variable power at most 1.

linear system of equ(s) in matrix form.

$$\begin{aligned} a_{11}x_1 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + \dots + a_{2n}x_n &= b_2 \\ \vdots & \\ a_{m1}x_1 + \dots + a_{mn}x_n &= b_m. \end{aligned}$$

- * the equations are given in the straight line;
- * terms varying at 'amn' are coefficients.
- * 'b1 ... bm' are the numbers given on the right
if all 'bj' $\Rightarrow 0$ it is homogeneous system
if atleast one 'bj' $\neq 0$ it is nonhomogeneous
- * For a homogeneous system the trivial solution exist (atleast)

$$AX = 0$$

$$X = 0$$

thus

- * any non-zero solution can be termed as a 'non-trivial' solution.

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \quad \left\{ X = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \right\} \quad \left\{ b = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} \right\}$$

COEFFICIENT MATRIX.

$$\tilde{A} \left[\begin{array}{ccc|c} a_{11} & \dots & a_{1n} & b_1 \\ \vdots & \dots & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} & b_m \end{array} \right]$$

AUGMENTED MATRIX.

CASE STUDY:-

If two equations and two unknown variable are given.

$$a_{11}x_1 + a_{12}x_2 = b_1$$

$$a_{21}x_1 + a_{22}x_2 = b_2$$

If we interpret x_1, x_2 in coordinates in x_1, x_2 -plane then each of the two equations represent a straight line and (x_1, x_2) solution if & only if the point P with coordinates x_1, x_2 lie on both the line.

Hence there are 3 possibilities:

- (i) Precisely one solution (lines intersect)
- (ii) Infinitely many solution (lines coincide)
- (iii) no solution (line parallel.)

* if the system is homogeneous i.e. $(b_1 \neq b_2 \neq 0)$ then case (iii) is not possible because for a homogeneous system; trivial solution always exists.

CONCEPT :-

TYPES OF LINEAR SYSTEM :-

Pivot = no. of eqns.

overdetermined

Determined

under determined

no. of

equation > no. of unknowns.

no. of equation = no. of unknowns

no. of equation < no. of

unknowns.

CONSISTENT :- If a system has at least one sol.
(i.e. one or infinitely many solutions).

INCONSISTENT :-

If a system has no solution.

* homogeneous system can never be inconsistent.

CASES :- (of Gauss Elimination)

(I) **Gauss Elimination if infinitely many solution exist**
Usually seen when under-determined
form exists (when case II does)
check $\Phi_7, \Phi_9, \Phi_{11}$

occurred of arbitrary values.

(II) **Gauss E; if no solution exists**

The condition appears when after achieving D
augmented matrix a contradiction occurs

e.g. $\Phi_{12} \quad 5 \neq 15$

III **SOLUTION EXISTS UNIQUELY**

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NOTES:-

Elementary Matrices:-

The elementary matrices can be obtained by matrix multiplication.

If A is a matrix of $(m \times n)$ order on which we want to perform operations (elementary) then there is a matrix 'E' such that 'EA' is the new matrix after the operation. Such E is called as the elementary matrix.

however generally elementary matrices are those matrices that can form an identity by only a single elementary row operation.

Example

$$Q_{24} \\ (a)+(b) \quad E_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_2 \leftrightarrow R_3 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ hence elementary matrix.}$$

$$(b) \quad E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -5 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad R_3 + 5R_1 \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

hence elementary matrix Galaxy

$$E_3 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 8 \end{bmatrix}$$

$\xrightarrow{R_4 \rightarrow}$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

hence
elementary
matrix

We can examine the operation we performed in the matrix to obtain

The concept required in the sol.

→ transforming into systems of equations

(i) $E_1 M \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} a \\ c \\ b \\ d \end{bmatrix}$

EXAMPLE:

(ii) $E_2 M \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -5 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} a \\ b \\ -5a+c \\ d \end{bmatrix}$

The equation :-
 $a_1 v_1 + a_2 v_2 + \dots + a_m v_m = 0$
 hold if we choose all a_j 's zero since
 atleast one of the vectors is non-zero.
 As a result the vectors v_1, v_2, \dots, v_m are
 linearly independent. If vice versa =
 linearly dependent.

7.4 Linear Independence & Dependence of vectors.

Given any set of m vectors v_1, v_2, \dots, v_m with same number of components, a linear combination of these vector is

$$a_1 v_1 + a_2 v_2 + \dots + a_m v_m ; \quad a_1, a_2, \dots, a_m \in \mathbb{R}$$

Check if the vectors are linearly independent or not.

$$a_1V_1 + a_2V_2 + a_3V_3 = 0$$

$$a_1[0 \ 1 \ 0 \ 1] + a_2[1 \ 1 \ 1 \ 1] + a_3[0 \ 0 \ 0 \ 1] = 0$$

$$[0 \ a_1 \ a_1] + [a_2 \ a_2 \ a_2] + [0 \ 0 \ a_3] = 0$$

$$[a_2, \ a_1 + a_2, \ a_1 + a_2 + a_3] = [0 \ 0 \ 0]$$

$a_2 = 0$ thus in this question

$a_3 = 0$ the components of

$a_1 + a_2 = 0$ vectors cannot be

$a_1 = 0$ written in terms of

one another.

\Rightarrow linear independence.

EXAMPLE:-

$$V_1 = [3 \ 0 \ 2 \ 2]$$

$$V_2 = [-6 \ 42 \ 24 \ 54]$$

$$V_3 = [21 \ -21 \ 0 \ -15]$$

Now drawing equations;

$$3a_1 - 6a_2 + 21a_3 = 0, \quad 42a_2 - 21a_3 = 0$$

$$2a_1 + 24a_2 + 0, \quad 2a_1 + 54a_2 - 15a_3 = 0$$

$$2a_1 + 24a_2 = 0 \quad (3)$$

$$2a_1 + 54a_2 - 15a_3 = 0 \quad (4)$$

Now to check if vectors are dependent or independent linearly.

$$a_1V_1 + a_2V_2 + a_3V_3 = 0$$

$$a_1[3 \ 0 \ 2 \ 2] + a_2[-6 \ 42 \ 24 \ 54] + a_3[21 \ -21 \ 0 \ -15] = 0$$

$$\text{using } \begin{cases} 2a_1 + 24a_2 = 0 \\ a_2 = \frac{1}{2}a_3 \end{cases}$$

$$\begin{cases} a_1 = -12a_2 \\ a_2 = a_3 \end{cases}$$

1.4

 $\alpha_1 - 10$
 $\alpha_2 - 26$

Rank of the matrix:-

The rank of the matrix A is the maximum number of linearly independent row vectors of A .

OR.

Rank of the matrix is the number of non-zero rows in echelon form.

Example:-

$$A = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 2 & 2 \\ -6 & 42 & 24 & 54 \\ 21 & -21 & 0 & -15 \end{bmatrix}$$

7.5

HOMOGENEOUS LINEAR SYSTEM:-

A homogeneous system of m equations in n unknowns, total no. of columns.

$$\begin{bmatrix} 3 & 0 & 2 & 2 \\ 0 & 42 & 24 & 58 \\ 0 & -21 & -14 & -29 \end{bmatrix} \xrightarrow{\substack{R_2 + 2R_1 \\ R_3 - 7R_1}} \begin{bmatrix} 3 & 0 & 2 & 2 \\ 0 & 42 & 24 & 58 \\ 0 & -14 & -29 & -29 \end{bmatrix}$$

Thus rank of the matrix = 2.

First two rows of the matrices corresponding to v_1, v_2 are non-zero suggesting that v_1, v_2 are linearly independent. But due to v_1, v_2, v_3 altogether they are dependent.

check:-

$$\alpha_1 v_1 + \alpha_2 v_2 = 0$$

$$\alpha_1 [3 & 0 & 2 & 2] + \alpha_2 [0 & 0 & 0 & 0] =$$

$$\begin{bmatrix} 3\alpha_1 - 6\alpha_2 & 42\alpha_2 & 2\alpha_1 + 24\alpha_2 & 2\alpha_1 + 54\alpha_2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \end{bmatrix}$$

$$3\alpha_1 - 6\alpha_2 = 0$$

$$4. \text{ always have trivial solution and non-trivial in } A \in \mathbb{R}^{m \times n}$$

EXAMPLE :-

$$\text{Let } \tilde{A} = \begin{bmatrix} 2 & 4 & 1 & 0 \\ 0 & 6 & -3 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Echelon form } \tilde{A} \begin{bmatrix} 2 & 4 & 1 & 0 \\ 0 & 6 & -3 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Non augmented matrix's rank.

$$\begin{bmatrix} 2 & 4 & 1 \\ 0 & 6 & -3 \\ 0 & 0 & 0 \end{bmatrix}$$

Now

Rank of the matrix = 2
No. of unknown variables = 3

hence only trivial solution exists. but also nontrivial

as $\text{rank } A < n$.

EXISTENCE & UNIQUENESS OF SOLUTION OF LINEAR SYSTEM.

NON-HOMOGENEOUS.

A linear system of equations in n unknowns has,

(1) A unique solution if $\text{rank } A = \text{rank } \tilde{A} = n$.

Example:-
electrical Network.

$$\text{Echelon form } \tilde{A} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 30 & -20 & 80 \\ 0 & 0 & 95 & 100 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$n = 3$
 $\text{rank } \tilde{A} = 3$
 $\text{rank of } A = 3$
hence unique solution exist.

(2) Infinite many solutions if

$\text{rank } A = \text{rank } \tilde{A} < n$.
Example: $\begin{bmatrix} 3 & 2 & 2 & -5 & 8 \\ 0.6 & 1.5 & 1.5 & -5.4 & 2.7 \\ 1.2 & -0.3 & 0.3 & 2.4 & 2.1 \end{bmatrix}$

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Echelon form

$$\left[\begin{array}{ccccc} 3 & 2 & 2 & -5 & : 18 \\ 0 & 1 & -4 & & : 1 \\ 0 & 0 & 0 & 0 & : 0 \end{array} \right]$$

$$\text{rank } A = 2$$

$$\text{rank } \tilde{A} = 2$$

$$n = 4$$

$$\text{rank } A = \text{rank } \tilde{A} < n.$$

- ③ System has no solution.
if A & \tilde{A} have different
solved ranks.

Example:

$$\tilde{A} = \left[\begin{array}{ccc|c} 3 & 2 & 1 & : 3 \\ 2 & 1 & 1 & : 0 \\ 0 & 2 & 4 & : 6 \end{array} \right]$$

echelon
form

$$\left[\begin{array}{ccc|c} 3 & 2 & 1 & : 3 \\ 0 & -1 & -1 & : -6 \\ 0 & 0 & 0 & : 12 \end{array} \right]$$

rank $\tilde{A} \Rightarrow 3 \Rightarrow$ no solution.

rank $A \Rightarrow 2$

"DETERMINANTS"

A determinant of order n is always associated with square matrix $\underline{A} = [a_{ij}]$

$$D = \det A = \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix}$$

Determinants :-

Determinant of a triangular matrix \uparrow is the product of its diagonal matrix's diagonal entries

Example:-

$$A = \begin{bmatrix} -3 & 0 & 0 \\ 0 & 4 & 0 \\ -1 & 2 & 5 \end{bmatrix}$$

$$|A| = (-3)(4)(5) = -60 \text{ Ans.}$$

apply's when gauss elimination has failed

→ happen when the pivoted element = 0 and zero cannot be removed.

CRAMMER'S RULE :-

If a linear system of n equations in n unknowns i.e. $x_1, x_2, x_3 \dots x_n$ has a non-zero determinant coefficient matrix. i.e. $\det A \neq 0$ then the system has unique solution.

$$\text{given } i \quad x_1 = \frac{D_i}{D}$$

nonsingular matrix.

$$x_2 = \frac{D_2}{D} \dots x_n = \frac{D_n}{D}$$

$$|A| = \begin{vmatrix} -1 & 1 & 2 \\ 3 & -1 & 1 \\ -1 & 3 & 4 \end{vmatrix}$$

$$= [-1(-4 - 3) - 1(12 + 1) + 2(9 - 1)]$$

$$= 7 - 13 + 16 = 10 \text{ Ans!}$$

⇒ Finding adjoint through cofactor method.

$$C_{11} = (-1)^{1+1} M_{11} \Rightarrow \begin{vmatrix} -1 & 1 \\ 3 & 4 \end{vmatrix} = -7$$

Inverse of a matrix.

The inverse of a matrix is defined

as

$$A^{-1} = \frac{\text{adj} A}{|A|} = \left[C_{ij} \right]^\top$$

factors $\leftarrow C_{ij} = (-1)^{i+j} M_{ij}$

where $i = 1, 2, 3, \dots, n$

where $j = 1, 2, 3, \dots, n$.

where M_{ij} is found by eliminating j^{th} column in $|A|$.

Example:-

$$A = \begin{bmatrix} -1 & 1 & 2 \\ 3 & -1 & 1 \\ -1 & 3 & 4 \end{bmatrix} \quad \text{find } A^{-1} = \frac{\text{Adj} A}{|A|}$$

$$C_{12} = (-1)^{1+2} M_{12} \Rightarrow \begin{vmatrix} 3 & 1 \\ -1 & 4 \end{vmatrix} = -13$$

$$C_{13} = (-1)^{1+3} M_{13} \Rightarrow \begin{vmatrix} 3 & -1 \\ -1 & 3 \end{vmatrix} = 8$$

a_1/a_{11}

$$C_{21} = (-1)^{2+1} \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} \Rightarrow 2$$

$$C_{22} = (-1)^{2+2} \begin{vmatrix} -1 & 2 \\ -1 & 4 \end{vmatrix} \Rightarrow -2$$

$$C_{23} = (-1)^{2+3} \begin{vmatrix} -1 & 1 \\ -1 & 3 \end{vmatrix} \Rightarrow 2.$$

Let

$$A = \begin{bmatrix} a_{11} & 0 & 0 & \dots & 0 \\ 0 & a_{22} & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}$$

* Inverse of a diagonal matrix exists iff all the elements in diagonal are non-zero and is given by:

10

$$C_{31} = (-1)^{3+1} \begin{vmatrix} 1 & 2 \\ -1 & 1 \end{vmatrix} = 3$$

$$C_{32} = (-1)^{3+2} \begin{vmatrix} -1 & 2 \\ 3 & 1 \end{vmatrix} \Rightarrow 7$$

$$A^{-1} = \begin{bmatrix} 1/a_{11} & 0 & 0 & \dots & 0 \\ 0 & 1/a_{22} & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}$$

$$C_{33} = (-1)^{3+3} \begin{vmatrix} -1 & 1 \\ 3 & -1 \end{vmatrix} \Rightarrow -2$$

7.8 Inverse of a matrix by Gauss-Jordan Method.

Extension of Gaussian Elimination.
Augmented matrix has a form.

$$\text{Now } (C_{ij})^T = \begin{bmatrix} -7 & 2 & 3 \\ -13 & -2 & 7 \\ 3 & 7 & -2 \end{bmatrix}$$

a_2/a_{22}

$$A^{-1} = \begin{bmatrix} -1 & 2 & 3 \\ -13 & -2 & 7 \\ 3 & 7 & -2 \end{bmatrix} \Rightarrow \begin{bmatrix} 0.7 & 0.2 & 0.3 \\ -1.3 & -0.2 & 0.7 \\ 0.3 & 0.2 & -0.2 \end{bmatrix}$$

$$c_{ij} = \begin{cases} c_{11} & (11) & (13) \\ c_{21} & (21) & (23) \\ c_{31} & (31) & (33) \end{cases} \quad (C_{ij})^T$$

Reduced echelon : has both upper & lower

upper & lower
As.

after row operations we require
Galaxy

Galaxy

$$A = \begin{bmatrix} -1 & 1 & 2 \\ 3 & -1 & 1 \\ -1 & 3 & 4 \end{bmatrix}$$

$$R_1 + R_2 \rightarrow A = \begin{bmatrix} -1 & 1 & 2 & : & 1 & 0 & 0 \\ 3 & -1 & 1 & : & 0 & 1 & 0 \\ -1 & 3 & 4 & : & 0 & 0 & 1 \end{bmatrix}$$

$$-1)R_1 \quad \begin{bmatrix} 1 & -1 & -2 & : & -1 & 0 & 0 \\ 1 & -1/3 & \sqrt{3} & : & 0 & 1/3 & 0 \\ -1 & 3 & 4 & : & 0 & 0 & 1 \end{bmatrix}$$

$$R_2 \rightarrow \begin{bmatrix} 1 & -1 & -2 & : & -1 & 0 & 0 \\ 0 & 1 & 2 & : & -1 & 0 & 1 \\ -1 & 3 & 4 & : & 0 & 0 & 1 \end{bmatrix}$$

make identity

hence now the inverse is:-

$$\begin{bmatrix} 1 & 0 & 0 & : & -7/10 & 1/5 & 3/10 \\ 0 & 1 & 0 & : & -13/10 & -1/5 & 7/10 \\ 0 & 0 & 1 & : & 4/5 & 1/5 & -1/5 \end{bmatrix}$$

$$\frac{3}{2} R_2 \rightarrow \begin{bmatrix} 1 & -1 & -2 & : & -1 & 0 & 0 \\ 0 & 1 & 2 & : & 3/2 & 1/2 & 0 \\ 0 & 2 & 4 & : & -1 & 0 & 1 \end{bmatrix}$$

$$R_3 - 0.2R_2 \rightarrow \begin{bmatrix} 1 & -1 & -2 & : & -1 & 0 & 0 \\ 0 & 1 & 2 & : & 3/2 & 1/2 & 0 \\ 0 & 0 & -4 & : & -4 & -1 & 1 \end{bmatrix}$$

$$R_1 + R_2 \rightarrow \begin{bmatrix} 1 & 0 & 0 & : & 3/2 & 1/2 & 0 \\ 0 & 1 & 1 & : & 3/2 & 1/2 & 0 \\ 0 & 0 & 0 & : & -4 & -1 & 1 \end{bmatrix}$$