

Math 493

Honors Algebra I

University of Michigan

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August 31, 2023

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INTRODUCTION & MOTIVATION

We will study

- (a) Linear algebra
- (b) Group Theory
- (c) Finite Group Representations

In 494 we will study

- (a) Ring Theory
- (b) Fields
- (c) Galois Theory

This class is good preparation for 575 or 676. The official textbook is Artin's Second edition. We will probably proceed in a different order than Artin. Other than Artin's look into Dummit & Foote, Lang, Hirstine. Pick the book that you like and read it. Sit four to a table.

Sometimes a polished proof will not be presented in class and you are expected to finish the proof at home.

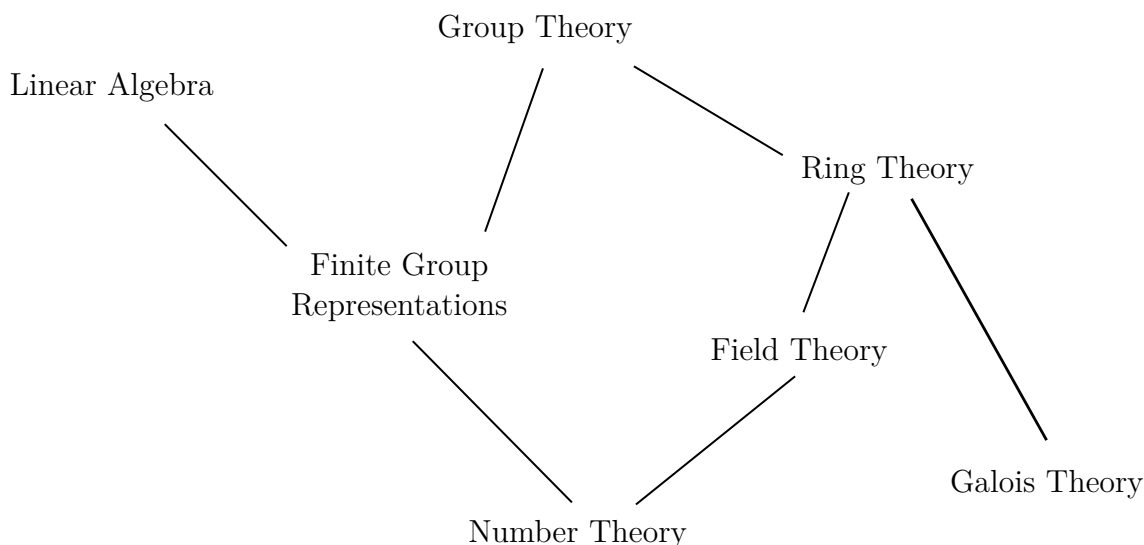


Figure 1: Partial Ordering of Course Topics

- (i) $\exists e \in G$ such that $e \star a = a \star e = a$ for all $a \in G$ (existence of identity)
- (ii) $\forall a, b, c \in G$ we have $(a \star b) \star c = a \star (b \star c)$ (distributivity of \star)
- (iii) $\forall a \in G, \exists a' \in G$ such that $a \star a' = a' \star a = e$ (existence of inverses)

- The trivial group
- $(\mathbb{Z}, +)$
- $(\mathbb{Z}/2\mathbb{Z}, \oplus)$
- $(\mathbb{Z}/n\mathbb{Z}, +)$
- $(\mathbb{Q}^\times, \cdot)$ (nonzero rationals)
- $\text{Aut}(S)$ for any set S , this is the symmetric group S_n when $|S| = n \in \mathbb{N}$
- Rotations of a square
- Free group on n elements

Note that S_2 has one generator and S_3 has two generators:

$$\sigma = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \tau = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

S_1	\parallel	e
e	\parallel	e

S_2	\parallel	e	$ $	σ
e	\parallel	e	$ $	σ
σ	\parallel	σ	$ $	e

S_3	\parallel	e	$ $	τ	$ $	τ^2	$ $	σ	$ $	$\sigma\tau$	$ $	$\sigma\tau^2$
e	\parallel	e	$ $	τ	$ $	τ^2	$ $	σ	$ $	$\sigma\tau$	$ $	$\sigma\tau^2$
τ	\parallel	τ	$ $	τ^2	$ $	e	$ $	$\sigma\tau^2$	$ $	σ	$ $	$\sigma\tau$
τ^2	\parallel	τ^2	$ $	e	$ $	τ	$ $	$\sigma\tau$	$ $	$\sigma\tau^2$	$ $	σ
σ	\parallel	σ	$ $	$\sigma\tau$	$ $	$\sigma\tau^2$	$ $	e	$ $	τ	$ $	τ^2
$\sigma\tau$	\parallel	$\sigma\tau$	$ $	$\sigma\tau^2$	$ $	σ	$ $	τ^2	$ $	e	$ $	τ
$\sigma\tau^2$	\parallel	$\sigma\tau^2$	$ $	σ	$ $	$\sigma\tau$	$ $	τ	$ $	τ^2	$ $	e

Note that $\tau\sigma = \sigma\tau^2 \implies \tau^k\sigma = \sigma\tau^{2k}$ for $k \in \mathbb{N}$.

Definition. (Subgroup)

Suppose G is a group and $H \subseteq G$ such that

- (a) $e \in H$
- (b) $\forall a, b \in H$ we have $a \star b \in H$
- (c) $\forall a \in H$ we have $a^{-1} \in H$

H is a group with the group law inherited from G . If $S \subseteq G$, then $\langle S \rangle$ is the subgroup generated by S (note that S may be a singleton).

Now we find all subgroups of S_3 : $S_3, \{e\}, \{e, \sigma\}, \{e, \tau, \tau^2\}, \{e, \sigma\tau\}, \{e, \sigma\tau^2\}$. There are three subsets of S_3 that are isomorphic to S_2 and one isomorphic to $\mathbb{Z}/3\mathbb{Z}$. You can find subgroups by taking a single element and taking all powers of it (positive and negative). We obtain a lattice of subgroups.

Definition. (Order)

If $a \in G$, the **order** of a is $\mu n \in \mathbb{N}$ such that $a^n = e$. If no such n exists, then a has **infinite order**. Note that the order of all elements in a finite group are finite (pigeon hole principal).

Note that $S_3 \cong D_3$, the rigid symmetries of an equilateral triangle. We have three reflections over each axis and rotations by $\frac{2\pi}{3}$ and $\frac{4\pi}{3}$.

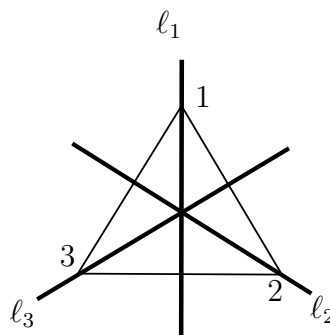


Figure 2: D_3

As isomorphisms of \mathbb{R}^2 we have

$$S_3 \cong D_3 \cong \left\{ I_2, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix} \right\}$$

Since rotations of \mathbb{R}^2 are parametrized by $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$.

D_n is the group of rigid rotations of a regular n -gon. Note that $D_n \hookrightarrow S_n$ and $|D_n| = 2n$.

MATRIX OPERATIONS

History