

$$\begin{cases} \bar{F}(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases} \rightarrow \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$

$$J = \frac{\partial(\bar{F}, G)}{\partial(u, v)} = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}$$

$$\bar{F}(x, y) = 0$$

$$\frac{dy}{dx} = - \frac{F_x}{F_y}$$

公式法

$$\begin{aligned} \frac{\partial u}{\partial x} &= -\frac{1}{J} \frac{\partial(\bar{F}, G)}{\partial(y, v)} = -\frac{1}{J} \begin{vmatrix} F_x & F_v \\ G_x & G_v \end{vmatrix} & \bar{F}(x, y, z) = 0 \\ \frac{\partial u}{\partial y} &= -\frac{1}{J} \frac{\partial(\bar{F}, G)}{\partial(x, v)} = -\frac{1}{J} \begin{vmatrix} F_y & F_v \\ G_y & G_v \end{vmatrix} & \frac{\partial z}{\partial x} = - \frac{F_x}{F_z} \\ \frac{\partial v}{\partial x} &= -\frac{1}{J} \frac{\partial(\bar{F}, G)}{\partial(u, x)} = -\frac{1}{J} \begin{vmatrix} F_u & F_x \\ G_u & G_x \end{vmatrix} & \frac{\partial z}{\partial y} = - \frac{F_y}{F_z} \\ \frac{\partial v}{\partial y} &= -\frac{1}{J} \frac{\partial(\bar{F}, G)}{\partial(u, y)} = -\frac{1}{J} \begin{vmatrix} F_u & F_y \\ G_u & G_y \end{vmatrix} \end{aligned}$$

直接法:

$$\text{对 } \begin{cases} \bar{F}(x, y, u(x, y), v(x, y)) = 0 \\ G(x, y, u(x, y), v(x, y)) = 0 \end{cases} \text{ 两边关于 } x \text{ 求偏导}$$

$$\begin{cases} \bar{F}'_1 \cdot 1 + \bar{F}'_2 \cdot 0 + \bar{F}'_3 \cdot \frac{\partial u}{\partial x} + \bar{F}'_4 \cdot \frac{\partial v}{\partial x} = 0 \\ G'_1 \cdot 1 + G'_2 \cdot 0 + G'_3 \cdot \frac{\partial u}{\partial x} + G'_4 \cdot \frac{\partial v}{\partial x} = 0 \end{cases}$$

$$\begin{cases} \bar{F}'_3 X_1 + \bar{F}'_4 X_2 = -\bar{F}'_1 \\ G'_3 X_1 + G'_4 X_2 = -G'_1 \end{cases}$$

由克拉默法则.

$$X_1 = \frac{D_1}{D} = \frac{\begin{vmatrix} -\bar{F}'_1 & \bar{F}'_4 \\ -G'_1 & G'_4 \end{vmatrix}}{\begin{vmatrix} \bar{F}'_3 & \bar{F}'_4 \\ G'_3 & G'_4 \end{vmatrix}} = -\frac{1}{J} \frac{\partial(\bar{F}, G)}{\partial(x, v)}$$

微分法:

$$\begin{cases} dF(x, y, u, v) = 0 \\ dG(x, y, u, v) = 0 \end{cases}$$

$$\begin{cases} F'_1 dx + F'_2 dy + F'_3 \overset{x_1}{du} + F'_4 \overset{x_2}{dv} = 0 \\ G'_1 dx + G'_2 dy + G'_3 \overset{x_1}{du} + G'_4 \overset{x_2}{dv} = 0 \end{cases} \Rightarrow \begin{matrix} du = (-F'_3 - F'_4 \frac{dv}{du}) \\ dv = (-G'_3 - G'_4 \frac{dv}{du}) \end{matrix}$$

例1

$$\begin{cases} F(x, u, v) = 0 \\ G(x, u, v) = 0 \end{cases} \rightarrow \begin{cases} u = u(x) \\ v = v(x) \end{cases} \quad \text{则} \frac{du}{dx}, \frac{dv}{dx}$$

$$J = \frac{\partial(F, G)}{\partial(u, v)} = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}$$

$$\frac{du}{dx} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)} \quad \frac{dv}{dx} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, u)}$$

例2

$$\begin{cases} F(x, y, u, v, w) = 0 \\ G(x, y, u, v, w) = 0 \\ H(x, y, u, v, w) = 0 \end{cases} \rightarrow \begin{cases} u = u(x, y) \\ v = v(x, y) \\ w = w(x, y) \end{cases} \quad \text{则} \frac{\partial w}{\partial y}$$

$$J = \frac{\partial(F, G, H)}{\partial(u, v, w)} = \begin{vmatrix} F_u & F_v & F_w \\ G_u & G_v & G_w \\ H_u & H_v & H_w \end{vmatrix}$$

$$\frac{\partial w}{\partial y} = -\frac{1}{J} \frac{\partial(F, G, H)}{\partial(x, v, y)} = -\frac{1}{J} \begin{vmatrix} \vdots & \vdots & F_y \\ \vdots & \vdots & G_y \\ \vdots & \vdots & H_y \end{vmatrix}$$

例3

$$\begin{cases} x + y + z = 0 \\ x^2 + y^2 + z^2 = 1 \end{cases} \rightarrow \begin{cases} x = x(z) \\ y = y(z) \end{cases} \quad \text{则} \frac{dx}{dz}, \frac{dy}{dz}$$

解: ① 法: 代入法
 $F(x, y, z) = x + y + z$
 $G(x, y, z) = x^2 + y^2 + z^2 - 1$

解: $F(x, y, z) = x + y + z$
 $G(x, y, z) = x^2 + y^2 + z^2 - 1$

$$J = \frac{\partial (F, G)}{\partial (x, y)} = \begin{vmatrix} F_x & F_y \\ G_x & G_y \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 2x & 2y \end{vmatrix} = 2(y-x)$$

$$\begin{aligned} \frac{dx}{dz} &= -\frac{1}{J} \frac{\partial (F, G)}{\partial (z, y)} = -\frac{1}{z(y-x)} \begin{vmatrix} F_z & F_y \\ G_z & G_y \end{vmatrix} \\ &= -\frac{1}{z(y-x)} \cdot \begin{vmatrix} 1 & 1 \\ 2z & 2y \end{vmatrix} = -\frac{y-z}{y-x} \end{aligned}$$

$$\frac{dy}{dz} = - \frac{1}{2(y-x)} \frac{\partial(F, G)}{\partial(x, z)} = - \frac{1}{2(y-x)} \begin{vmatrix} 1 & 1 \\ 2x & 2z \end{vmatrix}$$

$$= - \frac{z-x}{y-x}$$

含有 x, y, z

②法: 由 $x+y+z=0$ 可得 $x = -y-z$ 代入

$$(-y-z)^2 + y^2 + z^2 - 1 = 0 \quad \text{Für } (y, z) = 0 \text{ nicht } y = y(z)$$

则 $\frac{dy}{dz} = - \frac{F_z(y, z)}{F_y(y, z)}$ (含 y, z)

例. $u = f(x, y, xyz)$ $z = z(x, y)$ 由. 特值法:
 (z, xyz)

$$\int_{xy}^z g(xy+z-t) dt = e^{xyz} \int_{xy}^z (xy+z-t) dt = e^{xyz}$$

$$\text{例 } x \frac{\partial u}{\partial x} - y \frac{\partial u}{\partial y} = \underline{x f_1' - y f_2'}$$

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$$\text{解: } \frac{\partial u}{\partial x} = f_1' \cdot 1 + f_2' \cdot 0 + \underbrace{f_3' \cdot y (1 \cdot z)} + \underbrace{x \cdot \frac{\partial z}{\partial x}}$$

$$\frac{\partial u}{\partial y} = f_1' \cdot 0 + f_2' \cdot 1 + \underbrace{f_3' \cdot x (1 \cdot z)} + \underbrace{y \cdot \frac{\partial z}{\partial y}}$$

$$x \frac{\partial u}{\partial x} - y \frac{\partial u}{\partial y} = x f_1' - y f_2' + x y f_3' \left(\underbrace{x \frac{\partial z}{\partial x} - y \frac{\partial z}{\partial y}}_{=0} \right)$$

$$\bar{F}(x, y, z) = \int_{xy}^z g(xy+z-t) dt - e^{xyz} \stackrel{=0}{=} \text{则 } \frac{\partial z}{\partial x} = \dots$$

$$\frac{\partial z}{\partial x} = - \frac{F_x}{F_y}$$

$$\frac{\partial}{\partial z} \int_{xy}^z g(xy+z-t) dt$$

$$\frac{d}{dx} \left[\int_{a(x)}^{b(x)} \underbrace{f(t)}_{c(x)f(t)} dt \right] = f[b(x)] \cdot b'(x) - f[a(x)] \cdot a'(x)$$

$$\int_{xy}^z g(xy+z-t) dt \quad \begin{matrix} \text{变量} & \text{变量} \\ s = xy+z-t \end{matrix} \quad \int_z^{xy} g(s) d(xy+z-\underline{s})$$

$$= - \int_z^{xy} g(s) ds = \int_{xy}^z g(s) ds$$

$$\bar{F}(x, y, z) = \int_{xy}^z g(s) ds - e^{xyz} = 0$$

$$x \bar{F}_x = -g(xy) \cdot y - e^{xyz} \cdot yz$$

$$y \bar{F}_y = -g(xy) \cdot x - e^{xyz} \cdot xz$$

$$f_z$$

$$x \frac{\partial z}{\partial x} - y \frac{\partial z}{\partial y} = - \frac{x f_x - y f_y}{f_z}$$