

# Khang M. Nguyen

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## RESEARCH INTERESTS

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Robotic Grasping, Robot Perception, Cognitive Architecture.

## EDUCATION

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### University of Texas at Arlington

August 2020 – May 2024

B.Sc. (Hons.) in Computer Science, Minor in Bioengineering & Mathematics

Arlington, TX

**Cumulative GPA:** 3.82/4.00    **Major GPA:** 3.90/4.00    **Dean's List:** 5 semesters from Spring 2021 to Spring 2023.

**Coursework:** Advanced Linear Algebra, Algorithms & Data Structures, Artificial Intelligence, Autonomous Robots, Computer Vision, Engineering Probability & Statistics, Machine Learning, Medical Imaging, Multivariable Calculus, Neural Networks & Deep Learning, Signal Processing, Statistical Inference, Operating Systems, and Unmanned Vehicle Systems.

**Thesis:** In-progress    **Advisor:** Dr. Manfred Huber

## RESEARCH ACTIVITIES

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### Conference Proceedings:

- [5] **K. Nguyen**, T. Dang, and M. Huber. "Online 3D Deformable Object Classification for Mobile Cobot Manipulation". In *Proceedings of the International Symposium on Robotics (ISR)*, Stuttgart, Germany, September 2023.  
▷ [Paper](#) | [Code](#) | [Demo](#)
- [4] T. Dang, **K. Nguyen**, and M. Huber. "Multiplanar Self-Calibration for Mobile Cobot 3D Object Manipulation using 2D Detectors and Depth Estimation". In *Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Detroit, MI, October 2023.  
▷ [Paper](#) | [Code](#) | [Demo](#)
- [3] T. Dang, **K. Nguyen**, and M. Huber. "*ExtPerFC*: An Efficient 2D and 3D Perception Software-Hardware Framework for Mobile Cobot". *arXiv*, June 2023.  
▷ [Paper](#) | [Code](#) | [Demo](#)
- [2] T. Dang, **K. Nguyen**, and M. Huber. "*PerFC*: An Efficient 2D and 3D Perception Software-Hardware Framework for Mobile Cobot". In *Proceedings of the International FLAIRS Conference (FLAIRS)*, Clearwater Beach, FL, May 2023.  
▷ [Paper](#) | [Code](#) | [Demo](#)
- [1] T. Dang, T. Tran, **K. Nguyen**, T. Pham, N. Pham, T. Vu, and P. Nguyen. "*IoTree*: A Battery-free Wearable System with Biocompatible Sensors for Continuous Tree Health Monitoring". In *Proceedings of the ACM International Conference on Mobile Computing and Networking (MobiCom)*, Sydney, NSW, Australia, October 2022.  
▷ [Paper](#) | [Code](#) | [Demo](#)

### Abstracts & Poster Presentations:

- [2] **K. Nguyen** and W.J. Beksi. "An Autonomous Indoor Personal Robot with Real-Time Object Detection" at *the Annual UTA Innovation Day*, Arlington, TX, April 2023.  
▷ [Poster](#) | [Code](#)
- [1] H. Affleck, **K. Nguyen**, K. Brown, and Y. Liao. "The Use of Social Media Advertisements to Recruit a Diverse Sample of Hispanic and Black Women for a Virtual Focus Group Study" at *the American Public Health Association Annual Meeting and Expo (APHA)*, Boston, MA, December 2022.

### Conference Reviewing:

- *The 19th IEEE International Conference on Automation Science and Engineering (CASE '23)*.
- *The 20th IEEE International Conference on Ubiquitous Robots (UR '23)*.

### Professional Affiliations:

- *IEEE Member* (2023 – Present)
- *ACM Member* (2023 – Present)

## RESEARCH EXPERIENCE

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### Learning and Adaptive Robotics Lab

August 2022 – Present

Undergraduate Research Assistant

Arlington, TX

### Robotic Vision Lab

October 2022 – May 2023

Undergraduate Research Assistant

Arlington, TX

### Wireless and Sensor Systems Lab

August 2021 – August 2022

Undergraduate Research Assistant

Arlington, TX

## OUTREACH ACTIVITIES

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<b>UTA Senior Design Team</b> Team Leader	September 2023 – Present Arlington, TX
<b>HackMIT Hackathon</b> Participant	October 2022 Boston, MA
<b>GaTech IEEE RoboTech Hackathon</b> Team Leader/Participant	April 2022 Atlanta, GA
<b>Wolfram High School Summer Research Program</b> Participant	June 2019 – July 2019 Boston, MA

## TEACHING EXPERIENCE

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<b>OurCS@DFW Workshop: <u>CPS-Health</u></b>	February 2022
<b>UTA Department of Mathematics</b>	February 2022 – May 2022

## ACADEMIC AWARDS & HONORS

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<b>UTA Research Experiences for Undergraduates Sponsorship</b> Sponsored by UTA COE and UTA Robotic Vision Lab	October 2022
<b>Sponsorship Award for Assistive Technologies at HackMIT</b>	October 2022
<b>Top 8 of GaTech IEEE RoboTech Hackathon</b>	April 2022
<b>2nd Prize in Body Track &amp; 3rd Prize in Electrical Track</b> Awarded by GT IEEE RoboTech Hackathon Committee	April 2022
<b>UTA Freshman Distinction Roll Recognition Recipient</b>	December 2020
<b>UTA Maverick Academic Scholarship Recipient</b>	August 2020
<b>AP Scholar with Distinction Recipient</b> Awarded by College Board	July 2020
<b>Honorable Mention of the 14th Geometrical Olympiad in Honor of I. F. Sharygin</b> Ranked 10th over 49 participants in the Final Round	August 2018
<b>Honorable Mention of Singapore Mathematical Olympiad Open</b>	June 2018
<b>Bronze Medal of Vietnamese Mathematical Youth Talent Search</b> Ranked 13th over 198 participants in Grade 10	April 2018
<b>Bronze Ruler of the 4th Iranian Geometrical Olympiad</b> Ranked 4th nationally - Ranked 57th internationally	September 2017
<b>Second Prize of the Municipal Mathematical Competition</b>	March 2017

## TECHNICAL COMPETENCIES

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**Coding & Software:** Python, C/C++, MATLAB, Mathematica, HTML/CSS, JS, Java, and ROS.  
**Designing & Fabrication Tools:** Arduino, SOLIDWORKS, Prusa, Formlabs, NVIDIA Jetson, and Raspberry Pi.

## PROFESSIONAL REFERENCES

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### **Dr. Manfred Huber, Ph. D.**

Professor, Dept. of Computer Science & Engineering  
Director, Learning and Adaptive Robotics Lab  
The University of Texas at Arlington  
huber@cse.uta.edu

### **Dr. William Beksi, Ph. D.**

Assistant Professor, Dept. of Computer Science & Engineering  
Director, Robotic Vision Lab  
The University of Texas at Arlington  
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### **Dr. Vassilis Athitsos, Ph. D.**

Professor, Dept. of Computer Science & Engineering  
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### **Tuan Dang, M. S.**

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*Last updated: November 8, 2023.*