Uncertainties and covariances in an analytical random walk

Andrew R. McCluskey^{1,2,*}

¹European Spallation Source ERIC, P.O. Box 176, SE-221 00, Lund, Sweden ²Department of Chemistry, University of Bath, Claverton Down, Bath, BA2 7AY, UK

I. VARIANCES IN AN ANALYTICAL RANDOM WALK

Here, we derive the variance on the mean-squared displacement (MSD) of random walk, clarifying some aspects from the work of Smith and Gillan [1]. We will consider a single particle, travelling in 1 dimension over time. The particle is displaced by $h = \pm d_1$ (where the subscript 1 is indicative of the dimensionality of the system) in a single hop, where the hops are proportional to the timestep that has elapsed. The MSD of this particle, after n hops, can be described with the following,

$$\langle \mathbf{r}_{1}^{2}(n) \rangle = \left\langle \left[\sum_{i=1}^{n} h_{i} \right]^{2} \right\rangle = \left\langle \sum_{i=1}^{n} \sum_{j=1}^{n} h_{i} h_{j} \right\rangle = \left\langle \sum_{i=1}^{n} h_{i}^{2} \right\rangle + \left\langle \sum_{i=1}^{n} \sum_{j\neq i}^{n} h_{i} h_{j} \right\rangle$$

$$= \sum_{i=1}^{n} \left\langle h_{i}^{2} \right\rangle + \sum_{i=1}^{n} \sum_{j\neq i}^{n} \left\langle h_{i} h_{j} \right\rangle = n d_{1}^{2}.$$

$$(1)$$

In the fourth line above, the cross term double summation (where $j \neq i$) is equal to zero, as the product of h(i)h(j) is d_1^2 and therefore has equal probability of being 1 and -1 so the average must be zero. This shows the linear relationship between timestep and displacement.

The determination of the MSD allows for the derivation of the variance, $\sigma_1^2(n)$ of the MSD for each timestep. This variance can be found with the standard statistical formula,

$$\sigma_1^2(\mathbf{r}_1^2(n)) = \left\langle \left[\mathbf{r}_1^2(n) - \left\langle \mathbf{r}_1^2(n) \right\rangle \right]^2 \right\rangle, \tag{2}$$

which may be expanded and reformulated as,

$$\sigma_1^2(\mathbf{r}_1^2(n)) = \left\langle \left[\mathbf{r}_1^2(n) \right]^2 \right\rangle - 2 \left\langle \mathbf{r}_1^2(n) \right\rangle \left\langle \mathbf{r}_1^2(n) \right\rangle + \left\langle \mathbf{r}_1^2(n) \right\rangle^2 = \left\langle \mathbf{r}_1^4(n) \right\rangle - \left\langle \mathbf{r}_1^2(n) \right\rangle^2, \tag{3}$$

where,

$$\left\langle \mathbf{r}_1^2(n) \right\rangle^2 = \left(n d_1^2 \right)^2 \tag{4}$$

and.

$$\left\langle \mathbf{r}_{1}^{4}(n)\right\rangle = \left\langle \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=1}^{n} h_{i} h_{j} h_{k} h_{l} \right\rangle. \tag{5}$$

The term on the right-hand side of Equation 5 can be simplified substantially, as the four displacements are only uncorrelated when $i \neq j \neq k \neq l$. This leads to four possible conditions that will survive the averaging process,

- (a) i = j = k = l,
- (b) $(i = j) \neq (k = l)$,
- (c) $(i = k) \neq (j = l)$,
- (d) $(i = l) \neq (j = k)$,

 $^{^* \} and rew.mccluskey@ess.eu; a.r.mccluskey@bath.ac.uk\\$

these conditions will ensure a positive product for $h_i h_j h_k h_l$, additionally, the conditions (b), (c) and (d) are equivalent. The result from (a) will be,

$$\left\langle \sum_{i=1}^{n} h_i^4 \right\rangle = nd_1^4,\tag{6}$$

while from (b), (c), and (d) the following is obtained,

$$\left\langle \sum_{i=1}^{n} \sum_{j=1}^{n} h_i^2 h_j^2 \right\rangle = \left(n d_1^2 \right)^2. \tag{7}$$

This allows Equation 5 to be rewritten as,

$$\langle \mathbf{r}_1^4(n) \rangle = nd^4 + 3 \left[\left(nd^2 \right)^2 \right] = nd_1^4 + 3n^2d_1^4 = (3n^2 + n)d_1^4,$$
 (8)

as $n \to \infty$,

$$\left\langle \mathbf{r}_1^4(n) \right\rangle \to 3n^2 d_1^4.$$
 (9)

This means that by combining this with Equation 4 the variance can be determined as,

$$\sigma_1^2(\mathbf{r}_1^2(n)) = 3n^2 d_1^4 - n^2 d_1^4 = 2n^2 d_1^4. \tag{10}$$

From this result, the variance, $\delta(n)^2$, over many independent particles, $N_i(n)$, can be found as,

$$\sigma_{1,i}^2(\mathbf{r}_{1,i}^2(n)) = \frac{2}{N_i(n)} n^2 d_1^4. \tag{11}$$

To convert these one-dimensional results into three-dimensional results (we note that this conversion is generalisable to ν -dimensions), we multiply both the MSD and its variance by 3. Then, we must consider d_3 , which is the sum of three, orthogonal random walks in the x-, y-, and z-directions, so on average is $\sqrt{\langle d_x^2 \rangle + \langle d_y^2 \rangle + \langle d_z^2 \rangle}$ so $1/(\sqrt{3})d_3 = d_1$, therefore,

$$\langle \mathbf{r}_3^2(n) \rangle = 3nd_1^2 = 3n\left(\frac{1}{\sqrt{3}}d_3\right)^2 = nd_3^2,$$
 (12)

and,

$$\sigma_3^2(\mathbf{r}_3^2(n)) = 3(2n^2d_1^4) = 3\left(2n^2\left(\frac{1}{\sqrt{3}}d_3\right)^4\right) = 3\left(\frac{2n^2d_3^4}{9}\right) = \frac{2n^2d_3^4}{3}.$$
 (13)

Therefore the result over N independent trajectories is,

$$\sigma_{3,i}^2(\mathbf{r}_{3,i}^2(n)) = \frac{2n^2 d_3^4}{3N_i(n)}.$$
 (14)

where N_i is the sample size,

$$N_i(\Delta t) = N_{\text{atoms}}(\Delta t) \left[\frac{N_{\text{obs}}(0)}{N_{\text{obs}}(0) - N_{\text{obs}}(\Delta t) + 1} \right], \tag{15}$$

II. EXTENSION TO COVARIANCE MATRIX

Above, it is has been shown how the variance of an MSD after a given number of steps can be defined. Now, we will extend this derivation to show how the covariance is defined similarly. Let's consider two MSD values, after i steps and i + j steps,

$$\langle \mathbf{r}_1^2(n) \rangle = nd_1^2$$

$$\langle \mathbf{r}_1^2(n+m) \rangle = (n+m)d_1^2$$
(16)

The covariance between these values is defined as,

$$\operatorname{cov}\left(\left\langle \mathbf{r}_{1}^{2}(n)\right\rangle, \left\langle \mathbf{r}_{1}^{2}(n+m)\right\rangle\right) = \left\langle \left[\mathbf{r}_{1}^{2}(n) - \left\langle \mathbf{r}_{1}^{2}(n)\right\rangle\right] \left[\mathbf{r}_{1}^{2}(n+m) - \left\langle \mathbf{r}_{1}^{2}(n+m)\right\rangle\right]\right\rangle, \tag{17}$$

which can be expanded and reformulated,

$$\operatorname{cov}\left(\langle \mathbf{r}_{1}^{2}(n)\rangle, \langle \mathbf{r}_{1}^{2}(n+m)\rangle\right) = \left\langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m) - \mathbf{r}_{1}^{2}(n)\langle \mathbf{r}_{1}^{2}(n+m)\rangle - \mathbf{r}_{1}^{2}(n+m)\langle \mathbf{r}_{1}^{2}(n)\rangle + \langle \mathbf{r}_{1}^{2}(n)\rangle\langle \mathbf{r}_{1}^{2}(n+m)\rangle\right) \\
= \langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m)\rangle - \langle \mathbf{r}_{1}^{2}(n)\rangle\langle \mathbf{r}_{1}^{2}(n+m)\rangle, \tag{18}$$

where,

$$\langle \mathbf{r}_1^2(n)\rangle\langle \mathbf{r}_1^2(n+m)\rangle = nd^2(n+m)d^2 = n(n+m)d^4,\tag{19}$$

and by analogy to Equation 5,

$$\left\langle \mathbf{r}_1^2(n)\mathbf{r}_1^2(n+m)\right\rangle = \left\langle \sum_{i=1}^n \sum_{j=1}^n \sum_{k=1}^{n+m} \sum_{l=1}^{n+m} h_i h_j h_k h_l \right\rangle,\tag{20}$$

which we will rewrite as,

$$\langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m)\rangle = \left\langle \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=1}^{n} h_{i}h_{j}h_{k}h_{l} + \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=n+1}^{n+m} h_{i}h_{j}h_{k}h_{l} + \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=n+1}^{n+m} \sum_{l=n+1}^{n+m} h_{i}h_{j}h_{k}h_{l} + \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=n+1}^{n+m} \sum_{l=n+1}^{n+m} h_{i}h_{j}h_{k}h_{l} \right\rangle.$$

$$(21)$$

The second and third terms in Equation 21 tend to 0 due to the equal probability of positive and negative displacements, reducing to,

$$\left\langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m)\right\rangle = \left\langle \sum_{i=1}^{n}\sum_{j=1}^{n}\sum_{k=1}^{n}\sum_{l=1}^{n}h_{i}h_{j}h_{k}h_{l}\right\rangle + \left\langle \sum_{i=1}^{n}\sum_{j=1}^{n}\sum_{k=n+1}^{n+m}\sum_{l=n+1}^{n+m}h_{i}h_{j}h_{k}h_{l}\right\rangle,\tag{22}$$

and using Equation 9 gives,

$$\left\langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m)\right\rangle = 3n^{2}d_{1}^{4} + \left\langle \sum_{i=1}^{n}\sum_{j=1}^{n}\sum_{k=n+1}^{n+m}\sum_{l=n+1}^{n+m}h_{i}h_{j}h_{k}h_{l}\right\rangle. \tag{23}$$

Finally, we rewrite the above as,

$$\langle \mathbf{r}_{1}^{2}(n)\mathbf{r}_{1}^{2}(n+m)\rangle = 3n^{2}d_{1}^{4} + \left\langle \sum_{i=1}^{n} \sum_{j=1}^{n} h_{i}h_{j} \right\rangle \left\langle \sum_{k=n+1}^{n+m} \sum_{l=n+1}^{n+m} h_{k}h_{l} \right\rangle,$$
 (24)

where the following holds,

$$\langle \mathbf{r}_1^2(n)\mathbf{r}_1^2(n+m)\rangle = 3n^2d_1^4 + nd^2md^2 = 3n^2d_1^4 + nmd_1^4.$$
 (25)

Putting this result into Equation 18 allows the covariance to be written as,

$$\operatorname{cov}\left(\langle \mathbf{r}_{1}^{2}(n)\rangle, \langle \mathbf{r}_{1}^{2}(n+m)\rangle\right) = 3n^{2}d_{1}^{4} + nmd_{1}^{4} - n(n+m)d_{1}^{4} = 3n^{2}d_{1}^{4} - n^{2}d_{1}^{4} = 2n^{2}d_{1}^{4},\tag{26}$$

indicating that the covariance depends only on the number of overlapping points, n. This can be rationalised as the steps are random and therefore for any non-overlapping points the covariance must be 0. However, the difference between the variance and the covariance becomes clear when we consider the number of *independent* trajectories to consider, which for the covariance is,

$$\operatorname{cov}_{1,i}\left(\left\langle \mathbf{r}_{1}^{2}(n)\right\rangle, \left\langle \mathbf{r}_{1}^{2}(n+m)\right\rangle\right) = \frac{2}{N_{i}(n+m)} n^{2} d_{1}^{4}, \tag{27}$$

since $N_i(n+m)$ is the minimum number of independent trajectories in both n and n+m. This result extends to three-dimensions identically to the self-timestep uncertainty to give the following for independent trajectories,

$$\operatorname{cov}_{3,i}\left(\left\langle \mathbf{r}_{3}^{2}(n)\right\rangle ,\left\langle \mathbf{r}_{3}^{2}(n+m)\right\rangle \right) = \frac{2n^{2}d_{3}^{4}}{3N_{i}(n+m)} \tag{28}$$

[1] Smith, W. & Gillan, M. J. The Random Walk and the Mean Squared Displacement. Inf. Q. Comput. Simul. Condens. Phases 54–64 (1996).