



电子科技大学  
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# Capsule Neural Network and Discussion on Sync NN

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- Capsule Neural Network
  - Background and Motivation
  - Structure of CapsNet and a demo
  - Experiments
  
- Synchronization Neural Network
  - Background and Motivation
  - Potential ways and Related works



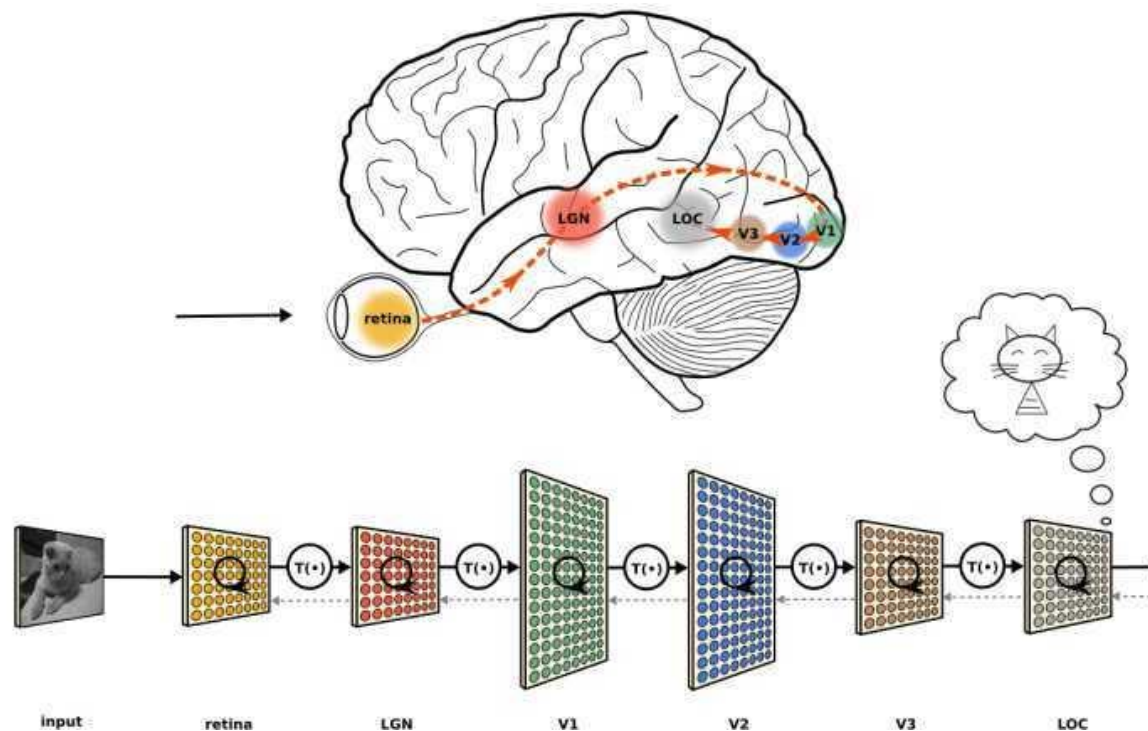
# Capsule Neural Network

# 1.1. Background and Motivation



Hinton's Thinking:

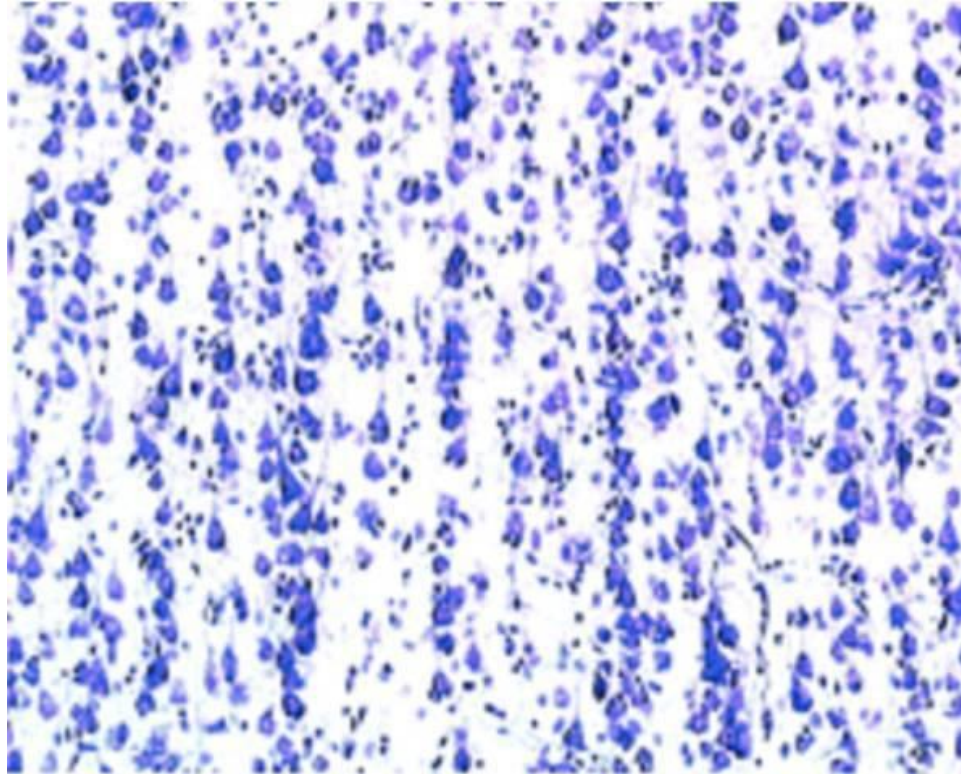
- No BP in the brain
- Fewer layers and slower computing



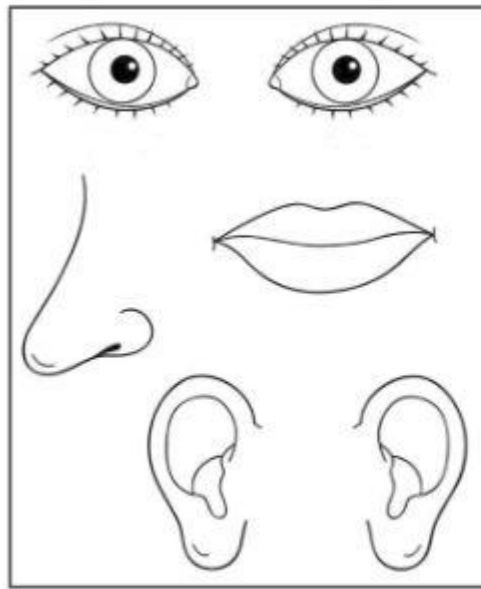
# 1.1. Background and Motivation



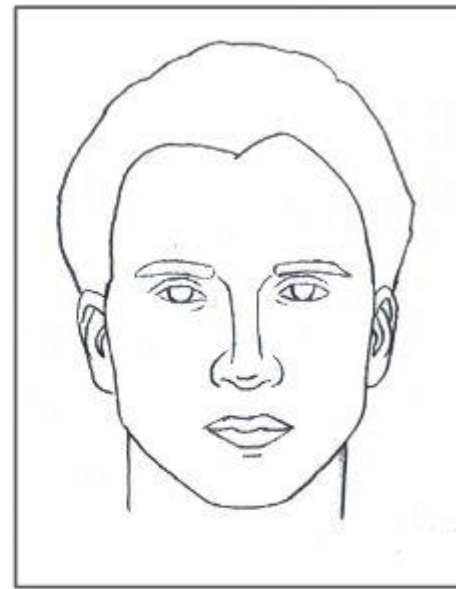
- Cortical minicolumn in the cortex
  - Include hundreds of neuros
  - Internal stratification



- Invariance & Equivariance



Not Face



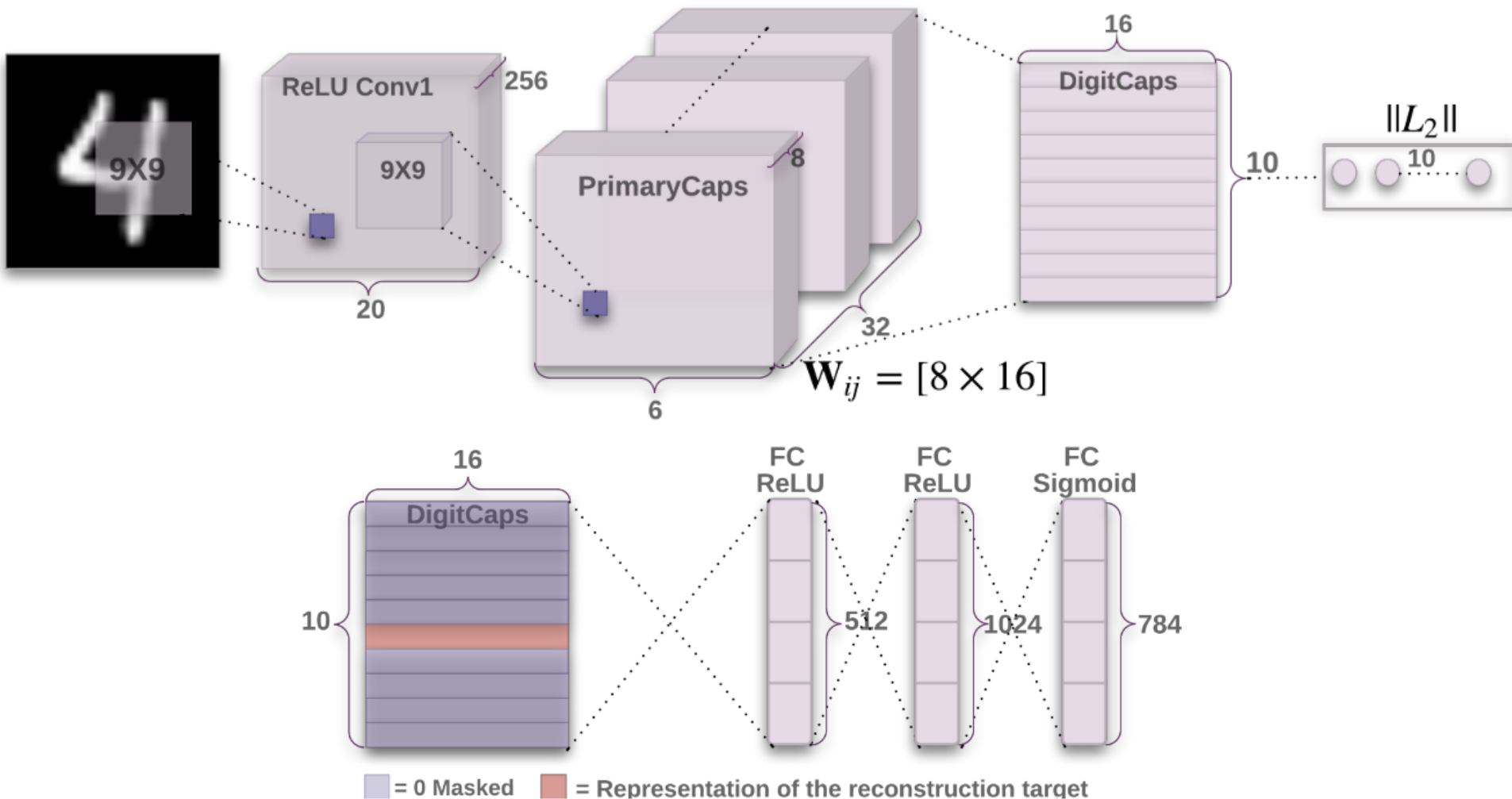
Face

- ‘Routing’ mechanism

# 1.2. Structure of CapsNet



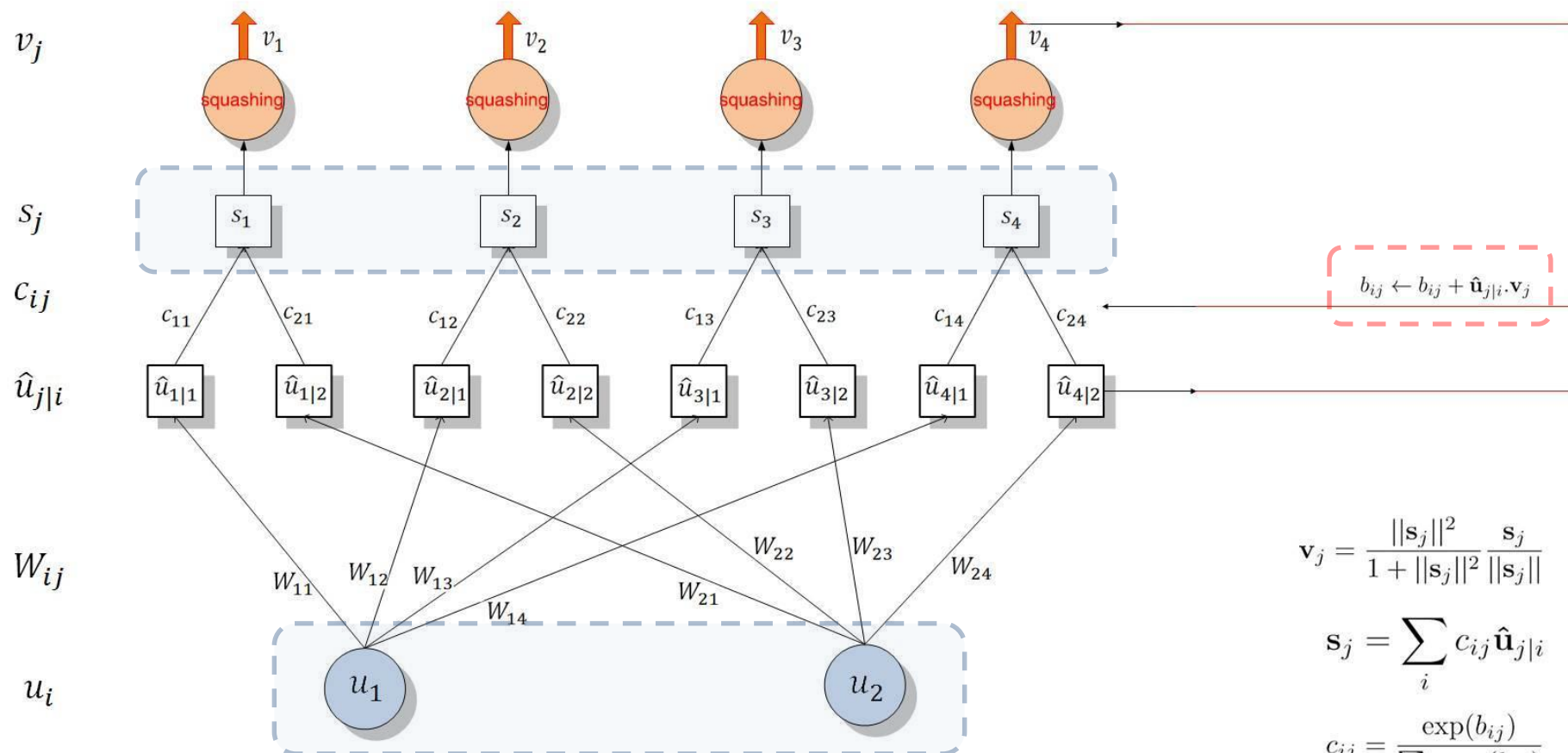
- Capsule: a group of neurons



# 1.2. Structure of CapsNet



- Layer connection



$$\mathbf{v}_j = \frac{\|\mathbf{s}_j\|^2}{1 + \|\mathbf{s}_j\|^2} \frac{\mathbf{s}_j}{\|\mathbf{s}_j\|}$$

$$\mathbf{s}_j = \sum_i c_{ij} \hat{\mathbf{u}}_{j|i}$$

$$c_{ij} = \frac{\exp(b_{ij})}{\sum_k \exp(b_{ik})}$$

$$\hat{u}_{j|i} = W_{ij} u_i$$

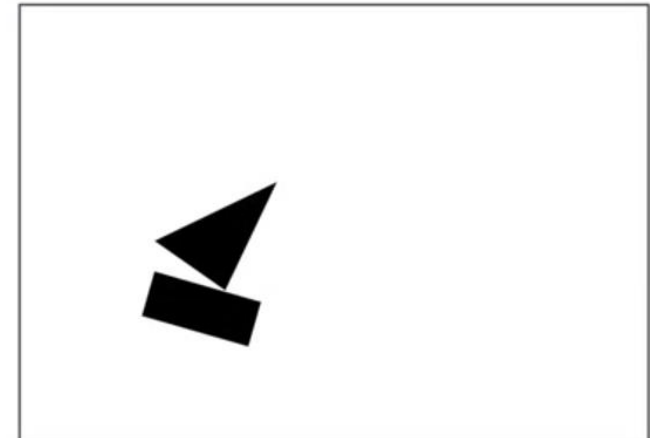
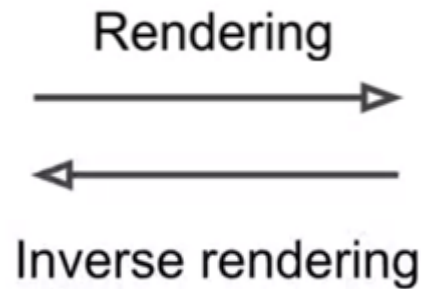


- Representation

Rectangle
x=20 y=30 angle=16°

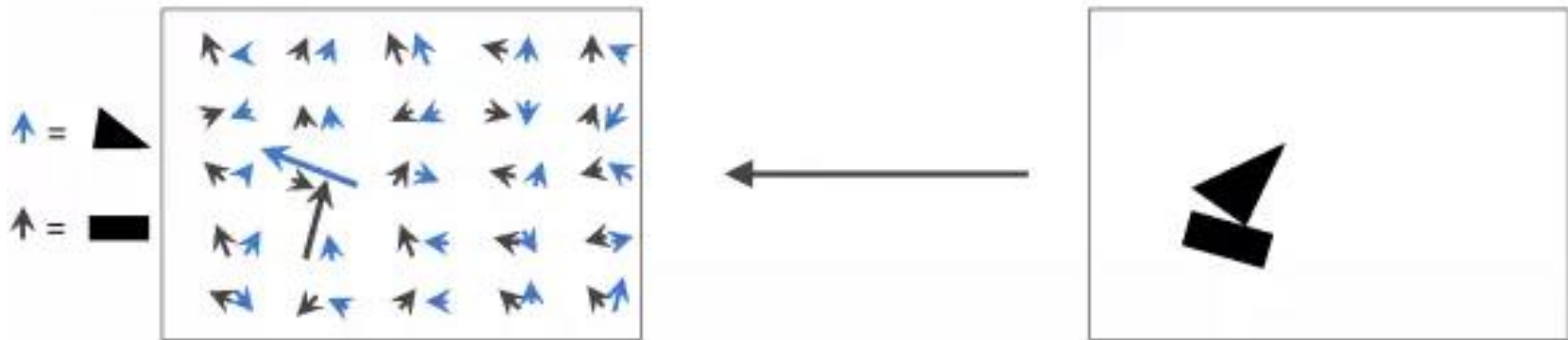
Triangle
x=24 y=25 angle=-65°

Instantiation parameters



Image

- Capsule

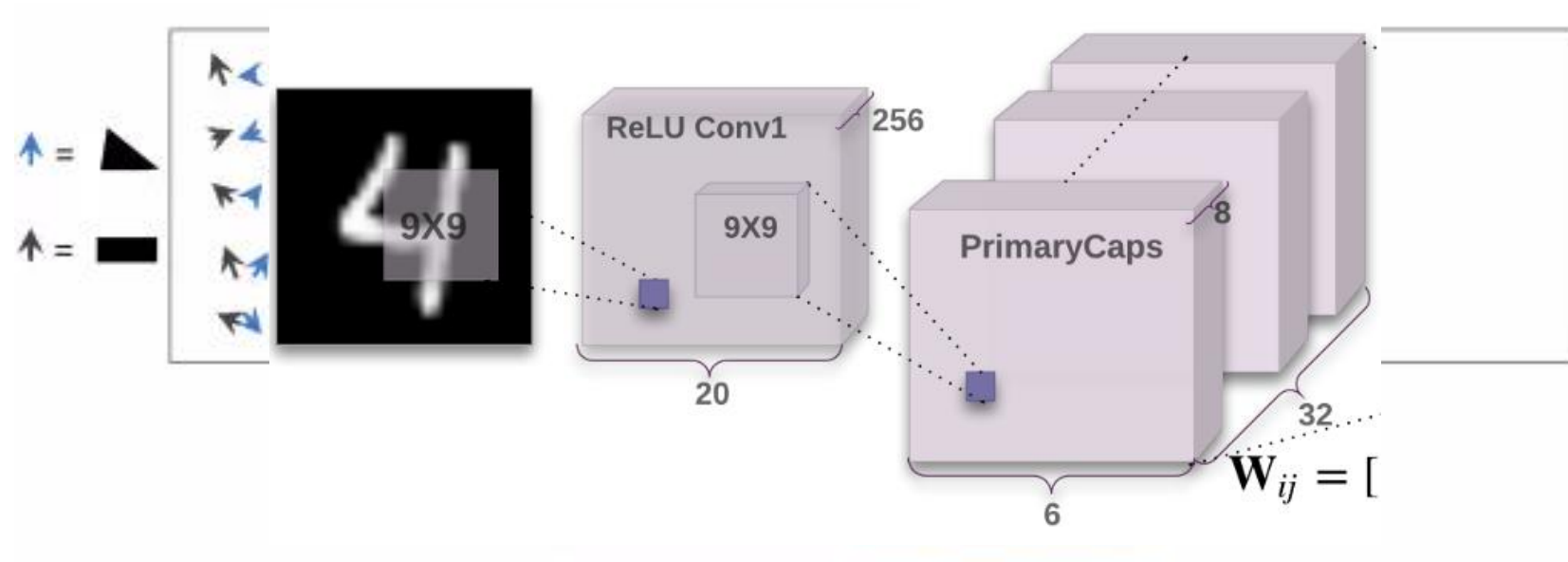


**Activation vector:**

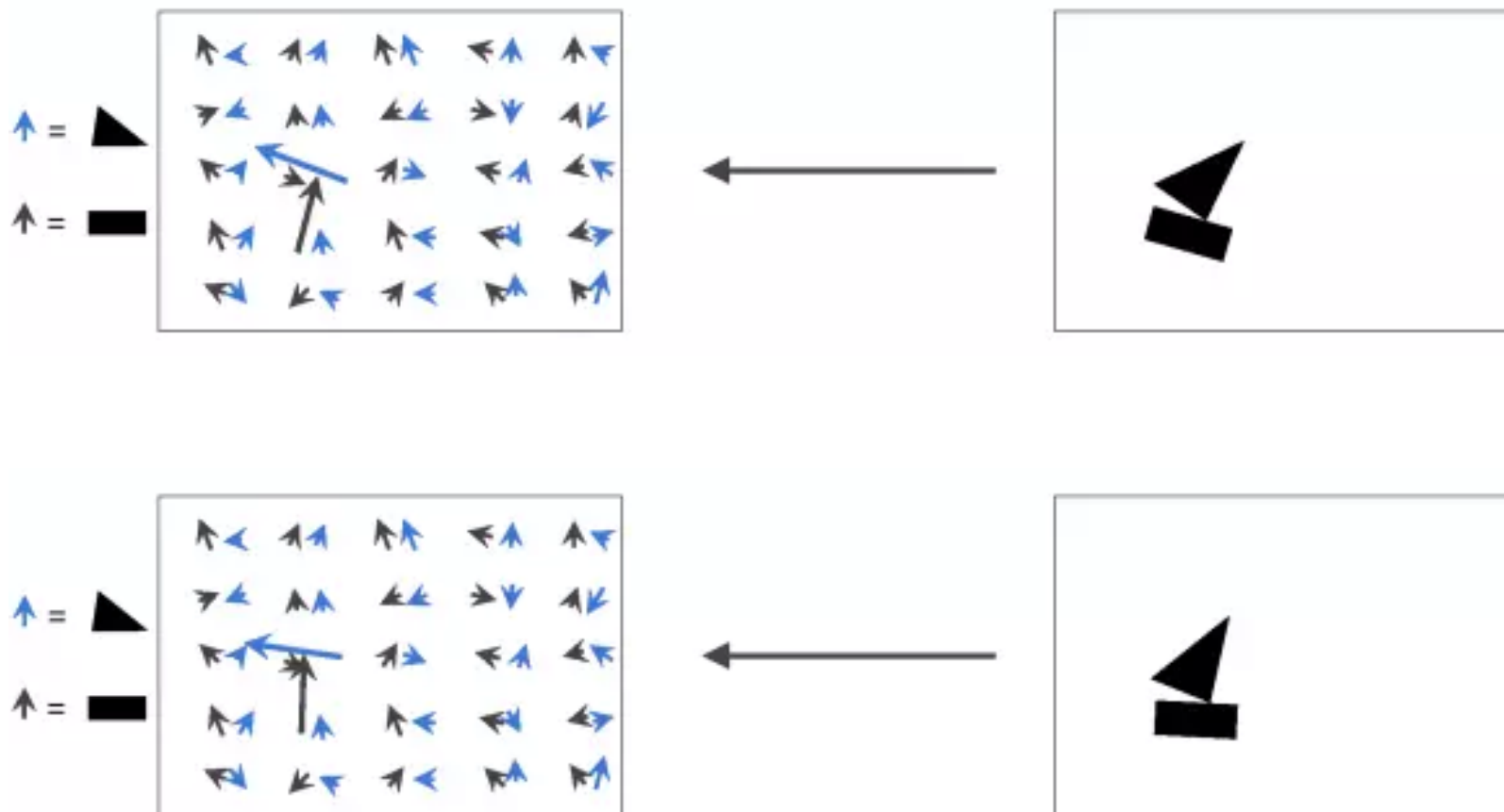
**Length** = estimated probability of presence

**Orientation** = object's estimated pose parameters

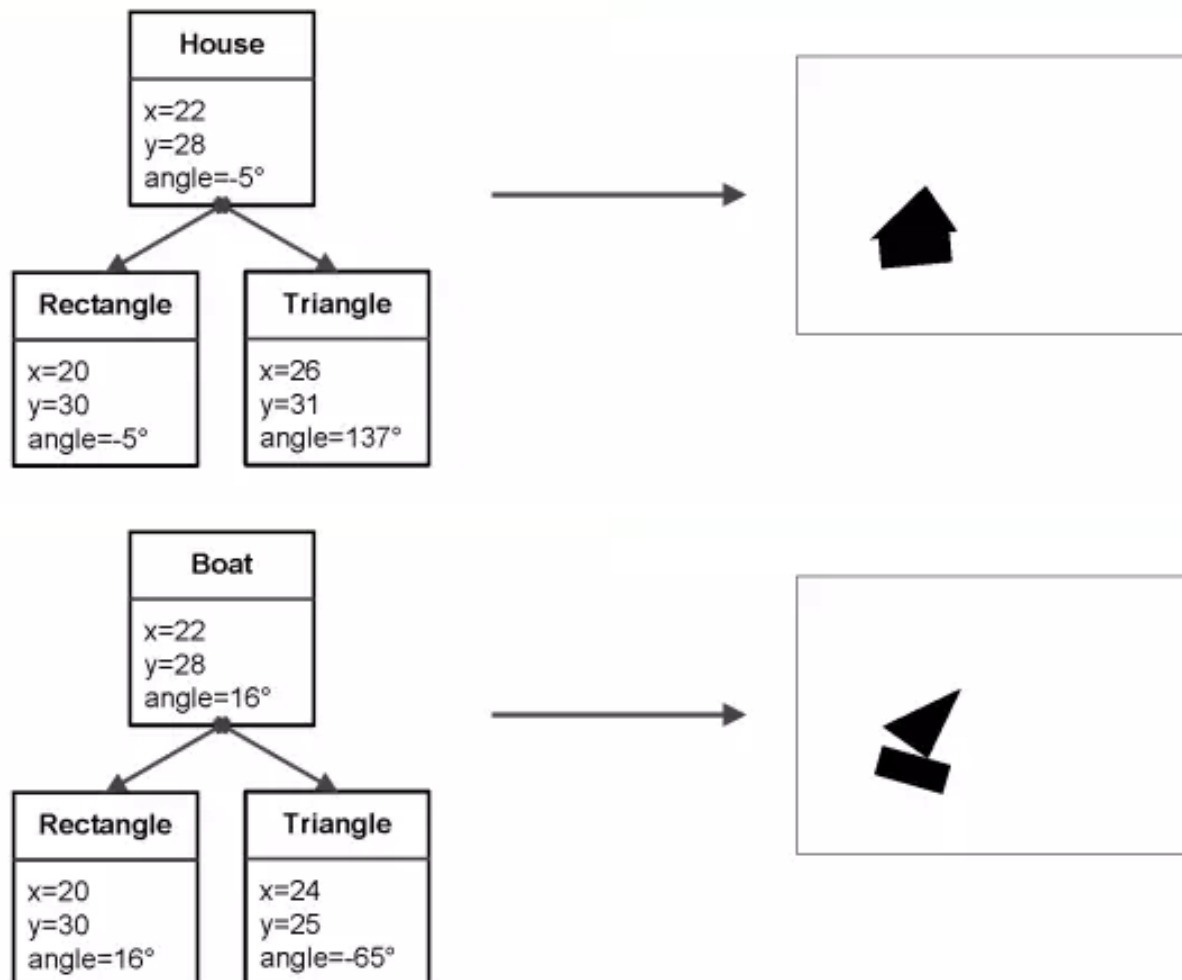
- Capsule



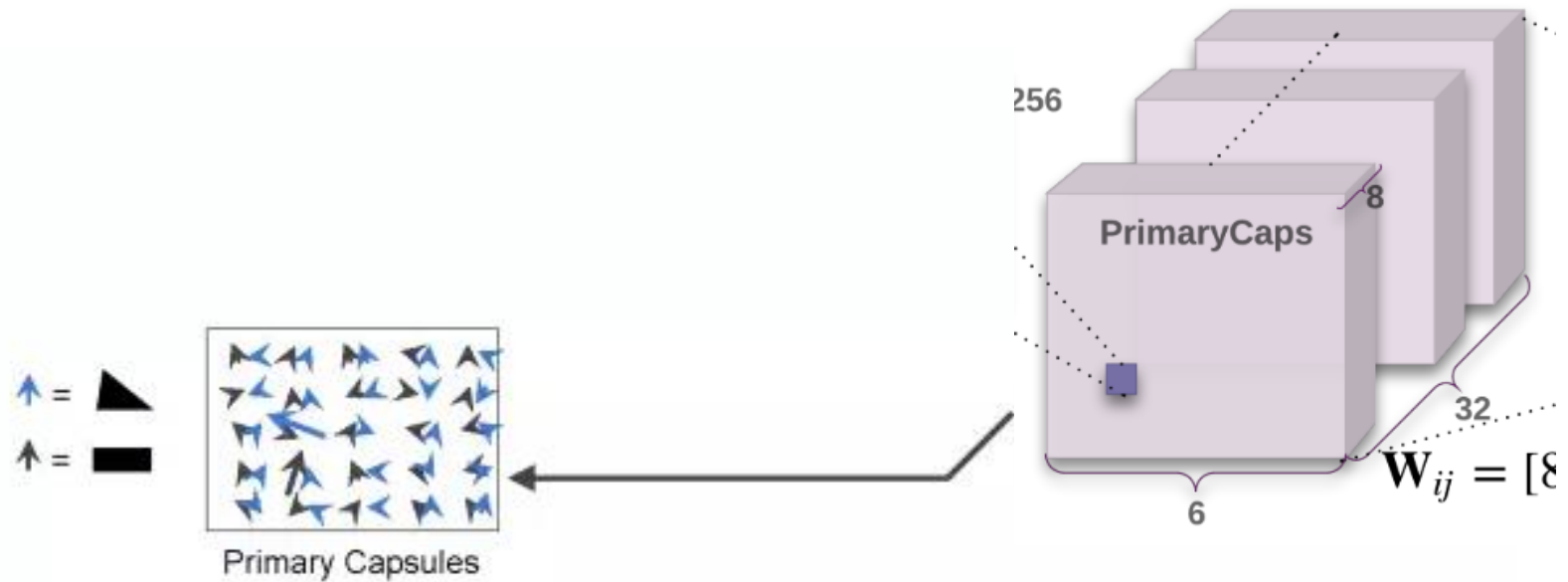
- Equivariance



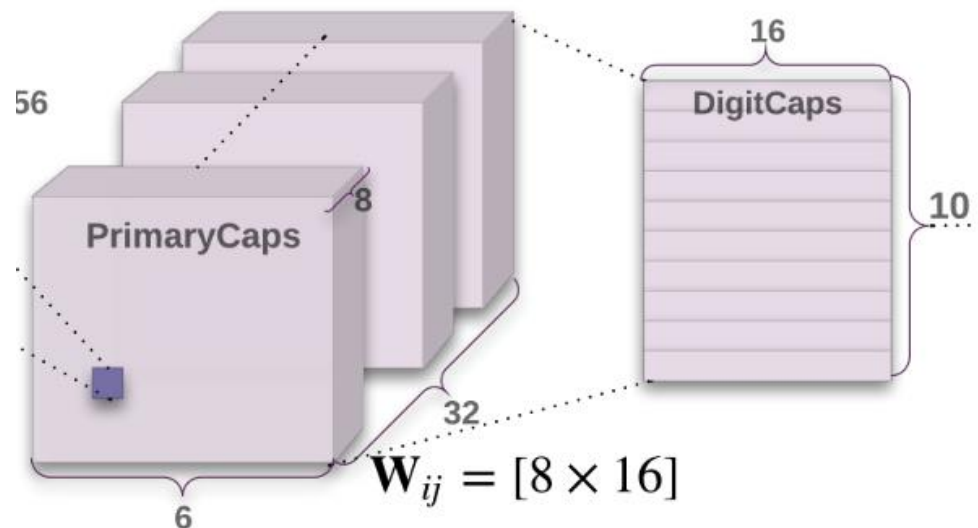
- Hierarchy of parts



- Primary Capsules



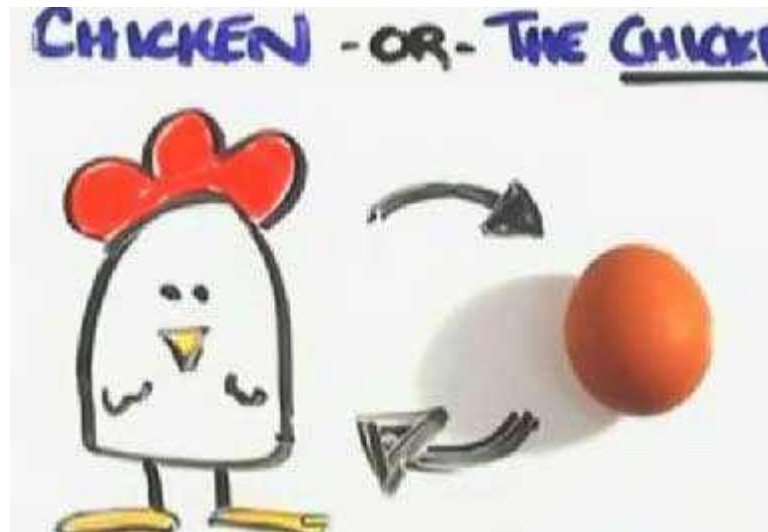
- Predict Next Layer's Output



- Chicken & Egg

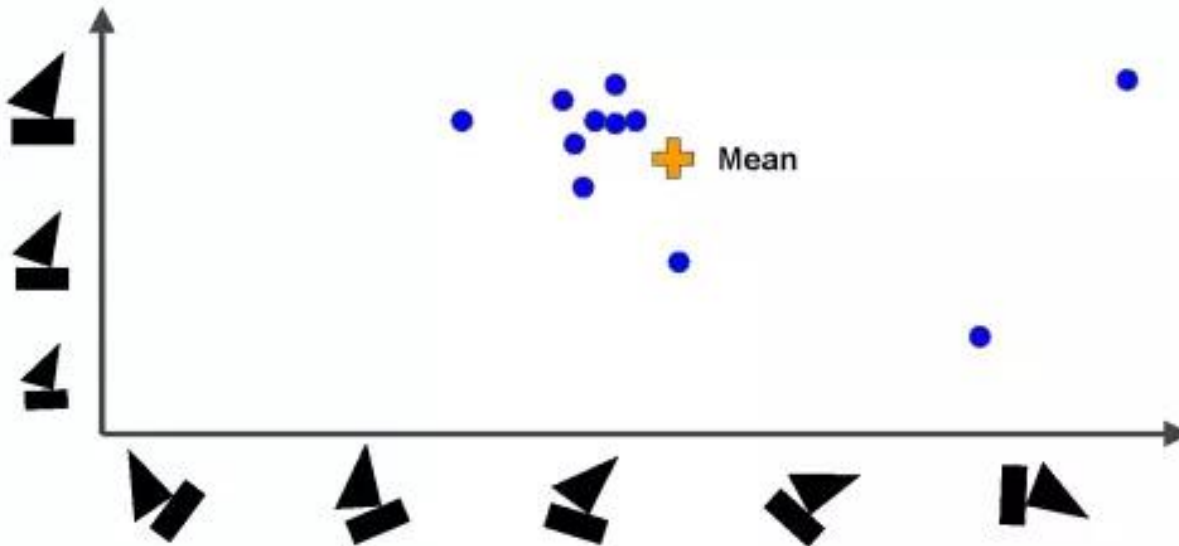
$$\mathbf{s}_j = \sum_i c_{ij} \hat{\mathbf{u}}_{j|i}, \quad \hat{\mathbf{u}}_{j|i} = \mathbf{W}_{ij} \mathbf{u}_i$$

where  $c_{ij}$  is the similarity of  $\mathbf{s}_j$  and  $\mathbf{u}_{j|i}$

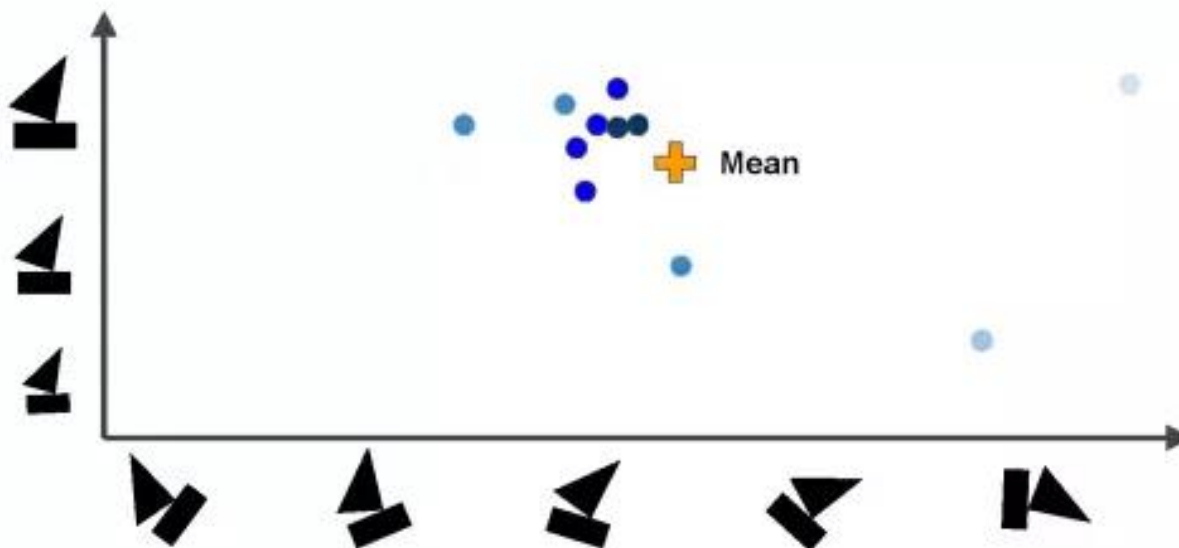




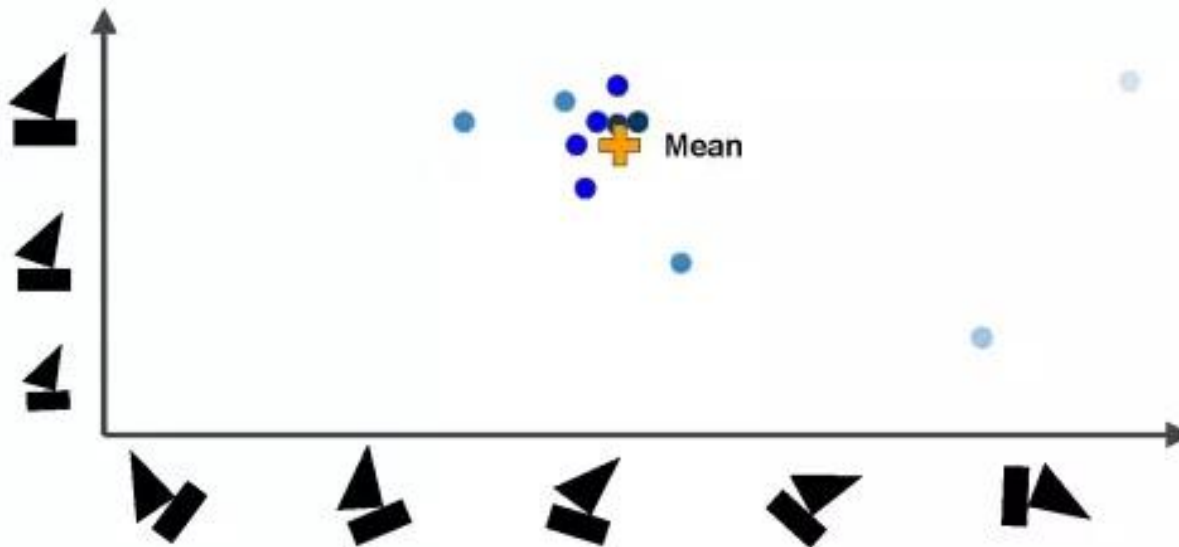
- Clusters of Agreement



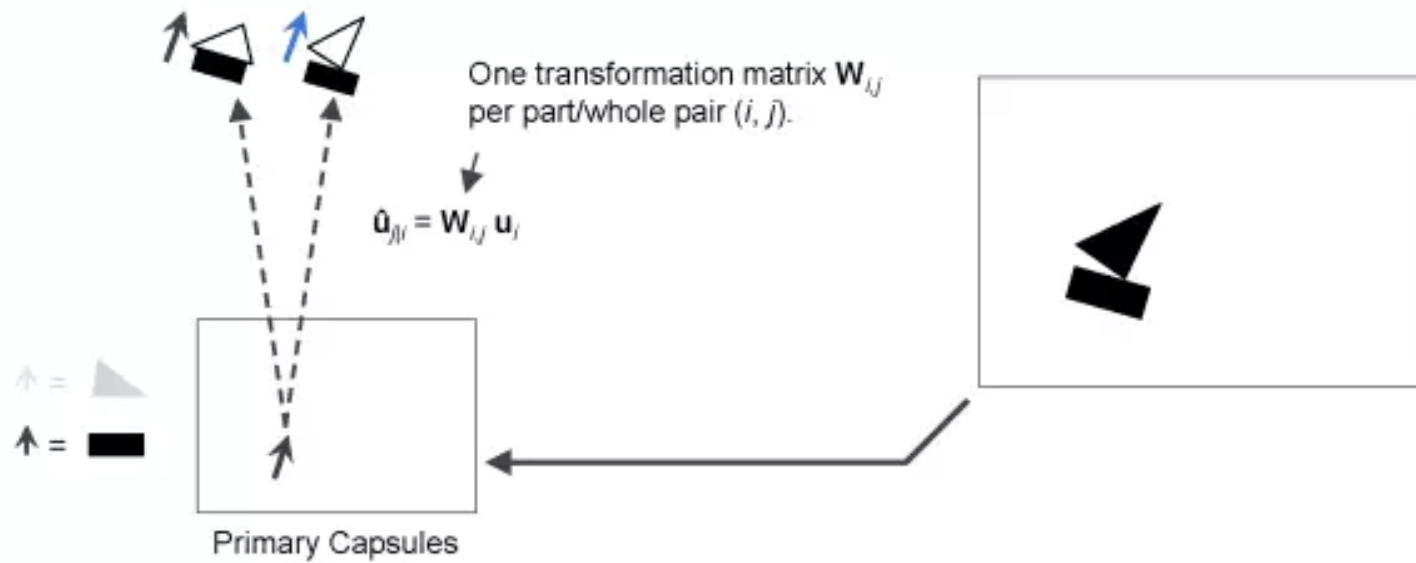
- Clusters of Agreement



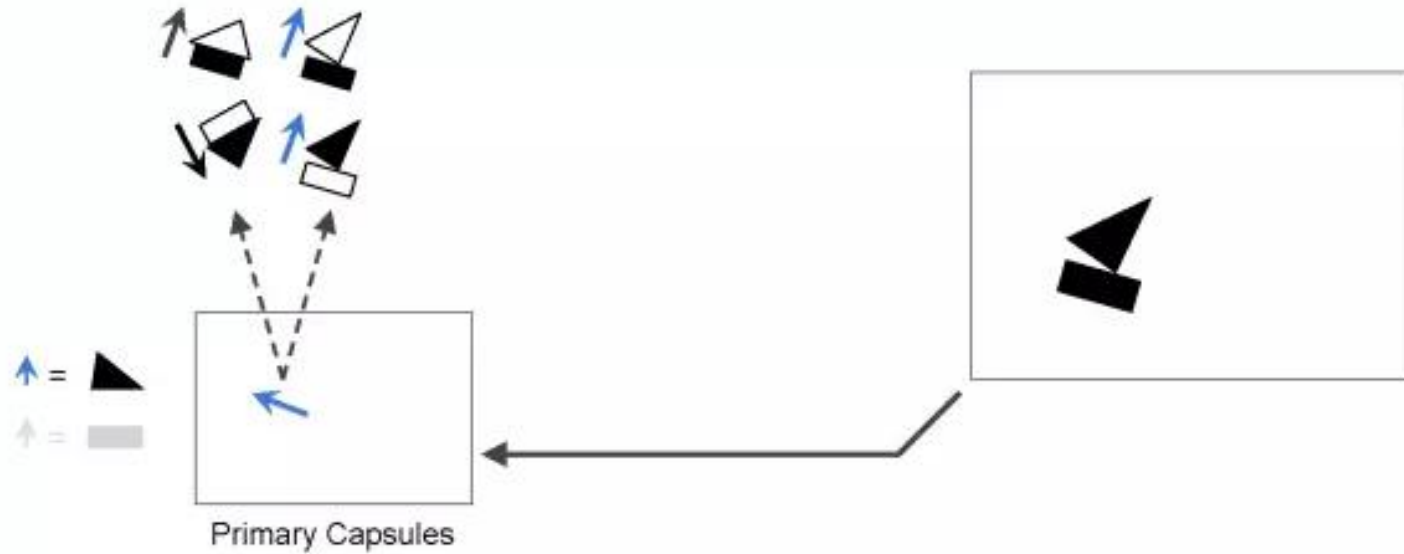
- Clusters of Agreement



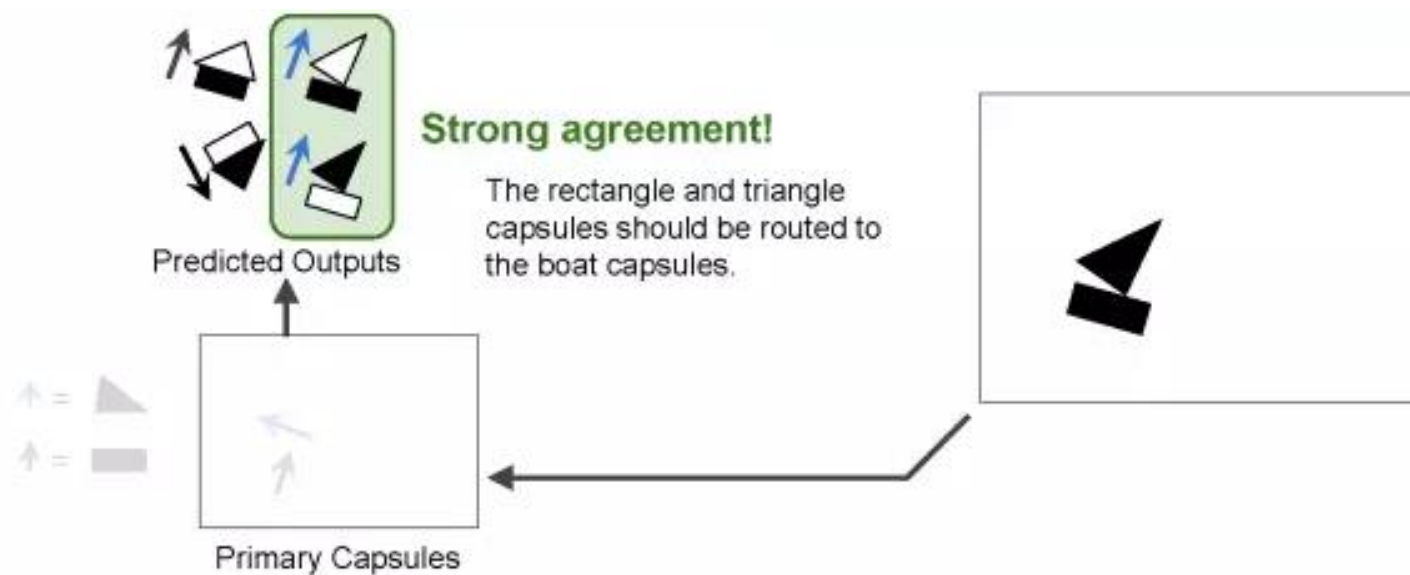
- Predict Next Layer's Output



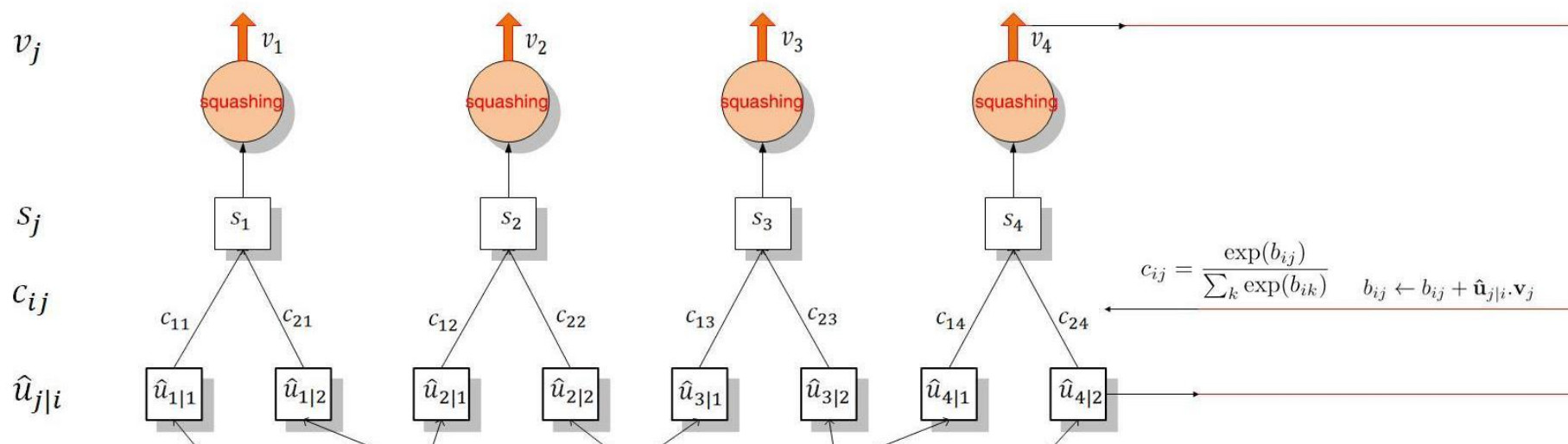
- Predict Next Layer's Output



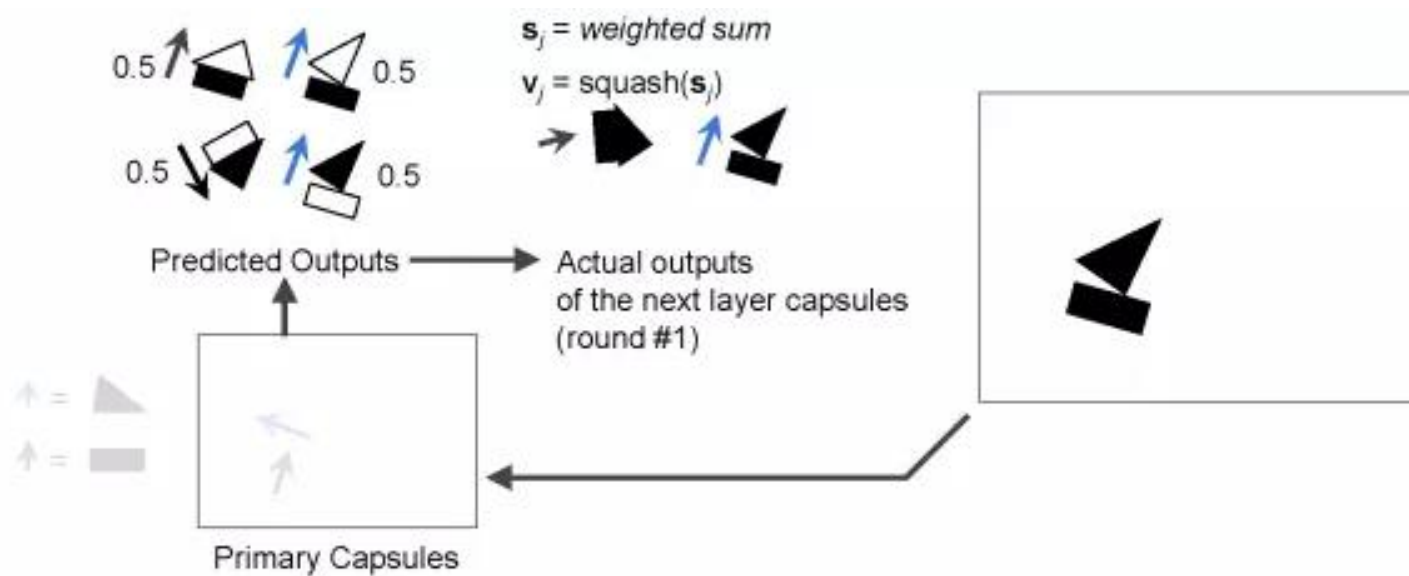
- Routing by Agreement



- Routing Weights

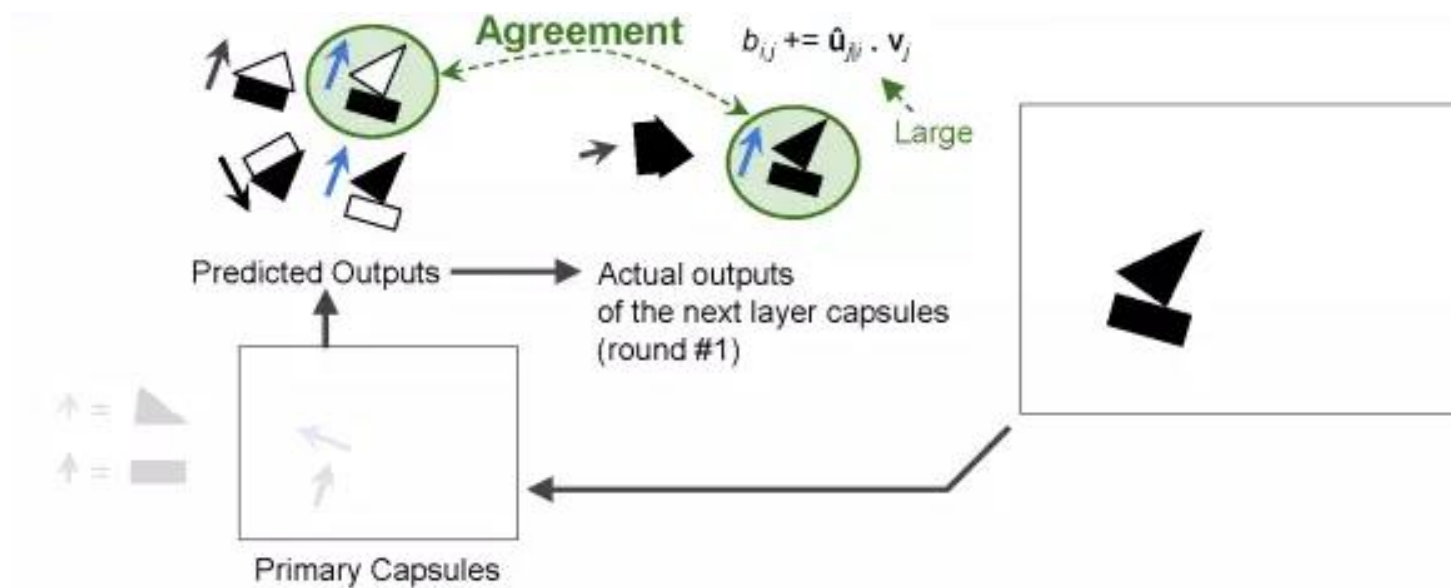


- Compute Next Layer's Output

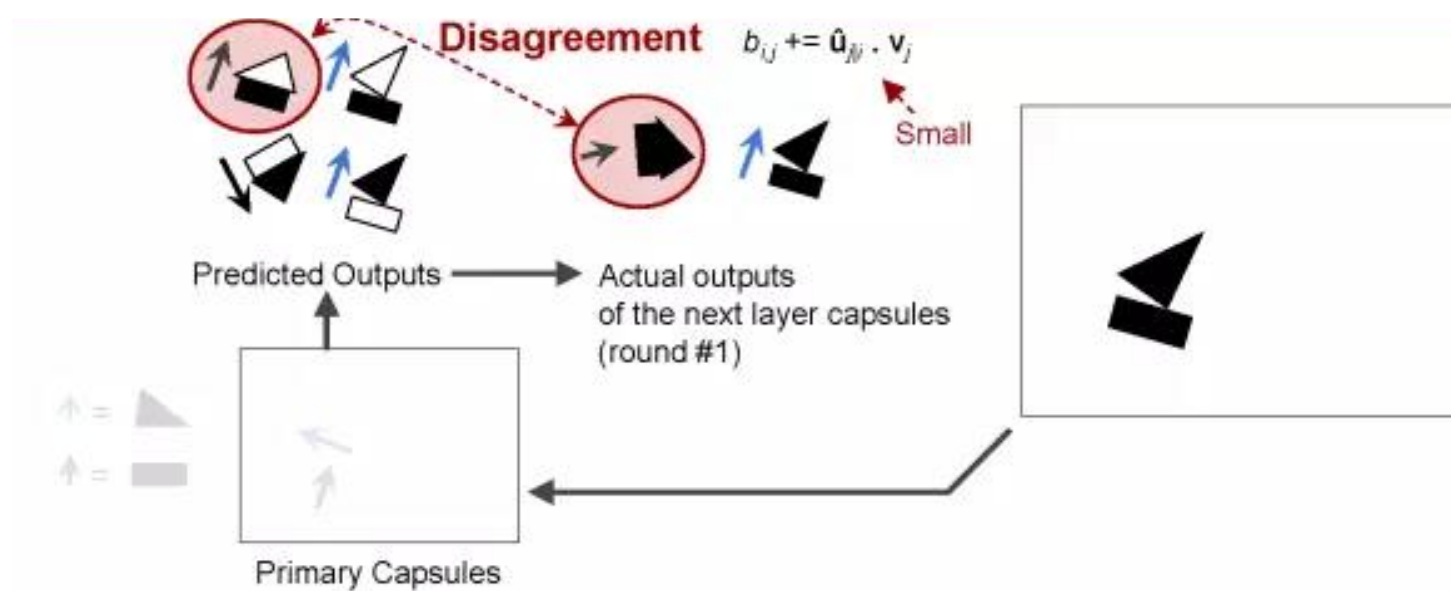




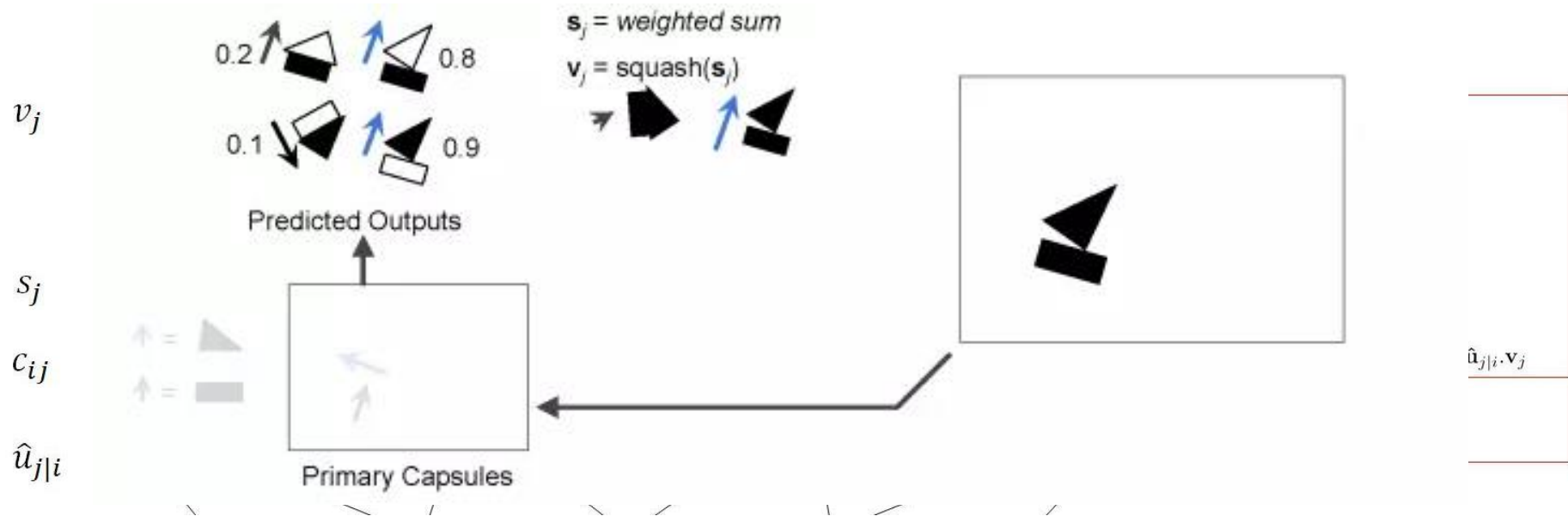
- Update Routing Weights



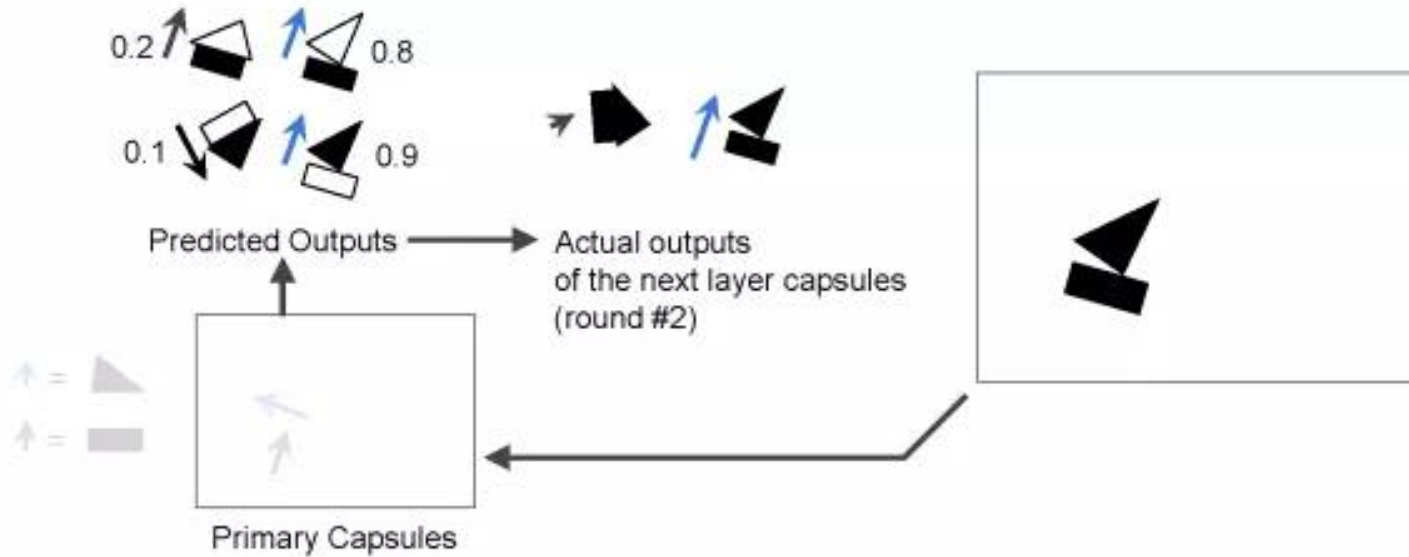
- Update Routing Weights



- Compute Next Layer's Output



- Compute Next Layer's Output



- Routing algorithm

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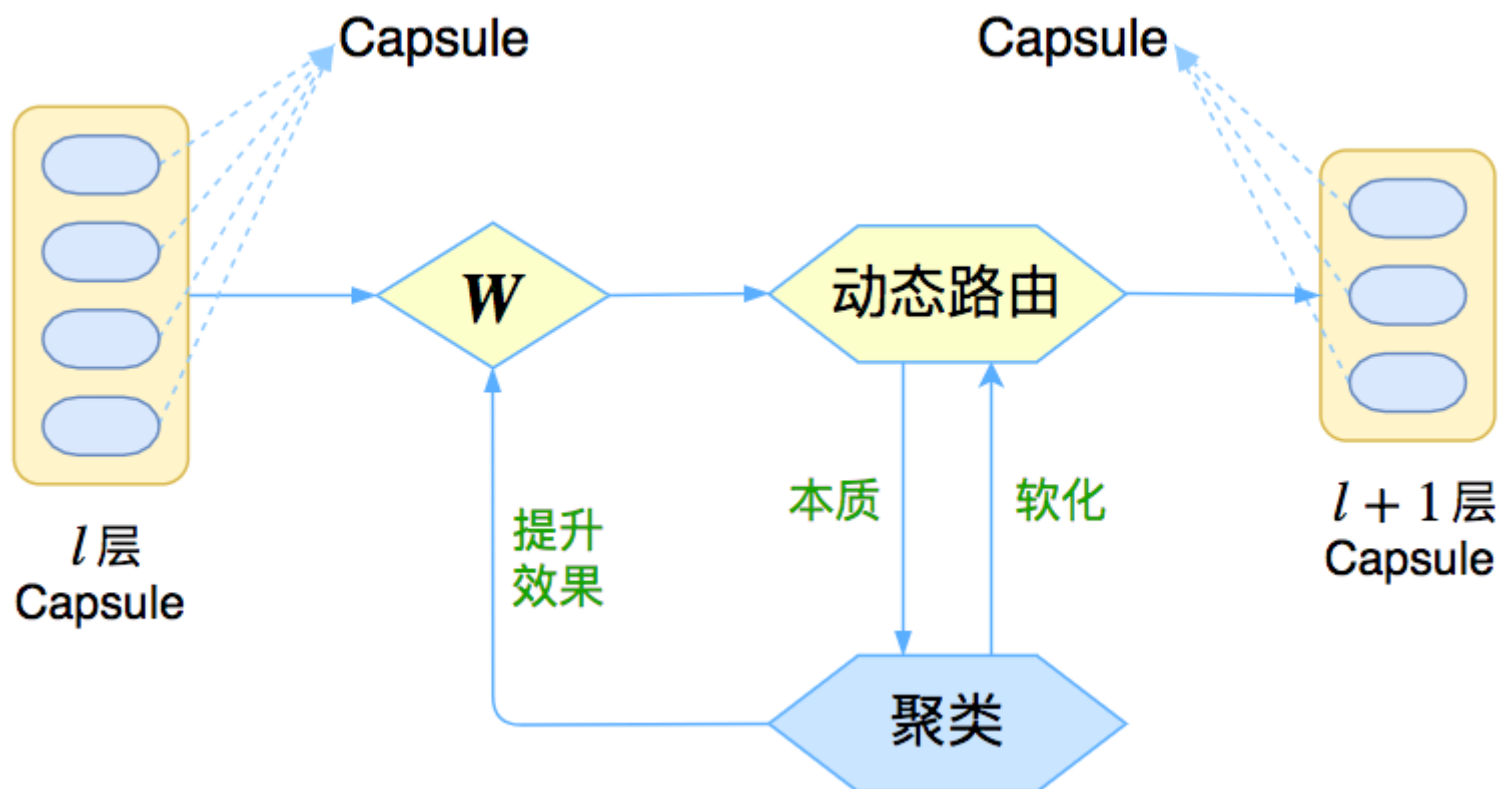
**Procedure 1** Routing algorithm.

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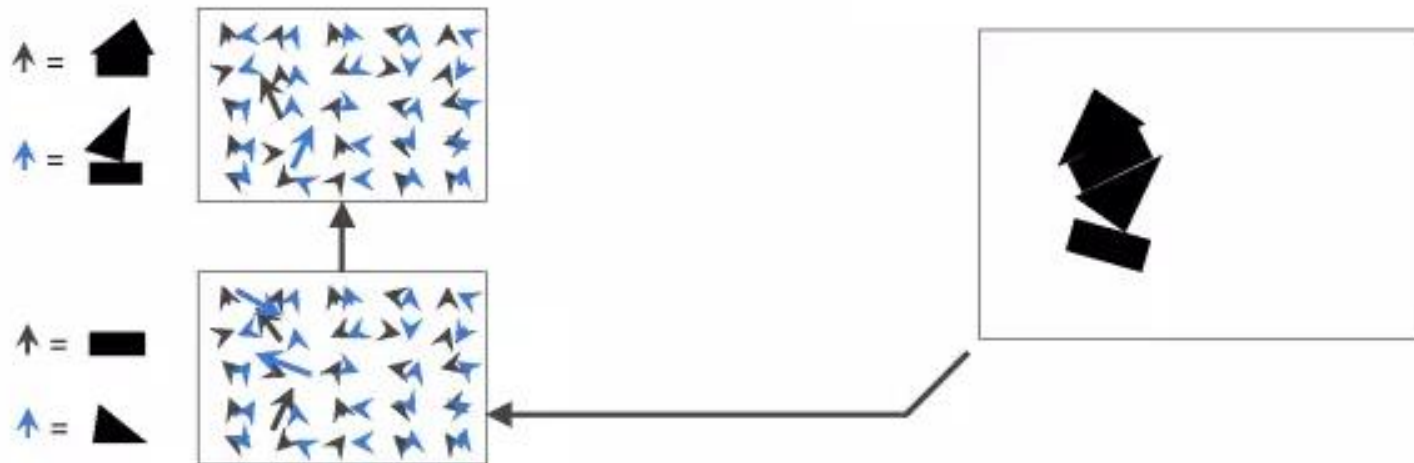
```
1: procedure ROUTING( $\hat{\mathbf{u}}_{j|i}, r, l$ )
2:   for all capsule  $i$  in layer  $l$  and capsule  $j$  in layer  $(l + 1)$ :  $b_{ij} \leftarrow 0$ .
3:   for  $r$  iterations do
4:     for all capsule  $i$  in layer  $l$ :  $\mathbf{c}_i \leftarrow \text{softmax}(\mathbf{b}_i)$  ▷ softmax computes Eq. 3
5:     for all capsule  $j$  in layer  $(l + 1)$ :  $\mathbf{s}_j \leftarrow \sum_i c_{ij} \hat{\mathbf{u}}_{j|i}$ 
6:     for all capsule  $j$  in layer  $(l + 1)$ :  $\mathbf{v}_j \leftarrow \text{squash}(\mathbf{s}_j)$  ▷ squash computes Eq. 1
7:     for all capsule  $i$  in layer  $l$  and capsule  $j$  in layer  $(l + 1)$ :  $b_{ij} \leftarrow b_{ij} + \hat{\mathbf{u}}_{j|i} \cdot \mathbf{v}_j$ 
   return  $\mathbf{v}_j$ 
```

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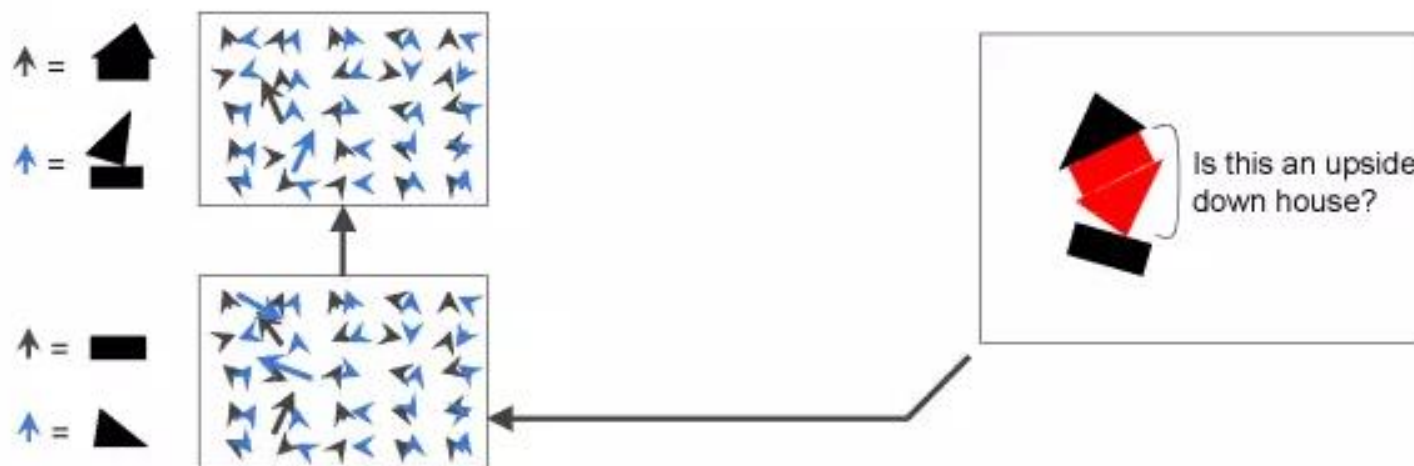
- Routing algorithm



- Handling Crowded Scenes

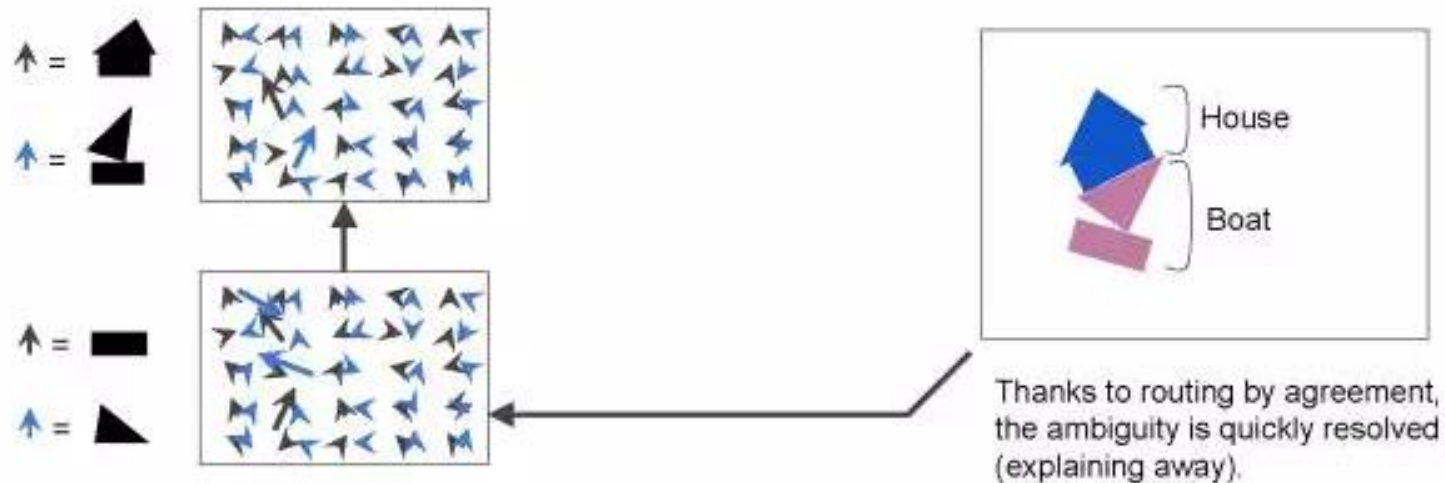


- Handling Crowded Scenes

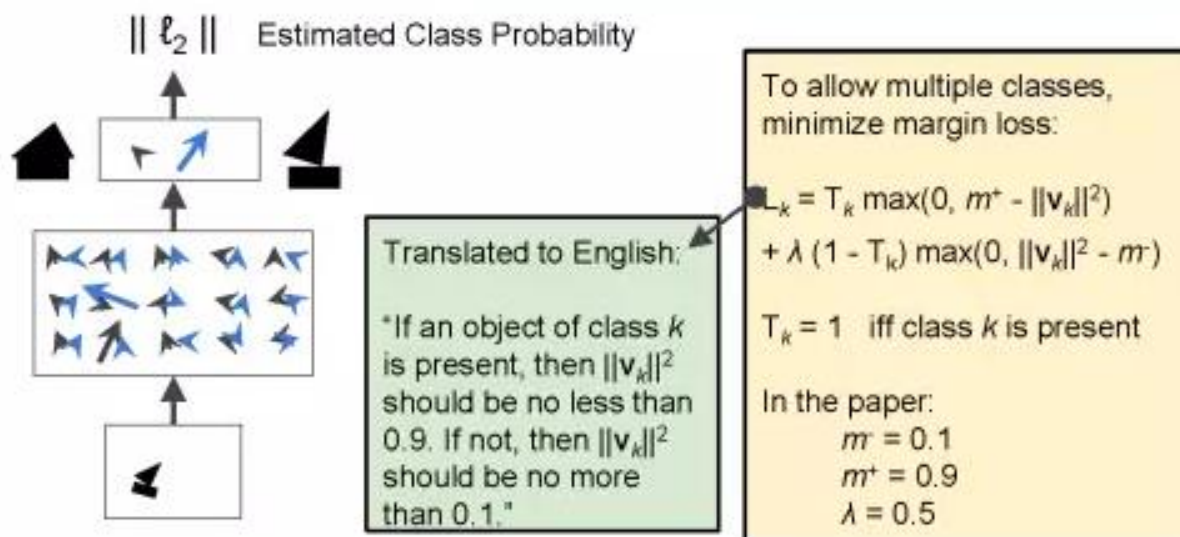




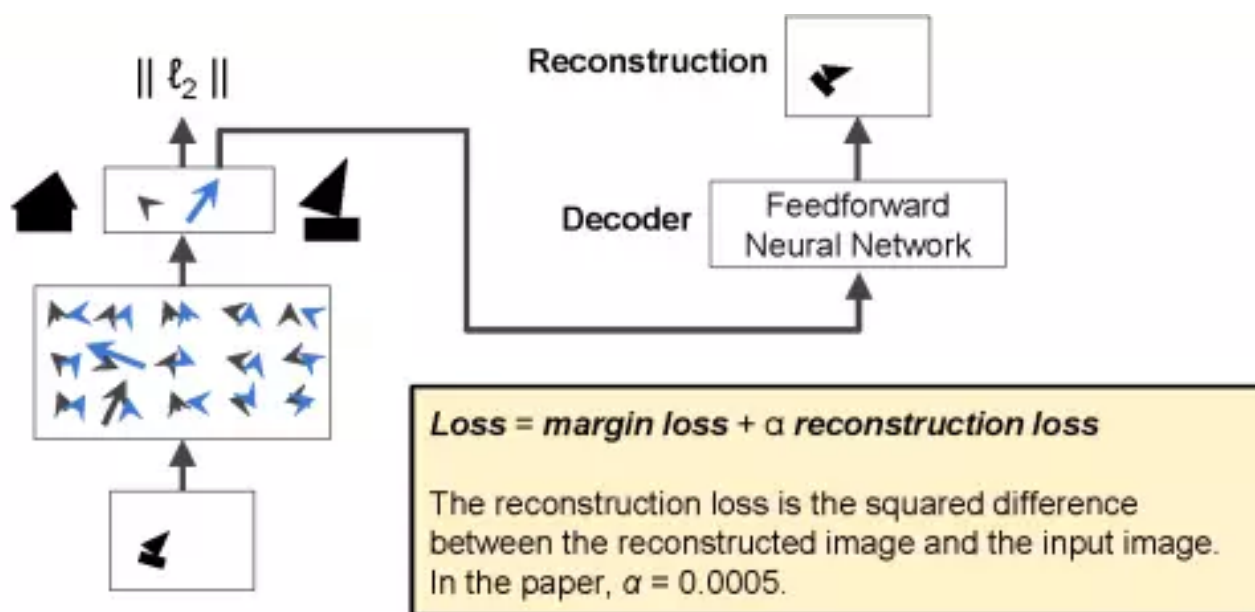
- Handling Crowded Scenes



- Training



- Regularization by Reconstruction



- Classification accuracy on MNIST

Table 1: CapsNet classification test accuracy. The MNIST average and standard deviation results are reported from 3 trials.






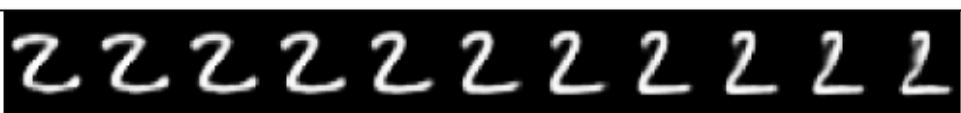
Method	Routing	Reconstruction	MNIST (%)	MultiMNIST (%)
Baseline	-	-	0.39	8.1
CapsNet	1	no	$0.34_{\pm 0.032}$	-
CapsNet	1	yes	$0.29_{\pm 0.011}$	7.5
CapsNet	3	no	$0.35_{\pm 0.036}$	-
CapsNet	3	yes	<b><math>0.25_{\pm 0.005}</math></b>	<b>5.2</b>

# 1.3. Experiments



- Reconstruction with perturbations

Figure 4: Dimension perturbations. Each row shows the reconstruction when one of the 16 dimensions in the DigitCaps representation is tweaked by intervals of 0.05 in the range  $[-0.25, 0.25]$ .

Scale and thickness	
Localized part	
Stroke thickness	
Localized skew	
Width and translation	
Localized part	

- Robustness to Affine Transformations

CNN: 99.22% -> 66%

CapsNet: 99.23% -> 79%

- MultiMNIST result

CNN:                    5% error rate -> in <4% overlapping

CapsNet:                5% error rate -> in 80% overlapping

# 1.3. Experiments



- Sample reconstructions on MultiMNIST

R:(2, 7) L:(2, 7)	R:(6, 0) L:(6, 0)	R:(6, 8) L:(6, 8)	R:(7, 1) L:(7, 1)	*R:(5, 7) L:(5, 0)	*R:(2, 3) L:(4, 3)	R:(2, 8) L:(2, 8)	R:P:(2, 7) L:(2, 8)
R:(8, 7) L:(8, 7)	R:(9, 4) L:(9, 4)	R:(9, 5) L:(9, 5)	R:(8, 4) L:(8, 4)	*R:(0, 8) L:(1, 8)	*R:(1, 6) L:(7, 6)	R:(4, 9) L:(4, 9)	R:P:(4, 0) L:(4, 9)

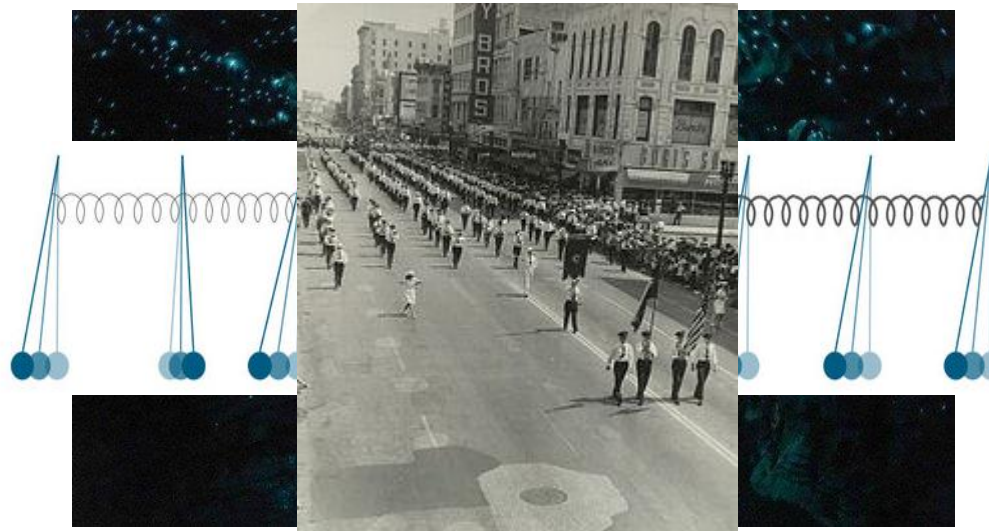


- Pros
  - Preserve position and pose information (equivariance)
  - Require less training data
  - Routing by agreement is great for overlapping objects
  - Robust to affine transformations
  - Interpretability
- Cons
  - Not effective in large datasets
  - Slow training



# **Discussion on Synchronization Neural Network**

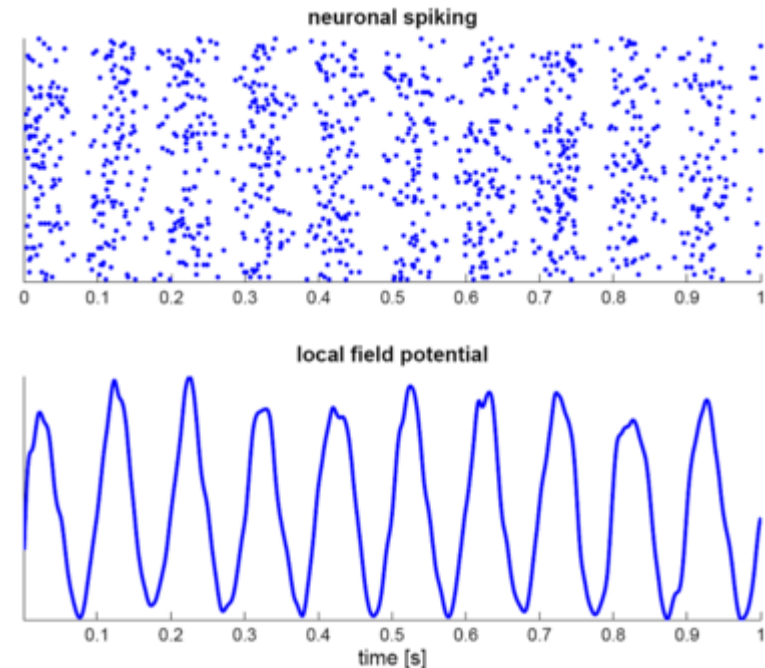
- Oscillations and Amazing Synchronization
  - Animate oscillator
  - Inanimate oscillator
  - Complex system



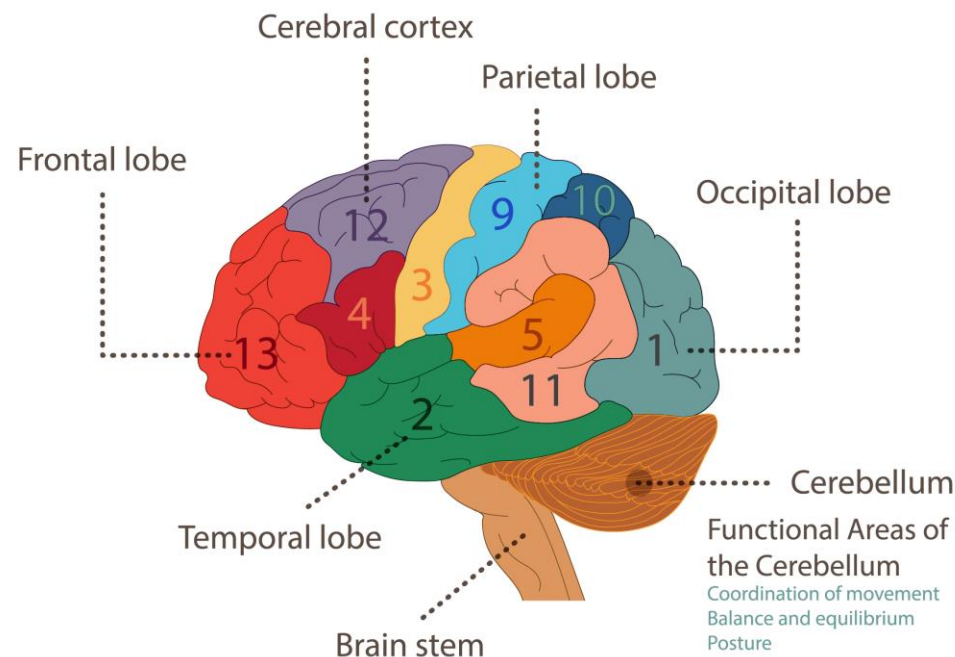
## 2.1. Background



- Neural oscillation / synchronization
  - Spike trains
  - Local field potentials
  - Large-scale oscillations
- Property
  - Frequency
  - Amplitude
  - Phase

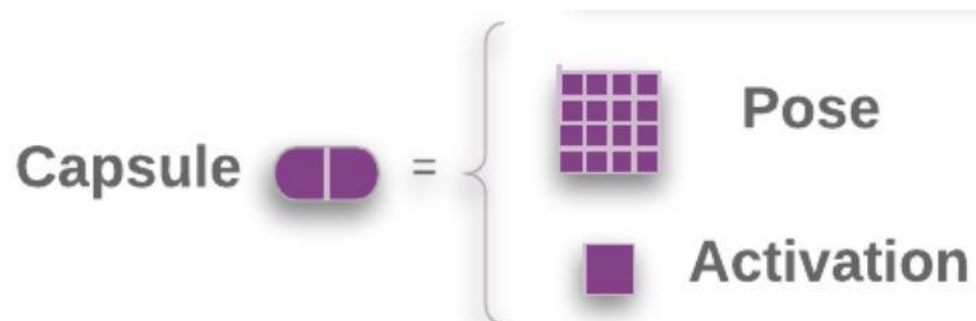


- What's wrong on ANN model (comparing to human brain)?
  - Overfitting / Flexible
  - Intricate representation
  - Task-dependent representation
  - Data hungry
  - Catastrophic forgetting



- Interpretability
- Hierarchy
  - Protocol oriented (multi-source) transfer learning
  - Life-long learning (besides Online learning)
  - Super-parallel (Task hierarchy)
- Disentangled representation
  - Robustness
  - Image segmentation / description
  - .....
- Additive decision (Multi-view)

- What to sync?
  - Vector/Matrix representation [1][2]
  - Complex Neural Network [3-6]
  - Amplitude and phase [7]
  - Reusable module [8]



[1] Sabour, S., Frosst, N., & Hinton, G. E. (2017). Dynamic routing between capsules. In *Advances in Neural Information Processing Systems* (pp. 3856-3866).

[2] Hinton, G. E., Sabour, S., & Frosst, N. (2018). Matrix capsules with EM routing.

- What to sync?
  - Vector/Matrix representation [1][2]
  - Complex Neural Network [3-6]
  - Amplitude and phase [7]
  - Reusable module [8]

[3] Jose, C., Cisse, M., & Fleuret, F. (2017). Kronecker Recurrent Units. *arXiv preprint arXiv:1705.10142*.

[4] Trabelsi, C., Bilaniuk, O., Zhang, Y., Serdyuk, D., Subramanian, S., Santos, J. F., ... & Pal, C. J. (2017). Deep complex networks. *arXiv preprint arXiv:1705.09792*.

[5] Mescheder, L., Nowozin, S., & Geiger, A. (2017). The numerics of GANs. In *Advances in Neural Information Processing Systems* (pp. 1825-1835).

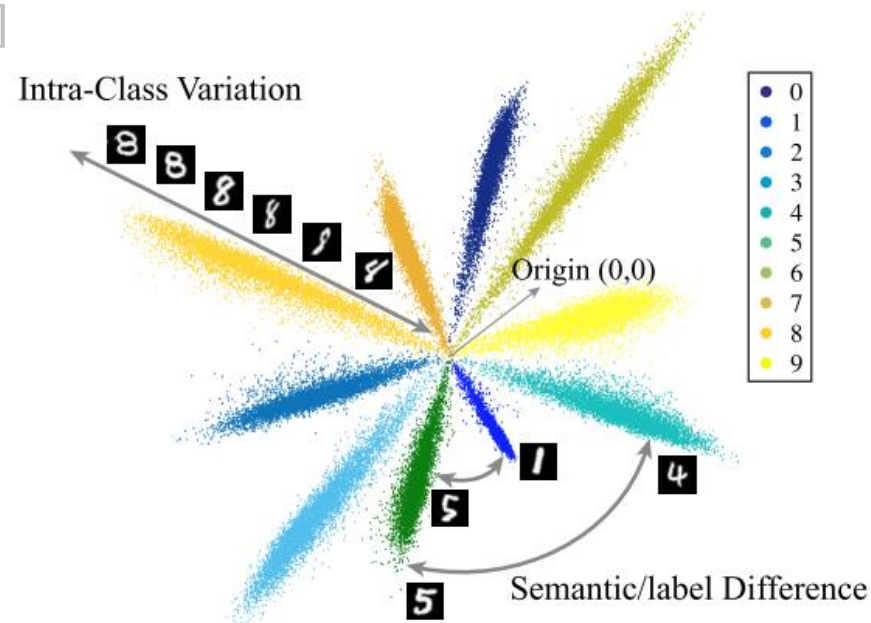
[6] Rahman, M., & Geiger, D. (2016). Quantum Clustering and Gaussian Mixtures. *arXiv preprint arXiv:1612.09199*.



## 2.2. Potential ways



- What to sync?
  - Vector/Matrix representation [1][2]
  - Complex Neural Network [3-6]
  - Amplitude and phase [7]
  - Reusable module [8]

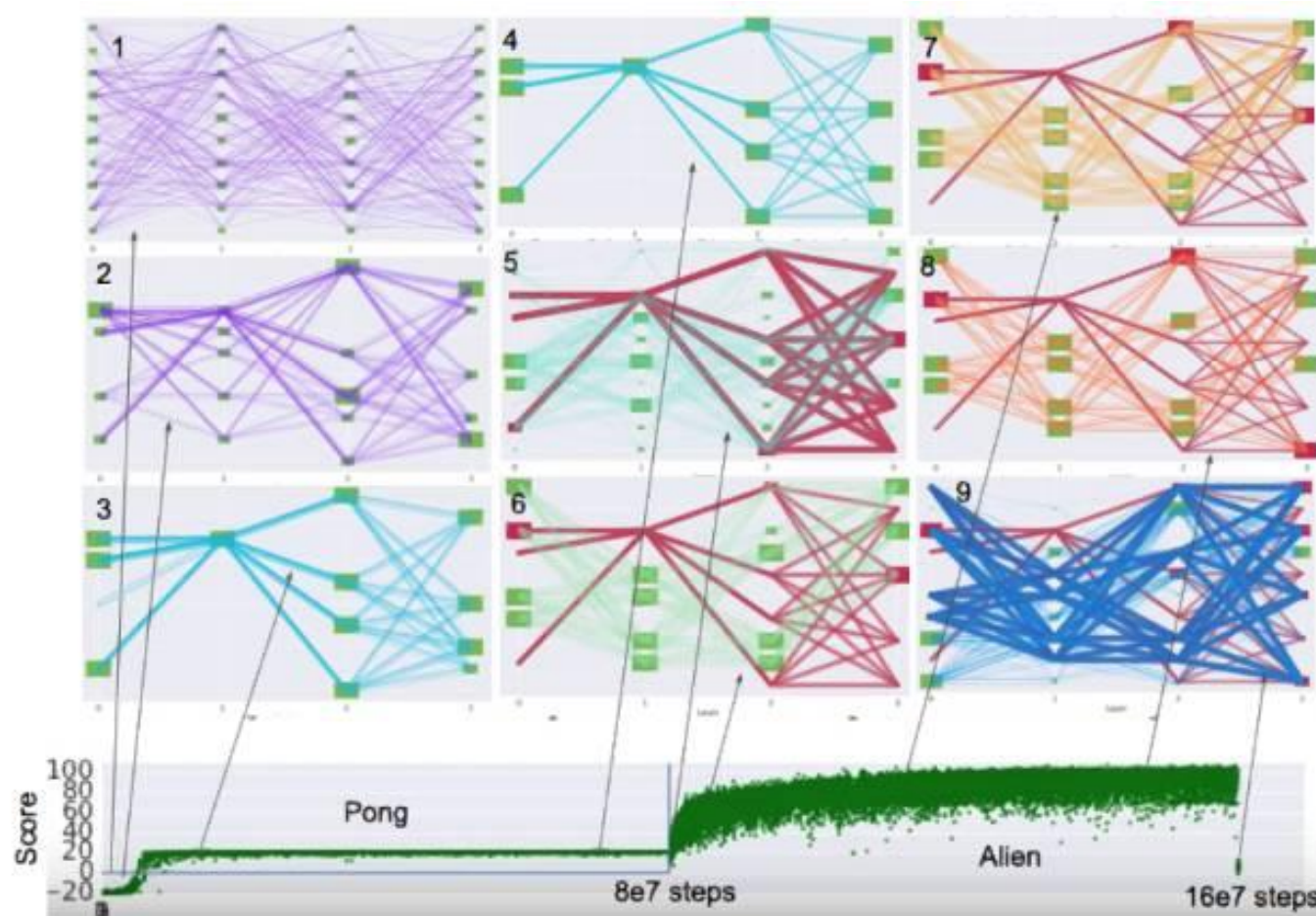


$$f(\mathbf{w}, \mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle = \mathbf{w}^\top \mathbf{x},$$

$$f(\mathbf{w}, \mathbf{x}) = \|\mathbf{w}\| \|\mathbf{x}\| \cos(\theta_{(\mathbf{w}, \mathbf{x})}) = h(\|\mathbf{w}\|, \|\mathbf{x}\|) \cdot g(\theta_{(\mathbf{w}, \mathbf{x})})$$

[7] Liu, W., Liu, Z., Yu, Z., Dai, B., Lin, R., Wang, Y., ... & Song, L. (2018, April). Decoupled Networks. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (pp. 2771-2779).

## 2.2. Potential ways



[8] Fernando, C., Banarse, D., Blundell, C., Zwols, Y., Ha, D., Rusu, A. A., ... & Wierstra, D. (2017). Pathnet: Evolution channels gradient descent in super neural networks. *arXiv preprint arXiv:1701.08734*.

Thank  
you

