

# General Heterogeneous Moran Processes

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## 1 Introduction

## 2 Literature Review

## 3 Model

In this section, we will look at the underlying model of the heterogeneous Moran process. We define the following:

- $N$  **ordered** individuals
- $k$  types  $A_1, A_2, \dots, A_k$
- A state space  $S$  given by the set of ordered  $N$ -tuples with entries of type  $A_1, A_2, \dots, A_k$ . Note that  $|S| = k^N$
- A fitness function  $f : S \rightarrow \mathbb{R}^N$

Let  $h(V, U)$  denote the Hamming distance between two states  $V$  and  $U$ . We consider a Markov chain, where for the transition  $V = (v_1, v_2, \dots, v_N) \rightarrow U = (u_1, u_2, \dots, u_N)$ , the transition probability is defined as follows:

$$P(V, U) = \begin{cases} \frac{\sum_{v_i=u_i} f(v_i)}{\sum_{v_i} f(v_i)} & \text{if } h(V, U) = 1, \text{ differing at position } i \\ 0 & \text{if } h(V, U) > 1 \\ 1 - \sum_{U \in S \setminus \{V\}} P(V, U) & \text{if } h(V, U) = 0 \end{cases} \quad (1)$$

The final case is given by the following notion.  $V$  can transition to itself through the removal of any constituting individual, and the duplication of any individual which shared a type with the removed one. Thus, directly calculating  $P(V, V)$  would require a large amount of computational time and effort. However, we can observe that a transition of some sort must occur, and so we simply take the probability of not transitioning to any **different** state as  $P(V, V)$ .

An important case which proceeds from (1) is that of a transition  $V \rightarrow U$  where  $U$  contains an individual of a *type* not found in  $V$ . For example, the transition  $(0, 1) \rightarrow (0, 2)$ . This would be forbidden by the intuition of a Moran process - i.e the new individual being the duplication of another individual in  $V$ . However, we can see that the standard formula yields  $P(V, U) = 0$  because no  $v_i$  shares a type with  $u_i$ . Following this, we see that (1) correctly gives us  $P(V, U) = 0$  for any **absorbing**  $V \neq U$ .