Rotations and Compound Angle Formulae

Objective: To understand the effect of a rotation on the coordinates of a point, and be able to use the compound angle formulae for trigonometric functions

Recap of previous material:

- 1. Sketch the graph of $y = x^3$. Hence sketch the graph of $y = (2x 3)^3 1$.
- 2. Identify the amplitude, angular frequency, ordinary frequency, and phase of the sinusoid $7\sin(\pi t 1.42)$. Sketch its graph.
- 3. Identify the amplitude, angular frequency, ordinary frequency, and phase of the sinusoid $-3\cos(2(t-1))$. Sketch its graph. Be careful—this one is tricky!

Warm-up:

Let's explore rotations of points about the origin.

- 1. Suppose the point (1,0) is rotated anticlockwise by an angle θ . What are its new coordinates? Hint: think about the definition of sin and cos.
- 2. Suppose the point (0,1) is rotated anticlockwise by an angle θ . What are its new coordinates? Hint: compare with (1,0).
- 3. Suppose the points (1,0), (0,1), and (a,b) are rotated anticlockwise by $\frac{\pi}{2}$.
 - (a) What are the coordinates of the rotations of (1,0) and (0,1)?
 - (b) The rotated coordinates of (a, b) are (-b, a). We can relate the original coordinates to each other by the equation

$$(a,b) = a(1,0) + b(0,1).$$

Write a similar equation linking the coordinates of the rotated points.

- 4. Suppose the points (1,0), (0,1), and (a,b) are rotated anticlockwise by $\frac{3\pi}{4}$.
 - (a) What are the coordinates of the rotations of (1,0) and (0,1)?
 - (b) The rotated coordinates of (a, b) are

$$\left(\frac{-a}{\sqrt{2}} - \frac{b}{\sqrt{2}}, \frac{b}{\sqrt{2}} - \frac{a}{\sqrt{2}}\right).$$

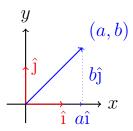
We can relate the original coordinates to each other by the equation

$$(a,b) = a(1,0) + b(0,1).$$

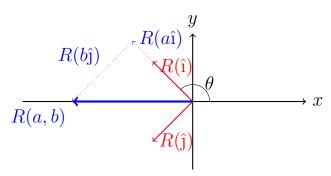
Write a similar equation linking the coordinates of the rotated points.

Theory—Vectors and Rotations:

Think of the point (1,0) as instructions "go one unit to the right." Call this instruction î. Similarly, (0,1) is the instruction "go one unit upwards." Call this \hat{j} . Then a general point (a,b) may be thought of as $a\hat{i}+b\hat{j}$ —"go a to the right and b upwards." We call \hat{i} and \hat{j} the **standard unit vectors**.



Let R denote rotation by an angle θ . Then $R(\hat{i})$ is the instruction "move one unit in the direction θ above the positive x-axis" and $R(\hat{j})$ is the instruction "move one unit in the direction θ anticlockwise of the positive y-axis." Rotate the whole setup above by θ :



Rotating everything by θ doesn't affect the *relative angles*. So if R is any rotation, we have

$$R(a\hat{\mathbf{i}} + b\hat{\mathbf{j}}) = aR(\hat{\mathbf{i}}) + bR(\hat{\mathbf{j}}).$$

So to understand a rotation, it is enough to understand what it does to the **unit vectors** \hat{i} and \hat{j} . We saw in the warm-up that, for rotation by angle θ :

$$R(\hat{\mathbf{i}}) = (\cos(\theta), \sin(\theta)) = \cos(\theta)\hat{\mathbf{i}} + \sin(\theta)\hat{\mathbf{j}}$$

$$R(\hat{\mathbf{j}}) = (-\sin(\theta), \cos(\theta)) = -\sin(\theta)\hat{\mathbf{i}} + \cos(\theta)\hat{\mathbf{j}}.$$

Therefore we have:

$$R(a,b) = aR(\hat{\mathbf{i}}) + bR(\hat{\mathbf{j}})$$

$$= a(\cos(\theta)\hat{\mathbf{i}} + \sin(\theta)\hat{\mathbf{j}}) + b(-\sin(\theta)\hat{\mathbf{i}} + \cos(\theta)\hat{\mathbf{j}})$$

$$= (a\cos(\theta) - b\sin(\theta))\hat{\mathbf{i}} + (a\sin(\theta) + b\cos(\theta))\hat{\mathbf{j}}$$

$$= (a\cos(\theta) - b\sin(\theta), a\sin(\theta) + b\cos(\theta))$$

Practice:

Recall: The formula derived above is that if the point (a, b) is rotated by an angle θ , its new coordinates are:

$$(a\cos(\theta) - b\sin(\theta), a\sin(\theta) + b\cos(\theta)).$$

- 1. Find the new coordinates of the point (7,2) after a rotation by $\frac{\pi}{3}$.
- 2. Find the new coordinates of the point (-4,3) after a rotation by -1.97.
- 3. A point is rotated by an angle $\frac{\pi}{12}$, after which its coordinates are (1.6, -2.9). What were the original coordinates of the point? Hint: think how geometrically to undo a rotation.

Application—Compound Angle Formulae:

We shall use rotations to derive the **compound angle formulae**. These are important trigonometric identities relating trig functions of two angles α and β with trig functions of their sum $\alpha + \beta$. The idea we will follow is to form an angle $\alpha + \beta$ by starting at an angle α and rotating by β ; by doing this in both polar and cartesian coordinates, we shall obtain the compound angle formulae.

Recall: The formula derived above is that if the point (a, b) (in cartesian coordinates) is rotated by an angle θ , its new coordinates are:

$$(a\cos(\theta) - b\sin(\theta), a\sin(\theta) + b\cos(\theta)).$$

- 1. What are the cartesian coordinates of the point P whose polar coordinates are $(1, \alpha)$?
- 2. In polar coordinates, the formula for a rotation is much easier than in cartesian coordinates. Write down the polar coordinates of the point obtained by rotating P through an angle β . Call this rotated point R(P).
- 3. Express R(P) in cartesian coordinates.
- 4. By comparing your answer to question 3 with the cartesian rotation formula above, derive the following **compound angle formulae**:

$$\cos(\alpha + \beta) = \cos(\alpha)\cos(\beta) - \sin(\alpha)\sin(\beta),$$

$$\sin(\alpha + \beta) = \sin(\alpha)\cos(\beta) + \cos(\alpha)\sin(\beta).$$

5. Hence deduce the compound angle formula for tan:

$$\tan(\alpha + \beta) = \frac{\tan(\alpha) + \tan(\beta)}{1 - \tan(\alpha)\tan(\beta)}.$$

Key Points to Remember:

- 1. The **standard unit vectors** are $\hat{i} = (1,0)$ and $\hat{j} = (0,1)$, thought of as instructions to move one unit to the right or upwards, respectively.
- 2. Any point with cartesian coordinates (a, b) can be expressed in terms of the standard unit vectors as $a\hat{\mathbf{i}} + b\hat{\mathbf{j}}$.
- 3. Applying a rotation R does not affect the *relative* positions of the vectors, so $R(a,b) = aR(\hat{i}) + bR(\hat{j})$. So a rotation is *completely determined* by what it does to the standard unit vectors.
- 4. In cartesian coordinates, rotation by angle θ moves the point (a, b) to

$$(a\cos(\theta) - b\sin(\theta), a\sin(\theta) + b\cos(\theta)).$$

- 5. In **polar coordinates**, rotation by angle ϕ moves the point (r, θ) to $(r, \theta + \phi)$.
- 6. The **compound angle formulae** are:

$$\cos(\alpha + \beta) = \cos(\alpha)\cos(\beta) - \sin(\alpha)\sin(\beta),$$

$$\sin(\alpha + \beta) = \sin(\alpha)\cos(\beta) + \cos(\alpha)\sin(\beta).$$

$$\tan(\alpha + \beta) = \frac{\tan(\alpha) + \tan(\beta)}{1 - \tan(\alpha)\tan(\beta)}.$$