

Exercise Sheet 1

Hints:

- The exercise sheet can be submitted until 20.04.2022 at 16:30 online via RWTHmoodle.
- The exercise sheets have to be solved in groups of 3-4. Submissions with other group sizes might not be corrected. Use the forum in RWTHmoodle to find group-mates.
- Submissions will be graded only for the sake of giving feedback to you. The points are not a precondition for admittance to the exam.
- However, we strongly advice you to solve the exercises and submit your solutions.
- Sample solutions will be presented in the exercise class and published in RWTHmoodle.
- Questions can be asked either during the lecture or exercise class or in the general discussion board on RWTHmoodle.

Exercise 1 (Opening a Bank Account):

10 Points

Together with a friend you are asked to design a system for a bank. One of the things this system should allow, is to let people open a bank account. The minimum balance is 0 Euros, so the bank does not allow for negative balances. Furthermore, for security reasons, the bank wants accounts to hold less than 10.000 Euros. You start with the following method.

Algorithm 1 Opening a bank account

```
1: if deposit  $\geq 0$  and deposit  $< 10.000$  then  
2:   do something with the deposit  
3: else  
4:   throw error
```

Your friend suggests to test this method on the following initial inputs: -1, 0, 500, 9.999, and 10.000. You have to convince him that model checking is the better thing to do. To do so, provide a scenario in which the testing is not sufficient.

Hint: It is sufficient to describe this scenario in words.

Exercise 2 (Transition Systems):

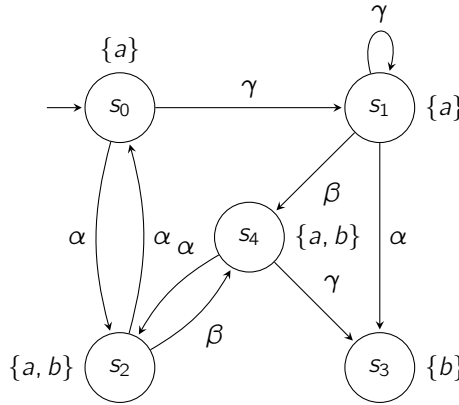
6+3+6+6+3+6=30 Points

We call a transition system $TS = (S, \text{Act}, \rightarrow, I, \text{AP}, L)$

- *action-deterministic* if $|I| \leq 1$ and $|\text{Post}(s, \alpha)| \leq 1$ for all $s \in S$ and $\alpha \in \text{Act}$, and
- *AP-deterministic* if $|I| \leq 1$ and $|\text{Post}(s) \cap \{s' \in S \mid L(s') = A\}| \leq 1$ for all $s \in S$ and $A \in 2^{\text{AP}}$,

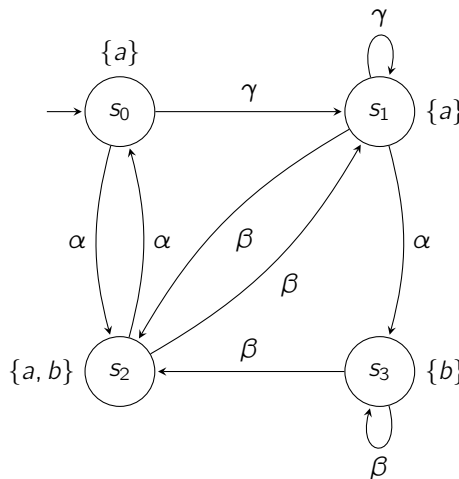
where $\text{Post}(s, \alpha) = \{s' \in S \mid \exists (s, \alpha, s') \in \rightarrow\}$ and $\text{Post}(s) = \bigcup_{\alpha \in \text{Act}} \text{Post}(s, \alpha)$.

Let the transition system TS_1 be as follows.



- Give the formal definition of TS_1 .
- Specify a finite and an infinite execution of TS_1 .
- Decide whether TS_1 is (i) *AP-deterministic*, and/or (ii) *action-deterministic*. Justify your answer.

Let the transition system TS_2 be as follows.



- Give the formal definition of TS_2 .
- Specify a path π of TS_2 , and provide the corresponding $\text{trace}(\pi)$.
- Decide whether TS_2 is (i) *AP-deterministic*, and/or (ii) *action-deterministic*. Justify your answer.

Exercise 3 (Program Graphs):

8+10+7=25 Points

- a) Draw the two program graphs PG_1 and PG_2 for the following programs **1** and **2** over the (shared) integer variables x and y . Use exactly two locations for PG_1 and exactly two locations for PG_2 .

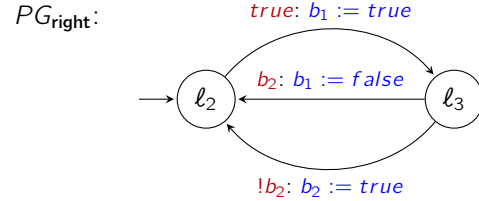
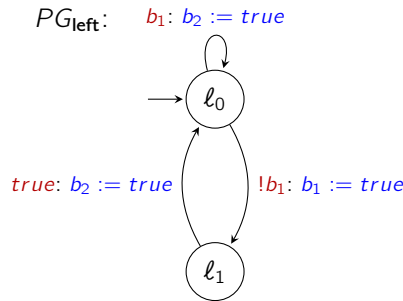
1:

```
while (true) do
  if (y > 0) then
    y := y - 1
  x := x - y
```

2:

```
while (true) do
  x := x - 1
  if (x < 0) then
    x := 1 - x
  else
    x := x - 1
```

- b) Draw the interleaving $PG_{\text{Left}} \parallel PG_{\text{Right}}$ for the following two program graphs.



- c) Draw the reachable part of the transition system $TS(PG_{\text{Left}} \parallel PG_{\text{Right}})$ of the program graph from c). Assume the initial condition $b_1 \wedge b_2$.

Exercise 4 (Handshaking):

10+5+20=35 Points

In the lecture we have seen techniques in order to deal with interleaving. A different approach to deal with interleaving is the parallel composition of transition systems via *handshaking*. The handshaking composition of two transition systems is defined as follows:

Let $TS_i = (S_i, \text{Act}_i, \rightarrow_i, I_i, \text{AP}_i, L_i)$, $i = 1, 2$ and $H \subseteq \text{Act}_1 \cap \text{Act}_2$.

$$TS_1 \parallel_H TS_2 := (S_1 \times S_2, \text{Act}_1 \cup \text{Act}_2, \rightarrow, I_1 \times I_2, \text{AP}_1 \uplus \text{AP}_2, L)$$

where $L(\langle s_1, s_2 \rangle) = L_1(s_1) \cup L_2(s_2)$ and with \rightarrow defined by:

$$\frac{s_1 \xrightarrow{\alpha_1} s'_1}{\langle s_1, s_2 \rangle \xrightarrow{\alpha} \langle s'_1, s_2 \rangle} \quad \frac{s_2 \xrightarrow{\alpha_2} s'_2}{\langle s_1, s_2 \rangle \xrightarrow{\alpha} \langle s_1, s'_2 \rangle} \quad \text{interleaving for } \alpha \notin H$$

$$\frac{s_1 \xrightarrow{\alpha_1} s'_1 \quad \wedge \quad s_2 \xrightarrow{\alpha_2} s'_2}{\langle s_1, s_2 \rangle \xrightarrow{\alpha} \langle s'_1, s'_2 \rangle} \quad \text{handshaking for } \alpha \in H.$$

We also define the handshaking operator $\parallel := \parallel_H$ for $H = \text{Act}_1 \cap \text{Act}_2$, that forces transition systems to synchronize over *all* common actions.

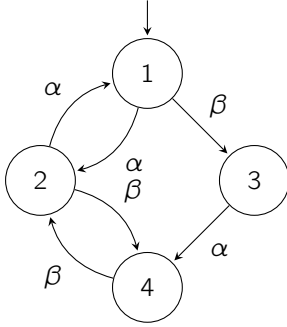
In all following tasks, whenever transition systems are compared via $=$ or \neq , this means (in)equality **up to isomorphism**.

- a) Show that the handshaking \parallel_H operator **is not** associative, i.e. that in general

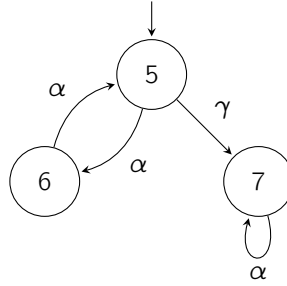
$$(TS_1 \parallel_H TS_2) \parallel_{H'} TS_3 \neq TS_1 \parallel_H (TS_2 \parallel_{H'} TS_3)$$

b) Consider the following three transition systems:

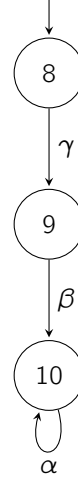
TS₁ :



TS₂ :



TS₃ :



Build the composition $(TS_1 \parallel TS_2) \parallel TS_3$. Show intermediate steps. You can use that the \parallel operator is associative which will be shown in exercise c).

c) Show that for arbitrary transition systems $TS_i = (S_i, Act_i, \rightarrow_i, S_0^i, AP_i, L_i)$ for $i \in \{1, 2, 3\}$, it is

$$\underbrace{(TS_1 \parallel TS_2) \parallel TS_3}_L = \underbrace{TS_1 \parallel (TS_2 \parallel TS_3)}_R.$$

To this end, show that the bijective function $f_{\approx} : ((S_1 \times S_2) \times S_3) \rightarrow (S_1 \times (S_2 \times S_3))$ given by $f_{\approx}(\langle\langle s_1, s_2 \rangle, s_3 \rangle) = \langle s_1, \langle s_2, s_3 \rangle \rangle$ preserves the transition relation in the sense that for all $\alpha \in Act_1 \cup Act_2 \cup Act_3$ we have

$$\ell \xrightarrow{\alpha}_L \ell' \iff f_{\approx}(\ell) \xrightarrow{\alpha}_R f_{\approx}(\ell') \quad (1)$$

where $\ell, \ell' \in S_L$, S_L is the state space of transition system L and $\xrightarrow{\alpha}_L, \xrightarrow{\alpha}_R$ are the transition relations of L and R , respectively.

Hint: When considering an action α , you only need to distinguish the cases

- (i) $\alpha \in Act_1 \setminus (Act_2 \cup Act_3)$
- (ii) $\alpha \in (Act_1 \cap Act_2) \setminus Act_3$
- (iii) $\alpha \in Act_1 \cap Act_2 \cap Act_3$

as all other cases are symmetric. Also, for simplicity, it suffices to show the direction " \implies " of condition (1). However, keep in mind that L and R are not necessarily action-deterministic.