# Brief Theory of Probability: Notes from MATH 431 Compiled by Harry Luo

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## 1 Sample Spaces, collection of events, probability measure

- Sample space  $\Omega$ : set of all possible outcomes of an experiment. Comes in n-tuples where n represents number of repeated trials.
- Collection of events  $\mathcal{F}$ : subset of state space to which we assign a probability.
- Probability measure: function that assigns a probability to each event.  $P: F \to \mathbb{R}$ .
  - ► Range is [0, 1].
  - $P(\Omega) = 1$  and  $P(\emptyset) = 0$
  - For pairwise disjoint events  $A_1, A_2, ...,$  $P(A_1 \cup A_2 \cup ...) = P(A_1) + P(A_2) + ...$

# 2 Sampling: Uniform, Replacement, Order

- uniform sampling: each outcome is equally likely
- · Binomial coeff

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} \tag{1}$$

#### 2.1 Replacement

• ex: sample K distinct marked balls from N balls in a box, with Replacement

$$\Omega = \left\{1,2,3,...,N\right\}^K$$
 
$$\|\Omega\| = N^K$$
 
$$(2)$$
 
$$P(\text{none of the balls is marked 1}) = \frac{(N-1)^K}{N^K}$$

• ex: sample K distinct marked balls from N balls in a box, without Replacement

$$\begin{split} \Omega &= \{(i_1,i_2,...,i_K) \mid i_1,...,i_K \in \{1,2,...,N\}, \text{distinct} \\ \|\Omega\| &= \binom{N-1}{K} \\ P(\text{none of the balls is marked 1}) &= \frac{\binom{N-1}{K}}{\binom{N}{K}} = \frac{N-K}{N} \end{split} \tag{3}$$

#### 2.2 Order

► order matters:  $A_n^k = \frac{n!}{(n-k)!}$ ► order doesn't matter:  $\binom{n}{k} = C_n^k = \frac{n!}{k!(n-k)!}$ 

## 3 Infinite Sample Spaces

#### 3.1 discrete

$$\Omega = \{\infty, 1, 2, \ldots\}$$

#### 3.2 continuous

$$P([a',b']) = \frac{\text{length of } [a',b']}{\text{length of} [a,b]} \tag{4} \label{eq:4}$$

single point, or sets of points:  $P(\lbrace x \rbrace) = P(\bigcup_{i=1}^{\infty} \lbrace x_i \rbrace) = 0$ 

• Complements:  $P(A) = 1 - P(A^C)$ 

# 4 Conditional Probability, Law of Total Prob., Bayes' Theorem, Independence

#### 4.1 Conditional prob.

$$P(A|B) = \frac{|A \cap B|}{|B|} \Rightarrow P(AB) = P(B)P(A|B) \tag{5}$$

(new sample space is B, total number of outcomes is  $A \cap B$ )

#### 4.2 Law of total probability:

Given partitions  $B_1, B_2, \dots$  of  $\Omega$ ,

$$P(A) = \sum_{i} P(A|B_i)P(B_i) \tag{6}$$

#### 4.3 Bayes' Theorem:

Given events A, B, P(A) and P(B) > 0,

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{P(A)} \tag{7}$$

Considering the law of total prob., the generalized form, when  $B_i$  are partitions, is given as:

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{\sum_j P(A|B_j)P(B_j)}$$
(8)

#### 4.4 Independence:

$$P(AB) = P(A)P(B) \Leftrightarrow P(B|A) = P(B) \tag{9}$$

Note: By virtue of conventions, we write  $A \cap B$  as AB in Probability.

If A,B,C,D are independent, it follows that P(ABCD) = P(A)P(B)P(C)P(D); however, the inverse is not always true.

• Independence of Random Variables (messy as hell...)

Given 2 random variables

$$\begin{split} X_1 &\in \{x_{11}, x_{12}, x_{13}, ..., x_{1m}\} \\ X_2 &\in \{x_{21}, x_{22}, x_{23}, ..., x_{2n}\} \\ \text{Random variables X\_1 and X\_2 are independent} &\Leftrightarrow \\ P\big(X_1 = x_{1i}, X_2 = x_{2j}\big) = P(X_1 = x_{1i}) P\big(X_2 = x_{2j}\big) \end{split} \tag{10}$$

Need to check n\*m equations to verify independence.

#### 4.5 Conditional Independence:

For events  $A_1, A_2, ..., A_n, B$ , any set of events in A:  $A_{i1}, A_{i2}, A_{i3}$ , they are conditionally independent given B if

$$P(A_{i1}A_{i2}A_{i3}|B) = P(A_{i1}|B) * P(A_{i2}|B) * P(A_{i3}|B)$$
(11)

## 5 Independent Trials, Distributions

#### 5.1 Bernoulli dirtribution:

a single trial, with success probability p, and failure probability 1-p. Prameter being the success probability.

$$X \sim \text{Ber}(p) \Rightarrow P(X = x) = p^x * (1 - p)^{1 - x}, x \in \{0, 1\}$$
 (12)

#### 5.2 Binomial Distribution:

multiple independent Bernoulli trials, with success probability p, and failure probability 1-p. Parameters being the number of trials n and the success probability p.

$$X \sim \text{Bin}(n, p) \Rightarrow P(X = k) = \binom{n}{k} p^k * (1 - p)^{n - k}, k \in \{0, 1, ..., n\}$$
 (13)

#### 5.3 Geometric distribution:

multiple independent Bernoulli trials with success probability p, while stoping the experiment at the first success.

$$X \sim \text{Geom}(p) = p * (1-p)^{k-1}, k \in \{1, 2, ...\}$$
 (14)

#### 5.4 Hypergeometric distribution:

There are N objects of type A, and  $N_A - N$  objects of type B. Pick n objects without replacement. Denote number of A objects we picked as k. Parameters are  $N, N_A, n$ .

$$P(X=k) = \frac{\binom{N_A}{k} \binom{N-N_A}{n-k}}{\binom{N}{n}} \tag{15}$$

choose k from N\_A, choose n-k from N-N\_A, divide by total number of ways to choose n from N

### 6 Probability Analysis: Probability Density Function

$$P(X \le b) = \int_{-\infty}^{b} f(x) \, \mathrm{d}x \tag{16}$$