

Brief Theory of Probability, Part 1

Survey of main ideas and equations

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1 Vector algebra

1.a Coordinate Transformation

1.a.a cylindrical

$$\begin{aligned}x &= \rho \cos \varphi \\y &= \rho \sin \varphi \\z &= z\end{aligned}$$

reverse

$$\begin{aligned}\rho &= \sqrt{x^2 + y^2} \\ \cos \varphi &= \frac{x}{\rho} \\ \sin \varphi &= \frac{y}{\rho}\end{aligned}$$

1.a.b spherical

$$\begin{aligned}x &= \rho \sin \varphi \cos \theta \\y &= \rho \sin \varphi \sin \theta \\z &= \rho \cos \varphi\end{aligned}$$

reverse

$$\rho = \sqrt{x^2 + y^2 + z^2}$$

$$\cos \varphi = \frac{z}{\rho}$$

$$\cos \theta = \frac{x}{r}$$

$$\sin \theta = \frac{y}{r}$$

1.b Dot product

- commutative
- positive definite
- distributive
- cauchy-schwarz inequality

1.c cross product

- anticommutative $\vec{u} \times \vec{v} = -(\vec{v} \times \vec{u})$
 - distributive $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$
 - scalar multiplication
 - triple scalar product $\vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$
 - triple vector product $\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{b} \cdot \vec{a})\vec{c} - (\vec{c} \cdot \vec{a})\vec{b}$
-

2 Vector calculus

2.a Arc length

- Def: Given a curve $\vec{r}(u) = (x(u), y(u), z(u))$ for $a \leq u \leq b$ the length of the curve S, as a function of time is given by

$$S(t) = \int_a^t \|\dot{\vec{r}}(u)\| du$$

where $\|\dot{\vec{r}}(u)\| = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$

- Curvature:

$$K(t) = \frac{\|\dot{\vec{T}}(t)\|}{\|\dot{\vec{r}}(t)\|} = \frac{\|(\dot{\vec{r}}(t) \times \ddot{\vec{r}}(t))\|}{(\|\dot{\vec{r}}(t)\|)^3}, \text{ where } \vec{T}(t) = \frac{\dot{\vec{r}}(t)}{\|\dot{\vec{r}}(t)\|}$$

2.b Line integration

- for curve $\vec{r}(t) = (x(t), y(t))$

$$\int_C f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

- center of mass $(\bar{x}, \bar{y}, \bar{z})$, where

$$\begin{cases} \bar{x} = \left(\frac{1}{M}\right) \int_C \rho(x, y, z) x ds \\ \bar{y} = \left(\frac{1}{M}\right) \int_C y \rho(x, y, z) ds \\ \bar{z} = \left(\frac{1}{M}\right) \int_C z \rho(x, y, z) ds \end{cases}$$

- Work done by force F along curve, $\vec{r}(t)$, which can be generalized into the formula for line integration,

$$W = \int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \vec{T} ds = \boxed{\int_a^b F[x(t), y(t)] \cdot (\dot{r}(t)) dt}$$

- When vector field $\vec{F} = \vec{F}(x, y, z) = (P, Q, R)$,

$$\int_C \vec{F} \cdot d\vec{r} = \int_C P dx + Q dy + R dz$$

2.c Surface integration

- Parametric representation of surface:

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$$

- Use normal vector at a point (u_0, v_0) of surface to represent tangent plane.

$$\vec{r}_v = \frac{\partial \vec{r}}{\partial v}(u_0, v_0), \vec{r}_u = \frac{\partial \vec{r}}{\partial u}(u_0, v_0)$$

$$\vec{N} = \vec{r}_u \times \vec{r}_v$$

- Surface area of a surface S with $(u, v) \in D$

$$A(S) = \iint_D \|\vec{r}_u \times \vec{r}_v\| du dv$$

2.d Jacobian

- Def: Given a transformation $(u, v) \in D \longrightarrow [x(u, v), y(u, v)] \in S$, the Jacobian is given by

$$J(u, v) = \frac{\partial(x, y)}{\partial(u, v)} \equiv \det \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix}$$

- Jacobian in coordinate transformation

$$\iint_S f(x, y) dA = \iint_D f(x(u, v), y(u, v)) |J(u, v)| du dv$$

2.e Gradient, Divergence, Curl

- Nabla operation:

$$\nabla = \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z}$$

- Gradient in 2D cartesian (r, θ) :

$$\nabla f = \frac{\partial f}{\partial r} i + \left(\frac{1}{r} \right) \frac{\partial f}{\partial \theta} j$$

- Gradient in polar

$$\nabla f = \frac{\partial f}{\partial \rho} i + \left(\frac{1}{\rho} \right) \frac{\partial f}{\partial \varphi} j$$

- Gradient in spherical

$$\nabla f = \partial_{\rho} \hat{\rho} + \hat{\varphi} \frac{1}{\rho} \partial_{\varphi} + \hat{\theta} \frac{1}{\rho \sin \varphi} \partial_{\theta}$$

2.f Green's theorem

2.g Stokes' theorem