

```

subroutine jacobian(A,u,J,beta,lambda)

  use header

  implicit none
  ! Evaluate the Jacobian F' (U)

  type(matrix), intent(in) :: A
  type(matrix), intent(out) :: J
  type(vector), intent(in) :: u
  integer :: i                               !,nrows
  real(kind=8) :: y, beta, lambda

  ! Initialise the Jacobian with the linear part A

  ! Note: As m grows 'J=A' becomes increasingly inefficient. using dcopy
  ! from LAPACK to efficiently copy the elements required would be better.
  ! Unfortunately, I was not able to get this idea working!
  ! Something along the lines of this code below was what I was thinking!

  !call dcopy(A%nnz, A%aa(A%ii(A%ibeg):(A%ii(A%iend+1)-1)),1,J%aa(J%ii(J%ibeg):(J%ii(J%i
end+1)-1)),1)
  !call dcopy(A%n+1, A%ii(1:(A%n+1)), 1, J%ii(1:(J%n+1)),1)
  !call dcopy(A%nnz, A%jj(A%ii(A%ibeg):(A%ii(A%iend+1)-1)),1,J%jj(J%ii(J%ibeg):(J%ii(J%i
end+1)-1)),1)

  ! Inefficient solution but works!

  J = A

  ! Calculates F' (U) = A - diag(G' (U))
  do i=A%ibeg,A%iend
    y = 1.0_8 + beta*u%xx(i)
    J%aa(J%ii(i)) = J%aa(j%ii(i)) - lambda*exp(u%xx(i)/y)/(y*y)
  end do

end subroutine jacobian

```