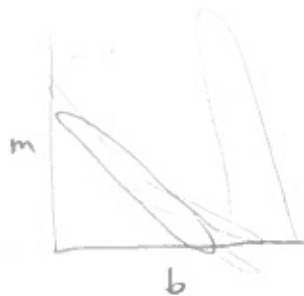
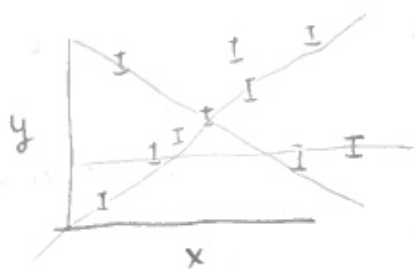


Last time

- we set up a foreground-background model:
 - data points can either be drawn from the real phenomenon we're interested in (fg) or a "bad" distribution (bg).
- we fit _{for} parameters describing both fg & bg and the "mixture weights" (P_{bad} , $1 - P_{\text{bad}}$;

$$p(y_i | m, b, P_{\text{bad}}, Y, V) = P_{\text{bad}} \cdot \frac{1}{\sqrt{2\pi(V + \sigma_i^2)}} \exp\left(-\frac{(y_i - Y)^2}{2(V + \sigma_i^2)}\right) + (1 - P_{\text{bad}}) \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{(y_i - mx_i - b)^2}{2\sigma_i^2}\right)$$

- this is a 5-parameter model
 - hard to explore by gridding up & plotting
 - we used Julia's optimize function to find maximum-likelihood (but we want the covariance)
 - but we found that it was multimodal



Today - Markov Chain Monte Carlo

The problem it solves:

- You have a probability distribution function with some parameters
- You want a sampling of parameter values that are fair draws from the distribution



The Idea:

- move a "particle" around in the parameter space.
- move the particle according to a "proposal distrib"
 $\theta_{\text{new}} = \theta + N(0, \sigma_{\theta}^2)$
- compute the probability at the new parameter
 $P_{\text{new}} = P(\theta_{\text{new}})$
- always keep improvements; sometimes keep moves that reduce the $P(\theta_{\text{new}})$
- in the long run, particle positions are your samples.

Markov Chain Monte Carlo

- list of samples
- jump from θ_i to θ_{i+1} depends only on θ_i
- the jump involves randomness.

Algorithm - Metropolis-Hastings

chain = []

params = [50, 2.]

jumpsizes = [10, 0.1]

prob = prob_function(params)

for i in 1:Nsteps

params_new = params + randn(2) * jumpsizes

prob_new = prob_function(params_new)

accept?

→ if (prob_new / prob \geq rand(Float64))

params = params_new

prob = prob_new

uniform
[0,1]

end

append!(chain, params)

return chain