

Introduction to Deep Learning – Some Practical Guidelines

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Outline

- **Part II - Practical Guidelines for Running a Project:**

Choosing Hyperparameters – a bit of exploration and exploitation

Job workflow - make it efficient and easy to organize

CPUs vs GPUs

Parallelizing Models and Multinode Execution, with an exercise

Choosing Hyperparameters

- Hyperparameters are found by searching, not by the network algorithm
- Generally, hyperparameters related to:
 - architecture (layers, units, activation, filters, ...)
 - algorithm (learning rate, optimizer, epochs, ...)
 - efficient learning (batch size, normalization, initialization, ...)
- Some options are determined by task:
 - e.g. the loss function, using CNN vs MLP, ...
- Use what works, from related work or the latest recommendations,

Hyperparameters Search

- Can take a long time, hard to find global optimal
- Start with small data, short runs to get sense of range of good parameter values
- Easy but possibly time-consuming method:
grid search over uniformly spaced values
- Do “exploration” then “exploitation”, ie search wide then search deep
Keras Tuner functions can help with the wide search
(Raytune is similar tool for Pytorch)

Keras Hyperparameter Search Tool

- Keras Hypertuner class implements several search strategies:

Hyperband is like a tournament of hyperparameter configurations

RandomSearch will search randomly through the space of configurations

Bayesian optimization is like a function approximation to pick out next configuration

Keras Tuner code snippet

Set up function to
make the model

```
def build_model(numfilters,activation_choice): #<<-----add code: if you want to change the list and change code to match the list
    #
    mymodel = keras.models.Sequential()
    mymodel.add(keras.layers.Convolution2D(numfilters,
                                            (3, 3),
                                            strides=1
```

Keras Tuner code snippet –

Set up function to
make the model

Set up
hyperparameter
choices

```
def build_model(numfilters, activation_choice): #<<-----add code: if you want to
# list and change code to your needs
mymodel = keras.models.Sequential()
mymodel.add(keras.layers.Convolution2D(numfilters,
(3, 3),
strides=1
```

Keras Tuner code snippet – put build-model inside a ‘wrapper’ function

Set up function to make the model

Set up hyperparameter choices

```
def build_model_hp(hp):  
    hp_numfilters = hp.Int('hpnumfilters', min_value=8, max_value=32, step=4)  
    #your variable name          ^^^ the parameter name in the hp object  
  
    return build_model(hp_numfilters, hp_Activation) #<<---- dont forget to pass the new  
  
def build_model(numfilters, activation_choice): #<<-----add code: if you  
    # list and change code to  
    mymodel = keras.models.Sequential()  
    mymodel.add(keras.layers.Convolution2D(numfilters,  
                                             (3, 3),  
                                             strides=1
```


Keras Tuner code snippet – put build-model inside a ‘wrapper’ function

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Set up hyperparameter choices

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    mymodel = keras.models.Sequential()
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                                            (3, 3),
                                            strides=1
```

Define ‘tuner’ object: use the wrapper and model fit to search configurations

```
tuner = kt.Hyperband(build_model_hp,
```

```
    objective = 'val_accuracy',
    max_epochs = num_max_epochs,
    factor = 3,
    hyperband_iterations=10,
```

Workflow and Organizing Jobs

Job Level: What makes sense to include in each job?

Model Level: run & test model for each parameter configuration

Data Level: loop through cross validation datasets (if applicable)

Workflow and Organizing Jobs

Job Level: What makes sense to include in each job?

Model Level: run & test model for each parameter configuration

Data Level: loop through cross validation datasets (if applicable)

- **Consider how long a model runs for 1 configuration of hyperparameters**
- **Organize jobs into reasonable chunks of work**
- **For large models consider model-checkpoints**
- **Tensorboard is available on Expanse (ask for details to run securely)**

note on using GPU

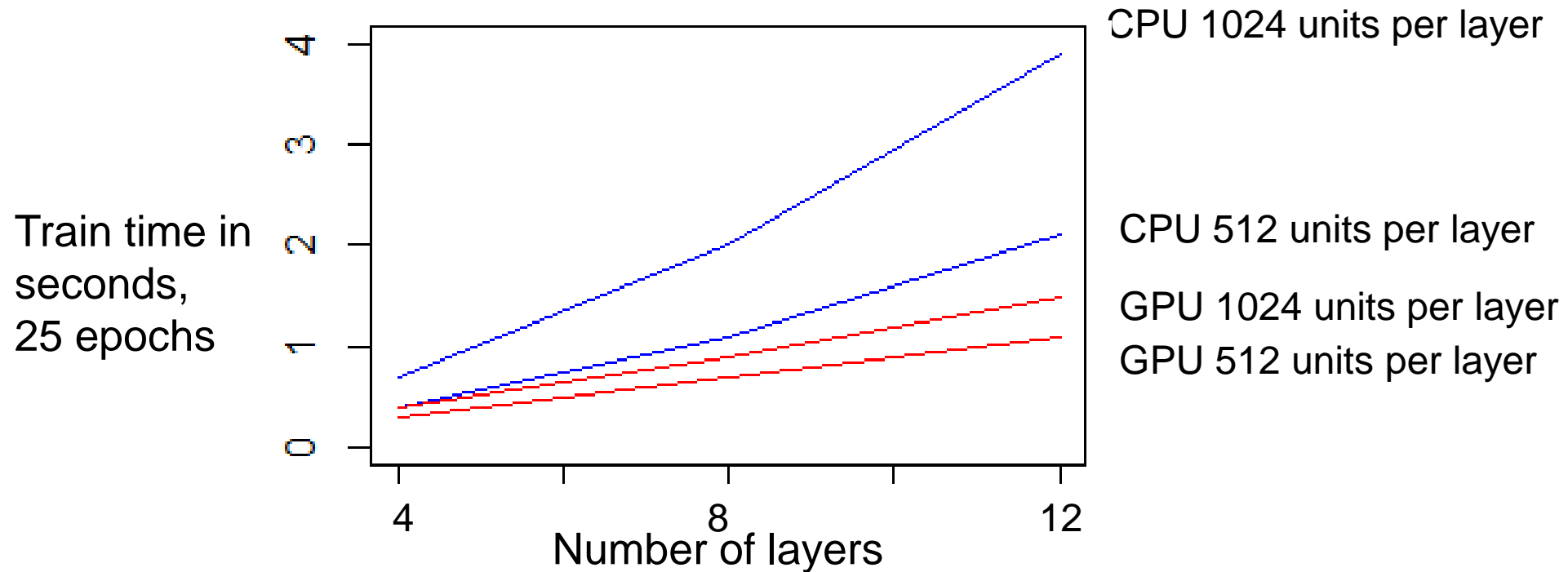
- GPU node has multiple GPU devices
- By default tensorflow will run on 0th gpu device if GPU is available, otherwise it will use all CPU cores available

Code snippet
to check for
GPU devices

```
import tensorflow as tf  
  
gpu_devices = tf.config.list_physical_devices("GPU")
```

GPU shared (V100) vs CPU (128 cores)

For MLP with Dense Layers, 80000x200 data matrix



GPUs faster, but you might have to wait more in job queue; also some memory limits compared to CPU, may need to use smaller batch size

Parallelism in Deep Learning

- **Two Goals**

1 Speed Up Learning - as data scales up training takes longer

**2 Optimize Memory - as models scale up they take up too much memory
e.g. V100s have 32Gb limit and 8B float32 parameters would fill that**

Parallelism strategies

- **Data Parallelism:** partition data and copy the model across devices, (this is probably easiest thing to do, least programming)
- **Pipeline Parallelism:** split up the model across devices, i.e. inter-layer (you organize layers)
- **Tensor Parallelism:** split up weight matrix across devices, i.e. intra-layer (model has to support it)

Reducing memory footprint

- Using mixed precision (e.g. bfloat16 for weights) lowers memory at a cost of accuracy
- ‘DEEPSPEED’ package partitions the optimization calculations at a cost of communication

Parallel DL models with multiple nodes/devices

- **Data Parallel:**

Each device trains a copy of the model with a part of the data
Weight updates have to be aggregated across devices

- **Main tools on Expanse:**

Keras/Tensorflow ‘strategy’ (simple for multidevice on 1 node)
or

Horovod MPI wrappers (for multinode)

Keras/Tensorflow strategy single GPU node

1. Get a list of gpu devices available

```
gpus_list = tf.config.experimental.list_physical_devices('GPU')
```

2. Set up a 'mirror' strategy

```
mirrored_strategy = tf.distribute.MirroredStrategy(["GPU:0", "GPU:1", "GPU:2", "GPU:3"])
```

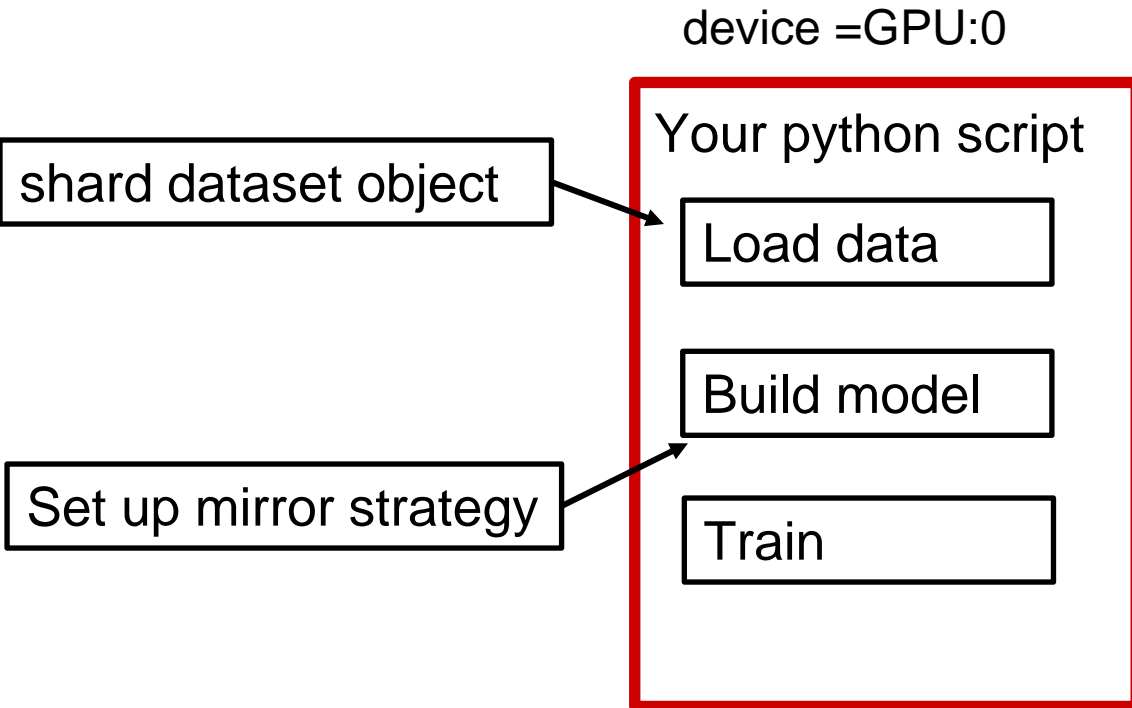
3. Use strategy scope around the model definition (so model gets copied)

```
with mirrored_strategy.scope():  
    multi_dev_model=build_model()
```

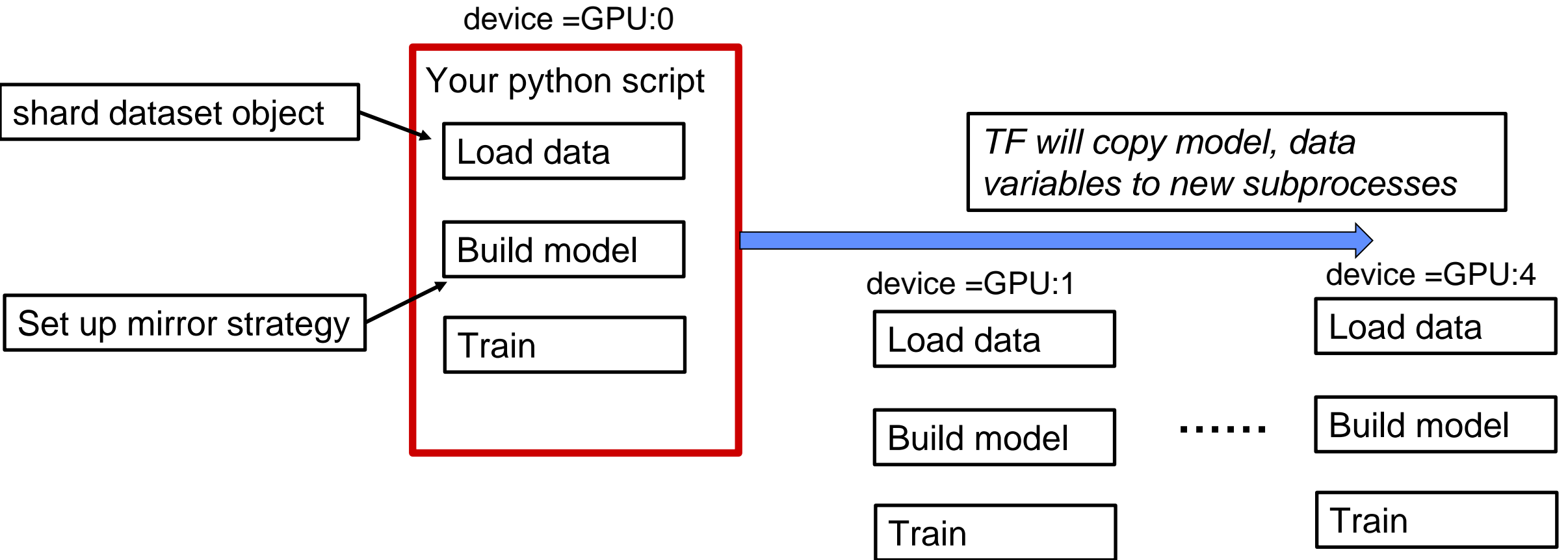
4. A tensorflow dataset object will 'shard' (ie split up) data among GPU devices

```
train_dataset = tf.data.Dataset.from_tensor_slices((X_train, Y_train)) ...
```

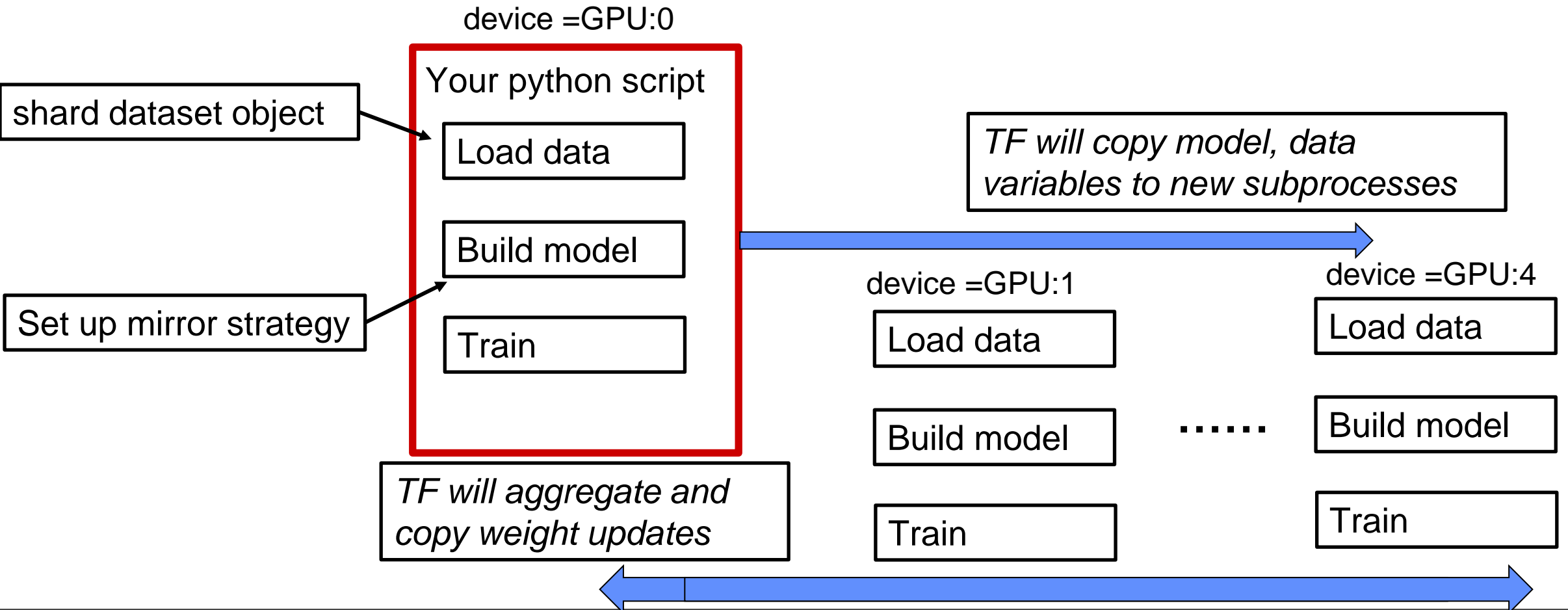
Mirror Strategy single GPU node



Mirror Strategy single GPU node



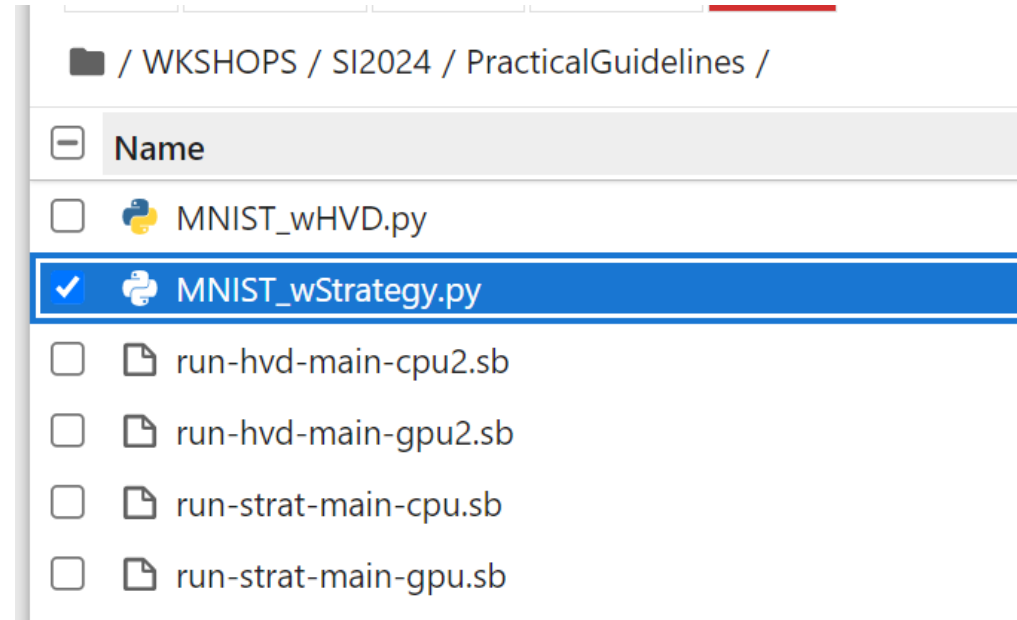
Mirror Strategy single GPU node



Keras/Tensorflow strategy single GPU node

Example, in github repo find:

MNIST_wStrategy.py
run-strat-main-gpu.sb
run-strat-main-cpu.sb



From terminal window submit a batch job:

```
4rodrig@login01 PracticalGuidelines]$  
4rodrig@login01 PracticalGuidelines]$ sbatch run-strat-main-gpu.sb
```

Keras/Tensorflow strategy single GPU node

View your job queue and 'ssh' into the GPU node

```
[p4rodrig@login01 PracticalGuidelines]$ squeue -u $USER
JOBID PARTITION NAME USER ST TIME NODES NODELIST(REASON)
32768950 gpu tfstrat- p4rodrig R 4:07 1 exp-3-57
32768191 shared galyleo- p4rodrig R 1:53:30 1 exp-1-48
[p4rodrig@login01 PracticalGuidelines]$ ssh exp-3-57
```

In the GPU node run 'nvidia-smi' to view GPU usage

```
Processes:
+-----+
| GPU  | GI  | CI  | PID  | Type | Process name          | GPU Memory |
|      | ID  | ID  |      |      |                       | Usage      |
+-----+
| 0     | N/A | N/A | 3541760 | C    | /usr/bin/python3      | 1006MiB    |
| 1     | N/A | N/A | 3541760 | C    | /usr/bin/python3      | 500MiB     |
| 2     | N/A | N/A | 3541760 | C    | /usr/bin/python3      | 500MiB     |
| 3     | N/A | N/A | 3541760 | C    | /usr/bin/python3      | 500MiB     |
+-----+
[p4rodrig@exp-3-57 PracticalGuidelines]$
```

TF has copied the model into each GPU, sharded the data, and coordinated learning

Keras/Tensorflow strategy single CPU node

View your job queue and 'ssh' into the CPU node

```
[p4rodrig@login02 PracticalGuidelines]$ sbatch run-strat-main-cpu.sb
Submitted batch job 32783480
[p4rodrig@login02 PracticalGuidelines]$ squeue -u $USER
```

JOBID	PARTITION	NAME	USER	ST	TIME	NODES	NODELIST (REASON)
32783384	compute	galyleo-	p4rodrig	PD	0:00	1	(Priority)
32783480	compute	tfstrat-	p4rodrig	R	0:42	1	exp-5-15

In the CPU node run `top -u $USER`

Then 'H', 'f', down arrow to 'n-th', space bar to toggle, (repeat for P), esc

```
top - 12:11:09 up 12 days, 16:48, 1 user, load average: 0.11, 1.32, 9.26
Threads: 2241 total, 1 running, 2233 sleeping, 0 stopped, 7 zombie
%Cpu(s): 0.0 us, 0.0 sy, 0.0 ni, 99.9 id, 0.0 wa, 0.0 hi, 0.0 si, 0.0 st
MiB Mem : 257485.8 total, 248059.2 free, 7220.5 used, 2206.2 buff/cache
MiB Swap: 0.0 total, 0.0 free, 0.0 used, 248576.1 avail Mem
```

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND	nTH	P
37332	p4rodrig	20	0	61016	6736	3572	R	1.0	0.0	0:00.39	top	1	47
36339	p4rodrig	20	0	89608	9708	8252	S	0.0	0.0	0:00.03	systemd	1	115
36341	p4rodrig	20	0	301604	6708	0	S	0.0	0.0	0:00.00	(sd-pam)	1	64
36392	p4rodrig	20	0	12992	3384	2840	S	0.0	0.0	0:00.00	bash	1	71
36458	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	40
36484	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	104
36485	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	37
36486	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	106
36487	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	105
36488	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	105
36498	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	100
36499	p4rodrig	20	0	1779320	19224	12896	S	0.0	0.0	0:00.00	starter-suid	8	50
36482	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:05.77	python3	384	48
36507	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.10	python3	384	45
36508	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.10	python3	384	72
36509	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.11	python3	384	32
36510	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.11	python3	384	101
36511	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.11	python3	384	12
36512	p4rodrig	20	0	23.4g	1.0g	339112	S	0.0	0.4	0:00.11	python3	384	104

TF uses threads and available CPU cores for parallelization

Keras/Tensorflow strategy multiple GPU/CPU node

Keras also has a 'multiworker' strategy but it requires setting up config files with IP addresses

But, on HPC systems resources are shared so IP addresses are dynamic

Thus, it is better to use Horovod with MPI and slurm batch job

Multinode, mpi launches instances

In slurm batch script:

`mpirun -n number of tasks singularity → python`

Your python script

Load data

Build model

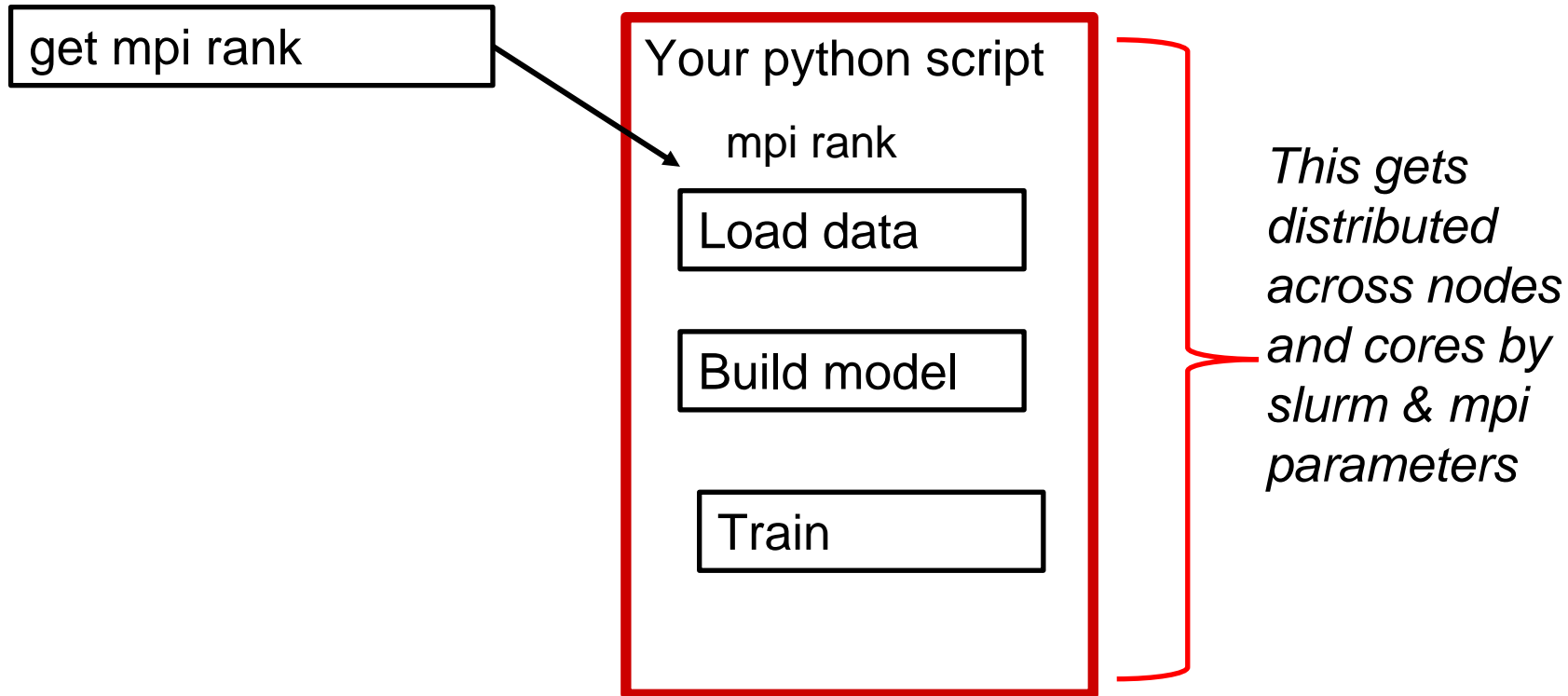
Train

*This gets
distributed
across nodes
and cores by
slurm & mpi
parameters*

Multinode, mpi launches instances

In slurm batch script:

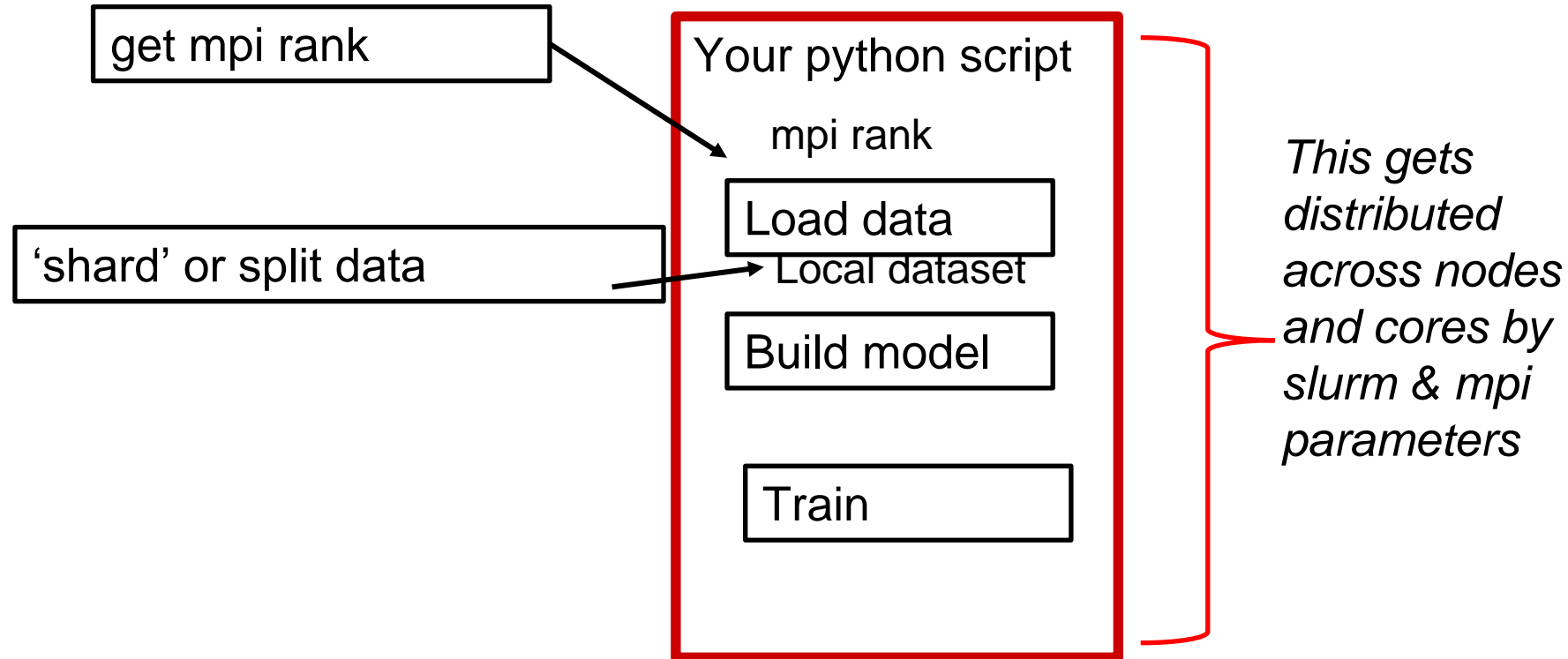
`mpirun -n number of tasks singularity → python`



Multinode, mpi launches instances

In slurm batch script:

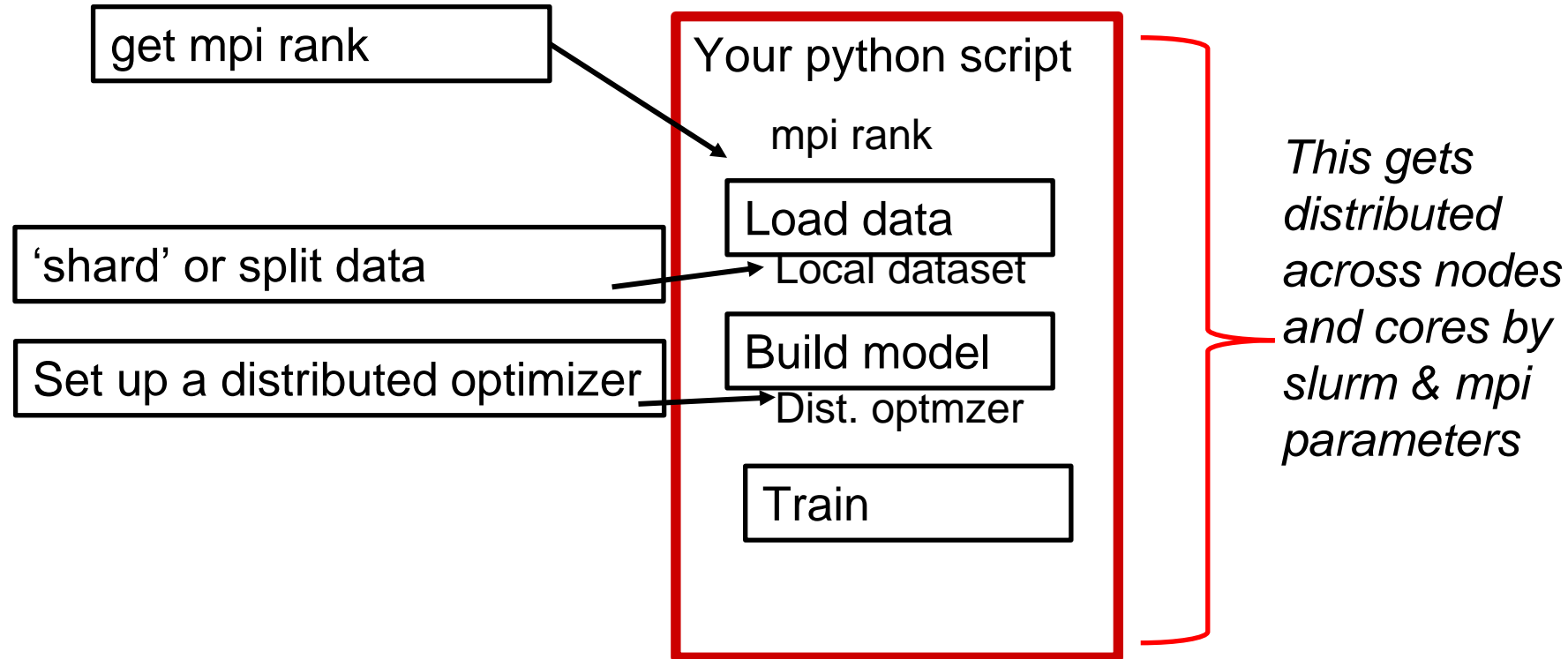
`mpirun -n number of tasks singularity → python`



Multinode, mpi launches instances

In slurm batch script:

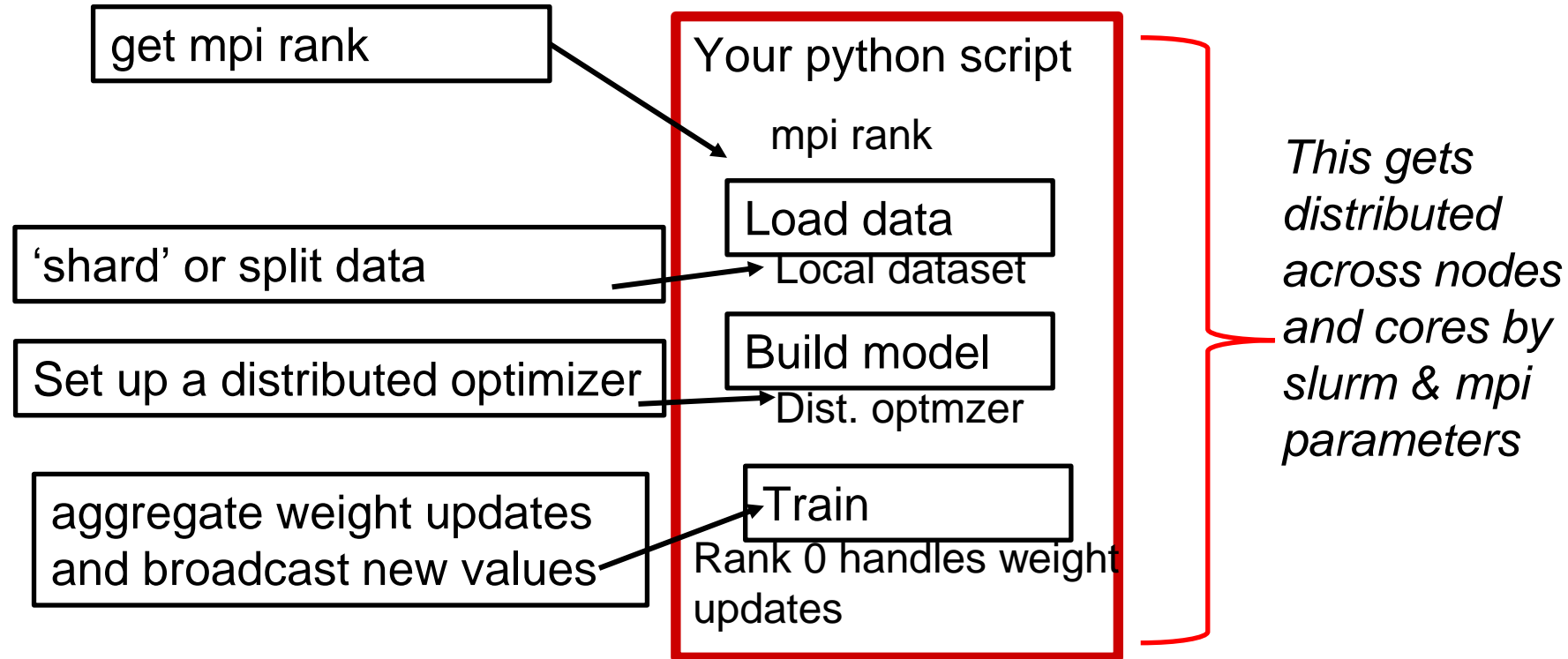
`mpirun -n number of tasks singularity → python`



Multinode, mpi launches instances

In slurm batch script:

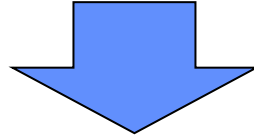
`mpirun -n number of tasks singularity → python`



mpi launches one instance per processor

In slurm batch script:

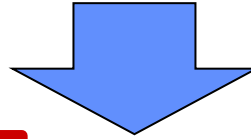
```
mpirun -n number of tasks singularity → python
```



mpi launches one instance per processor

In slurm batch script:

`mpirun -n number of tasks singularity → python`



device =GPU:0

Your python script

mpi rank

Load data

Local dataset

Build model

Dist. optmzer

Train

Rank 0 handles
updates

device =GPU:0

Your python script

mpi rank

Load data

Local dataset

Build model

Dist. optmzer

Train

.....

.....

device =GPU:0

Your python script

mpi rank

Load data

Local dataset

Build model

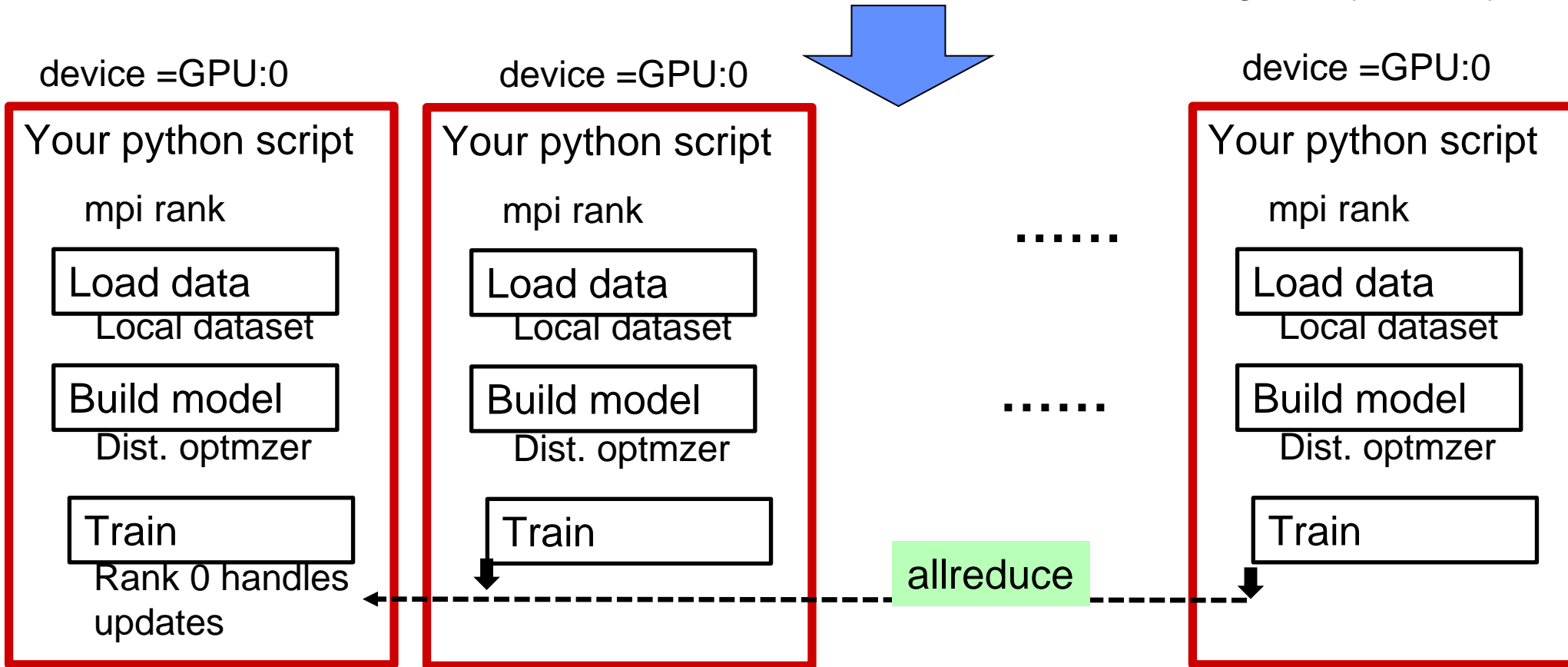
Dist. optmzer

Train

For each batch: Horovod will aggregate & share weights updates

In slurm batch script:

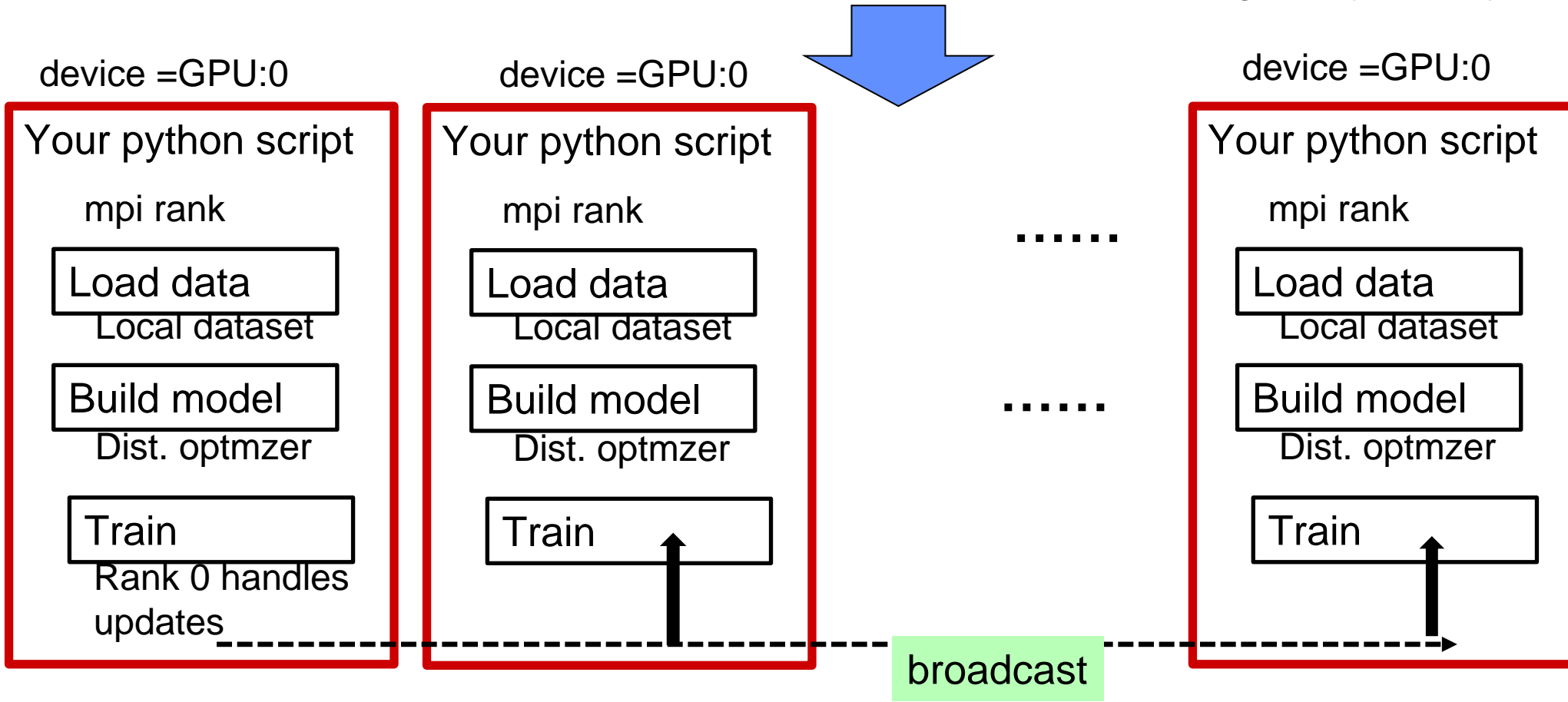
`mpirun -n number of tasks singularity → python`



For each batch: Horovod will aggregate & share weights updates

In slurm batch script:

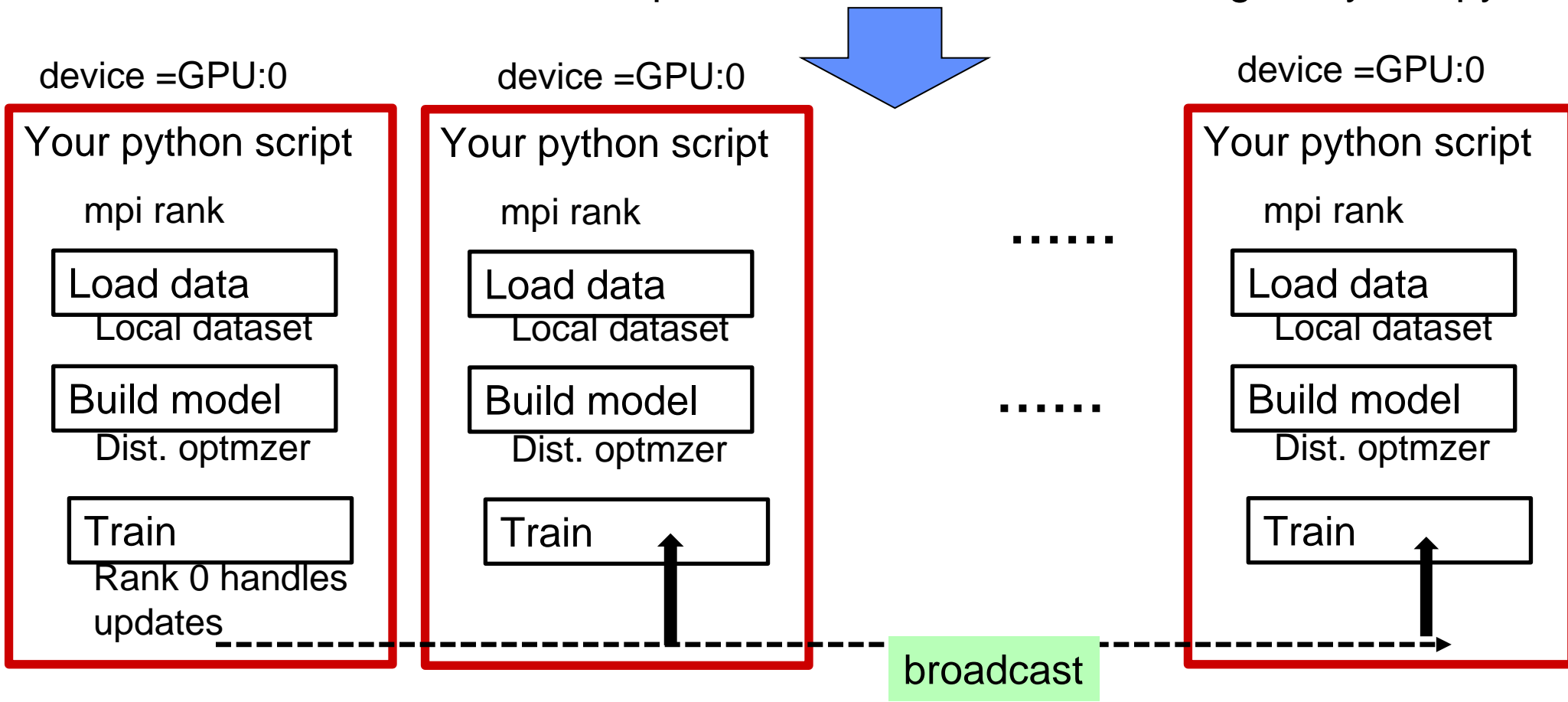
`mpirun -n number of tasks singularity → python`



For each batch: Horovod will aggregate & share weights updates

In slurm batch script:

`mpirun -n number of tasks singularity → python`



Bigger batch size helps, but it uses more memory

Code snippets – Horovod functions

Initialize back end
communication,
get mpi rank

```
import horovod.tensorflow.keras as hvd  
hvd.init()
```

'shard' or split data

Note: many ways to do this, either directly
splitting numpy arrays and/or using TF datasets

Set up a distributed optimizer

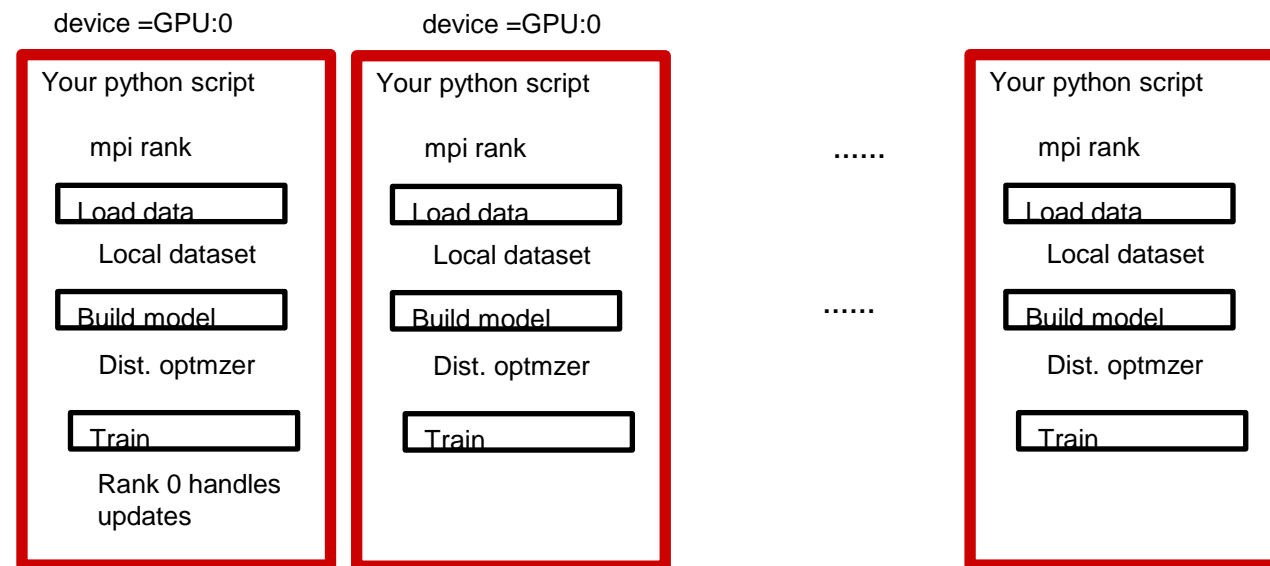
```
optimizer2use = hvd.DistributedOptimizer(.....)
```

Horovod takes care of the communication for
training and updating weights

Exercise, multinode MNIST programming and execution

- **Goal: Get familiar with Keras and Horovod coding for multinode execution**
- **Goal: Get familiar with slurm batch script multinode parameters**
- **Let's login and start a notebook (see next pages for quick overview)**

`mpirun -n number of tasks singularity → python`



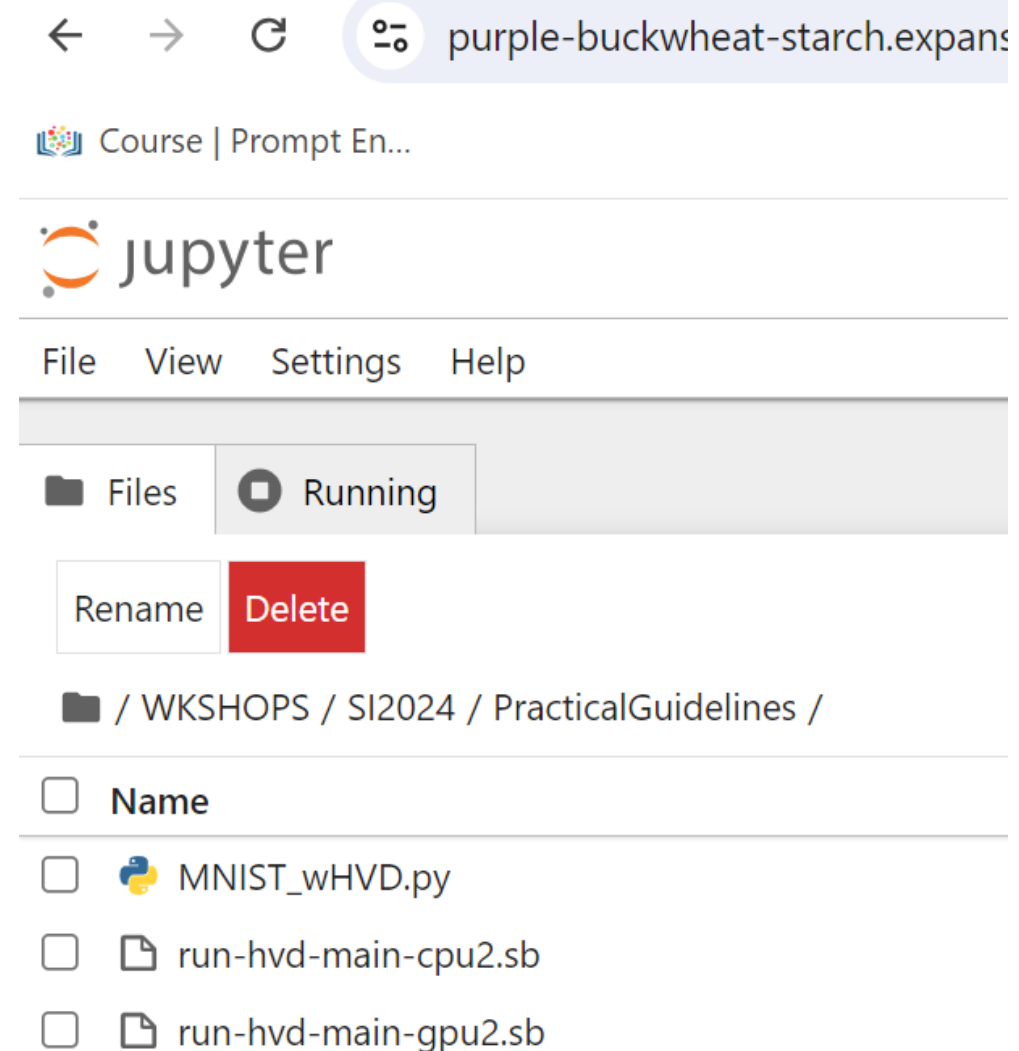
In terminal

```
$ jupyter-compute-tensorflow
```

In jupyter notebook session open the *MNIST_wHVD* notebook

Open the *run-hvd-main-cpu2.sb* slurm batch script

Follow instructions in the notebook and batch script



Initialize back end
communication,
get mpi rank

```
▶ #-----  
import horovod.keras as hvd  
hvd.init()  
print('INFO, global rank:', hvd.rank(), ' localrank ', hvd.local_rank())  
#-----
```

split data using
numpy arrays

```
# ----- Get Dataset -----  
per_worker_batch_size = 32          #Pick factors of 32 (especially for GPU)  
num_workers            = hvd.size()
```

Set up a distributed optimizer
to manage weight updates

```
# -----  
  
#----- Enter the num of processes to scale the Learning rate here -----  
optimizer2use = tf.keras.optimizers.Adam(learning_rate=0.001*hvd.size()) #<<<<<<-----  
optimizer2use = hvd.DistributedOptimizer(optimizer2use)  
  
# ----- for HVD -----  
#Specify `experimental_run_tf_function=False` to ensure TensorFlow
```

Your Task:

- run sbatch command for the slurm script (for cpu)
- change number of cpus to use, rerun, and review stdout output file

```
Launcher X MNIST_wHVD_solution.py X +
10 # 2
11 # Do a File->open of the run-hvd-main-cpu2.sb slurm batch script
12 # optionally edit the number of cpus to use, try for example 4,8,16, and/or 32
13 # 3
14 # In a terminal window, submit the script and review the job status
15 # ]$ sbatch run-hvd-main-cpu2.sb
16 # ]$ squeue -u your-userid
17 #
18 # Optionally, ssh into the running nodes and run top command (top -u userid)
19 #
20 # 4
21 # After the job finishes look at the stdout .txt file
```

jupyter run-hvd-main-cpu2.sb ✓ 15 minutes ago Logout

File Edit View Language Plain Text

```
2
3 #SBATCH --job-name=tfhvd-cpu
4 #SBATCH --account=use300
5 #SBATCH --partition=compute
6 #SBATCH --nodes=2
7 #SBATCH --ntasks-per-node=16 #<<<<<----- change this to 16 and observe changes in training time
8 #SBATCH --cpus-per-task=1
9 #SBATCH --mem=243G
10 #SBATCH --time=00:15:00
11 #SBATCH --output=slurm.cpu2.%x.o%j.out
12
```

```
[p4rodrig@login01 MNODE_wHVD]$
[p4rodrig@login01 MNODE_wHVD]$ grep 'done, rk: 15' stdout_*
stdout_cpu2_mnist_32.txt:INFO,done, rk: 15 train time: 2.48225 secs
stdout_mainhvd_cpu2.txt:INFO,done, rk: 15 train time: 2.31222 secs
[p4rodrig@login01 MNODE_wHVD]$
[p4rodrig@login01 MNODE_wHVD]$
```


- **Pause** ... you might find trade offs in communication vs cpus

```
in113@login01 3.3.Practical-Training]$ grep 'done, rank: 0 train' stdout_cpu2_mnist_*
ut_cpu2_mnist_16.txt:INFO,done, rank: 0 train time: 19.10057 secs
ut_cpu2_mnist_32.txt:INFO,done, rank: 0 train time: 15.46317 secs
ut_cpu2_mnist_8.txt:INFO,done, rank: 0 train time: 33.32454 secs
in113@login01 3.3.Practical-Training]$
```

- **End**