

Harsh Arya (B20043)

1 a.

Table 1 Minimum and Maximum Attribute Values Before and After Min-Max Normalization

| S. No. | Attribute | Before Min-Max Normalization | | After Min-Max Normalization | |
|--------|----------------------------------|------------------------------|-----------|-----------------------------|---------|
| | | Minimum | Maximum | Minimum | Maximum |
| 1 | Temperature (in °C) | 10.085 | 31.375 | 3.0 | 9.0 |
| 2 | Humidity (in g.m ⁻³) | 34.206 | 99.720 | 3.0 | 9.0 |
| 3 | Pressure (in mb) | 992.654 | 1037.604 | 3.0 | 9.0 |
| 4 | Rain (in ml) | 0.000 | 2470.500 | 3.0 | 9.0 |
| 5 | Lightavgw/o0 (in lux) | 0.000 | 10565.352 | 3.0 | 9.0 |
| 6 | Lightmax (in lux) | 2259.000 | 54612.000 | 3.0 | 9.0 |
| 7 | Moisture (in %) | 0.000 | 100.000 | 3.0 | 9.0 |

Inferences:

- 1. Outliers are replaced with median of the remaining data. It is necessary as outliers affects the range of the data.
- 2. Before normalization the range of attributes were different. After normalization the range of all attributes becomes the same (3-9).
- 3. Normalization helps to prevent attributes with large ranges from overweighting attributes with smaller attributes.

b.

Table 2 Mean and Standard Deviation Before and After Standardization

| S. No. | Attribute | Before Standardization | | After Standardization | |
|--------|----------------------------------|-------------------------------|----------------|-----------------------|----------------|
| | | Mean | Std. Deviation | Mean | Std. Deviation |
| 1 | Temperature (in °C) | 21.370 | 4.125 | 0.0 | 1.0 |
| 2 | Humidity (in g.m ⁻³) | 83.992 | 17.566 | 0.0 | 1.0 |
| 3 | Pressure (in mb) | 1014.760 | 6.121 | 0.0 | 1.0 |
| 4 | Rain (in ml) | 168.400 | 399.689 | 0.0 | 1.0 |
| 5 | Lightavgw/o0 (in lux) | 2197.392 | 2220.820 | 0.0 | 1.0 |
| 6 | Lightmax (in lux) | 21788.623 | 22064.993 | 0.0 | 1.0 |
| 7 | Moisture (in %) | 32.386 | 33.653 | 0.0 | 1.0 |



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- 1. Before standardization the mean and standard deviation of the attributes are of different values. After standardization the mean becomes 0 and the standard deviation becomes 1 for all attributes in the data.
- 2. It is useful when the actual minimum and maximum of attribute are unknown.

2 a.

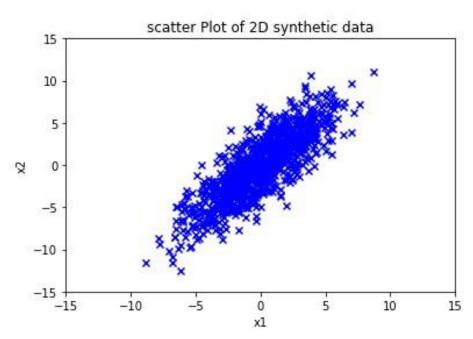


Figure 1 Scatter Plot of 2D Synthetic Data of 1000 samples Inferences:

- 1. Attributes seem to have a strong positive correlation. As the value of x1 increases x2 also increases. On computation the Pearson's correlation coefficient is around 0.82 same as expected from the covariance matrix.
- 2. The plot has high density around origin (mean value). The variance of x1 is smaller than that of x2 as expected
- 3. The plot shows the Gaussian bivariate distribution.



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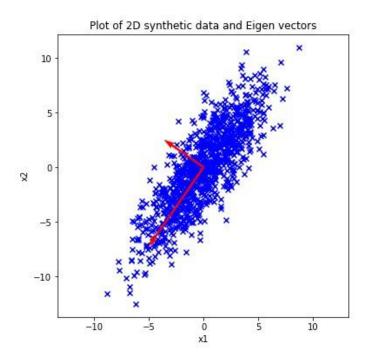


Figure 2 Plot of 2D Synthetic Data and Eigen Directions

Inferences:

- 1. Eigen value1: 1.703, Eigen vector1: [-0.833, 0.554]
- 2. Eigen value2: 19.688, Eigen vector2: [-0.554, -0.833]
- 3. We can observe that the spread of the data is more across 2nd eigen vector than the 1st. This is because the magnitude of eigen value 2 is greater than eigen value 1.
- 4. The plot has high density around the origin (point of intersection of eigen axes), since it is the mean of the distribution as we move away along 2 axes the density decreases.
- 5. Larger the eigen value, larger the distribution of data along the corresponding eigen vector.

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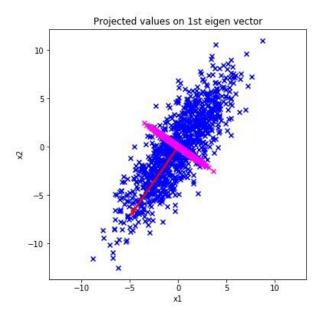


Figure 3 Projected Eigen Directions onto the Scatter Plot with 1st Eigen Direction highlighted

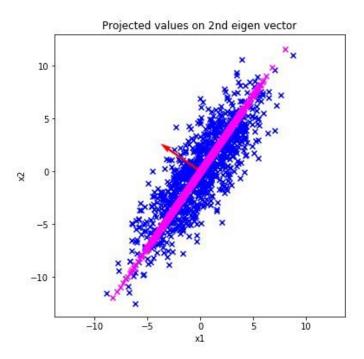


Figure 4 Projected Eigen Directions onto the Scatter Plot with 2nd Eigen Direction highlighted



Assignment 3 Harsh Arya (B20043)

Inferences:

- 1. Eigen value1: 1.703, Eigen value2: 19.688. Eigen value ∝ variance in projection.
- 2. Variance of data along eigen vector2> variance of data along eigen vector2. Variance along eigen vector ∝ spread of data along eigen vector 1/∝ density of data. Variance along eigen vector = Magnitude of eigen value.
- 3. Larger the eigen value, larger the information content in the direction of corresponding eigen vector.
- **d.** Reconstruction Error = 0.000

- 1. Magnitude of reconstruction error \propto Loss of information in compressed data.
- 2. Reconstruction Error= 0 <=> The data reduction is called lossless.



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Table 3 Variance and Eigen Values of the projected data along the two directions

| Direction | Variance | Eigen Value | | |
|-----------|----------|-------------|--|--|
| 1 | 2.1999 | 2.2022 | | |
| 2 | 1.4193 | 1.4208 | | |

Inferences:

1. Eigenvalues and variances of the directions of projection in this reduced data are numerically very close meaning eigenvalues signify the spread/variance of data around a direction of projection.

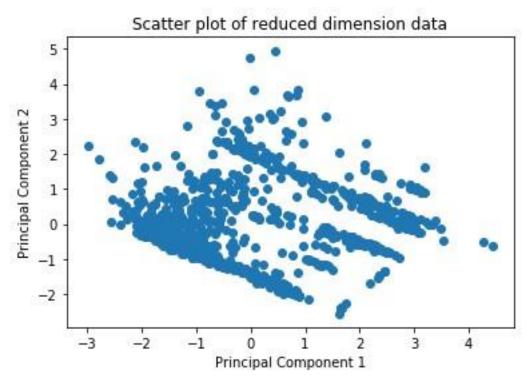


Figure 5 Plot of Landslide Data after dimensionality reduction



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- 1. Since the number of eigendirections and the original dimensions of the data are the same, no actual dimension reduction has been performed. The data points only have been projected onto a new basis.
- 2. Therefore, the MSE calculated for this instance is vanishingly close to zero as the "reduced data" takes up the same number of dimensions as previous data.
- 3. From the plot the median of both attributes of the reduced data seem to be less than the mean (positively skewed).
- 4. The reduced data is uncorrelated.

b)

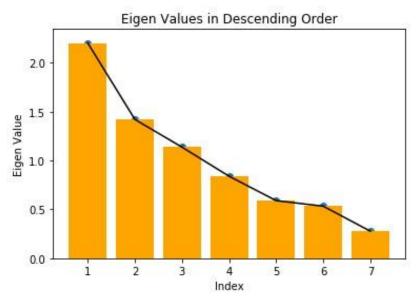


Figure 6 Plot of Eigen Values in descending order

- 1. Eigen values decrease gradually.
- 2. Highest rate of decrease is from eigen value 1 to eigen value 2.



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c.

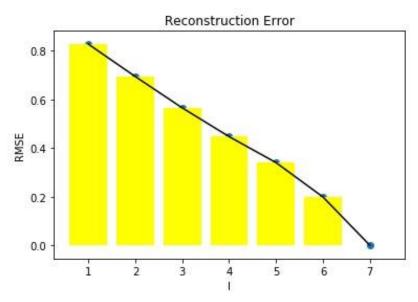


Figure 7 Line Plot to demonstrate Reconstruction Error vs. Components

- 1. Magnitude of reconstruction error $1/\alpha$ the quality of reconstruction.
- 2. As I -> d, reconstruction error -> 0.
- 3. Reconstruction error = $0 \Rightarrow Data$ reduction is lossless. If reconstruction error $\neq 0 \Rightarrow Data$ reduction is called lossy.