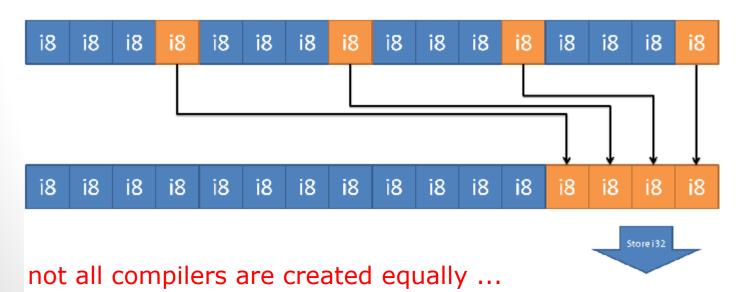
cse5441 - parallel computing



vectorizing compilers



array programming

array programming languages (such as Fortran 90) provide operators which generalize scalar functions to higher dimensions

Fortran 77

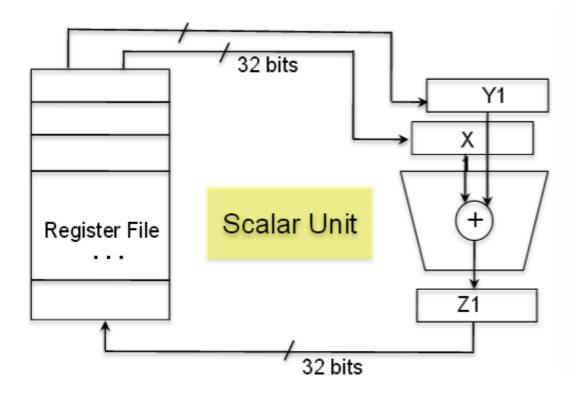
do
$$i=1,n$$

do $j=1,n$
 $C(j,i) = A(j,i) + B(j,i)$
enddo
enddo

Fortran 90

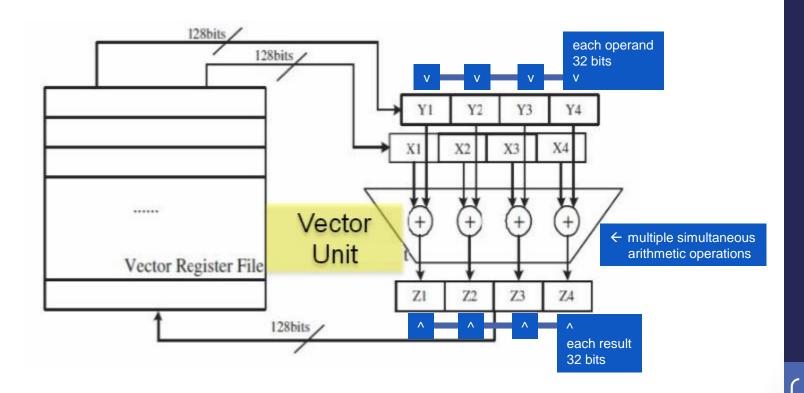
$$C = A + B$$

scalar arithmetic / logic unit (ALU)



3

vector arithmetic / logic unit



4

unordered data distribution

```
for (iband = 0; iband < nbands; iband++)
    for (idir = 0; idir < ndir; idir++)
        for (icell = 0; icell < ncells; icell++)
              for (iface = 0; iface < nfcell[icell]; iface++)
                   if (bface[currf] == 0)
                                                 //interior face
                      do stuff(interior);
                                                 //boundary face
                  else
                      if (bctype[ibface] == ADIA)
                           do stuff(ADIA);
                      else if (bctype[ibface] == ISOT)
                           do stuff(ISOT);
                   }//end -- if interior or boundary case
                   else
              }//end -- loop over cell faces
        }//end - cell loop
   }//end – dir loop
}//end - band loop
```

INPUT DATA (stylized)

INTER
INTER
ADIA
ISOT
PERM
INTER
PERM
ADIZ
ADIZ
INTER
PERM
ISOT
PERM

ADIA

ISOT XPR

ISOT

PERM ADIA INTER assume all inputs are of same type, and in these application categories

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SIMD adaptation

UNORDERED INPUT DATA

INTER INTER ADIA ISOT **PERM INTER PERM** ADIZ ADIZ **INTER PERM** ISOT **PERM ADIA ISOT XPR** ISOT **PERM ADIA INTER**

PARTITIONED INPUT DATA

ADIA ADIA INTER INTER INTER INTER INTER

SIMD adaptation

```
for (iband = 0; iband < nbands; iband++)
    for (idir = 0; idir < ndir; idir++)
        for (icell = 0; icell < ncells; icell++)
              for (iface = 0; iface < nfcell[icell]; iface++)
                   if ( bface[currf] == 0 )
                                                  //interior face
                       do stuff(interior);
                                                  //boundary face
                   else
                       if (bctype[ibface] == ADIA)
                           do_stuff(ADIA);
                       else if (bctype[ibface] == ISOT)
                           do_stuff(ISOT);
                   }//end -- if interior or boundary case
              }//end -- loop over cell faces
        }//end - cell loop
    }//end - dir loop
}//end - band loop
```

```
for (iband = 0; iband < nbands; iband++)
   for (idir = 0; idir < ndir; idir++)
       for (iface = 0; iface < nf max; iface++)
              //process interior cell faces
              for (indx = 0; indx < num if cells[iface]; indx++)
                  do stuff(interior);
              //process ISOT cell faces
              for (indx = ISOT offset;
                  indx < ISOT offset+num isot cells[iface];
                  indx++)
                  do stuff(ISOT);
              //process ADIA cell faces
              for (indx = ADIA offset;
                  indx < ADIA offset+num adia cells[iface];
                   indx++)
                  do stuff(ADIA);
       }//end - face loop
   }//end - dir loop
}//end - band loop
```

C/C++ vectorizing compilers

```
for (int i = 0; i < n; i++)
c[i] = a[i] + b[i];
```

compilers automatically handle the simple cases

```
for (int i = 0; i < n; i++)
{
    sum = 0.0;
    for (int j = 0; j < n; j++)
    {
        sum += A[j][i];
    }
    B[i] = sum;
}</pre>
```

what makes this loop more challenging?

- no stride-1 access
- sum creates a loop-carried dependency for i

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C/C++ vectorizing compilers

example

```
for (int i = 0; i < n; i++)
  sum = 0.0;
  for (int j = 0; j < n; j++)
     sum += A[j][i];
  B[i] = sum;
```

```
for (int i = 0; i < n; i++)
  sum[i] = 0.0;
  for (int j = 0; j < n; j++)
     sum[i] += A[j][i];
  B[i] = sum[i];
                        В
```

```
scalar expansion:
```

eliminates loop dependency

```
for (int i = 0; i < n; i++)
  sum[i] = 0.0;
for (int j = 0; j < n; j++)
  for (int i = 0; i < n; i++)
     sum[i] += A[j][i];
for (int i = 0; i < n; i++)
  B[i] = sum[i];
                         C
```

plus loop reordering and distribution:

> provides stride-1 access

C/C++ vectorizing compilers

example

```
for (int i = 0; i < n; i++)
{
    sum = 0.0;
    for (int j = 0; j < n; j++)
    {
        sum += A[j][i];
    }
    B[i] = sum;
}</pre>
```

Intel Nehalem

loop not vectorized

IBM Power 7

loop not vectorized

```
for (int i = 0; i < n; i++)
{
    sum[i] = 0.0;
    for (int j = 0; j < n; j++)
    {
        sum[i] += A[j][i];
    }
    B[i] = sum[i];
}</pre>
```

Intel Nehalem

loop vectorized speedup: 2.6 (62% faster) relative run-time 0.6

IBM Power 7

loop interchanged and vectorized speedup: 2.0 (50% faster) relative run-time 0.2

10

stripmine

step 1 of 2

ORIGINAL

```
for (int i = 0; i < n; i++)
{
S1 A[i] = B[i] + 1.0;
S2 C[i] = A[i] + 2.0;
}
```

STRIPMINE

```
for (int i = 0; i < n; i+= stripsize)
{
   for (int j = i; j < i+stripsize; j++)
   {
      A[j] = B[j] + 1.0;
      C[j] = A[j] + 2.0;
   }
}</pre>
```

stripmine - distribute

step 2 of 2

ORIGINAL

```
for (int i = 0; i < n; i++)
{
S1 A[i] = B[i] + 1.0;
S2 C[i] = A[i] + 2.0;
}
```

STRIPMINE

```
for (int i = 0; i < n; i+= stripsize)
{
   for (int j = i; j < i+stripsize; j++)
   {
      A[j] = B[j] + 1.0;
      C[j] = A[j] + 2.0;
   }
}</pre>
```

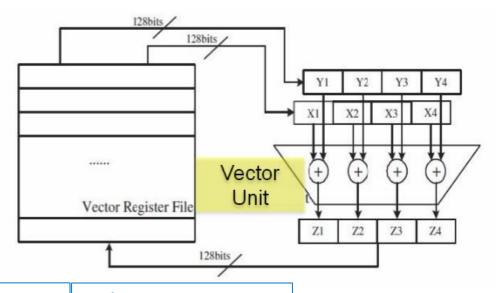
VECTORIZED

```
for (int i = k; i < n; i+=q)
{
    A[i:i+q-1] = B[i:i+q-1] + 1.0;
}
for (int i = k; i < n; i+=q)
    {
    C[i:i+q-1] = B[i:i+q-1] + 2.0;
}</pre>
```

DISTRIBUTE

```
for (int i = 0; i < n; i+= stripsize)
{
    for (int j = i; j < i+stripsize; j++)
    {
        A[j] = B[j] + 1.0;
    }
    for (int j = i; j < i+stripsize; j++)
    {
        C[j] = A[j] + 2.0;
    }
}</pre>
```

vectorization result



scalar:

&operand1 load r1 load &operand2 add r1, r2 store r3 &result &operand1a load &operand2a load add r1, r2 r3 &result store

scalar:

load r1 &operand1b &operand2b load add r1, r2 &result store r3 &operand1c load &operand2c load add r1, r2 &result r3 store

vector:

loadv vr1 &operand1 loadv vr2 &operand2 addv vr3 vr1, vr2 storev vr3 &result

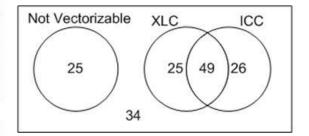
13

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how well do compilers vectorize?

| Compiler | XLC | ICC | GCC |
|------------------|------|------|------|
| Total | 159 | | |
| Vectorized | 74 | 75 | 32 |
| Not vectorized | 85 | 84 | 127 |
| Average Speed Up | 1.73 | 1.85 | 1.30 |

| Compiler | XLC but not ICC | ICC but not XLC |
|------------|-----------------|--------------------|
| Vectorized | 25 | 26 |

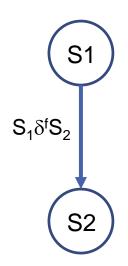


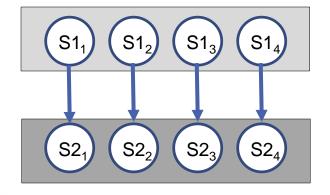
adding manual vectorization hints increased the average speedup (IBM) from 1.73 to 3.78

acyclic dependence graphs

forward dependencies

```
for (int i = 0; i < max; i++)
{
S1 a[i] = b[i] + c[i];
S2 d[i] = a[i] + 1;
}
```



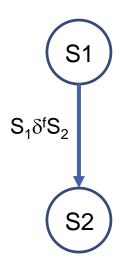


can we group all the S1_n and follow with S2_n?

forward dependencies

example

```
for (int i = 0; i < max; i++)
{
S1 a[i] = b[i] + c[i];
S2 d[i] = a[i] + 1;
}
```



XLC: vectorized, speedup 2.0

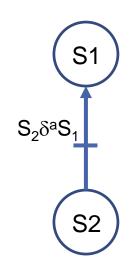
ICC: vectorized, speedup 1.6

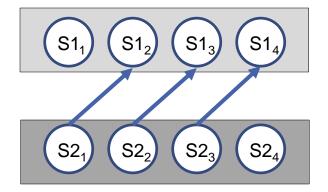
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acyclic dependence graphs

backward dependencies

```
for (int i = 0; i < max; i++)
{
S1 a[i] = b[i] + c[i];
S2 d[i] = a[i+1] + 1;
}
```



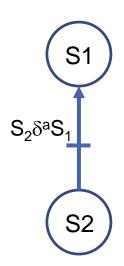


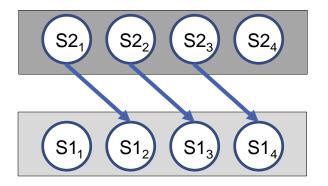
can we group all the S2_n and follow with S1_n?

acyclic dependence graphs

backward dependencies

```
for (int i = 0; i < max; i++)
{
S2 d[i] = a[i+1] + 1;
S1 a[i] = b[i] + c[i];
}
```





can we group all the S2_n and follow with S1_n?

backward dependencies

example

```
original

for (int i = 0; i < max; i++)
{
    a[i] = b[i] + c[i];
    d[i] = a[i+1] + 1;
}</pre>
re-ordered

for (int i = 0; i < max; i++)
{
    d[i] = a[i+1] + 1;
    a[i] = b[i] + c[i];
}</pre>
```

ICC time 12.6

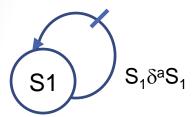
XLC time 0.6 vectorized

ICC time 9.4 vectorized

XLC time 0.6 vectorized

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cyclic dependence graphs



```
for (int i = 0; i < max; i++)
{
    a[i] = a[i+1] + b[i];
}
```

vectorized
XLC
vectorized

```
S_1 S_1\delta^fS_1
```

```
for (int i = 0; i < max; i++)
{
    a[i] = a[i-1] + b[i];
}
```

ICC
non-vectorized
XLC
non-vectorized

```
S_1 S_1\delta^fS_1
```

```
for (int i = 0; i < max; i++)
{
    a[ i ] = a[ i-4] + b[ i ];
}
```

vectorized XLC vectorized

more on vectorizing compilers ...

references:

- "Intel® Cilk™ Plus Support," [online] _software.intel.com/en-us/articles/intel-cilk-plus-support
- "A Guide to Auto-vectorization with Intel® C++ Compilers," [online] software.intel.com/en-us/articles/a-guide-to-auto-vectorization-with-intel-c-compilers
- "Quick-Reference Guide to Optimization with Intel® Compilers version 13," [online] software.intel.com/sites/default/files/Compiler_QRG_2013.pdf
- "Intel® C++ Intrinsics Reference," [online] software.intel.com/sites/products/documentation/studio/composer/en-us/2011/compiler_c/intref_cls/common/intref_bk_intro.htm
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- "Compiler Prefetching for the Intel® Xeon Phi™ coprocessor," [online] software.intel.com/sites/default/files/managed/5d/f3/5.3-prefetching-on-mic-4.pdf

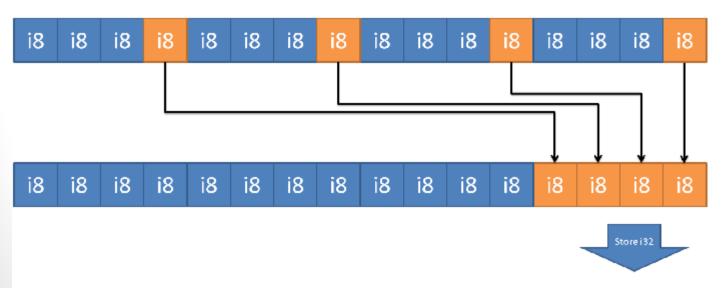
trade-offs



vectorization is not always profitable ...

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vectorizing compilers



not all compilers are created equally ...

23