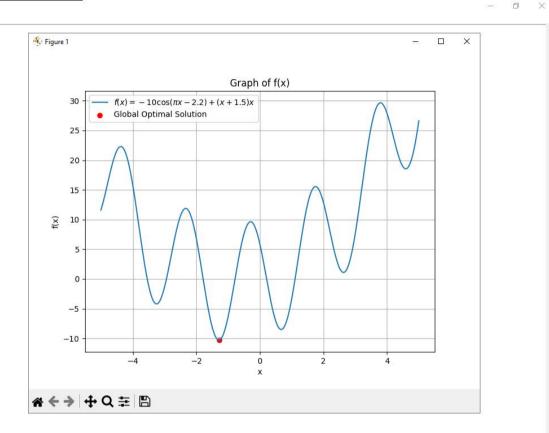
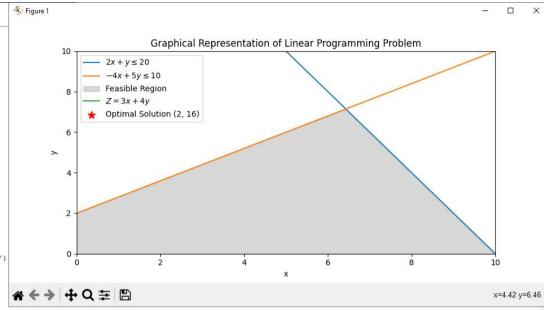
```
JDLE Shell 3.11.0 - C;/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/WAP LPP graphically.py (3.11.0)
                                                                                                                                                                                                                                           - 0 X
File Edit She<u>ll Debug Options Window H</u>elp
      🖟 Line search method.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/Line search method.py (3.11.0)
                                                                                                                                                                                                                                                File Edit Format Run Options Window Help
     import numpy as np
     # Define the objective function
     def f(x):
        return x^*2 + 5 * x + 6 # Example function: <math>f(x) = x^2 + 5x + 6
     # Define the derivative of the objective function
     def f prime(x):
        return 2 * x + 5 # Derivative of f(x)
     # Line search method to find the optimal solution
     def line_search_method(x_start, direction, step_size, epsilon=le-5, max_iterations=1000):
         iteration = 0
         while iteration < max iterations:
             gradient = f_prime(x)
             new x = x + step size * direction
             # If the change is negligible or the gradient is close to zero, stop
             if np.abs(new_x - x) < epsilon or np.abs(gradient) < epsilon:</pre>
                 break
             x = new x
             iteration += 1
         return x, f(x)
     # Set initial values
     x start = 0 # Initial value of x
     search direction = -1 # Direction of search (-1 for minimizing the function)
     step = 0.1 # Step size for the line search
     # Perform line search
     optimal solution, minimum value = line search method(x start, search direction, step)
     print("Optimal Solution (x):", optimal solution)
     print("Minimum Value of f(x):", minimum_value)
                                                                                                                                                                                                                                                Ln: 39 Col: 0
                                                                       KESTAKI. C./ OSCIS/HCHUI/Apppada/ EGGAI/IIOGIAMS/IYUHOH/IYUHOHJI/GOIIEGE WOIX HCHUI NO/BINC SCAICH MCCHOULPY
     Optimal Solution (x): -2.5000000000000001
    Minimum Value of f(x): -0.2499999999999991
                                                                                                                                                                                                                                                 Ln: 52 Col: 0
```

```
🚡 *global solution graphically.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/global solution graphically.py (3.11.0)*
<u>File Edit Format Run Options Window Help</u>
 import numpy as np
import matplotlib.pyplot as plt
# Define the function
def f(x):
    return -10 * np.cos(np.pi * x - 2.2) + (x + 1.5) * x
# Generate x values
x_values = np.linspace(-5, 5, 1000)
# Calculate corresponding y values (function values)
y_values = f(x_values)
# Find the x value that corresponds to the minimum y value (global minimum)
optimal_x = x_values[np.argmin(y_values)]
optimal_y = np.min(y_values)
# Plot the function
plt.figure(figsize=(8, 6))
plt.plot(x\_values, y\_values, label=r'\$f(x)=-10\\cos(\pi x - 2.2)+(x+1.5)x\$')
plt.scatter(optimal_x, optimal_y, color='red', label='Global Optimal Solution')
plt.title('Graph of f(x)')
plt.xlabel('x')
plt.ylabel('f(x)')
plt.legend()
plt.grid(True)
plt.show()
print("Global Optimal Solution (x):", optimal_x)
```

print("Minimum Value of f(x):", optimal_y)



```
🝌 *WAP LPP graphically.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/WAP LPP graphically.py (3.11.0)*
<u>File Edit Format Run Options Window Help</u>
import matplotlib.pyplot as plt
import numpy as np
\sharp Define the objective function coefficients (Z = cx + dy)
# Define the constraints (in the form ax + by <= c)
constraint1 = {'a': 2, 'b': 1, 'c': 20} # 2x + y <= 20
constraint2 = {'a': -4, 'b': 5, 'c': 10} # -4x + 5y <= 10
# Calculate the feasible region
x = np.linspace(0, 10, 400) # Range of x values
# Constraint 1: 2x + y <= 20
yl = (constraintl['c'] - constraintl['a']*x) / constraintl['b']
# Constraint 2: -4x + 5y <= 10
y2 = (constraint2['c'] - constraint2['a']*x) / constraint2['b']
# Plotting the constraints and feasible region
plt.figure(figsize=(8, 6))
plt.plot(x, yl, label=r'$2x + y \leq 20$')
plt.plot(x, y2, label=r'$-4x + 5y \leq 10$')
plt.fill\_between(x, 0, np.minimum(yl, y2), where=(yl>0) \& (y2>0), color='gray', alpha=0.3, label='Feasible Region')
plt.xlim((0, 10))
plt.ylim((0, 10))
plt.xlabel('x')
plt.ylabel('y')
plt.legend()
plt.title('Graphical Representation of Linear Programming Problem')
# Plot the objective function Z = cx + dy for some values of x and corresponding y in the feasible region
Z = c^*x + d^*yl + Using yl as it represents the upper bound of feasible y values
plt.plot(x, Z, label=r'$Z = 3x + 4y$')
optimal x = 2
optimal_y = 16
plt.scatter(optimal_x, optimal_y, color='red', marker='*', s=100, label='Optimal Solution (2, 16)')
plt.legend()
plt.show()
```



WAP for global Solution.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/WAP for global Solution.py (3.11.0) File Edit Format Run Options Window Help from scipy.optimize import fsolve IDLE Shell 3,11.0 import numpy as np File Edit Shell Debug Options Window Help # Define the derivative function Python 3.11.0 (main, Oct 24 2022, 18:26:48) [MSC v.1933 64 bit (AMD64)] on win32 def derivative(x): return 10 * np.pi * np.sin(np.pi * x - 2.2) + 2 * x + 1.5 Type "help", "copyright", "credits" or "license()" for more information. = RESTART: C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work M # Use fsolve to find the roots (where the derivative is zero) critical points = fsolve(derivative, [-2, 2]) # Initial guesses for roots ehul NO/WAP for global Solution.py Critical Points: [-2.3318272 1.75118297] Function Values at Critical Points: [11.88884336 15.565831] # Evaluate the function at the critical points Global Optimal Solution (Minimum): -2.3318271970896833 values_at_critical_points = -10 * np.cos(np.pi * critical_points - 2.2) + (critical_points + 1.5) * critical_points Minimum Function Value: 11.888843364338118 # Find the minimum value among the critical points global min index = np.argmin(values at critical points) global optimal solution = critical points[global_min_index] min_function_value = values_at_critical_points[global_min_index] print("Critical Points:", critical points) print("Function Values at Critical Points:", values at critical points) print("Global Optimal Solution (Minimum):", global optimal solution) print("Minimum Function Value:", min function value)

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Ln: 9 Col: 0

```
# WAP Hessian of the fuction.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/WAP Hessian of the fuction.py (3.11.0)

File Edit Format Run Options Window Help

import sympy as sp

# Define the variables
x1, x2 = sp.symbols('x1 x2')

# Define the function
f = 100 * (x2 - x1**2)**2 + (1 - x1)**2

# Compute the gradient
gradient = [sp.diff(f, var) for var in (x1, x2)]

# Compute the Hessian matrix
hessian = sp.hessian(f, (x1, x2))

# Print the gradient and Hessian matrix

# Print the gradient and Hessian matrix

Gradient of f(x): [-400*x1*(-x1**2 + x2) + 2
```

print("Gradient of f(x):", gradient)

print("\nHessian of f(x):")

print (hessian)

```
DLE Shell 3.11.0 - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Me... 

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File Edit Shell Debug Options Window Help
    Python 3.11.0 (main, Oct 24 2022, 18:26:48) [MSC v.1933 64 bit (AMD64)] on win32
    Type "help", "copyright", "credits" or "license()" for more information.
>>>
    = RESTART: C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work M
    ehul NO/WAP Hessian of the fuction.py
    = RESTART: C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work M
    ehul NO/WAP Hessian of the fuction.py
    Gradient of f(x): [-400*x1*(-x1**2 + x2) + 2*x1 - 2, -200*x1**2 + 200*x2]
    Hessian of f(x):
    Matrix([[1200*x1**2 - 400*x2 + 2, -400*x1], [-400*x1, 200]])
>>>
    = RESTART: C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work M
    ehul NO/WAP Hessian of the fuction.py
    Gradient of f(x): [-400*x1*(-x1**2 + x2) + 2*x1 - 2, -200*x1**2 + 200*x2]
    Hessian of f(x):
   Matrix([[1200*x1**2 - 400*x2 + 2, -400*x1], [-400*x1, 200]])
>>>
                                                                               Ln: 17 Col: 0
```

```
🚡 *global solution graphically.py - C:/Users/Mehul/AppData/Local/Programs/Python/Python311/College Work Mehul NO/global solution graphically.py (3.11.0)*
<u>File Edit Format Run Options Window Help</u>
 import numpy as np
import matplotlib.pyplot as plt
# Define the function
def f(x):
    return -10 * np.cos(np.pi * x - 2.2) + (x + 1.5) * x
# Generate x values
x_values = np.linspace(-5, 5, 1000)
# Calculate corresponding y values (function values)
y_values = f(x_values)
# Find the x value that corresponds to the minimum y value (global minimum)
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optimal_y = np.min(y_values)
# Plot the function
plt.figure(figsize=(8, 6))
plt.plot(x\_values, y\_values, label=r'\$f(x)=-10\\cos(\pi x - 2.2)+(x+1.5)x\$')
plt.scatter(optimal_x, optimal_y, color='red', label='Global Optimal Solution')
plt.title('Graph of f(x)')
plt.xlabel('x')
plt.ylabel('f(x)')
plt.legend()
plt.grid(True)
plt.show()
print("Global Optimal Solution (x):", optimal_x)
```

print("Minimum Value of f(x):", optimal_y)

