

# MTH 377/577 Convex Optimization

## Quiz 1

*Instructions: Answer all questions. Time= 1 hr 10 minutes.*

1. Let  $A$  be an  $m \times n$  matrix,  $b \in R^m$ .

- (a) Show that if the system of inequalities  $yA \geq 0$ ,  $yb < 0$  has a solution then the feasible set of non-negative solutions for  $Ax = b$  is empty. (3)

Ans. Suppose  $\exists y$  such that  $yA \geq 0$ ,  $yb < 0$  and the set  $F = \{x \geq 0 | Ax = b\}$  is non-empty. For any  $x \in F$ ,  $Ax = b \implies yAx = yb$ . However  $yA \geq 0$  and  $yb < 0$ . Therefore either  $y$  does not exist or  $F$  is empty.

- (b) Let  $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 1 \\ 2 & 1 & 3 \end{bmatrix}$  and  $b = \begin{bmatrix} 6 \\ 8 \\ 0 \end{bmatrix}$ . Use Farkas Lemma to find out if the system  $Ax = b$  has a non-negative solution. Show all the steps. (2)

Ans.(indicative) Solution to  $yA \geq 0$ ,  $yb < 0$  exists therefore  $Ax = b$  does not have a non-negative solution. For example:  $y = (1, -1, 2)$ . Show all the steps on your own as demonstrated in earlier problem sets.

2. State whether each of the following statements are true or false. Provide a brief mathematical explanation/counterexample to support your answer.

- (a) A polyhedron is always convex. (2)

Ans. True. A polyhedron is the intersection of finite number of halfspaces and hyperplanes.  $P = \{x \in R^n | Ax \leq b\}$ . Consider  $x_1, x_2 \in P$ , and any  $\theta \in [0, 1]$ .  $\theta x_1 \leq \theta b$  and  $(1 - \theta)x_2 \leq (1 - \theta)b$ . Adding, we get  $\theta x_1 + (1 - \theta)x_2 \leq b$  therefore  $\theta x_1 + (1 - \theta)x_2 \in P$ .

- (b) Let  $A = \{x, y, z\}$  be a set of vectors in  $R^2$ . Is the conic hull of  $A$  always convex? Is the convex hull of  $A$  a cone? (3)

Ans. (a) True. (b) False- convex hull is not necessarily a cone.

(Refer Page 4 onwards for Q(b) sol<sup>n</sup>) →

3. Let  $S = \{(x_1, x_2, x_3) \in R^3 \mid -10 \leq x_1, x_2, x_3 \leq 10\}$ . Do the following functions have a maxima/minima? Provide an explanation in support of your answer. (2+2+1)

- (a) Let  $f : S \rightarrow R$  where  $f(x) = x_1^2 + x_2^2 + x_3^2$ ; for all  $x = (x_1, x_2, x_3)$  in  $S$ . **Ans.**  $f$  is continuous and  $S$  is compact. By Weierstrass theorem, maxima and minima exist.

- (b) Let  $g : S \rightarrow R$  such that  $g(x) = \begin{cases} f(x) + 2, & x_1, x_2, x_3 \geq 0 \\ 0, & \text{otherwise} \end{cases}$   
**Ans**  $g$  is discontinuous at  $x = 0$ . Weierstrass theorem cannot be applied. We however can observe that  $x < 0$  and  $x = 10$  generate the minimum and maximum values of the function.

- (c) Does your answer change for  $f$  and  $g$  if

$$S = \{(x_1, x_2, x_3) \in R^3 \mid -10 < x_1, x_2, x_3 < 10\}$$

**Ans.** Yes,  $S$  is no longer closed, therefore it is not compact. We cannot apply Weierstrass theorem to  $f$ . For  $g$  now supremum exists at  $x = 10$  but it is no longer in the feasible set, therefore not maxima.

4. Consider the following sets in  $R^n$ :

$$A = \{(x_1, x_2, \dots, x_n) \in R^n \mid x_i \geq 2\}$$

$$B = \{(x_1, x_2, \dots, x_n) \in R^n \mid \sum_{i=1,2,\dots,n} x_i^2 \leq 2\}$$

$$C = \{(x_1, x_2, \dots, x_n) \in R^n \mid (x_1 - 2)^2 + \sum_{j=2,\dots,n} x_j^2 < 1\}$$

- (a) Does a separating hyperplane exist that separates  $A$  from  $B$ ? What about between  $A$  and  $B \cup C$ ? Why/why not? Use separating hyperplane theorems in your explanation. (3)

Ans.  $A, B$  are disjoint. Therefore, we must claim that a strictly separating hyperplane will exist using the hyperplane theorems (must contain some kind of mathematical derivation in order to prove that  $A$  and  $B$  are disjoint sets, diagrams might be included as

well.).  $B \cup C$  is non-convex (show diagram/brief proof) therefore, we cannot claim using the theorems that a separating hyperplane will exist between  $A$  and  $B \cup C$  (1.5+1.5).

- (b) Does a separating hyperplane exist that separates  $A$  from  $C$ ? If yes, explain how you can find such a hyperplane. If no, provide a reason/counterexample. Use separating hyperplane theorems in your explanation. (2)

Ans.  $A$  and  $C$  are not disjoint even if they might be convex and non-empty hence, according to the hyperplane theorem, since the intersection is not a null set, no separating hyperplane would exist. Construction (indicative): take  $a \in A$ ,  $c \in C$  such that these minimize  $d(x, y)$  for all  $x \in A$  and  $y \in C$  and show the shaded intersecting region. (1+1).

Q2 (b) **convex hull**: set of all convex combinations of points in set  $C$

$$\text{conv}(C) = \left\{ \sum_{i=1}^k \theta_i x_i \mid x_i \in C, \theta_i \geq 0, i=1 \text{ to } k \right\}$$

$$\text{set } A = \{x, y, z\}$$

$$\text{convex hull of set } A = \text{conv}(A) = \{ \theta_1 x + \theta_2 y + \theta_3 z \mid \theta_1, \theta_2, \theta_3 \geq 0 \}$$

for convexity let  $\alpha \in [0, 1]$   $v, w \in \text{conv}(A)$

$$v = \lambda_1 x + \lambda_2 y + \lambda_3 z, \quad \lambda_1, \lambda_2, \lambda_3 \geq 0$$
$$w = \mu_1 x + \mu_2 y + \mu_3 z, \quad \mu_1, \mu_2, \mu_3 \geq 0$$

$$\begin{aligned} \alpha v + (1-\alpha)w &= \alpha(\lambda_1 x + \lambda_2 y + \lambda_3 z) + (1-\alpha)(\mu_1 x + \mu_2 y + \mu_3 z) \\ &= (\alpha\lambda_1 + (1-\alpha)\mu_1)x + (\alpha\lambda_2 + (1-\alpha)\mu_2)y \\ &\quad + (\alpha\lambda_3 + (1-\alpha)\mu_3)z \end{aligned}$$

since  $\lambda_1, \lambda_2, \lambda_3, \mu_1, \mu_2, \mu_3 \geq 0$   
 $\alpha \in [0, 1]$

$$\Rightarrow \alpha \cdot \lambda_i + (1-\alpha)\mu_i \geq 0$$

$$\therefore \alpha v + (1-\alpha)w \in \text{conv}(A)$$

$\therefore$  convex hull of set  $A$  is convex

**convex hull**: convex hull of set  $C \subseteq \mathbb{R}^n$  is set of all convex combinations of elements in  $C$

$$\text{conv}(C) = \left\{ \sum_{i=1}^k \theta_i x_i \mid x_i \in C, \theta_i \geq 0 \forall i, \sum_{i=1}^k \theta_i = 1 \right\}$$

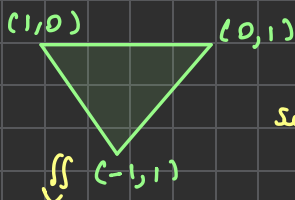
**convex**: set  $C$  is called convex if for every  $x \in C, \theta \geq 0$   
 $\theta x \in C$ .

No, convex hull of set A is not necessarily a cone

as a cone requires that if  $v \in A$  then  $\theta v \in A, \theta \geq 0$

But, convex hull do not necessarily satisfy this property, as they allow convex combinations of set A.

counter eg :



$$\text{set } A = \{(1,0), (0,1), (-1,-1)\} \in \mathbb{R}^2$$

convex hull of set A

it is not a cone as  $(1,0) \in A$

but  $2(1,0) = (2,0) \notin A$