

EDUCATION

B.Eng(Hons) Mechatronics Engineering OntarioTech University

09/2020 - Present

GPA: 3.12/4.3 (B)

Courses:

- **Control Systems**, Machine Design, Kinematics & Dynamics of Machines, Fluid Mechanics, CAD, Thermodynamics & Heat Transfer, Solid Mechanics.
- **Actuators & Power Electronics**, Electronic Circuit Design, **Microprocessors & Digital Systems**, Object Oriented Programming, Probability & Statistics.
- President's List F2020 & W2021, Dean's List F2021 & W2022
- Lean **Six Sigma Yellow Belt** Certified

WORK EXPERIENCE

Jr. Engineering Specialist, Advanced Engineering | Co-op Stackpole International Inc.

05/2022 - 09/2022

Toronto, Canada

Achievements/Tasks

- Created and implemented automotive-standard **Verification and Validation** testing procedures for mechatronic pumps, meeting IEC, ISO, and ASPICE requirements.
- Performed mechatronic pumps **benchmark testing**, analyzed results in Excel/PowerPoint, and mapped key performance parameters with respect to environmental conditions and system requirements for future design improvements.
- Applied **GD&T** and reviewed 2D/3D mechanical drawings and manufacturer specification sheets to conduct tolerance analysis for pump parts, ensuring desired fit and functionality.
- Managed warranty returns and conducted **RCA** (Root Cause Analysis) to develop effective resolution and mitigation plans for production pump issues, supporting studies and examinations.

Fanatics Customer Service Representative Teleperformance Canada

05/2019 - 09/2019

Toronto, Canada

Achievements/Tasks

- Provided outstanding customer service by utilizing in-depth knowledge of products and services, resulting in a **95% satisfaction** rate among customers.
- Handled customer inquiries on merchandise stock, sales, pricing, and company changes while upselling special orders to **increase total sales by 10%**.
- Liaised with vendors to obtain back order availability, track future inventory shipments, and place special orders.

SKILLS

3D CAD Modeling & Simulation

C/C++, Java & Python

SOLIDWORKS, Siemens NX, AutoCAD & SketchUp

Research & Technical Report Writing

HTML, CSS & JS

MS Excel, PowerPoint & Word

MATLAB & Simulink

NI Multisim & LabVIEW

Benchmark Testing

Use of Multimeter, Oscilloscope & Spectrum Analyzer

Strong Written & Verbal Communication

Arduino

Lean Six Sigma

Xilinx FPGA

Team Leadership

Product Development

Data Visualization

PROJECT EXPERIENCE

Personal Portfolio Website (01/2022 - Present)

- **URL:** harshkachhia.github.io/
- Coded a responsive personal website to showcase the Mechanical, Electrical and Software projects completed, along with their respective files, code & working video.

Electric Vehicle Driving/Regenerative Braking Model (02/2023 - 04/2023)

- Designed and tested software simulation of actuators and power electronics using **MATLAB Simulink**, and developed a hardware solution using Arduino, PM DC Motor, and Buck Boost module to harness braking energy for battery recharging.

Microprocessor Digital Counter (03/2023 - 04/2023)

- Designed and developed a digital circuit system utilizing the **Xilinx FPGA** design tool and Verilog code to count the number of guests entering a restaurant's drive-thru for statistical analysis, incorporating various components such as logic gates, registers, storage elements, and counters, with the output displayed using a 7-segment display.

Smart Home Security System (03/2023 - 04/2023)

- Developed a miniature smart home security system with Arduino that utilizes multiple analog and digital sensors, such as photocell sensors to detect light changes, PSD sensors to detect motion, infrared sensors to detect interruptions, sound sensors to detect noise levels, and touch sensors to detect physical contact for different intrusion scenarios.

IoT Thermometer (06/2022 - 06/2022)

- Constructed a portable thermometer using Arduino Uno attached to a power bank. Coded the device to accurately update temperature and humidity index data once every 1 second.
- Temperature data updates live on the OLED screen on the breadboard as well Bluetooth transmission to the phone via App for remote monitoring.

Autonomous Mechanical Rickshaw (10/2021 - 11/2021)

- Lead a team which designed and constructed a humanoid robot pulling a rickshaw carriage(Meccano Kit) that incorporated a gearbox mechanism to upscale torque from a 6V motor by 150% and a carriage with passive suspension using **DFMEA & 8D's methodology**.
- Modelled physical prototype in SOLIDWORKS to create a virtual model with an accurate motion analysis video.