PROGRAM:

Code:

```
#include <stdio.h>
#include <conio.h>
#include <math.h>
#include <graphics.h>
void multiply(float[3][3], float[3]), clearMat(float[3][3]);
void translate(float[3], float, float);
void rotate(float[3], float);
void scale(float[3], float, float);
void reflectX(float[3]), reflectY(float[3]), reflect(float[3]);
void shear(float[3], float, float);
void Triangle(float[3], float[3]);
       void main() {
       float p1[3] = \{0, 0, 1\}, p2[3] = \{0, 0, 1\}, p3[3] = \{0, 0, 1\};
       float tx, ty, sx, sy, shx, shy, theta;
       int ch;
       int gd = DETECT, gm;
       initgraph(&gd, &gm, "C:\\TURBOC3\\BGI");
       line(320, 0, 320, 480); //y-axis
       line(0, 240, 640, 240); //x-axis
       printf("Enter coordinates of first point of triangle\n");
       scanf("%f %f", &p1[0], &p1[1]);
       printf("Enter coordinates of second point of triangle\n");
       scanf("%f %f", &p2[0], &p2[1]);
       printf("Enter coordinates of third point of triangle\n");
       scanf("%f %f", &p3[0], &p3[1]);
```

```
Triangle(p1, p2, p3);
       printf("Enter your choice\n1-Translate\n2-Rotate\n3-Scale\n4-Reflect\n5-
Shear\n");
       scanf("%d", &ch);
switch(ch){
case 1:
       printf("Enter value of translation value in x direction\n");
       scanf("%f", &tx);
       printf("Enter translation value in y direction\n");
       scanf("%f", &ty);
       translate(p1, tx, ty);
       translate(p2, tx, ty);
       translate(p3, tx, ty);
       Triangle(p1, p2, p3);
       break;
case 2:
       printf("Enter angle of rotation in degrees\n");
       scanf("%f", &theta);
       theta *= 3.1415 f/180;
       rotate(p1, theta);
       rotate(p2, theta);
       rotate(p3, theta);
       Triangle(p1, p2, p3);
       break;
case 3:
       printf("Enter scale value in x direction\n");
       scanf("%f", &sx);
       printf("Enter scale value in y direction\n");
       scanf("%f", &sy);
```

```
scale(p1, sx, sy);
      scale(p2, sx, sy);
      scale(p3, sx, sy);
      Triangle(p1, p2, p3);
      break;
case 4:
      printf("Reflection about what ?\n");
      printf("1 - X axis\n2- Y axis\n3 - Origin");
      scanf("%d", &ch);
      if(ch == 1){
      reflectX(p1);
      reflectX(p2);
      reflectX(p3);
      else if(ch == 2){
      reflectY(p1);
      reflectY(p2);
      reflectY(p3);
      }
      else{
      reflect(p1);
      reflect(p2);
      reflect(p3);
      }
      Triangle(p1, p2, p3);
      break;
case 5:
      printf("Enter shearing value in x direction\n");
      scanf("%f", &shx);
```

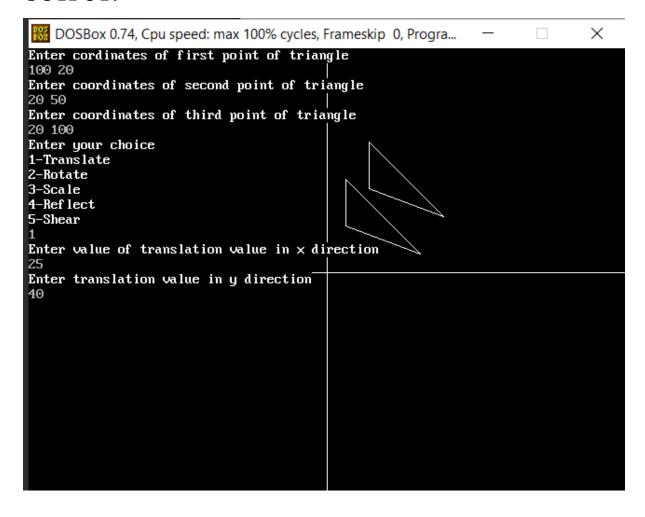
```
printf("Enter shearing value in y direction\n");
       scanf("%f", &shy);
       shear(p1, shx, shy);
       shear(p2, shx, shy);
       shear(p3, shx, shy);
       Triangle(p1, p2, p3);
       break;
}
getch();
closegraph();
}
void translate(float p[], float tx, float ty){
       int i, j;
       float mat[3][3];
       clearMat(mat);
mat[0][0] = 1;
mat[1][1] = 1;
mat[2][2] = 1;
mat[0][2] = tx;
mat[1][2] = ty;
multiply(mat, p);
}
void rotate(float p[], float theta){
       int i, j;
       float mat[3][3];
       clearMat(mat);
mat[0][0] = cos(theta);
mat[0][1] = -sin(theta);
mat[1][0] = sin(theta);
```

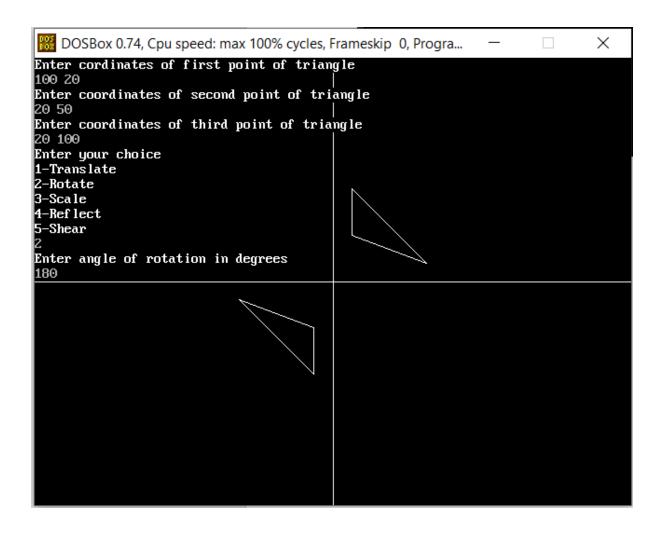
```
mat[1][1] = cos(theta);
mat[2][2] = 1;
multiply(mat, p);
void scale(float p[3], float sx, float sy){
       int i, j;
      float mat[3][3];
      clearMat(mat);
mat[0][0] = sx;
mat[1][1] = sy;
mat[2][2] = 1;
multiply(mat, p);
}
void reflectX(float p[3]){
      float mat[3][3];
       clearMat(mat);
mat[0][0] = 1;
mat[1][1] = -1;
mat[2][2] = 1;
multiply(mat, p);
}
void reflectY(float p[3]){
      float mat[3][3];
      clearMat(mat);
mat[0][0] = -1;
mat[1][1] = 1;
mat[2][2] = 1;
multiply(mat, p);
}
```

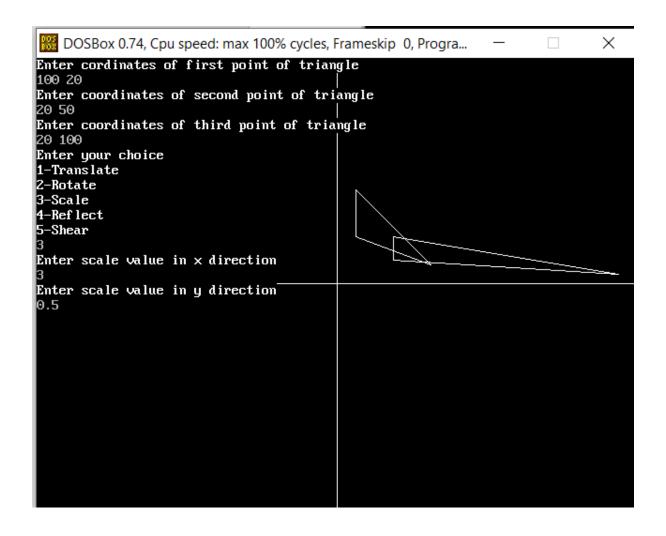
```
void reflect(float p[3]){
       float mat[3][3];
       clearMat(mat);
mat[0][0] = -1;
mat[1][1] = -1;
mat[2][2] = 1;
multiply(mat, p);
}
void shear(float p[3], float shx, float shy){
       float mat[3][3];
       clearMat(mat);
mat[0][0] = 1; mat[1][1] = 1; mat[2][2] = 1;
mat[1][0] = shx;
mat[0][1] = shy;
multiply(mat, p);
}
void multiply(float mat[3][3], float pt[3]){
       int pt0 = pt[0], pt1 = pt[1], pt2 = pt[2];
pt[0] = pt0*mat[0][0] + pt1*mat[0][1] + pt2*mat[0][2];
pt[1] = pt0*mat[1][0] + pt1*mat[1][1] + pt2*mat[1][2];
pt[2] = pt0*mat[2][0] + pt1*mat[2][1] + pt2*mat[2][2];
}
void Triangle(float p1[], float p2[], float p3[]){
line(320+p1[0], 240-p1[1], 320+p2[0], 240-p2[1]);
line(320+p2[0], 240-p2[1], 320+p3[0], 240-p3[1]);
line(320+p3[0], 240-p3[1], 320+p1[0], 240-p1[1]);
}
void clearMat(float mat[3][3]){
int i, j;
```

```
\begin{split} for(i=0;\, i<3;\, i++) \\ for(j=0;\, j<3;\, j++) \\ mat[i][j]=0; \end{split}
```

OUTPUT:







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| DOSBox 0.74, Cpu speed: max 100% cycles, F | rameskip 0, Progra | _ | | × | | | |
| Enter cordinates of first point of trian | gle | | | | | | |
| 100 20 | | | | | | | |
| Enter coordinates of second point of triangle | | | | | | | |
| 20 50 | | | | | | | |
| Enter coordinates of third point of triangle | | | | | | | |
| 20 100 | | | | | | | |
| Enter your choice | | | | | | | |
| 1-Translate | | | | | | | |
| 2-Rotate | | | | | | | |
| 3-Scale | | | | | | | |
| 4-Ref lect | | | | | | | |
| 5-Shear | | | | | | | |
| 4 | | | | | | | |
| Reflection about what ? | | | | | | | |
| 1 - X axis | | | | | | | |
| 2- Y axis | | | | | | | |
| 3 - Origin2 | | | | | | | |
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| DOSBox 0.74, Cpu speed: max 100% cycles, F | rameskip 0, Progra | _ | × |
|---|--------------------|---|---|
| Enter cordinates of first point of trian | gle | | |
| 0 0 Enter coordinates of second point of tri 40 | ang le | | |
| 0 Enter coordinates of third point of tria 0 | ngle | | |
| 40 Enter your choice 1-Translate 2-Rotate 3-Scale | | | |
| 4-Ref lect 5-Shear 5 | \geq | | |
| Enter shearing value in × direction 0 | | | |
| Enter shearing value in y direction 1 | | | |
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