

# Probability Assignment

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Question: The frequency response  $H(f)$  of of a linear time-invariant system has magnitude as shown in Fig. 0

Statement 1: The system is necessarily a pure delay system for inputs which are bandlimited to  $-a \leq f \leq a$ .

Statement 2: For any wide-sense stationary input process with power spectral density  $S_X(f)$ , the output power spectral density  $S_Y(f)$  obeys  $S_X(f) = S_Y(f)$  for  $-a \leq f \leq a$ .

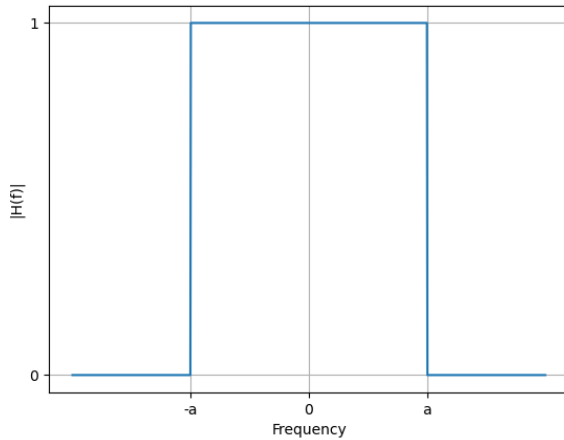


Fig. 0.  $|H(f)|$  vs frequency

**Solution:** A system where output signal is a delayed version of input signal with no other transformations or operations is called a pure delay system.

- 1) Let us consider a pure delay LTI system with  $x(t)$  and  $y(t)$  as input and output signals in time domain. Let  $T_d$  be delay between input and output. So,

$$y(t) = x(t - T_d) \quad (1)$$

Applying fourier transform,

$$\int_{-\infty}^{\infty} y(t) e^{-2\pi f j \omega t} dt = \int_{-\infty}^{\infty} x(t - T_d) e^{-2\pi f j \omega t} dt \quad (2)$$

$$= \int_{-\infty}^{\infty} x(t) e^{-2\pi f j \omega (t + T_d)} d(t + T_d) \quad (3)$$

$$= e^{-2\pi f j T_d} \int_{-\infty}^{\infty} x(t) e^{-2\pi f j \omega t} dt \quad (4)$$

$$Y(f) = e^{-2\pi f j T_d} X(f) \quad (5)$$

Here  $Y(f)$  and  $X(f)$  are output and input signals in frequency domain. Let  $H(f)$  be

$$H(f) = \frac{Y(f)}{X(f)} \quad (6)$$

$$= e^{-2\pi f j T_d} \quad (7)$$

$$= (1) e^{-2\pi f j T_d} \quad (8)$$

Comparing (8) with

$$H(f) = |H(f)| e^{j\angle H(f)} \quad (9)$$

$$|H(f)| = 1 \quad (10)$$

$$\angle H(f) = 2\pi f T_d \quad (11)$$

Here,  $\angle H(f)$  is directly proportional to frequency and time delay. The system will act as pure delay system. Now, if we take  $f^2$  as frequency, the system doesn't act as pure delay system because  $\angle H(f)$  is proportional to  $f^2$  but not  $f$ .

As input is bandlimited in  $-a \leq f \leq a$ . We have

$$|H(f)| = \begin{cases} 1 & \text{if } -a \leq f \leq a \\ 0 & \text{otherwise} \end{cases} \quad (12)$$

From (12) and Fig. 0,  $|H(f)|$  is same. Statement 1 is correct.

- 2) For wide-sense stationary LTI system,

$$S_Y(f) = |H(f)|^2 S_X(f) \quad (13)$$

From (12), for  $-a \leq f \leq a$ ,

$$S_Y(f) = (1)^2 S_X(f) \quad (14)$$

$$S_Y(f) = S_X(f) \quad (15)$$

Statement 2 is correct.